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# **numericalmodel Documentation**

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## What is `numericalmodel`?

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The Python package `numericalmodel` is an attempt to **make prototyping simple numerical models** in Python an **easy and painless** task.

## Why should I prototype a numerical model in Python?

During development phase of a model, it is very handy to be able to flexibly change crucial model parts. One might want to quickly:

- add more **variables/parameters/forcings**
- add another **model equation**
- have specific **forcings be time-dependent**
- test another **numerical scheme**
- use **different numerical schemes for each equation**
- **combine numerical schemes** to solve different equation parts
- etc.

Quickly achieving this in a compiled, inflexible language like **Fortran** or **C** may not be that easy. Also, debugging or unit testing such a language is way more inconvenient than it is in Python. With Python, one can take advantage of the extreme flexibility that object orientation and object introspection provides.

While it is obvious, that such a prototyped model written in an interpreted language like Python will never come up to the speed and efficiency of a compiled language, it may seem very appealing in terms of flexibility. Once it's clear how the model should look like and fundamental changes are unlikely to occur anymore, it can be translated into another, faster language.

## Can I implement any numerical model with `numericalmodel`?

No, at least for now :-). Currently, there are a couple of restrictions:

- **only zero-dimensional models** are supported for now. Support for more dimensions is on the TODO-list.
- `numericalmodel` is focused on **physical models**

But that doesn't mean that you can't create new subclasses from `numericalmodel` to fit your needs.

## Is setting up a numerical model with `numericalmodel` really that easy?

Have a look at the *Basics*, *Setting up a model* and the *Examples* and see for yourself.

## CHAPTER 2

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### Installation

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*numericalmodel* is best installed via pip:

```
pip3 install --user numericalmodel
```





## Basic structure

The basic model structure is assumed the following:

- The model itself (*NumericalModel*) knows:
  - some metadata
  - the variables (*SetOfStateVariables*)
  - the parameters (*SetOfParameters*)
  - the forcing (*SetOfForcingValues*)
  - the numerical schemes (*SetOfNumericalSchemes*)
  - *[output facilities]*
- The numerical schemes (*SetOfNumericalSchemes*) know:
  - the individual numerical schemes (*NumericalScheme*) each for a specific equation (*Equation*)
  - how to integrate their equations (*NumericalScheme.integrate*)
- The equations (*SetOfEquations*) know:
  - the equation variable (*StateVariable*)
  - the equation input (*SetOfInterfaceValues*) - which may contain other variables
  - how to calculate the equation (e.g. the linear and nonlinear part of a derivative)

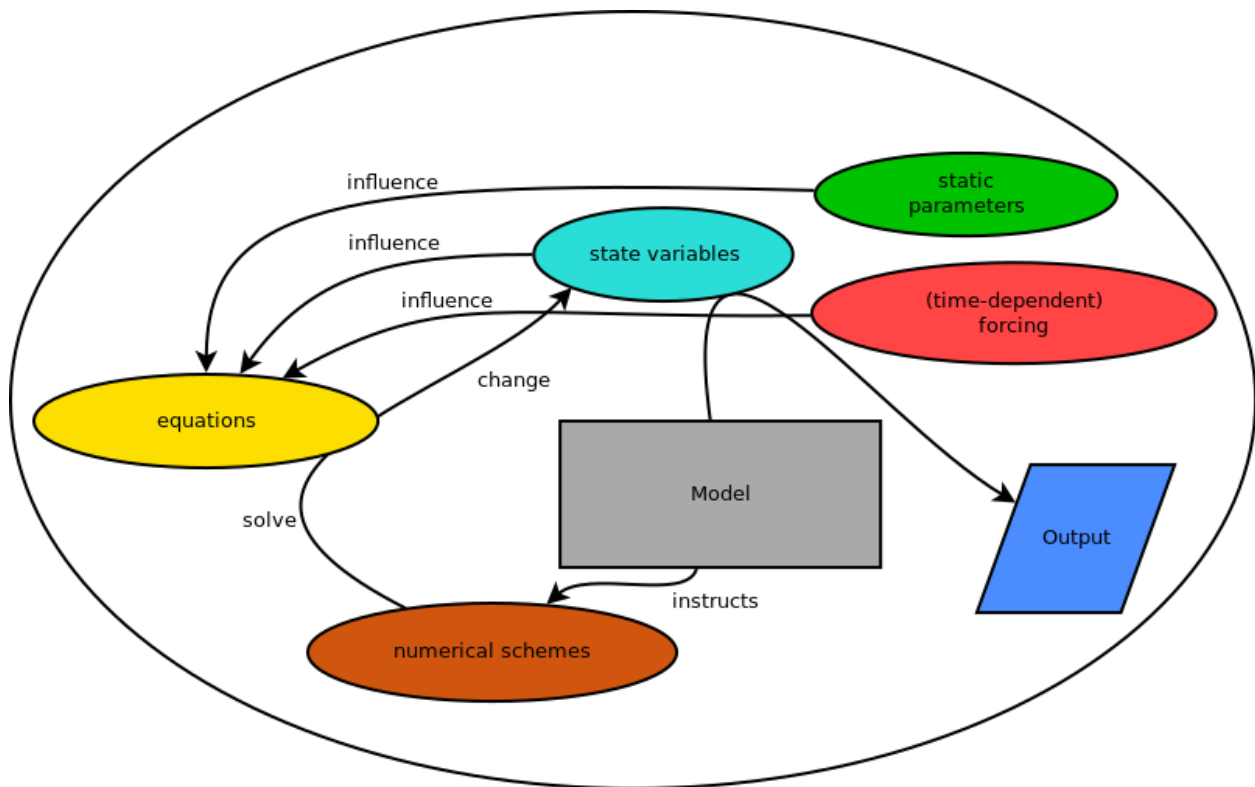


Fig. 3.1: The basic model structure

## CHAPTER 4

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### Setting up a model

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We are going to implement a simple linear decay equation:

$$\frac{dT}{dt} = -a \cdot T + F$$

Where  $T$  is the temperature in Kelvin,  $a > 0$  is the linear constant and  $F$  the forcing parameter.

To set up the model, some straight-forward steps are necessary. First, import the *numericalmodel* module:

```
import numericalmodel
```

### Creating a model

First initialize an object of *NumericalModel*:

```
model = numericalmodel.numericalmodel.NumericalModel()
```

We may tell the model to start from time 0:

```
model.initial_time = 0
```

### Defining variables, parameters and forcing

The *StateVariable*, *Parameter*, and *ForcingValue* classes all derive from *InterfaceValue*, which is a convenient class for time/value management. It also provides interpolation (*InterfaceValue.\_\_call\_\_*). An *InterfaceValue* has a (sensibly unique) *id* for it to be referencable in a *SetOfInterfaceValues*.

For convenience, let's import everything from the *interfaces* submodule:

```
from numericalmodel.interfaces import *
```

Let's define our state variable. For the simple case of the linear decay equation, our only state variable is the temperature  $T$ :

```
temperature = StateVariable( id = "T", name = "temperature", unit = "K" )
```

Providing a name and a unit documents your model on the fly.

