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# **advertorch\_test Documentation**

**tracy**

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### 1.1 Latest version (v0.1)

Installing AdverTorch itself

We developed AdverTorch under Python 3.6 and PyTorch 1.0.0 & 0.4.1. To install AdverTorch, simply run

```
pip install advertorch
```

or clone the repo and run

```
python setup.py install
```

To install the package in “editable” mode:

```
pip install -e .
```

### 1.2 Setting up the testing environments

Some attacks are tested against implementations in [Foolbox](<https://github.com/bethgelab/foolbox>) or [CleverHans](<https://github.com/tensorflow/cleverhans>) to ensure correctness. Currently, they are tested under the following versions of related libraries.

```
conda install -c anaconda tensorflow-gpu==1.11.0
pip install git+https://github.com/tensorflow/cleverhans.
↪git@336b9f4ed95dccc7f0d12d338c2038c53786ab70
pip install Keras==2.2.2
pip install foolbox==1.3.2
```





```
[ ]: # Copyright (c) 2018-present, Royal Bank of Canada.  
# All rights reserved.  
#  
# This source code is licensed under the license found in the  
# LICENSE file in the root directory of this source tree.  
#
```

```
[1]: import matplotlib.pyplot as plt  
%matplotlib inline  
  
import os  
import argparse  
import torch  
import torch.nn as nn  
  
from advertorch.utils import predict_from_logits  
from advertorch_examples.utils import get_mnist_test_loader  
from advertorch_examples.utils import _imshow  
  
torch.manual_seed(0)  
use_cuda = torch.cuda.is_available()  
device = torch.device("cuda" if use_cuda else "cpu")
```

### 2.1 Load model that is trained with `tut_train_mnist.py`

```
[2]: from advertorch.test_utils import LeNet5  
from advertorch_examples.utils import TRAINED_MODEL_PATH  
  
filename = "mnist_lenet5_clntrained.pt"  
# filename = "mnist_lenet5_advtrained.pt"
```

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```

model = LeNet5()
model.load_state_dict(
    torch.load(os.path.join(TRAINED_MODEL_PATH, filename)))
model.to(device)
model.eval()

```

```

/home/gavin/anaconda3/envs/dev/lib/python3.6/site-packages/h5py/__init__.py:36:
↪FutureWarning: Conversion of the second argument of issubdtype from `float` to `np.
↪floating` is deprecated. In future, it will be treated as `np.float64 == np.
↪dtype(float).type`.
    from ._conv import register_converters as _register_converters

```

```

[2]: LeNet5(
      (conv1): Conv2d(1, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
      (relu1): ReLU(inplace)
      (maxpool1): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_
↪mode=False)
      (conv2): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
      (relu2): ReLU(inplace)
      (maxpool2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_
↪mode=False)
      (linear1): Linear(in_features=3136, out_features=200, bias=True)
      (relu3): ReLU(inplace)
      (linear2): Linear(in_features=200, out_features=10, bias=True)
    )

```

## 2.2 Load data

```

[3]: batch_size = 5
      loader = get_mnist_test_loader(batch_size=batch_size)
      for cln_data, true_label in loader:
          break
      cln_data, true_label = cln_data.to(device), true_label.to(device)

```

## 2.3 Construct a LinfPGDAttack adversary instance

```

[4]: from advertorch.attacks import LinfPGDAttack

      adversary = LinfPGDAttack(
          model, loss_fn=nn.CrossEntropyLoss(reduction="sum"), eps=0.15,
          nb_iter=40, eps_iter=0.01, rand_init=True, clip_min=0.0, clip_max=1.0,
          targeted=False)

```

## 2.4 Perform untargeted attack

