# **ROS Qt Creator Plug-in**

Oct 06, 2018

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# Installation

## 1.1 How to Install (Users)

This wiki explains the procedure for installing the ROS Qt Creator Plug-in.

**Note:** If you primarily want to use this tool for development of other ROS packages (ie: not to work on the plugin itself), please follow the following instructions.

### 1.1.1 Installation

**Important:** The install method has changed from using the ppa method to a custom installer. This is to enable the ability to provide richer support leveraging existing ros tools which was not possible using the ppa.

#### Installation Procedure for Ubuntu 16.04

- 1. Download Installer:
  - (a) Xenial Online Installer (Recommended)
  - (b) Xenial Offline Installer

Note: The Offline Installer is to be used on machines that do not have internet access.

2. Next proceed to Qt Installer Procedure

Important: If previously installed using the ppa please follow the procedure below to remove old version.

```
sudo apt install ppa-purge
sudo ppa-purge -o beineri
sudo ppa-purge levi-armstrong/qt-libraries-xenial
sudo ppa-purge levi-armstrong/ppa
```

**Warning:** The ppa-purge removes everything installed from the ppa, so if the ppa is used for other development do not purge.

### Installation Procedure for Ubuntu 14.04

- 1. Download Installer:
  - (a) Trusty Online Installer (Recommended)
  - (b) Trusty Offline Installer

Note: The Offline Installer is to be used on machines that do not have internet access.

2. Next proceed to Qt Installer Procedure

Important: If previously installed using the ppa please follow the procedure below to remove old version.

```
sudo apt install ppa-purge
sudo ppa-purge -o beineri
sudo ppa-purge levi-armstrong/qt-libraries-xenial
sudo ppa-purge levi-armstrong/ppa
```

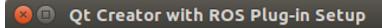
**Warning:** The ppa-purge removes everything installed from the ppa, so if the ppa is used for other development do not purge.

#### **Archived Versions**

If for some reason you need a version other than the latest, all installers may be found here.

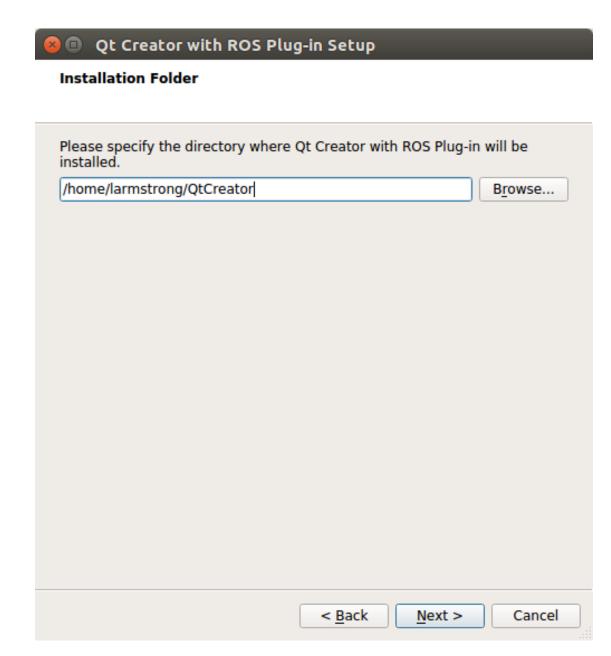
### **Qt Installer Procedure**

- 1. Then right click on the installer file, select properties and enable execution under permissions.
- 2. Next double click the installer and it should open and step throught the installer.



## Setup - Qt Creator with ROS Plug-in





# 😣 💿 🛛 Qt Creator with ROS Plug-in Setup

## Select Components

Please select the components you want to install.