---

**Tip:** All classes in *numericalmodel* are subclasses of *ReprObject*. This makes them have a proper `__repr__` method to provide an as-exact-as-possible representation. So at any time you might do a `print(repr(temperature))` or just `temperature<ENTER>` in an interactive python session to see a representation of this object:

```
numericalmodel.interfaces.StateVariable(  
    unit = 'K',  
    bounds = [-inf, inf],  
    name = 'temperature',  
    times = array([], dtype=float64),  
    time_function = numericalmodel.utils.utcnowow,  
    id = 'T',  
    values = array([], dtype=float64),  
    interpolation = 'zero'  
)
```

---

The others -  $a$  and  $F$  - are created similarly:

```
parameter = Parameter( id = "a", name = "linear parameter", unit = "1/s" )  
forcing = ForcingValue( id = "F", name = "forcing parameter", unit = "K/s" )
```

Now we add them to the model:

```
model.variables = SetOfStateVariables( [ temperature ] )  
model.parameters = SetOfParameters( [ parameter ] )  
model.forcing = SetOfForcingValues( [ forcing ] )
```

---

**Note:** When an *InterfaceValue*'s *value* is set, a corresponding time is determined to record it. The default is to use the return value of the *InterfaceValue.time\_function*, which in turn defaults to the current utc timestamp. When the model was told to use temperature, parameter and forcing, it automatically set the *InterfaceValue.time\_function* to its internal *model\_time*. That's why it makes sense to define initial values **after** adding the *InterfaceValue*s to the model.

---

Now that we have defined our model and added the variables, parameters and forcing, we may set initial values:

```
temperature.value = 20 + 273.15  
parameter.value = 0.1  
forcing.value = 28
```

---

**Tip:** We could also have made use of *SetOfInterfaceValues*' handy indexing features and have said:

```
model.variables["T"].value = 20 + 273.15  
model.parameters["a"].value = 0.1  
model.forcing["F"].value = 28
```

**Tip:** A lot of objects in *numericalmodel* also have a sensible `__str__` method, which enables them to print a summary of themselves. For example, if we do a `print(model)`:

```
###
### "numerical model"
### - a numerical model -
### version 0.0.1
###
```

```
by:
anonymous
```

```
a numerical model
```

```
-----
This is a numerical model.
```

```
#####
### Model data ###
#####
```

```
initial time: 0
```

```
#####
### Variables ###
#####
```

```
"temperature"
--- T [K] ---
currently: 293.15 [K]
bounds: [-inf, inf]
interpolation: zero
1 total recorded values
```

```
#####
### Parameters ###
#####
```

```
"linear parameter"
--- a [1/s] ---
currently: 0.1 [1/s]
bounds: [-inf, inf]
interpolation: linear
1 total recorded values
```

```
#####
### Forcing ###
#####
```

```
"forcing parameter"
--- F [K/s] ---
currently: 28.0 [K/s]
bounds: [-inf, inf]
interpolation: linear
1 total recorded values
```

```
#####  
### Schemes ###  
#####  
  
none
```

## Defining equations

We proceed by defining our equation. In our case, we do this by subclassing *PrognosticEquation*, since the linear decay equation is a prognostic equation:

```
class LinearDecayEquation(numericalmodel.equations.PrognosticEquation):  
    """  
    Class for the linear decay equation  
    """  
    def linear_factor(self, time = None):  
        # take the "a" parameter from the input, interpolate it to the given  
        # "time" and return the negative value  
        return - self.input["a"](time)  
  
    def independent_addend(self, time = None):  
        # take the "F" forcing parameter from the input, interpolate it to  
        # the given "time" and return it  
        return self.input["F"](time)  
  
    def nonlinear_addend(self, *args, **kwargs):  
        return 0 # nonlinear addend is always zero (LINEAR decay equation)
```

Now we initialize an object of this class:

```
decay_equation = LinearDecayEquation(  
    variable = temperature,  
    input = SetOfInterfaceValues( [parameter, forcing] ),  
)
```

We can now calculate the derivative of the equation with the *derivative* method:

```
>>> decay_equation.derivative()  
-28.314999999999998
```

## Choosing numerical schemes

Alright, we have all input we need and an equation. Now everything that's missing is a numerical scheme to solve the equation. *numericalmodel* ships with the most common numerical schemes. They reside in the submodule *numericalmodel.numericalschemes*. For convenience, we import everything from there:

```
from numericalmodel.numericalschemes import *
```

For a linear decay equation whose parameters are independent of time, the *EulerImplicit* scheme is a good choice:

```
implicit_scheme = numericalmodel.numericalschemes.EulerImplicit(
    equation = decay_equation
)
```

We may now add the scheme to the model:

```
model.numericalschemes = SetOfNumericalSchemes( [ implicit_scheme ] )
```

That's it! The model is ready to run!

## Running the model

Running the model is as easy as telling it a final time:

```
model.integrate( final_time = model.model_time + 60 )
```

## Model results

The model results are written directly into the *StateVariable*'s cache. You may either access the values directly via the *values* property (a *numpy.ndarray*) or interpolated via the *InterfaceValue.\_\_call\_\_* method.

One may plot the results with *matplotlib.pyplot*:

```
import matplotlib.pyplot as plt

plt.plot( temperature.times, temperature.values,
          linewidth = 2,
          label = temperature.name,
          )
plt.xlabel( "time [seconds]" )
plt.ylabel( "{} [{}].format( temperature.name, temperature.unit ) )
plt.legend()
plt.show()
```

The full code can be found in the *Examples* section.