```

[5]: adv_untargeted = adversary.perturb(cln_data, true_label)

```

## 2.5 Perform targeted attack

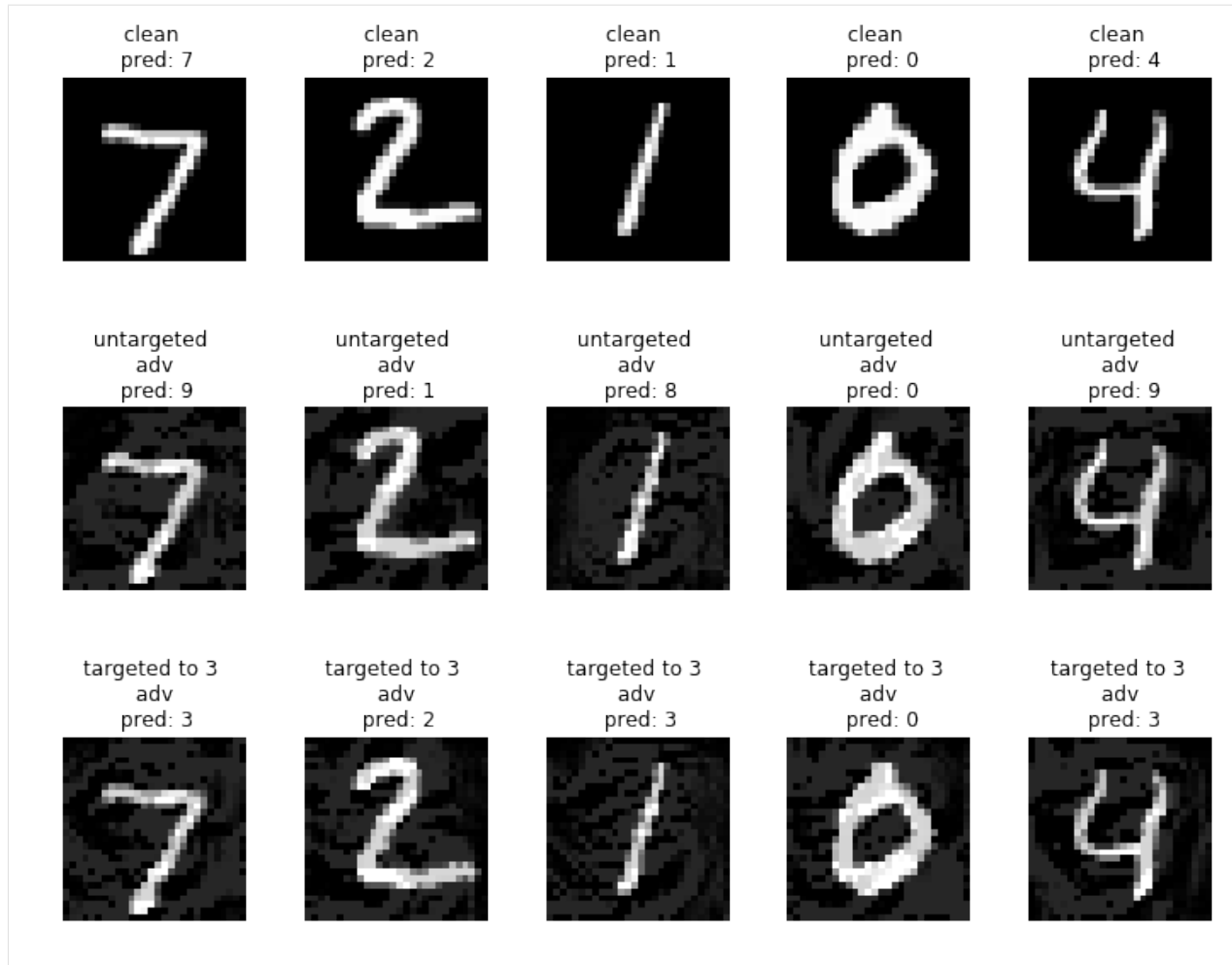
```
[6]: target = torch.ones_like(true_label) * 3
     adversary.targeted = True
     adv_targeted = adversary.perturb(cln_data, target)
```

## 2.6 Visualization of attacks

```
[7]: pred_cln = predict_from_logits(model(cln_data))
     pred_untargeted_adv = predict_from_logits(model(adv_untargeted))
     pred_targeted_adv = predict_from_logits(model(adv_targeted))

import matplotlib.pyplot as plt
plt.figure(figsize=(10, 8))
for ii in range(batch_size):
    plt.subplot(3, batch_size, ii + 1)
    _imshow(cln_data[ii])
    plt.title("clean \n pred: {}".format(pred_cln[ii]))
    plt.subplot(3, batch_size, ii + 1 + batch_size)
    _imshow(adv_untargeted[ii])
    plt.title("untargeted \n adv \n pred: {}".format(
        pred_untargeted_adv[ii]))
    plt.subplot(3, batch_size, ii + 1 + batch_size * 2)
    _imshow(adv_targeted[ii])
    plt.title("targeted to 3 \n adv \n pred: {}".format(
        pred_targeted_adv[ii]))

plt.tight_layout()
plt.show()
```



## 2.7 Construct defenses based on preprocessing

```
[8]: from advertorch.defenses import MedianSmoothing2D
from advertorch.defenses import BitSqueezing
from advertorch.defenses import JPEGFilter

bits_squeezing = BitSqueezing(bit_depth=5)
median_filter = MedianSmoothing2D(kernel_size=3)
jpeg_filter = JPEGFilter(10)

