
PyNLO Documentation

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Contents:

Welcome to pyNLO's documentation!

1.1 Package Design

Information about the design of the package and its classes.

1.1.1 Package Organization

In pyNLO, object-oriented programming is used to mimic the physics of nonlinear interactions. Whenever possible, each physical entity with intrinsic properties – for example an optical pulse or nonlinear fiber – is mapped to a single Python class. These classes keep track of the objects' properties, calculate interactions between them and other objects, and provide simple calculator-type helper functions.

1.1.2 Pulse Class

class `pynlo.light.Pulse` (*frep_MHz=None, n=None*)

Class which carried all information about the light field. This class is a base upon which various cases are built (eg analytic pulses, CW fields, or pulses generated from experimental data.)

AT

Property: time-domain electric field grid

Returns **AT** – Complex electric field in time domain.

Return type ndarray, shape NPTS

AW

Property: frequency-domain electric field grid

Returns **AW** – Complex electric field in frequency domain.

Return type ndarray, shape NPTS

T_mks

Property: time grid

Returns **T_mks** – Time grid corresponding to AT [s]

Return type ndarray, shape NPTS

T_ps

Property: time grid

Returns **T_ps** – Time grid corresponding to AT [ps]

Return type ndarray, shape NPTS

V_THz

Property: relative angular frequency grid

Returns V_THz – Relative angular frequency grid corresponding to AW [THz]

Return type ndarray, shape NPTS

V_mks

Property: relative angular frequency grid

Returns V_mks – Relative angular frequency grid corresponding to AW [Hz]

Return type ndarray, shape NPTS

W_THz

Property: angular frequency grid

Returns W_THz – Angular frequency grid corresponding to AW [THz]

Return type ndarray, shape NPTS

W_mks

Property: angular frequency grid

Returns W_mks – Angular frequency grid corresponding to AW [Hz]

Return type ndarray, shape NPTS

add_time_offset (*offset_ps*)

Shift field in time domain by offset_ps picoseconds. A positive offset moves the pulse forward in time.

calc_epp ()

Calculate and return energy per pulse via numerical integration of $A^2 dt$

Returns x – Pulse energy [J]

Return type float

calculate_intensity_autocorrelation ()

Calculates and returns the intensity autocorrelation, $\int P(t)P(t + \tau)dt$

Returns x – Intensity autocorrelation. The grid is the same as the pulse class' time grid.

Return type ndarray, shape N_pts

center_frequency_THz

Property: center frequency

Returns center_frequency_THz – Frequency of center point in AW grid [THz]

Return type float

center_frequency_mks

Property: center frequency

Returns center_frequency_mks – Frequency of center point in AW grid [Hz]

Return type float

center_wavelength_mks

Property: center wavelength

Returns center_wavelength_mks – Wavelength of center point in AW grid [m]

Return type float

center_wavelength_nm

Property: center wavelength

Returns **center_wavelength_nm** – Wavelength of center point in AW grid [nm]

Return type **float**

chirp_pulse_W (*GDD, TOD=0, FOD=0.0, w0_THz=None*)

Alter the phase of the pulse

Apply the dispersion coefficients $\beta_2, \beta_3, \beta_4$ expanded around frequency ω_0 .

Parameters

- **GDD** (*float*) – Group delay dispersion (β_2) [ps²]
- **TOD** (*float, optional*) – Group delay dispersion (β_3) [ps³], defaults to 0.
- **FOD** (*float, optional*) – Group delay dispersion (β_4) [ps⁴], defaults to 0.
- **w0_THz** (*float, optional*) – Center frequency of dispersion expansion, defaults to grid center frequency.