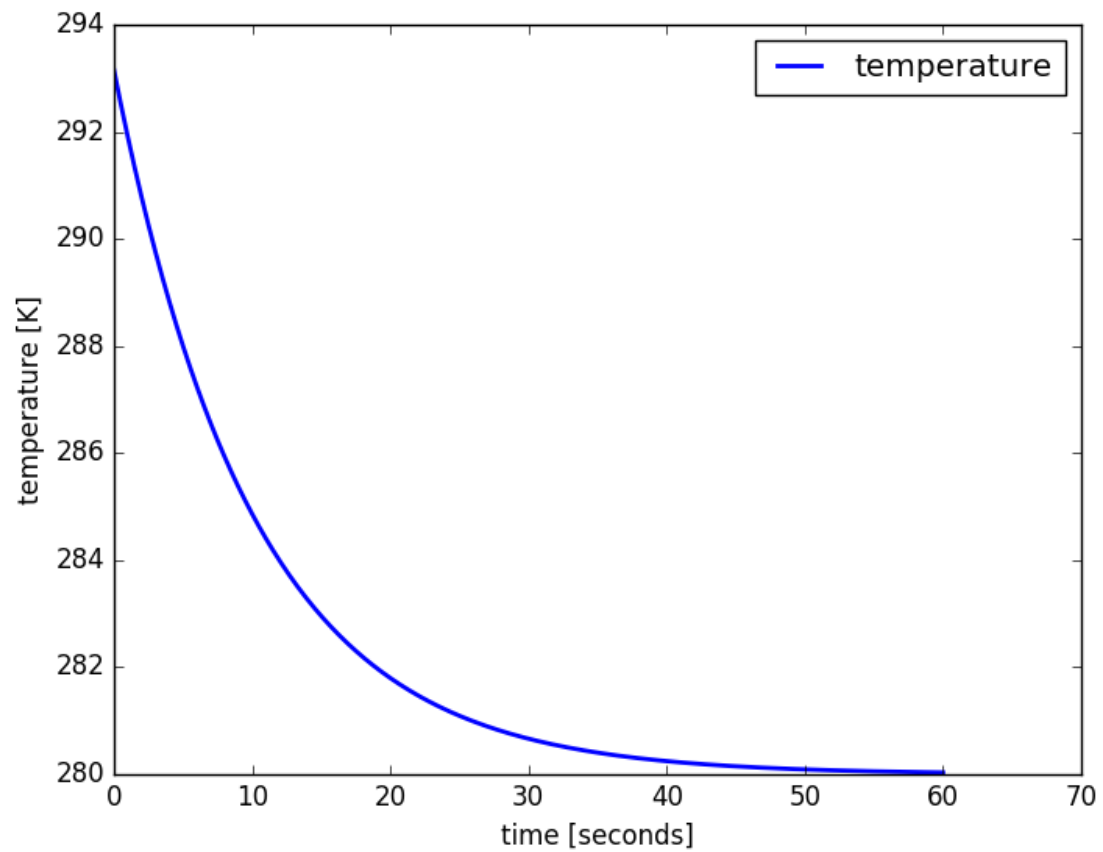


Fig. 4.1: The linear decay model results



## Linear decay equation

This is the full code from the *Setting up a model* section.

```
# import the module
import numericalmodel
from numericalmodel.interfaces import *
from numericalmodel.numericalschemes import *

# create a model
model = numericalmodel.numericalmodel.NumericalModel()
model.initial_time = 0

# define values
temperature = StateVariable( id = "T", name = "temperature", unit = "K" )
parameter = Parameter( id = "a", name = "linear parameter", unit = "1/s" )
forcing = ForcingValue( id = "F", name = "forcing parameter", unit = "K/s" )

# add the values to the model
model.variables = SetOfStateVariables( [ temperature ] )
model.parameters = SetOfParameters( [ parameter ] )
model.forcing = SetOfForcingValues( [ forcing ] )

# set initial values
model.variables["T"].value = 20 + 273.15
model.parameters["a"].value = 0.1
model.forcing["F"].value = 28

# define the equation
class LinearDecayEquation(numericalmodel.equations.PrognosticEquation):
    """
    Class for the linear decay equation
    """
    def linear_factor(self, time = None ):
```

```
# take the "a" parameter from the input, interpolate it to the given
# "time" and return the negative value
return - self.input["a"](time)

def independent_addend(self, time = None ):
    # take the "F" forcing parameter from the input, interpolate it to
    # the given "time" and return it
    return self.input["F"](time)

def nonlinear_addend(self, *args, **kwargs):
    return 0 # nonlinear addend is always zero (LINEAR decay equation)

# create an equation object
decay_equation = LinearDecayEquation(
    variable = temperature,
    input = SetOfInterfaceValues( [parameter, forcing] ),
)

# create a numerical scheme
implicit_scheme = numericalmodel.numericalschemes.EulerImplicit(
    equation = decay_equation
)

# add the numerical scheme to the model
model.numericalschemes = SetOfNumericalSchemes( [ implicit_scheme ] )

# integrate the model
model.integrate( final_time = model.model_time + 60 )

# plot the results
import matplotlib.pyplot as plt

plt.plot( temperature.times, temperature.values,
    linewidth = 2,
    label = temperature.name,
)
plt.xlabel( "time [seconds]" )
plt.ylabel( "{} [{}]".format( temperature.name, temperature.unit ) )
plt.legend()
plt.show()
```

## Heat transfer equation

This is an implementation of the heat transfer equation to simulate heat transfer between two reservoirs:

$$c_1 m_1 \frac{dT_1}{dt} = -a \cdot (T_2 - T_1)$$

$$c_2 m_2 \frac{dT_2}{dt} = -a \cdot (T_1 - T_2)$$

```
# system module
import logging

# own modules
import numericalmodel
```