defense = nn.Sequential(
    jpeg_filter,
    bits_squeezing,
    median_filter,
)
```

## 2.8 Process the inputs using the defense

here we use the previous untargeted attack as the running example.

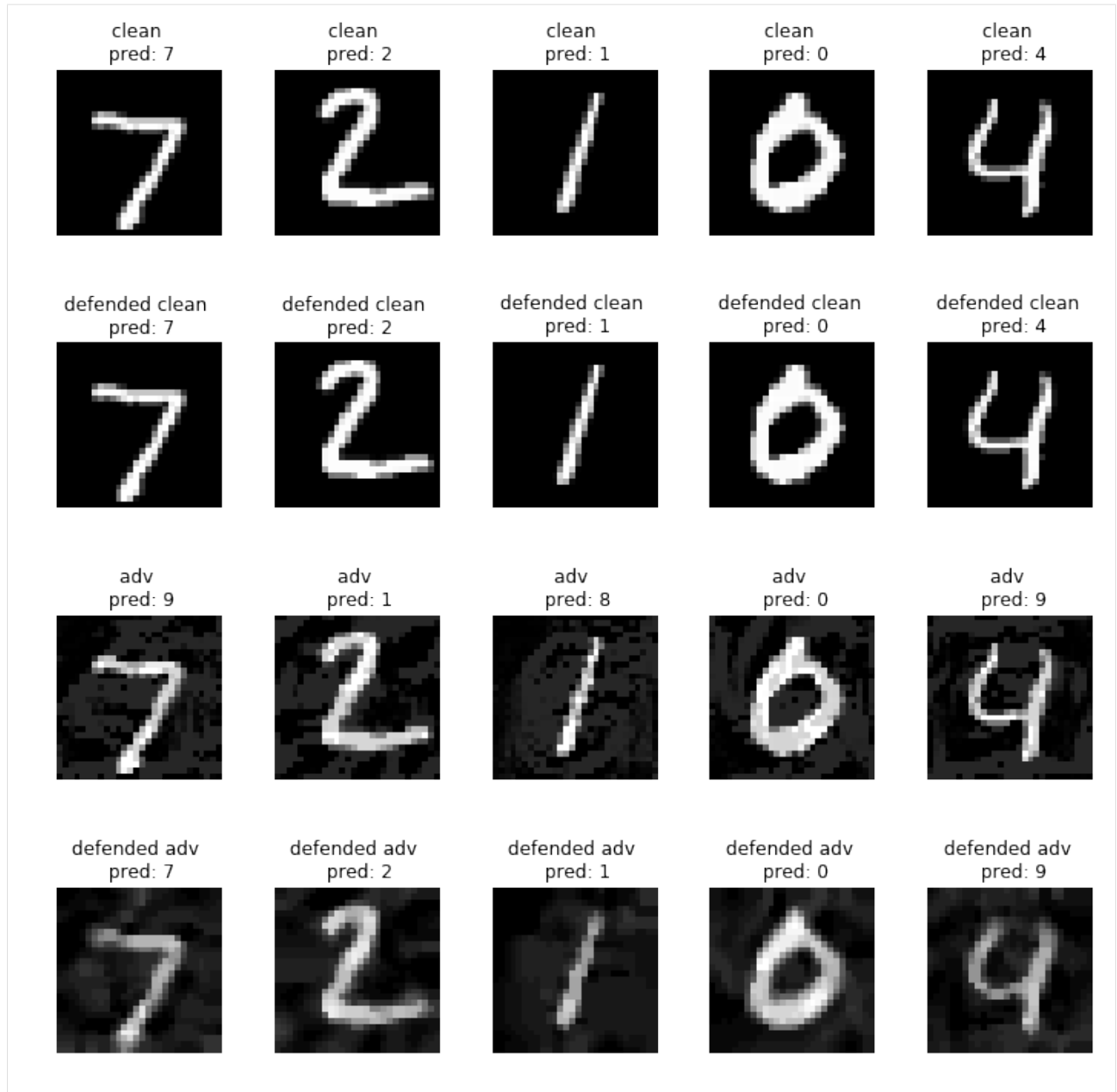
```
[9]: adv = adv_untargeted
     adv_defended = defense(adv)
     cln_defended = defense(cln_data)
```

## 2.9 Visualization of defenses

```
[10]: pred_cln = predict_from_logits(model(cln_data))
     pred_cln_defended = predict_from_logits(model(cln_defended))
     pred_adv = predict_from_logits(model(adv))
     pred_adv_defended = predict_from_logits(model(adv_defended))

import matplotlib.pyplot as plt
plt.figure(figsize=(10, 10))
for ii in range(batch_size):
    plt.subplot(4, batch_size, ii + 1)
    _imshow(cln_data[ii])
    plt.title("clean \n pred: {}".format(pred_cln[ii]))
    plt.subplot(4, batch_size, ii + 1 + batch_size)
    _imshow(cln_data[ii])
    plt.title("defended clean \n pred: {}".format(pred_cln_defended[ii]))
    plt.subplot(4, batch_size, ii + 1 + batch_size * 2)
    _imshow(adv[ii])
    plt.title("adv \n pred: {}".format(
        pred_adv[ii]))
    plt.subplot(4, batch_size, ii + 1 + batch_size * 3)
    _imshow(adv_defended[ii])
    plt.title("defended adv \n pred: {}".format(
        pred_adv_defended[ii]))