Qt Creator for ROS Qt Creator (4.5.1) ROS Plug-in (0.2.1)	Install Qt Creator for ROS Development This component will occupy approximately 385.11 MiB on your hard disk drive.
Def <u>a</u> ult Select All Deselect All	1
< <u>B</u> ac	k <u>N</u> ext > Cancel

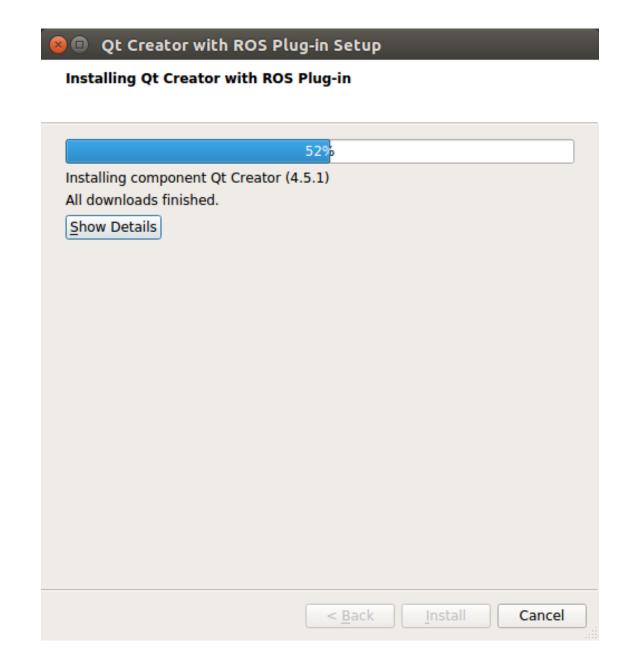
# 😣 💿 Qt Creator with ROS Plug-in Setup

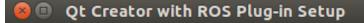
### License Agreement

Please read the following license agreements. You must accept the terms contained in these agreements before continuing with the installation.

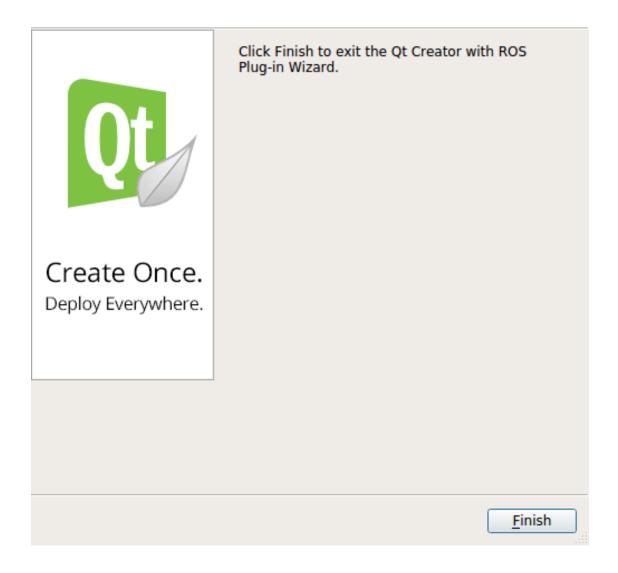
Copyright (c) 2017 ROS Industr	ial			
Contact: https://github.com/ros	-industrial/ros_qtc_plugin			
Licensed under the Apache Lice you may not use this file excep You may obtain a copy of the L	ense, Version 2.0 (the "License"); t in compliance with the License. icense at			
http://www.apache.org/licenses/LICENSE-2.0				
distributed under the License is WITHOUT WARRANTIES OR COI implied.	aw or agreed to in writing, software distributed on an "AS IS" BASIS, NDITIONS OF ANY KIND, either express or language governing permissions and			
<ul> <li>I accept the licenses.</li> </ul>				
I do not accept the licenses.				

<mark>8</mark> 🛛 🤇	t Creator	with ROS P	lug-in Sel	tup		
Ready	to Install					
Setup compu	is now ready ter. Installati	to begin inst on will use 3	alling Qt Cr 85.11 MiB d	eator wi f disk sp	th ROS Plug bace.	-in on your
			< Ba	ck	Install	Cancel





### **Completing the Qt Creator with ROS Plug-in Wizard**



1. How to get future updates, open Qt Creator and on the menubar under Help select "Check for Updates".

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	Projects	② Contents	> <no docum<="" th=""><th>ent&gt; •   ×</th><th></th><th>8+</th></no>	ent> •   ×		8+
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E		Technical Support				
Edit		Report Bug				
1		System Information				
Design		About Qt Creator About Plugins				
Debug		Check for Updates				
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0						
Help						
					<ul> <li>type c<space><pattern> to jump to a class definition</pattern></space></li> <li>type m<space><pattern> to jump to a function definition</pattern></space></li> <li>type f<space><filename> to open file from file system</filename></space></li> </ul>	
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### 1.1.2 Installation Issues and Conflicts

• No known issues

### 1.1.3 Testing Plugin.

- 1. Start Qt Creator
  - Option 1: Launch using the desktop icon.
  - Option 2: Launch from terminal.

qtcreator-ros

2. To verify that the plugin exist, goto File>New File or Project>Project>Other Project>ROS Workspace. If the ROS Workspace is present then everything built correctly and is ready for development and testing.