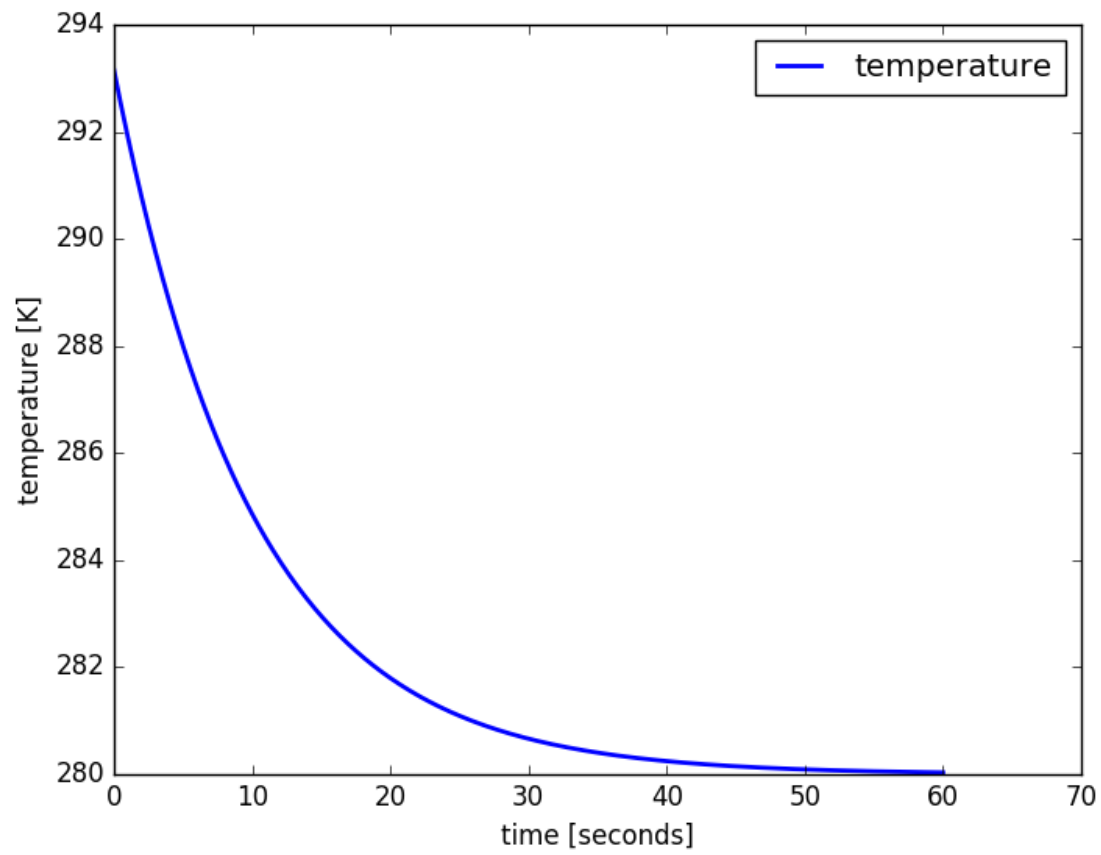


Fig. 5.1: The linear decay model results

```

from numericalmodel.numericalmodel import NumericalModel
from numericalmodel.interfaces import *
from numericalmodel.equations import *
from numericalmodel.numericalschemes import *

# external modules
import numpy as np
import matplotlib.pyplot as plt

logging.basicConfig(level = logging.INFO)

model = NumericalModel()
model.name = "simple heat transfer model"

### Variables ###
temperature_1 = StateVariable(id = "T1", name = "air temperature", unit = "K")
temperature_2 = StateVariable(id = "T2", name = "water temperature", unit = "K")

### Parameters ###
transfer_parameter = Parameter(
    id = "a", name = "heat transfer parameter", unit = "W/K")
spec_heat_capacity_1 = Parameter(
    id = "c1", name = "specific heat capacity of dry air", unit = "J/(kg*K)")
spec_heat_capacity_2 = Parameter(
    id = "c2", name = "specific heat capacity of water", unit = "J/(kg*K)")
mass_1 = Parameter(id = "m1", name = "mass of air", unit = "kg")
mass_2 = Parameter(id = "m2", name = "mass of water", unit = "kg")

# add variables and parameters to model
model.variables = \
    SetOfStateVariables( [temperature_1, temperature_2] )
model.parameters = \
    SetOfParameters( [ transfer_parameter, spec_heat_capacity_1,
                        spec_heat_capacity_2, mass_1, mass_2, ] )

### set initial values ###
model.initial_time = 0
temperature_1.value = 30 + 273.15
temperature_2.value = 10 + 273.15
mass_1.value = 20
mass_2.value = 10
spec_heat_capacity_1.value = 1005
spec_heat_capacity_2.value = 4190
transfer_parameter.value = 1.5

### define the heat transfer equation ###
class HeatTransferEquation( PrognosticEquation ):
    """
    Heat transfer equation:
    
$$c_1 * m_1 * \frac{dT_1}{dt} = a * (T_2 - T_1)$$

    
$$c_2 * m_2 * \frac{dT_2}{dt} = a * (T_1 - T_2)$$

    """
    def linear_factor( self, time = None ):
        v = lambda var: self.input[var](time)
        res = {
            "T1" : - v("a") / ( v("c1") * v("m1") ) ,
            "T2" : - v("a") / ( v("c2") * v("m2") ) ,
        }

```

```

        return res.get(self.variable.id,0)

    def nonlinear_addend( self, *args, **kwargs ):
        return 0

    def independent_addend( self, time = None ):
        v = lambda var: self.input[var](time)
        res = {
            "T1": v("a") * v("T2") / ( v("c1") * v("m1") ),
            "T2": v("a") * v("T1") / ( v("c2") * v("m2") ),
        }
        return res.get(self.variable.id,0)

# define equation input
equation_input = SetOfInterfaceValues( [
    temperature_1, temperature_2, transfer_parameter, spec_heat_capacity_1,
    spec_heat_capacity_2, mass_1, mass_2,
])

# set up equations
transfer_equation_1 = \
    HeatTransferEquation( variable = temperature_1, input = equation_input )
transfer_equation_2 = \
    HeatTransferEquation( variable = temperature_2, input = equation_input )

### numerical schemes ###
model.numericalschemes = SetOfNumericalSchemes( [
    EulerExplicit( equation = transfer_equation_1 ),
    EulerExplicit( equation = transfer_equation_2 ),
] )

# integrate the model
model.integrate( final_time = model.model_time + 3600 * 24 )

### calculate the analytical stationary solution ###
v = lambda var: equation_input[var].value
stationary_temperature = \
    ( v("c1") * v("m1") * v("T1") + v("c2") * v("m2") * v("T2") ) \
    / ( v("c1") * v("m1") + v("c2") * v("m2") )

logging.info("stationary solution: {}".format(stationary_temperature))
logging.info("    air temperature: {}".format(temperature_1.value))
logging.info("    water temperature: {}".format(temperature_2.value))

### Plot ###
fig, ax = plt.subplots()
ax.set_title(model.name)
ax.plot( ( temperature_1.times.min()/3600, temperature_1.times.max()/3600 ),
        ( stationary_temperature, stationary_temperature ),
        linewidth = 2,
        label = "analytical stationary solution",
    )
ax.plot( temperature_1.times/3600, temperature_1.values,
        linewidth = 2,
        label = temperature_1.name,
    )
ax.plot( temperature_2.times/3600, temperature_2.values,
        linewidth = 2,

```

```
label = temperature_2.name,  
)  
ax.set_xlabel( "time [hours]" )  
ax.set_ylabel( "temperature [{}]" .format( temperature_1.unit ) )  
ax.legend()  
plt.show()
```