plt.tight_layout()
plt.show()
```



## 2.10 BPDA (Backward Pass Differentiable Approximation)

BPDA is a method proposed in [1], which can be used to attack non-differentiable preprocessing based defenses. Here we use  $f(x)$  to denote a non-differentiable component, and  $g(x)$  to denote a differentiable component that is similar to  $f(x)$ . In BPDA,  $f(x)$  is used in forward computation, and in the backward computation  $g(x)$  is used to propagate down the gradients.

Here we use BPDA to perform adaptive attack towards the defenses we used above.

[1] Athalye, A., Carlini, N. & Wagner, D.. (2018). Obfuscated Gradients Give a False Sense of Security: Circumventing Defenses to Adversarial Examples. Proceedings of the 35th International Conference on Machine Learning, in PMLR 80:274-283

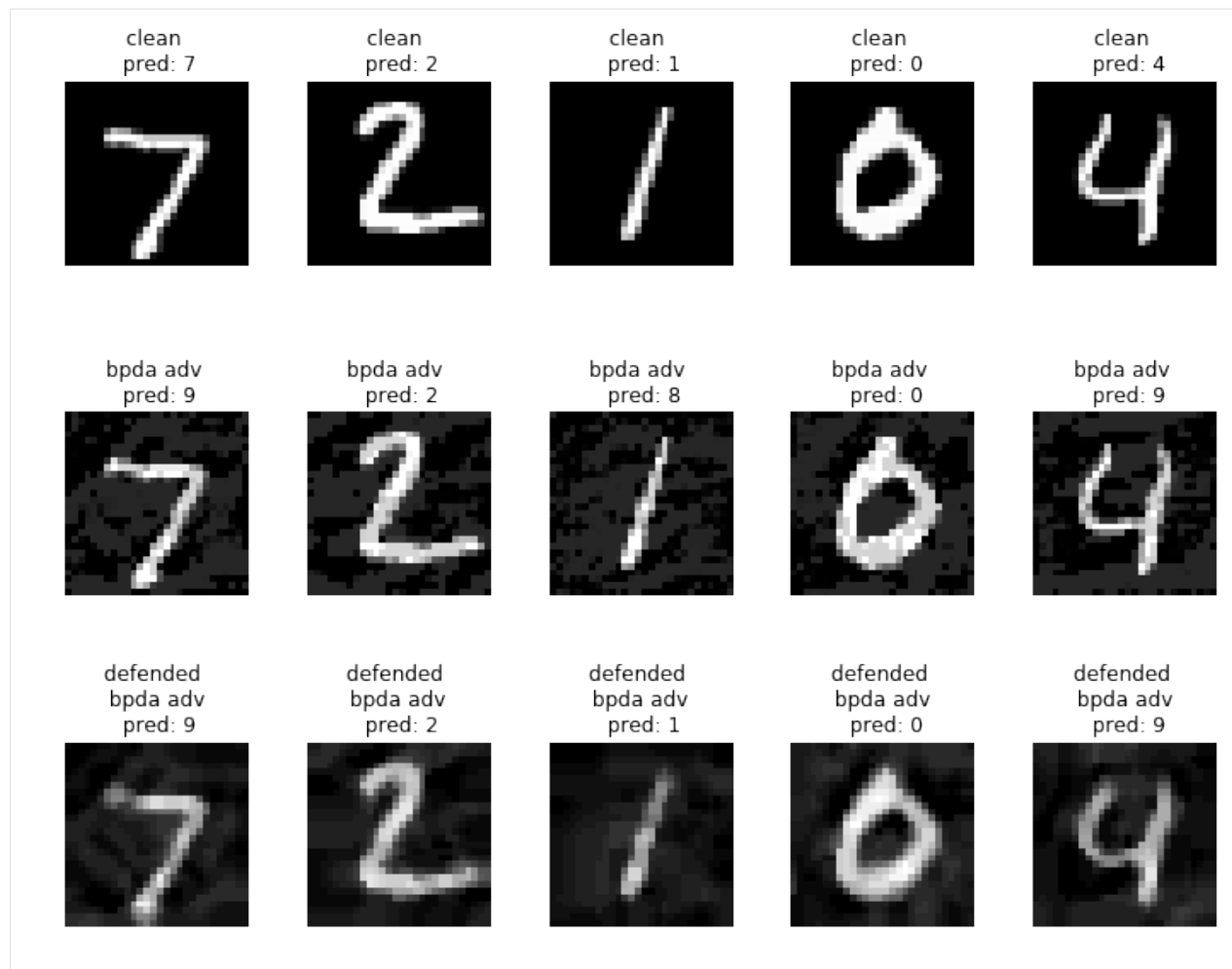
```
[11]: from advertorch.bpda import BPDAWrapper
defense_withbpda = BPDAWrapper(defense, forwardsub=lambda x: x)
defended_model = nn.Sequential(defense_withbpda, model)
bpda_adversary = LinfPGDAttack(
    defended_model, loss_fn=nn.CrossEntropyLoss(reduction="sum"), eps=0.15,
    nb_iter=1000, eps_iter=0.005, rand_init=True, clip_min=0.0, clip_max=1.0,
    targeted=False)

bpda_adv = bpda_adversary.perturb(cln_data, true_label)
bpda_adv_defended = defense(bpda_adv)
```