Notes

The convention used for dispersion is

$$E_{new}(\omega) = \exp \left(i \left(\frac{1}{2} GDD \omega^2 + \frac{1}{6} TOD \omega^3 + \frac{1}{24} FOD \omega^4 \right) \right) E(\omega)$$

clone_pulse (*p*)

Copy all parameters of pulse_instance into this one

create_cloned_pulse ()

Create and return new pulse instance identical to this instance.

create_subset_pulse (*center_wl_nm, NPTS*)

Create new pulse with smaller frequency span, centered at closest grid point to center_wl_nm, with NPTS grid points and frequency-grid values from this pulse.

dF_THz

Property: frequency grid spacing

Returns **dF_ps** – Frequency grid spacing [ps]

Return type **float**

dF_mks

Property: frequency grid spacing

Returns **dF_mks** – Frequency grid spacing [s]

Return type **float**

dT_mks

Property: time grid spacing

Returns **dT_mks** – Time grid spacing [s]

Return type **float**

dT_ps

Property: time grid spacing

Returns `dT_ps` – Time grid spacing [ps]

Return type `float`

frep_MHz

Property: Repetition rate. Used for calculating average beam power.

Returns `frep_MHz` – Pulse repetition frequency [MHz]

Return type `float`

frep_mks

Property: Repetition rate. Used for calculating average beam power.

Returns `frep_mks` – Pulse repetition frequency [Hz]

Return type `float`

rotate_spectrum_to_new_center_wl (*new_center_wl_nm*)

Change center wavelength of pulse by rotating the electric field in the frequency domain. Designed for creating multiple pulses with same gridding but of different colors. Rotations is by integer and to the closest omega.

set_AT (*AT_new*)

Set the value of the time-domain electric field.

Parameters `AW_new` (*array_like*) – New electric field values.

set_AW (*AW_new*)

Set the value of the frequency-domain electric field.

Parameters `AW_new` (*array_like*) – New electric field values.

set_NPTS (*NPTS*)

Set the grid size.

The actual grid arrays are *not* altered automatically to reflect a change.

Parameters `NPTS` (*int*) – Number of points in grid

set_center_wavelength_m (*wl*)

Set the center wavelength of the grid in units of meters.

Parameters `wl` (*float*) – New center wavelength [m]

set_center_wavelength_nm (*wl*)

Set the center wavelength of the grid in units of nanometers.

Parameters `wl` (*float*) – New center wavelength [nm]

set_epp (*desired_epp_J*)

Set the energy per pulse (in Joules)

Parameters `desired_epp_J` (*float*) – the value to set the pulse energy [J]

Returns

Return type `nothing`

set_frep_MHz (*fr_MHz*)

Set the pulse repetition frequency.

This parameter used internally to convert between pulse energy and average power.

Parameters `fr_MHz` (*float*) – New repetition frequency [MHz]

set_frequency_window_THz (*DF*)

Set the total frequency window of the grid.

This sets the grid dF, and implicitly changes the temporal span ($\sim 1/dF$).

Parameters *DF* (*float*) – New grid time span [THz]

set_frequency_window_mks (*DF*)

Set the total frequency window of the grid.

This sets the grid dF, and implicitly changes the temporal span ($\sim 1/dF$).

Parameters *DF* (*float*) – New grid time span [Hz]

set_time_window_ps (*T*)

Set the total time window of the grid.

This sets the grid dT, and implicitly changes the frequency span ($\sim 1/dT$).

Parameters *T* (*float*) – New grid time span [ps]

set_time_window_s (*T*)

Set the total time window of the grid.

This sets the grid dT, and implicitly changes the frequency span ($\sim 1/dT$).