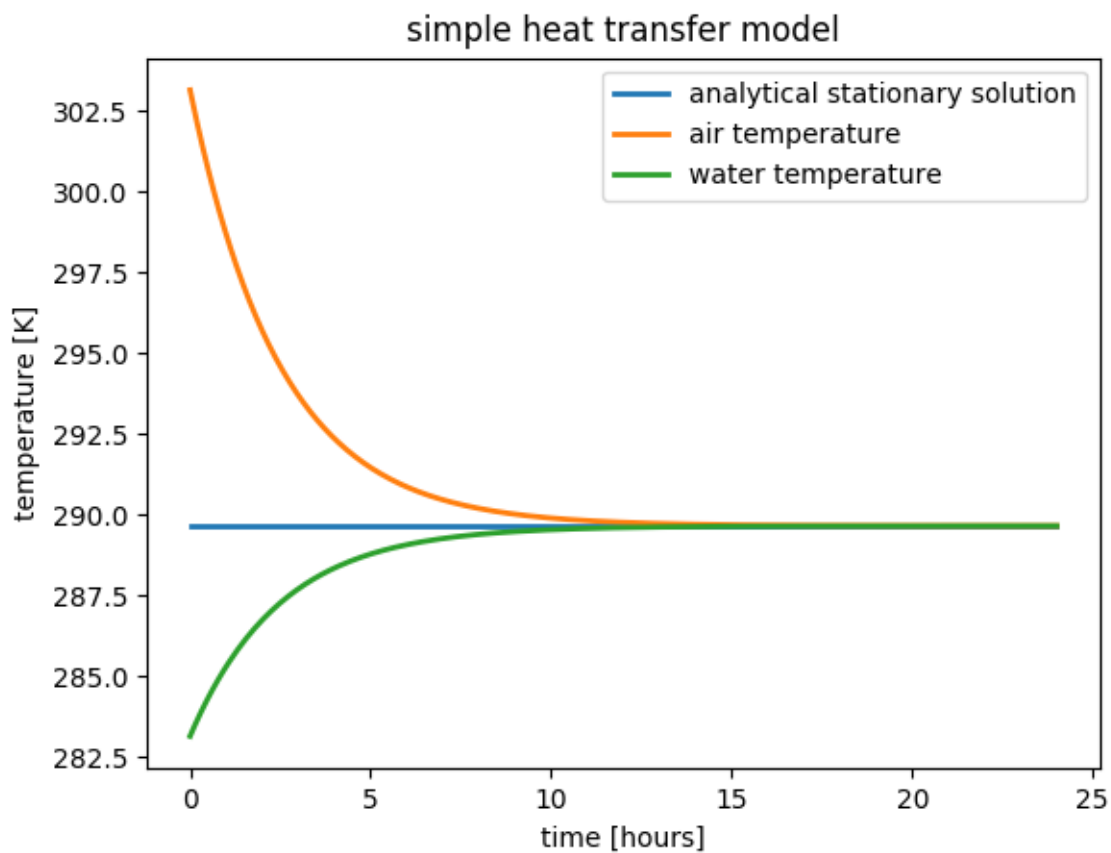


Fig. 5.2: heat transfer model results

### numericalmodel package

numericalmodel Python module

### Subpackages

#### numericalmodel.gui package

Graphical user interface for a NumericalModel. This module is only useful if the system package `python3-gi` is installed to provide the `gi` module.

To install, use your system's package manager and install `python3-gi`.

On Debian/Ubuntu:

```
sudo apt-get install python3-gi
```

---

**Note:** If you don't have system privileges, there is also the (experimental) `pgi` module on [PyPi](#) that you can install via:

```
pip3 install --user pgi
```

Theoretically, the `NumericalModelGui` might work with this package as well.

---

**class** `numericalmodel.gui.NumericalModelGui` (*numericalmodel*)

Bases: `numericalmodel.utils.LoggerObject`

class for a GTK gui to run a `NumericalModel` interactively

**Parameters** `numericalmodel` (`NumericalModel`) – the NumericalModel to run

`__getitem__` (*key*)

When indexed, return the corresponding Glade gui element

**Parameters** *key* (*str*) – the Glade gui element name

`quit` (*\*args*)

Stop the gui

`run` ()

Run the gui

`setup_gui` ()

Set up the GTK gui elements

`setup_signals` (*signals*, *handler*)

This is a workaround to `signal.signal(signal, handler)` which does not work with a `Glib.MainLoop` for some reason. Thanks to: <http://stackoverflow.com/a/26457317/5433146>

**Parameters**

- **signals** (*list*) – the signals (see `signal` module) to connect to
- **handler** (*callable*) – function to be executed on these signals

**builder**

The gui's `GtkBuilder`. This is a read-only property.

**Getter** Return the `GtkBuilder`, load the `gladefile` if necessary.

**Type** `GtkBuilder`

**gladefile**

The gui's Glade file. This is a read-only property.

**Type** `str`

## Submodules

### numericalmodel.equations module

**class** `numericalmodel.equations.DerivativeEquation` (*variable=None*, *description=None*,  
*long\_description=None*, *input=None*)

Bases: `numericalmodel.equations.Equation`

Class to represent a derivative equation

**derivative** (*time=None*, *variablevalue=None*)

Calculate the derivative (right-hand-side) of the equation

**Parameters**

- **time** (*single numeric*, *optional*) – the time to calculate the derivative. Defaults to the variable's current (last) time.
- **variablevalue** (*numpy.ndarray*, *optional*) – the variable value to use. Defaults to the value of `self.variable` at the given time.

**Returns** the derivatives corresponding to the given time

**Return type** `numpy.ndarray`

**independent\_addend** (*time=None*)

Calculate the derivative's addend part that is independent of the variable.



**Parameters** `time` (*single numeric, optional*) – the time to calculate the derivative.  
Defaults to the variable’s current (last) time.

**Returns** the equation’s variable-independent addend at the corresponding time

**Return type** `numpy.ndarray`

**linear\_factor** (`time=None`)

Calculate the derivative’s linear factor in front of the variable

**Parameters** `time` (*single numeric, optional*) – the time to calculate the derivative.  
Defaults to the variable’s current (last) time.

**Returns** the equation’s linear factor at the corresponding time

**Return type** `numpy.ndarray`

**nonlinear\_addend** (`time=None, variablevalue=None`)

Calculate the derivative’s addend part that is nonlinearly dependent of the variable.

**Parameters**

- **time** (*single numeric, optional*) – the time to calculate the derivative. Defaults to the variable’s current (last) time.
- **variablevalue** (`numpy.ndarray, optional`) – the variable value to use. Defaults to the value of `self.variable` at the given time.

**Returns** the equation’s nonlinear addend at the corresponding time

**Return type** `numpy.ndarray`

**class** `numericalmodel.equations.DiagnosticEquation` (`variable=None, description=None, long_description=None, input=None`)

Bases: `numericalmodel.equations.Equation`

Class to represent diagnostic equations

**class** `numericalmodel.equations.Equation` (`variable=None, description=None, long_description=None, input=None`)

Bases: `numericalmodel.utils.LoggerObject, numericalmodel.utils.ReprObject`

Base class for equations

**Parameters**

- **description** (`str, optional`) – short equation description
- **long\_description** (`str, optional`) – long equation description
- **variable** (`StateVariable, optional`) – the variable obtained by solving the equation
- **input** (`SetOfInterfaceValues, optional`) – set of values needed by the equation

**\_\_str\_\_** ()

Stringification

**Returns** a summary

**Return type** `str`

**depends\_on** (`id`)

Check if this equation depends on a given `InterfaceValue`

**Parameters** `id` (`str or InterfaceValue`) – an `InterfaceValue` or an `id`

**Returns** True if 'id' is in *input*, False otherwise

**Return type** *bool*

**description**

The description of the equation

**Type** *str*

**input**

The input needed by the equation. Only real dependencies should be included. If the equation depends on the *variable*, it should also be included in *input*.

**Type** *SetOfInterfaceValues*

**long\_description**

The longer description of this equation

**Type** *str*

**variable**

The variable the equation is able to solve for

**Type** *StateVariable*

**class** `numericalmodel.equations.PrognosticEquation` (*variable=None, description=None, long\_description=None, input=None*)

Bases: *numericalmodel.equations.DerivativeEquation*

Class to represent prognostic equations

**class** `numericalmodel.equations.SetOfEquations` (*elements=[]*)

Bases: *numericalmodel.utils.SetOfObjects*

Base class for sets of Equations

**Parameters** *elements* (*list* of *Equation*, optional) – the list of *Equation* instances

**\_object\_to\_key** (*obj*)

key transformation function.