```
[12]: pred_cln = predict_from_logits(model(cln_data))
pred_bpda_adv = predict_from_logits(model(bpda_adv))
pred_bpda_adv_defended = predict_from_logits(model(bpda_adv_defended))

import matplotlib.pyplot as plt
plt.figure(figsize=(10, 8))
for ii in range(batch_size):
    plt.subplot(3, batch_size, ii + 1)
    _imshow(cln_data[ii])
    plt.title("clean \n pred: {}".format(pred_cln[ii]))
    plt.subplot(3, batch_size, ii + 1 + batch_size)
    _imshow(bpda_adv[ii])
    plt.title("bpda adv \n pred: {}".format(
        pred_bpda_adv[ii]))
    plt.subplot(3, batch_size, ii + 1 + batch_size * 2)
    _imshow(bpda_adv_defended[ii])
    plt.title("defended \n bpda adv \n pred: {}".format(
        pred_bpda_adv_defended[ii]))

plt.tight_layout()
plt.show()
```





advertorch.attacks

### 3.1 Attacks

<i>Attack</i>	Abstract base class for all attack classes.
<i>GradientAttack</i>	Perturbs the input with gradient (not gradient sign) of the loss wrt the input.
<i>GradientSignAttack</i>	One step fast gradient sign method (Goodfellow et al, 2014).
<i>FastFeatureAttack</i>	Fast attack against a target internal representation of a model using gradient descent (Sabour et al.
<i>L2BasicIterativeAttack</i>	Like GradientAttack but with several steps for each epsilon.
<i>LinfBasicIterativeAttack</i>	Like GradientSignAttack but with several steps for each epsilon.
<i>PGDAttack</i>	The projected gradient descent attack (Madry et al, 2017).
<i>LinfPGDAttack</i>	PGD Attack with order=Linf
<i>L2PGDAttack</i>	PGD Attack with order=L2
<i>MomentumIterativeAttack</i>	The L-inf projected gradient descent attack (Dong et al.
<i>CarliniWagnerL2Attack</i>	Carlini, Nicholas, and David Wagner “Towards evaluating the robustness of neural networks” 2017 IEEE Symposium on Security and Privacy (SP) IEEE, 2017.
<i>LBFGSAttack</i>	The attack that uses L-BFGS to minimize the distance of the original and perturbed images
<i>SinglePixelAttack</i>	Single Pixel Attack Algorithm 1 in <a href="https://arxiv.org/pdf/1612.06299.pdf">https://arxiv.org/pdf/1612.06299.pdf</a>
<i>LocalSearchAttack</i>	Local Search Attack Algorithm 3 in <a href="https://arxiv.org/pdf/1612.06299.pdf">https://arxiv.org/pdf/1612.06299.pdf</a>
<i>SpatialTransformAttack</i>	Spatially Transformed Attack

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Table 1 – continued from previous page

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<i>JacobianSaliencyMapAttack</i>	Jacobian Saliency Map Attack This includes Algorithm 1 and 3 in v1
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## 3.2 Detailed description

**class** advertorch.attacks.**Attack** (*predict, loss\_fn, clip\_min, clip\_max*)

Abstract base class for all attack classes.

### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function that takes .
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.

**perturb** (*x, \*\*kwargs*)

Generate the adversarial examples. This method should be overridden in any child class that implements an actual attack.

### Parameters

- **x** – the model’s input tensor.
- **\*\*kwargs** – optional parameters used by child classes.

**Returns** adversarial examples.

**class** advertorch.attacks.**GradientAttack** (*predict, loss\_fn=None, eps=0.3, clip\_min=0.0, clip\_max=1.0, targeted=False*)

Perturbs the input with gradient (not gradient sign) of the loss wrt the input.

### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – attack step size.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **targeted** – indicate if this is a targeted attack.

**perturb** (*x, y=None*)

Given examples (x, y), returns their adversarial counterparts with an attack length of eps.

### Parameters

- **x** – input tensor.
- **y** – label tensor. - if None and self.targeted=False, compute y as predicted labels.
  - if self.targeted=True, then y must be the targeted labels.

**Returns** tensor containing perturbed inputs.

**class** advertorch.attacks.**GradientSignAttack** (*predict*, *loss\_fn=None*, *eps=0.3*,  
*clip\_min=0.0*, *clip\_max=1.0*, *targeted=False*)

One step fast gradient sign method (Goodfellow et al, 2014). Paper: <https://arxiv.org/abs/1412.6572>

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – attack step size.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **targeted** – indicate if this is a targeted attack.

**perturb** (*x*, *y=None*)

Given examples (*x*, *y*), returns their adversarial counterparts with an attack length of *eps*.

#### Parameters

- **x** – input tensor.
- **y** – label tensor. - if *None* and *self.targeted=False*, compute *y* as predicted labels.
- if *self.targeted=True*, then *y* must be the targeted labels.

**Returns** tensor containing perturbed inputs.

**class** advertorch.attacks.**FastFeatureAttack** (*predict*, *loss\_fn=None*, *eps=0.3*,  
*eps\_iter=0.05*, *nb\_iter=10*, *rand\_init=True*,  
*clip\_min=0.0*, *clip\_max=1.0*)

Fast attack against a target internal representation of a model using gradient descent (Sabour et al. 2016). Paper: <https://arxiv.org/abs/1511.05122>

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – maximum distortion.
- **eps\_iter** – attack step size.
- **nb\_iter** – number of iterations
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.

**perturb** (*source*, *guide*, *delta=None*)

Given *source*, returns their adversarial counterparts with representations close to that of the *guide*.

#### Parameters

- **source** – input tensor which we want to perturb.
- **guide** – targeted input.
- **delta** – tensor contains the random initialization.

**Returns** tensor containing perturbed inputs.