# 1.2 How to Install (Developers)

**Note:** If you'd like to contribute to the development of the ROS Qt Creator Plug-in, you are considered a *developer*, please follow the following instructions.

### 1.2.1 Installation

### Installation Procedure for Ubuntu 14.04

```
sudo add-apt-repository ppa:ubuntu-toolchain-r/test
sudo add-apt-repository ppa:levi-armstrong/qt-libraries-trusty
sudo add-apt-repository ppa:levi-armstrong/ppa
sudo apt-get update && sudo apt-get install qt57creator-plugin-ros libqtermwidget57-0-
$\imple$ dev
```

#### Installation Procedure for Ubuntu 16.04

### 1.2.2 Configure system to use the new version of Qt

After installation you need to tell qtchooser where to find this install. Replace the two lines in the file below with the location to the local version shown below. Make sure to change *username* and *version* in the file path to match your system.

File:

```
sudo gedit /usr/lib/x86_64-linux-gnu/qt-default/qtchooser/default.conf
```

File content:

/opt/qt57/bin /opt/qt57/lib

### 1.2.3 Run ROS Qt Creator setup script

1. Clone your fork of the repository.

```
git clone -b master https://github.com/<username>/ros_qtc_plugins.git
```

2. Next in a terminal, navigate into the repository directory and execute the command below.

bash setup.sh -d

**Note:** Instruction 2 can can be repeated to get the latest updates for Qt Creator source. The developer must manually update there fork to get the latest version of ros\_qtc\_plugins.

### 1.2.4 Testing Plugin

1. Execute the command below or launch using the desktop launcher.

qtcreator

2. To verify that the plugin exist, goto File>New File or Project>Project>Other Project>ROS Workspace. If the ROS Workspace is present then everything built correctly and is ready for development and testing.

### 1.2.5 Debug issues with Plugin

1. Next in a terminal, navigate to the repository ros\_qtc\_plugin and execute the command below.

bash setup.sh -di

2. Now launch qtcreator using gdb as shown below and after the plugin segfaults post the trace back in the active/new issue.

```
gdb <local>/qt-creator-build/bin/qtcreator
(gdb) run
```

After error:

(gdb) bt

# FAQ

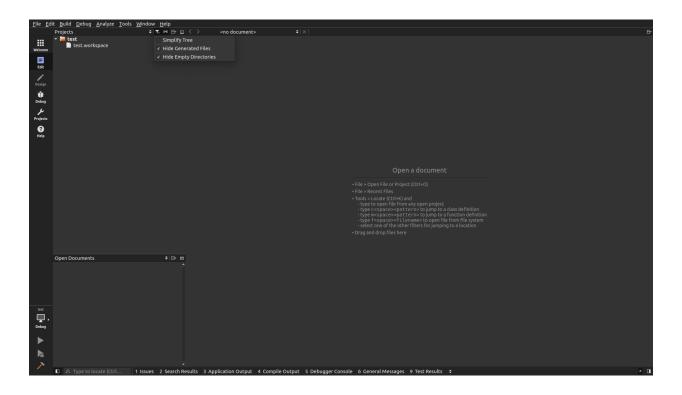
# 2.1 Frequently Asked Questions

This wiki highlights the frequently asked questions on the issue tracker.

- 1. How to show empty folders?
- 2. Are new files automaticly added to the CMakeLists.txt file?
- 3. Warning: This file is not part of any project.?

## 2.1.1 How to show empty folders?

By default Qt Creator hides empty folders. In the above image you can see that the workspace **src** folder is not shown. Under the project filters uncheck **Hide Empty Directories**.



## 2.1.2 Are new files automaticly added to the CMakeLists.txt file?

Currently it is the developers responsibility to edit the CMakeLists.txt file.