**Parameters** *obj* (*object*) – the element

**Returns** the unique key for this object. The *Equation.variable*'s *id* is used.

**Return type** *str*

## numericalmodel.genericmodel module

**class** `numericalmodel.genericmodel.GenericModel` (*name=None, version=None, description=None, long\_description=None, authors=None*)

Bases: *numericalmodel.utils.LoggerObject, numericalmodel.utils.ReprObject*

Base class for models

**Parameters**

- **name** (*str*, optional) – the model name
- **version** (*str*, optional) – the model version
- **description** (*str*) – a short model description
- **long\_description** (*str*) – an extended model description

- **authors** (*str*, *list* or *dict*, optional) – the model author(s). One of
  - str**: name of single author
  - list of str**: list of author names
  - dict**: dict of {'task': ['name1', 'name1']} pairs

**\_\_str\_\_()**  
Stringification

**Returns** a summary

**Return type** *str*

**authors**  
The model author(s)

- str**: name of single author
- list of str**: list of author names
- dict**: dict of {'task': ['name1', 'name1']} pairs

**description**  
The model description

**Type** *str*

**long\_description**  
Longer model description

**Type** *str*

**name**  
The model name

**Type** *str*

**version**  
The model version

**Type** *str*

## numericalmodel.interfaces module

**class** numericalmodel.interfaces.**ForcingValue** (*name=None*, *id=None*, *unit=None*,  
*time\_function=None*, *interpolation=None*,  
*values=None*, *times=None*, *bounds=None*,  
*remembrance=None*)

Bases: *numericalmodel.interfaces.InterfaceValue*

Class for forcing values

**class** numericalmodel.interfaces.**InterfaceValue** (*name=None*, *id=None*, *unit=None*,  
*time\_function=None*, *interpolation=None*,  
*values=None*, *times=None*, *bounds=None*,  
*remembrance=None*)

Bases: *numericalmodel.utils.LoggerObject*, *numericalmodel.utils.ReprObject*

Base class for model interface values

### Parameters

- **name** (*str*, *optional*) – value name

- **id**(*str*, *optional*) – unique id
- **values** (1d `numpy.ndarray`, *optional*) – all values this InterfaceValue had in chronological order
- **times** (1d `numpy.ndarray`, *optional*) – the corresponding times to values
- **unit** (*str*, *optional*) – physical unit of value
- **bounds** (*list*, *optional*) – lower and upper value bounds
- **interpolation** (*str*, *optional*) – interpolation kind. See `scipy.interpolate.interp1d` for documentation. Defaults to “zero”.
- **time\_function** (*callable*, *optional*) – function that returns the model time as utc unix timestamp
- **remembrance** (*float*, *optional*) – maximum *time* difference to keep past *values*

**\_\_call\_\_** (*times=None*)

When called, return the value, optionally at a specific time

**Parameters** **times** (*numeric*, *optional*) – The times to obtain data from

**\_\_str\_\_** ()

Stringification

**Returns** a summary

**Return type** *str*

**forget\_old\_values** ()

Drop *values* and *times* older than *remembrance*.

**Returns** *True* is data was dropped, *False* otherwise

**Return type** *bool*

**bounds**

The *values*’ bounds. Defaults to an infinite interval.

**Getter** Return the current bounds

**Setter** If the bounds change, check if all *values* lie within the new bounds.

**Type** *list*, [lower, upper]

**id**

The unique id

**Type** *str*

**interpolation**

The interpolation kind to use in the **\_\_call\_\_** method. See `scipy.interpolate.interp1d` for documentation.

**Getter** Return the interpolation kind.

**Setter** Set the interpolation kind. Reset the internal interpolator if the interpolation kind changed.

**Type** *str*

**interpolator**

The interpolator for interpolation of *values* over *times*. Creating this interpolator is costly and thus

only performed on demand, i.e. when `__call__` is called **and** no interpolator was created previously or the previously created interpolator was unset before (e.g. by setting a new *value* or changing *interpolation*)

**Type** `scipy.interpolate.interp1d`

**name**

The name.

**Type** `str`

**next\_time**

The next time to use when *value* is set.

**Getter** Return the next time to use. Defaults to the value of *time\_function* if no *next\_time* was set.

**Setter** Set the next time to use. Set to `None` to unset and use the default time in the getter again.

**Type** `float`

**remembrance**

How long should this *InterfaceValue* store its *values*? This is the greatest difference the current *time* may have to the smallest *time*. Values earlier than the *remembrance* time are discarded. Set to `None` for no limit.

**Type** `float` or `None`

**time**

The current time

**Getter** Return the current time, i.e. the last time recorded in *times*.

**Type** `float`

**time\_function**

**times**

All times the *value* has ever been set in chronological order

**Type** `numpy.ndarray`

**unit**

The SI-unit.

**Type** `str`, SI-unit

**value**

The current value.

**Getter** the return value of `__call__`, i.e. the current value.

**Setter** When this property is set, the given value is recorded to the time given by *next\_time*. If this time exists already in *times*, the corresponding value in *values* is overwritten. Otherwise, the new time and value are appended to *times* and *values*. The value is also checked to lie within the *bounds*.

**Type** `numeric`

**values**

All values this *InterfaceValue* has ever had in chronological order

**Getter** Return the current values

**Setter** Check if all new values lie within the *bounds*

Type `numpy.ndarray`

**class** `numericalmodel.interfaces.Parameter` (`name=None`, `id=None`, `unit=None`,  
`time_function=None`, `interpolation=None`, `values=None`, `times=None`, `bounds=None`, `remembrance=None`)

Bases: `numericalmodel.interfaces.InterfaceValue`

Class for parameters

**class** `numericalmodel.interfaces.SetOfForcingValues` (`elements=[]`)

Bases: `numericalmodel.interfaces.SetOfInterfaceValues`

Class for a set of forcing values

**class** `numericalmodel.interfaces.SetOfInterfaceValues` (`elements=[]`)

Bases: `numericalmodel.utils.SetOfObjects`

Base class for sets of interface values

**Parameters** `values` (list of `InterfaceValue`, optional) – the list of values

**\_\_call\_\_** (`id`)

Get the value of an `InterfaceValue` in this set

**Parameters** `id` (`str`) – the id of an `InterfaceValue` in this set

**Returns** the `value` of the corresponding `InterfaceValue`

**Return type** `float`

**\_object\_to\_key** (`obj`)

key transformation function.

**Parameters** `obj` (`object`) – the element

**Returns** the unique key for this object. The `InterfaceValue.id` is used.

**Return type** `key` (`str`)

**time\_function**

The time function of all the `InterfaceValue`s in the set.