```
class advertorch.attacks.L2BasicIterativeAttack(predict, loss_fn=None, eps=0.1,
                                                nb_iter=10, eps_iter=0.05,
                                                clip_min=0.0, clip_max=1.0, tar-
                                                geted=False)
```

Like GradientAttack but with several steps for each epsilon.

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – maximum distortion.
- **nb\_iter** – number of iterations.
- **eps\_iter** – attack step size.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **targeted** – if the attack is targeted.

```
class advertorch.attacks.LinfBasicIterativeAttack(predict, loss_fn=None, eps=0.1,
                                                  nb_iter=10, eps_iter=0.05,
                                                  clip_min=0.0, clip_max=1.0,
                                                  targeted=False)
```

Like GradientSignAttack but with several steps for each epsilon. Aka Basic Iterative Attack. Paper: <https://arxiv.org/pdf/1611.01236.pdf>

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – maximum distortion.
- **nb\_iter** – number of iterations.
- **eps\_iter** – attack step size.
- **rand\_init** – (optional bool) random initialization.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **ord** – (optional) the order of maximum distortion (inf or 2).
- **targeted** – if the attack is targeted.

```
class advertorch.attacks.PGDAttack(predict, loss_fn=None, eps=0.3, nb_iter=40,
                                   eps_iter=0.01, rand_init=True, clip_min=0.0,
                                   clip_max=1.0, ord=<Mock name='mock.inf'
                                   id='139818535385576'>, targeted=False)
```

The projected gradient descent attack (Madry et al, 2017). The attack performs nb\_iter steps of size eps\_iter, while always staying within eps from the initial point. Paper: <https://arxiv.org/pdf/1706.06083.pdf>

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – maximum distortion.

- **nb\_iter** – number of iterations.
- **eps\_iter** – attack step size.
- **rand\_init** – (optional bool) random initialization.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **ord** – (optional) the order of maximum distortion (inf or 2).
- **targeted** – if the attack is targeted.

**perturb** (*x*, *y=None*)

Given examples (*x*, *y*), returns their adversarial counterparts with an attack length of *eps*.

#### Parameters

- **x** – input tensor.
- **y** – label tensor. - if None and self.targeted=False, compute y as predicted labels.
- if self.targeted=True, then y must be the targeted labels.

**Returns** tensor containing perturbed inputs.

```
class advertorch.attacks.LinfPGDAttack (predict, loss_fn=None, eps=0.3, nb_iter=40,  
                                         eps_iter=0.01, rand_init=True, clip_min=0.0,  
                                         clip_max=1.0, targeted=False)
```

PGD Attack with order=Linf

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – maximum distortion.
- **nb\_iter** – number of iterations.
- **eps\_iter** – attack step size.
- **rand\_init** – (optional bool) random initialization.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **targeted** – if the attack is targeted.

```
class advertorch.attacks.L2PGDAttack (predict, loss_fn=None, eps=0.3, nb_iter=40,  
                                         eps_iter=0.01, rand_init=True, clip_min=0.0,  
                                         clip_max=1.0, targeted=False)
```

PGD Attack with order=L2

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – maximum distortion.
- **nb\_iter** – number of iterations.

- **eps\_iter** – attack step size.
- **rand\_init** – (optional bool) random initialization.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **targeted** – if the attack is targeted.