## 2.1.3 Warning: This file is not part of any project.?

This can be for several reason.

- 1. The workspace has not been built from within Qt Creator. Specific flags are passed to cmake which create specific project files which the IDE can parse to build a code model.
- 2. The file or files have not been added to the CMakeLists.txt file followed by a build from within Qt Creator.
- 3. Sometime is persist event if you address the previous items, but if code following is working then it should be ignored.

# **Users Help**

## 3.1 Setup Qt Creator for ROS

### 3.1.1 Setup Ubuntu to allow debugging/ptrace

- 1. Open file: sudo gedit /etc/rc.local
- 2. Add this line before the exit 0 line: echo 0 | tee /proc/sys/kernel/yama/ptrace\_scope
- 3. Reboot computer

### 3.1.2 Set Theme

If version 3.3.1 or higher was installed you are able to set the theme to dark following the steps bellow.

- 1. Open Qt Creator
- 2. Goto: Tools > Options > Environment > General
- 3. There should be a setting for Theme in the "User Interface" group containing a drop down box with two options "default or dark".

### 3.1.3 Set Syntax Color Schemes

- 1. Open Qt Creator
- 2. Goto: Tools > Options > Text Editor > Font & Colors
- 3. There is a drop down box in the "Color Scheme" group where you select different syntax color schemes.
- 4. Addition schemes can be added as explained in the below links.
  - (a) https://github.com/welkineins/qtcreator-themes
  - (b) https://github.com/alexpana/qt-creator-wombat-theme

## 3.1.4 Set ROS Code Format

- 1. Open Qt Creator
- 2. On the sidebar: Projects > Editor
  - Changing it globally at Tools > Options > C++ or within Projects > Code Style does not work.

## 3.1.5 Setup Clang Formatting

- 1. Install Clang sudo apt-get install clang-format-3.6
- 2. Goto: Tools > Options > Environment > External Tools
- 3. Select: Add > Add Tool
- 4. Fill in the information below.
  - Description: Clang Cpp Format
  - Executable: /usr/bin/clang-format-3.6
  - Arguments:

```
-style="{Language: Cpp, AccessModifierOffset: -2, AlignAfterOpenBracket: true,
→ AlignEscapedNewlinesLeft: false, AlignOperands:
                                                 true,
→AlignTrailingComments: true, AllowAllParametersOfDeclarationOnNextLine:
↔AllowShortCaseLabelsOnASingleLine: false,
→AllowShortIfStatementsOnASingleLine: false, AllowShortLoopsOnASingleLine:...
⇔false, AllowShortFunctionsOnASingleLine: All,
→AlwaysBreakAfterDefinitionReturnType: false,
→AlwaysBreakTemplateDeclarations: false, AlwaysBreakBeforeMultilineStrings:
→false, BreakBeforeBinaryOperators: None, BreakBeforeTernaryOperators: true,
→BreakConstructorInitializersBeforeComma: false, BinPackParameters: true,
→BinPackArguments: true, ColumnLimit:
                                         80,_
→ConstructorInitializerAllOnOneLineOrOnePerLine: false,...
→ConstructorInitializerIndentWidth: 4, DerivePointerAlignment: false,
→ExperimentalAutoDetectBinPacking: false, IndentCaseLabels: false,
→IndentWrappedFunctionNames: false, IndentFunctionDeclarationAfterType:_
→false, MaxEmptyLinesToKeep: 1, KeepEmptyLinesAtTheStartOfBlocks: true,
→NamespaceIndentation: None, ObjCBlockIndentWidth: 2,
→ObjCSpaceAfterProperty: false, ObjCSpaceBeforeProtocolList: true,
→PenaltyBreakBeforeFirstCallParameter: 19, PenaltyBreakComment: 300,
→PenaltyBreakString: 1000, PenaltyBreakFirstLessLess: 120,
→PenaltyExcessCharacter: 1000000, PenaltyReturnTypeOnItsOwnLine: 60,
↔PointerAlignment: Left , SpacesBeforeTrailingComments: 1,
→Cppl1BracedListStyle: true, Standard: Cppl1, IndentWidth: 2, TabWidth: 8,
↔UseTab: Never, BreakBeforeBraces: Allman, SpacesInParentheses: false,
⇔SpacesInSquareBrackets: false, SpacesInAngles: false,
→SpaceInEmptyParentheses: false, SpacesInCStyleCastParentheses: false,
→SpaceAfterCStyleCast: false, SpacesInContainerLiterals: true,
→SpaceBeforeAssignmentOperators: true, ContinuationIndentWidth: 4,
→CommentPragmas: '^ IWYU pragma:', ForEachMacros: [ foreach, Q_FOREACH,
→BOOST_FOREACH ], SpaceBeforeParens: ControlStatements, DisableFormat:
→false}" -i %{CurrentDocument:FilePath}
```