**Getter** Return a list of time functions from the elements

**Setter** Set the time function of each element

**Type** (list of) callables

**class** `numericalmodel.interfaces.SetOfParameters` (`elements=[]`)

Bases: `numericalmodel.interfaces.SetOfInterfaceValues`

Class for a set of parameters

**class** `numericalmodel.interfaces.SetOfStateVariables` (`elements=[]`)

Bases: `numericalmodel.interfaces.SetOfInterfaceValues`

Class for a set of state variables

**class** `numericalmodel.interfaces.StateVariable` (`name=None`, `id=None`, `unit=None`,  
`time_function=None`, `interpolation=None`,  
`values=None`, `times=None`, `bounds=None`,  
`remembrance=None`)

Bases: `numericalmodel.interfaces.InterfaceValue`

Class for state variables

## numericalmodel.numericalmodel module

**class** numericalmodel.numericalmodel.NumericalModel (*name=None, version=None, description=None, long\_description=None, authors=None, initial\_time=None, parameters=None, forcing=None, variables=None, numericalschemes=None*)

Bases: numericalmodel.genericmodel.GenericModel

Class for numerical models

### Parameters

- **name** (*str, optional*) – the model name
- **version** (*str, optional*) – the model version
- **description** (*str*) – a short model description
- **long\_description** (*str*) – an extended model description
- **authors** (*str, list or dict, optional*) – the model author(s). One of
  - str**: name of single author
  - list of str**: list of author names
  - dict**: dict of {'task': ['name1', 'name1']} pairs
- **initial\_time** (*float*) – initial model time (UTC unix timestamp)
- **parameters** (*SetOfParameters, optional*) – model parameters
- **forcing** (*SetOfForcingValues, optional*) – model forcing
- **variables** (*SetOfStateVariables, optional*) – model state variables
- **numericalschemes** (*SetOfNumericalSchemes, optional*) – model schemes with equation

**\_\_str\_\_** ()

Stringification

**Returns** a summary

**Return type** *str*

**get\_model\_time** ()

The current model time

**Returns** current model time

**Return type** *float*

**integrate** (*final\_time*)

Integrate the model until final\_time

**Parameters** **final\_time** (*float*) – time to integrate until

**run\_interactively** ()

Open a GTK window to interactively run the model:

- change the model variables, parameters and forcing on the fly
- directly see the model output
- control simulation speed

- pause and continue or do stepwise simulation

---

**Note:** This feature is still in development and currently not really functional.

---

**forcing**

The model forcing

Type `SetOfForcingValues`

**initial\_time**

The initial model time

Type `float`

**model\_time**

The current model time

Type `float`

**numericalschemes**

The model numerical schemes

Type `str`

**parameters**

The model parameters

Type `SetOfParameters`

**variables**

The model variables

Type `SetOfStateVariables`

## numericalmodel.numericalschemes module

```
class numericalmodel.numericalschemes.EulerExplicit (description=None,
long_description=None,
equation=None, fall-
back_max_timestep=None,
ignore_linear=None, ig-
nore_independent=None, ig-
nore_nonlinear=None)
```

Bases: `numericalmodel.numericalschemes.NumericalScheme`

Euler-explicit numerical scheme

**step** (*time=None, timestep=None, tendency=True*)

```
class numericalmodel.numericalschemes.EulerImplicit (description=None,
long_description=None,
equation=None, fall-
back_max_timestep=None,
ignore_linear=None, ig-
nore_independent=None, ig-
nore_nonlinear=None)
```

Bases: `numericalmodel.numericalschemes.NumericalScheme`

Euler-implicit numerical scheme



**step** (*time=None, timestep=None, tendency=True*)

Integrate one “timestep” from “time” forward with the Euler-implicit scheme and return the resulting variable value.

#### Parameters

- **time** (*single numeric*) – The time to calculate the step FROM
- **timestep** (*single numeric*) – The timestep to calculate the step
- **tendency** (*bool, optional*) – return the tendency or the actual value of the variable after the timestep?

**Returns** The resulting variable value or tendency

**Return type** `numpy.ndarray`

**Raises** `AssertionError` – when the equation’s nonlinear part is not zero and `ignore_nonlinear` is not set to True

```
class numericalmodel.numericalschemes.LeapFrog (description=None, long_description=None,
                                                equation=None,                fall-
                                                back_max_timestep=None,
                                                ignore_linear=None,            ig-
                                                nore_independent=None,          ig-
                                                nore_nonlinear=None)
```

Bases: `numericalmodel.numericalschemes.NumericalScheme`

Leap-Frog numerical scheme

**step** (*time=None, timestep=None, tendency=True*)

```
class numericalmodel.numericalschemes.NumericalScheme (description=None,
                                                         long_description=None,
                                                         equation=None,                fall-
                                                         back_max_timestep=None,
                                                         ignore_linear=None,            ig-
                                                         nore_independent=None,          ig-
                                                         nore_nonlinear=None)
```

Bases: `numericalmodel.utils.ReprObject`, `numericalmodel.utils.LoggerObject`

Base class for numerical schemes

#### Parameters

- **description** (*str*) – short equation description
- **long\_description** (*str*) – long equation description
- **equation** (`DerivativeEquation`) – the equation
- **fallback\_max\_timestep** (*single numeric*) – the fallback maximum timestep if no timestep can be estimated from the equation
- **ignore\_linear** (*bool*) – ignore the linear part of the equation?
- **ignore\_independent** (*bool*) – ignore the variable-independent part of the equation?
- **ignore\_nonlinear** (*bool*) – ignore the nonlinear part of the equation?

**\_\_str\_\_** ()

Stringification

**Returns** a summary

**Return type** `str`

**`_needed_timesteps_for_integration_step`** (*timestep=None*)

Given a timestep to integrate from now on, what other timesteps of the dependencies are needed?

**Parameters** **timestep** (*single numeric*) – the timestep to calculate

**Returns** the timesteps

**Return type** `numpy.ndarray`

---

**Note:** timestep 0 means the current time

---

**`independent_addend`** (*time=None*)

Calculate the equation’s addend part that is independent of the variable.

**Parameters** **time** (*single numeric, optional*) – the time to calculate the derivative.

Defaults to the variable’s current (last) time.

**Returns** the independent addend or 0 if `ignore_independent` is True.

**Return type** numeric

**`integrate`** (*time=None, until=None*)

Integrate until a certain time, respecting the `max_timestep`.

**Parameters**

- **time** (*single numeric, optional*) – The time to begin. Defaults to current variable `time`.
- **until** (*single numeric, optional*) – The time to integrate until. Defaults to one `max_timestep` further.

**`integrate_step`** (*time=None, timestep=None*)

Integrate “timestep” forward and set results in-place

**Parameters**

- **time** (*single numeric, optional*) – The time to calculate the step FROM. Defaults to the current variable time.
- **timestep** (*single numeric, optional*) – The timestep to calculate the step. Defaults to `max_timestep`.

**`linear_factor`** (*time=None*)

Calculate the equation’s linear factor in front of the variable.

**Parameters** **time** (*single numeric, optional*) – the time to calculate the derivative.

Defaults to the variable’s current (last) time.

**Returns** the linear factor or 0 if `ignore_linear` is True.

**Return type** numeric

**`max_timestep_estimate`** (*time=None, variablevalue=None*)

Based on this numerical scheme and the equation parts, estimate a maximum timestep. Subclasses may override this.

**Parameters**

- **time** (*single numeric, optional*) – the time to calculate the derivative. Defaults to the variable’s current (last) time.
- **variablevalue** (*numpy.ndarray, optional*) – the variable value to use. Defaults to the value of `self.variable` at the given time.

**Returns** an estimate of the current maximum timestep. Definitely check the result for integrity.

**Return type** single numeric or bogus

**Raises** `Exception` – any exception if something goes wrong

**needed\_timesteps** (*timestep*)

Given a timestep to integrate from now on, what other timesteps of the dependencies are needed?