```
class advertorch.attacks.MomentumIterativeAttack (predict, loss_fn=None, eps=0.3,  
nb_iter=40, decay_factor=1.0,  
eps_iter=0.01, clip_min=0.0,  
clip_max=1.0, targeted=False)
```

The L-inf projected gradient descent attack (Dong et al. 2017). The attack performs nb\_iter steps of size eps\_iter, while always staying within eps from the initial point. The optimization is performed with momentum. Paper: <https://arxiv.org/pdf/1710.06081.pdf>

#### Parameters

- **predict** – forward pass function.
- **loss\_fn** – loss function.
- **eps** – maximum distortion.
- **nb\_iter** – number of iterations
- **decay\_factor** – momentum decay factor.
- **eps\_iter** – attack step size.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **targeted** – if the attack is targeted.

**perturb** (*x, y=None*)

Given examples (x, y), returns their adversarial counterparts with an attack length of eps.

#### Parameters

- **x** – input tensor.
- **y** – label tensor. - if None and self.targeted=False, compute y as predicted labels.  
– if self.targeted=True, then y must be the targeted labels.

**Returns** tensor containing perturbed inputs.

```
class advertorch.attacks.CarliniWagnerL2Attack (predict, num_classes, confi-  
dence=0, targeted=False, learn-  
ing_rate=0.01, binary_search_steps=9,  
max_iterations=10000,  
abort_early=True, initial_const=0.001,  
clip_min=0.0, clip_max=1.0,  
loss_fn=None)
```

Carlini, Nicholas, and David Wagner “Towards evaluating the robustness of neural networks” 2017 IEEE Symposium on Security and Privacy (SP) IEEE, 2017. <https://arxiv.org/abs/1608.04644>

#### Parameters

- **predict** – forward pass function.

- **num\_classes** – number of classes.
- **confidence** – confidence of the adversarial examples.
- **targeted** – TODO
- **learning\_rate** – the learning rate for the attack algorithm
- **binary\_search\_steps** – number of binary search times to find the optimum
- **max\_iterations** – the maximum number of iterations
- **abort\_early** – if set to true, abort early if getting stuck in local min
- **initial\_const** – initial value of the constant c
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **loss\_fn** – loss function

**perturb** (*x*, *y=None*)

Generate the adversarial examples. This method should be overridden in any child class that implements an actual attack.

#### Parameters

- **x** – the model’s input tensor.
- **\*\*kwargs** – optional parameters used by child classes.

**Returns** adversarial examples.

```
class advertorch.attacks.LBFGSAttack (predict, num_classes, batch_size=1, binary_search_steps=9, max_iterations=100, initial_const=0.01, clip_min=0, clip_max=1, loss_fn=None, targeted=False)
```

The attack that uses L-BFGS to minimize the distance of the original and perturbed images

#### Parameters

- **predict** – forward pass function.
- **num\_classes** – number of classes.
- **batch\_size** – number of samples in the batch
- **binary\_search\_steps** – number of binary search times to find the optimum
- **max\_iterations** – the maximum number of iterations
- **initial\_const** – initial value of the constant c
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **loss\_fn** – loss function
- **targeted** – if the attack is targeted.

**perturb** (*x*, *y=None*)

Generate the adversarial examples. This method should be overridden in any child class that implements an actual attack.

#### Parameters

- **x** – the model’s input tensor.

- **\*\*kwargs** – optional parameters used by child classes.

**Returns** adversarial examples.

```
class advertorch.attacks.SinglePixelAttack (predict, max_pixels=100, clip_min=0.0,  
                                           loss_fn=None, clip_max=1.0, com-  
                                           ply_with_foolbox=False, targeted=False)
```

Single Pixel Attack Algorithm 1 in <https://arxiv.org/pdf/1612.06299.pdf>

#### Parameters

- **predict** – forward pass function.
- **max\_pixels** – max number of pixels to perturb.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **loss\_fn** – loss function
- **targeted** – if the attack is targeted.

**perturb** (*x, y=None*)

Generate the adversarial examples. This method should be overridden in any child class that implements an actual attack.

#### Parameters

- **x** – the model's input tensor.
- **\*\*kwargs** – optional parameters used by child classes.

**Returns** adversarial examples.

```
class advertorch.attacks.LocalSearchAttack (predict, clip_min=0.0, clip_max=1.0,  
                                           p=1.0, r=1.5, loss_fn=None,  
                                           d=5, t=5, k=1, round_ub=10,  
                                           seed_ratio=0.1, max_nb_seeds=128, com-  
                                           ply_with_foolbox=False, targeted=False)
```

Local Search Attack Algorithm 3 in <https://arxiv.org/pdf/1612.06299.pdf>

#### Parameters

- **predict** – forward pass function.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **p** – parameter controls pixel complexity
- **r** – perturbation value
- **loss\_fn** – loss function
- **d** – the half side length of the neighbourhood square
- **t** – the number of pixels perturbed at each round
- **k** – the threshold for k-misclassification
- **round\_ub** – an upper bound on the number of rounds

**perturb** (*x, y=None*)

Generate the adversarial examples. This method should be overridden in any child class that implements an actual attack.



**Parameters**

- **x** – the model’s input tensor.
- **\*\*kwargs** – optional parameters used by child classes.

**Returns** adversarial examples.