- Working directory: %{CurrentProject:Path}
- Output: Show in Pane

- Error output: Show in Pane
- Environment: No Changes to apply.
- Modifies current document: Checked
- 5. Select Apply
- 6. Now lets add a quick key.
- 7. Goto: Tools > Options > Environment > Keyboard
- 8. In the filter box type "Clang" and you should pull up the new tool.
- 9. In the Shortcut section enter the Target text box and press Ctrl + Shift + k to set the shortcut.
- 10. Now to apply the Clang format to a C++ file open the file in Qt Creator and press Ctrl + Shift + k and the file should be formatted correctly.

### 3.1.6 Preventing Qt Creator form stepping into Boost, Eigen, etc.

- 1. First clone this repository https://github.com/Levi-Armstrong/gdb-7.7.1.git
- 2. Follow the instruction in the README file
  - (a) ./configure
  - (b) make
  - (c) sudo checkinstall
- 3. Goto: Tools > Options > Debugger > GDB
- 4. Add the following code below to the "Additional Startup Commands"

```
skip pending on
python
for root, dirs, files in os.walk("/usr/include/boost/"):
    for file in files:
        if file.endswith(".hpp"):
            cmd = "skip file " + os.path.join(root, file)
            gdb.execute(cmd, True)

for root, dirs, files in os.walk("/usr/include/eigen3/Eigen/"):
    for file in files:
        if file.endswith(".hpp"):
            cmd = "skip file " + os.path.join(root, file)
            gdb.execute(cmd, True)
end
skip enable
```

- Now when you are stepping through your code it should not step into Boost or Eigen. You can also add additional directories following the same process.
- 6. Also if you would like to skip a particular function refer to the GDB documentation for instruction. It is something along the lines of *skip function function\_name*.

## 3.2 How to Import a ROS Workspace

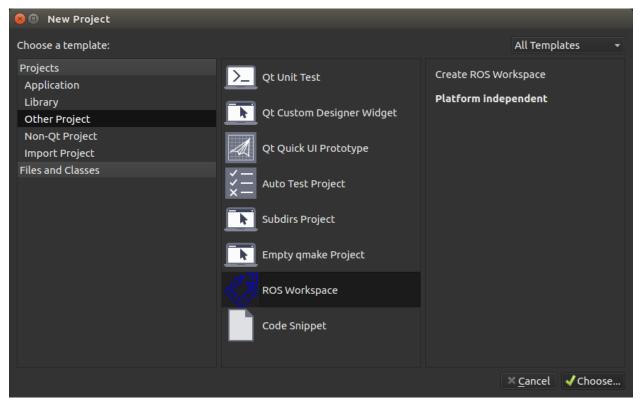
This wiki explains the procedure for importing a ROS Workspace.

Note: The pictures may not look identical based on version but the process flow is the same.

## 3.2.1 User Guide

### Step 1

On the Welcome screen select New Project and the following screen should show.



### Step 2

Under Projects select Other Projects > ROS Workspace then select Choose... and the following screen should show.

😣 💷 Creates New ROS Project				
Project Name and Location	Project Name and Location			
Summary	Name:	[		
	Distribution:	kinetic	•	
	Build System:	CatkinMake	•	
	Workspace Path:		Browse	
		<u>N</u> ext >	Cancel	

## Step 3

Fill out the project information.

Field	Description
Name	Name of the project.
Distribution	The ROS Distribution (indigo, kinetic, etc.)
Build System	The desired build system.
Workspace Path	The path to the workspace folder.