**Parameters** **timestep** (*single numeric*) – the timestep to calculate

**Returns** the timesteps

**Return type** `numpy.ndarray`

---

**Note:** timestep 0 means the current time

---

**nonlinear\_addend** (*time=None, variablevalue=None*)

Calculate the derivative's addend part that is nonlinearly dependent of the variable.

**Parameters**

- **time** (*single numeric, optional*) – the time to calculate the derivative. Defaults to the variable's current (last) time.
- **variablevalue** (*numpy.ndarray, optional*) – the variable value to use. Defaults to the value of `self.variable` at the given time.

**Returns** the nonlinear addend or 0 if `ignore_nonlinear` is `True`.

**Return type** `res` (numeric)

**step** (*time, timestep, tendency=True*)

Integrate one “timestep” from “time” forward and return value

**Parameters**

- **time** (*single numeric*) – The time to calculate the step FROM
- **timestep** (*single numeric*) – The timestep to calculate the step
- **tendency** (*bool, optional*) – return the tendency or the actual value of the variable after the timestep?

**Returns** The resulting variable value or tendency

**Return type** `numpy.ndarray`

**description**

The numerical scheme description

**Type** `str`

**equation**

The equation the numerical scheme's should solve

**Type** `DerivativeEquation`

**fallback\_max\_timestep**

The numerical scheme's fallback maximum timestep

**Type** `float`

**ignore\_independent**

Should this numerical scheme ignore the equation's variable-independent addend?

Type `bool`

**ignore\_linear**

Should this numerical scheme ignore the equation's linear factor?

Type `bool`

**ignore\_nonlinear**

Should this numerical scheme ignore the equation's nonlinear addend?

Type `bool`

**long\_description**

The longer numerical scheme description

Type `str`

**max\_timestep**

Return a maximum timestep for the current state. First tries the `max_timestep_estimate`, then the `fallback_max_timestep`.

**Parameters**

- **time** (*single numeric, optional*) – the time to calculate the derivative. Defaults to the variable's current (last) time.
- **variablevalue** (*numpy.ndarray, optional*) – the variable value to use. Defaults to the value of `self.variable` at the given time.

**Returns** an estimate of the current maximum timestep

**Return type** `float`

```
class numericalmodel.numericalschemes.RungeKutta4 (description=None,
                                                    long_description=None,
                                                    equation=None,          fall-
                                                    back_max_timestep=None,
                                                    ignore_linear=None,        ig-
                                                    nore_independent=None,        ig-
                                                    nore_nonlinear=None)
```

Bases: `numericalmodel.numericalschemes.NumericalScheme`

Runte-Kutta-4 numerical scheme

**step** (*time=None, timestep=None, tendency=True*)

```
class numericalmodel.numericalschemes.SetOfNumericalSchemes (elements=[],          fall-
                                                                back_plan=None)
```

Bases: `numericalmodel.utils.SetOfObjects`

Base class for sets of `NumericalSchemes`

**Parameters**

- **elements** (*list of `NumericalScheme`, optional*) – the the numerical schemes
- **fallback\_plan** (*list, optional*) – the fallback plan if automatic planning fails. Depending on the combination of numerical scheme and equations, a certain order or solving the equations is crucial. For some cases, the order can be determined automatically, but if that fails, one has to provide this information by hand. Has to be a `list` of `[varname, [timestep1, timestep2, ...]]` pairs.

**varname:** the name of the equation variable. Obviously there has to be at least one entry in the list for each equation.

**timestepN:** the normed timesteps (betw. 0 and 1) to calculate. Normed means, that if it is requested to integrate the set of numerical equations by an overall timestep, what percentages of this timestep have to be available of this variable. E.g. an overall timestep of 10 is requested. Another equation needs this variable at the timesteps 2 and 8. Then the timesteps would be [0.2,0.8]. Obviously, the equations that looks farrest into the future (e.g. Runge-Kutta or Euler-Implicit) has to be last in this `fallback_plan` list.

**`_object_to_key`** (*obj*)

key transformation function.

**Parameters** `obj` (*object*) – the element

**Returns** the unique key for this object. The equation’s variable’s id is used.

**Return type** `key` (*str*)

**`integrate`** (*start\_time*, *final\_time*)

Integrate the model until `final_time`

**Parameters**

- **`start_time`** (*float*) – the starting time
- **`final_time`** (*float*) – time to integrate until

**`fallback_plan`**

The fallback plan if automatic plan determination does not work

**Type** *list*

**`plan`**

The unified plan for this set of numerical schemes. First try to determine the plan automatically, if that fails, use the `fallback_plan`.

**Type** *list*

## numericalmodel.utils module

**class** `numericalmodel.utils.LoggerObject` (*logger=<logging.Logger object>*)

Bases: `object`

Simple base class that provides a ‘logger’ property

**Parameters** `logger` (*logging.Logger*) – the logger to use

**`logger`**

the `logging.Logger` used for logging. Defaults to `logging.getLogger(__name__)`.

**class** `numericalmodel.utils.ReprObject`

Bases: `object`

Simple base class that defines a `__repr__` method based on an object’s `__init__` arguments and properties that are named equally. Subclasses of `ReprObject` should thus make sure to have properties that are named equally as their `__init__` arguments.

**`__repr__`** ()

Python representation of this object

**Returns** a Python representation of this object based on its `__init__` arguments and corresponding properties.

**Return type** *str*

**classmethod** `_full_variable_path` (*var*)

Get the full string of a variable

**Parameters** **var** (*any*) – The variable to get the full string from

**Returns** The full usable variable string including the module

**Return type** `str`

**class** `numericalmodel.utils.SetOfObjects` (*elements=[]*, *element\_type=<class 'object'>*)

**Bases:** `numericalmodel.utils.ReprObject`, `numericalmodel.utils.LoggerObject`,  
`collections.abc.MutableMapping`

Base class for sets of objects

**\_\_str\_\_** ()

Stringification

**Returns** a summary

**Return type** `str`

**\_object\_to\_key** (*obj*)

key transformation function. Subclasses should override this.

**Parameters** **obj** (*object*) – object

**Returns** the unique key for this object. Defaults to `repr(obj)`

**Return type** `str`

**add\_element** (*newelement*)

Add an element to the set

**Parameters** **newelement** (object of type *element\_type*) – the new element

**element\_type**

The base type the elements in the set should have

**elements**

return the list of values

**Getter** get the list of values

**Setter** set the list of values. Make sure, every element in the list is an instance of (a subclass of)  
*element\_type*.

**Type** `list`

`numericalmodel.utils.is_numeric` (*x*)

Check if a given value is numeric, i.e. whether numeric operations can be done with it.

**Parameters** **x** (*any*) – the input value

**Returns** True if the value is numeric, False otherwise

**Return type** `bool`

`numericalmodel.utils.utcnow` ()

Get the current utc unix timestamp, i.e. the utc seconds since 01.01.1970.

**Returns** the current utc unix timestamp in seconds

**Return type** `float`

## CHAPTER 7

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