```
class advertorch.attacks.SpatialTransformAttack(predict, num_classes, confidence=0,  
                                                initial_const=1, max_iterations=1000,  
                                                search_steps=1,      loss_fn=None,  
                                                clip_min=0.0,      clip_max=1.0,  
                                                abort_early=True, targeted=False)
```

Spatially Transformed Attack

**Parameters**

- **predict** – forward pass function.
- **num\_classes** – number of classes.
- **confidence** – confidence of the adversarial examples.
- **initial\_const** – initial value of the constant c
- **max\_iterations** – the maximum number of iterations
- **search\_steps** – number of search times to find the optimum
- **loss\_fn** – loss function
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.
- **abort\_early** – if set to true, abort early if getting stuck in local min
- **targeted** – if the attack is targeted

**perturb** (*x, y=None*)

Generate the adversarial examples. This method should be overridden in any child class that implements an actual attack.

**Parameters**

- **x** – the model’s input tensor.
- **\*\*kwargs** – optional parameters used by child classes.

**Returns** adversarial examples.

```
class advertorch.attacks.JacobianSaliencyMapAttack(predict, num_classes,  
                                                  clip_min=0.0, clip_max=1.0,  
                                                  loss_fn=None, theta=1.0,  
                                                  gamma=1.0,      com-  
                                                  ply_cleverhans=False)
```

Jacobian Saliency Map Attack This includes Algorithm 1 and 3 in v1

**Parameters**

- **predict** – forward pass function.
- **num\_classes** – number of classes.
- **clip\_min** – minimum value per input dimension.
- **clip\_max** – maximum value per input dimension.

- **gamma** – highest percentage of pixels can be modified
- **theta** – perturb length, range is either  $[\text{theta}, 0]$ ,  $[0, \text{theta}]$

**perturb** ( $x$ ,  $y=None$ )

Generate the adversarial examples. This method should be overridden in any child class that implements an actual attack.

### Parameters

- **x** – the model's input tensor.
- **\*\*kwargs** – optional parameters used by child classes.

**Returns** adversarial examples.

---

advertorch.defenses

---

## 4.1 Defenses

<i>Processor</i>	
<i>ConvSmoothing2D</i>	Conv Smoothing 2D.
<i>AverageSmoothing2D</i>	Average Smoothing 2D.
<i>GaussianSmoothing2D</i>	Gaussian Smoothing 2D.
<i>MedianSmoothing2D</i>	Median Smoothing 2D.
<i>JPEGFilter</i>	JPEG Filter.
<i>BitSqueezing</i>	Bit Squeezing.
<i>BinaryFilter</i>	Binary Filter.

## 4.2 Detailed description

**class** advertorch.defenses.**Processor**

**class** advertorch.defenses.**ConvSmoothing2D** (*kernel*)  
Conv Smoothing 2D.

**Parameters** **kernel\_size** – size of the convolving kernel.

**class** advertorch.defenses.**AverageSmoothing2D** (*channels, kernel\_size*)  
Average Smoothing 2D.

**Parameters**

- **channels** – number of channels in the output.
- **kernel\_size** – aperture size.

**class** advertorch.defenses.**GaussianSmoothing2D** (*sigma, channels, kernel\_size=None*)  
Gaussian Smoothing 2D.

**Parameters**

- **sigma** – sigma of the Gaussian.
- **channels** – number of channels in the output.
- **kernel\_size** – aperture size.

**class** advertorch.defenses.**MedianSmoothing2D** (*kernel\_size=3, stride=1*)  
Median Smoothing 2D.

### Parameters

- **kernel\_size** – aperture linear size; must be odd and greater than 1.
- **stride** – stride of the convolution.

**class** advertorch.defenses.**JPEGFilter** (*quality=75*)  
JPEG Filter.

### Parameters **quality** – quality of the output.

**class** advertorch.defenses.**BitSqueezing** (*bit\_depth, vmin=0.0, vmax=1.0*)  
Bit Squeezing.

### Parameters

- **bit\_depth** – bit depth.
- **vmin** – min value.
- **vmax** – max value.

**class** advertorch.defenses.**BinaryFilter** (*vmin=0.0, vmax=1.0*)  
Binary Filter.

### Parameters

- **vmin** – min value.
- **vmax** – max value.

---

advertorch.bpda

---

## 5.1 BPDA

---

*BPDAWrapper*

---

Wrap forward module with BPDA backward path If forwardsub is not None, then ignore backward

---

## 5.2 Detailed description

**class** advertorch.bpda.**BPDAWrapper** (*forward, forwardsub=None, backward=None*)  
 Wrap forward module with BPDA backward path If forwardsub is not None, then ignore backward

### Parameters

- **forwardsub** – substitute forward function for BPDA
- **backward** – substitute backward function for BPDA



---

`advertorch.context`

---

## 6.1 Context

---

`ctx_noparamgrad`

---

`ctx_eval`

---

## 6.2 Detailed description

**class** `advertorch.context.ctx_noparamgrad` (*module*)

**class** `advertorch.context.ctx_eval` (*module*)





## CHAPTER 7

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