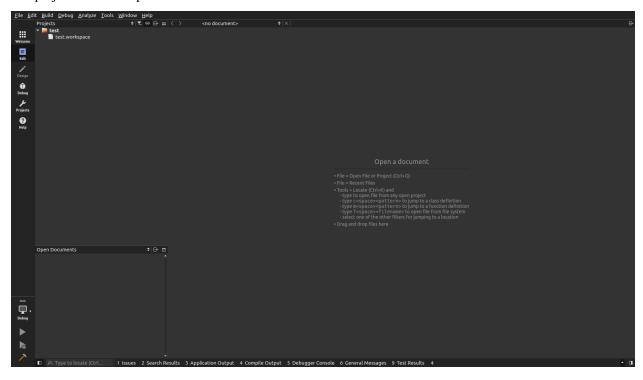
### Step 4

Select  ${\tt Next}$  and the following screen should show and select  ${\tt Finish}$  .

😣 🗈 Creates New ROS Project						
Project Name and Location	Project Management					
Summary	Add as a subproject to project:	<none></none>	-			
	Add to <u>v</u> ersion control:	<none> -</none>	Configure			
	Files to be added in					
	/home/larmstrong/catkin	n_ws/qtc_te	st:			
	test.workspace					
	< <u>B</u> ack	<u>F</u> inish	Cancel			

### Step 5

The project should be open look similar to the screen below.



### Step 6 (Optional)

By default Qt Creator hides empty folders. In the above image you can see that the workspace **src** folder is not shown. Under the project filters uncheck **Hide Empty Directories**.

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	Open Documents	• 8- 0	
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test Debug			
a.			Π
>	D     Q     Type to locate (Ctrl     1 Issue	2 Search Results 3 Application Output 4 Compile Output 5 Debugger Console 6 General Messages 9 Test Results +	
	I Issu	z scoren reservation o sepuer a complee o unplier o bebugger console o deneral messages o reservatica a	- <b>1</b>

## 3.3 Debugging Catkin Workspace

### 3.3.1 Prerequisite

1. Allow ptrace by following these instructions

### 3.3.2 Attach to a unstarted process

- 1. Next in Qt Creator browse to the file you wish to debug and insert break points.
- 2. Menu Bar>Debug>Start Debugging>Attach to Unstarted Application...
- 3. Browse to the executable then select Start Watching.
- 4. Now run your project. Ctrl + R
- 5. Now depending on where the breakpoints were placed in qt, it should be stopped at a break point when it reaches one.

### 3.3.3 Attach to a running process

- 1. Next in Qt Creator browse to the file you wish to debug and insert break points.
- 2. Now run your project. Ctrl + R

- 3. Menu Bar>Debug>Start Debugging>Attach to Running Application...
- 4. Now select the Process ID and then click the button  ${\tt Attach}$  to  ${\tt Process}.$
- 5. Now depending on where the breakpoints were placed in qt, it should be stopped at a break point when it reaches one.

#### Note:

- 1. Sometime it will be paused at a ros::spin, so check after it has attached and if it is passed and not at a inserted breakpoint click the continue button in the debugger.
- 2. Some nodes can execute fast enough to where the debugger is not fully attach to the process before it reaches the first breakpoint, resulting in it never stopping at the breakpoint. To solve this add a *sleep(NumberOfSeconds)* command at the start of the node to allow enough time for the debugger to attach. Usually 3 seconds is enough but varies depending on the size of the node.

# **Developers Help**

# 4.1 Where to find Qt Creator Plug-in Support

There are three reliable ways to get into contact:

- 1. There is the bug tracker on bugreports.qt.io. People here are very aware of everything entered there, but may not react immediately. But this is the best place for feature requests, bug reports and similar things that should not be forgotten.
- 2. Our mailing list is actively read by all developers. That is available here which should get most questions answered.
- 3. The fastest option is IRC: #qt-creator on the freenode network. All developers hang out there, at least while they are in the office. So European business hours tend to work best.

Note: This link provides a good overview of names to ping for specific questions.

# **Old Tutorials**

- 1. How to create a catkin workspace.
- 2. How to configure the run and build settings.

**Note:** Videos may not always be up-to-date so if you are not sure about something please refer to the *User Help* section.