Parameters *T* (*float*) – New grid time span [s]

time_window_mks

Property: time grid span

Returns *time_window_mks* – Time grid span [ps]

Return type *float*

time_window_ps

Property: time grid span

Returns *time_window_ps* – Time grid span [ps]

Return type *float*

wl_mks

Property: Wavelength grid

Returns *wl_mks* – Wavelength grid corresponding to AW [m]

Return type ndarray, shape NPTS

wl_nm

Property: Wavelength grid

Returns *wl_nm* – Wavelength grid corresponding to AW [nm]

Return type ndarray, shape NPTS

write_frog (*fileloc='broadened_er_pulse.dat', flip_phase=True*)

Save pulse in FROG data format. Grid is centered at wavelength center_wavelength (nm), but pulse properties are loaded from data file. If flip_phase is true, all phase is multiplied by -1 [useful for correcting direction of time ambiguity]. time_window (ps) sets temporal grid size.

power sets the pulse energy: if power_is_epp is True then the number is pulse energy [J] if power_is_epp is False then the power is average power [W], and is multiplied by frep to calculate pulse energy

1.1.3 DFG Integrand

Difference frequency generation module

Defines:

- The `dfg_problem`, a class which can be intergrated by the `pyNLO ODEsolve`
- The `fftcomputer`, which handles FFTs using `pyFFTW`
- A helper class, `dfg_results_interface`, which provides a `Pulse`-class based wrapper around the `dfg` results.

Authors: Dan Maser, Gabe Ycas

```
class pynlo.interactions.ThreeWaveMixing.DFG_integrand.dfg_problem(pump_in,
                                                                    sgnl_in, crys-
                                                                    tal_in, dis-
                                                                    able_SPM=False,
                                                                    pump_waist=1e-
                                                                    05, ap-
                                                                    ply_gouy_phase=False,
                                                                    plot_beam_overlaps=False)
```

This class defines the integrand for a DFG or OPO parametric interaction. Following Eqn (8) in Seres & Hebling, “Nonstationary theory of synchronously pumped femtosecond optical parametric oscillators”, JOSA B Vol 17 No 5, 2000.

gen_j1 (*y*)

Following Eqn (8) in Seres & Hebling, “Nonstationary theory of synchronously pumped femtosecond optical parametric oscillators”, JOSA B Vol 17 No 5, 2000. A call to this function updates the `:math: chi_3` mixing terms used for four-wave mixing.

Parameters *y* (*array-like*, *shape is 3 * NPTS*) – Concatenated pump, signal, and idler fields

poling (*x*)

Helper function to get sign of `:math: d_{extrm{eff}}` at position `:math: x` in the crystal. Uses `self.crystal's` `pp` function.

Returns *x* – Sign (+1 or -1) of `:math: d_{extrm{eff}}`.

Return type `int`

process_stepper_output (*solver_out*)

Post-process output of ODE solver.

The saved data from an ODE solved are the pump, signal, and idler in the dispersionless reference frame. To see the pulses “as they really are”, this dispersion must be added back in.

Parameters *solver_out* – Output class instance from `ODEsolve`

Returns Instance of `dfg_results_interface` class

Return type `dfg_results`

```
class pynlo.interactions.ThreeWaveMixing.DFG_integrand.dfg_results_interface(integrand_instance,
                                                                                pump,
                                                                                sgnl,
                                                                                idlr,
                                                                                z)
```

Interface to output of DFG solver. This class provides a clean way of working with the DFG field using the `Pulse` class.

Notes

After initialization, calling:

```
get_{pump,sgnl,idlr}(n)
```

will set the dfg results class' "pulse" instance to the appropriate field and return it.

Example

To plot the 10th saved signal field, you would call:

```
p = dfg_results_interface.get_sgnl(10-1)
plt.plot(p.T_ps, abs(p.AT)**2 )
```

To get the actual position (z [meters]) that this corresponds to, call:

```
z = dfg_results_interface.get_z(10-1)
```

1.1.4 Numerical Recipes-based ODEsolve

These classes are an adaptation of the very nice *Numerical Recipes* ODE solvers into Python. The solver is divided into two parts: specific step iterators (eg Dopri853) and the framework for stepping through the ODE (steppers)

1.1.5 Steppers and helpers

class `pynlo.util.ode_solve.steppers.Output` (*nsaves=None*)

The output class is used by the ode solver to store the integrated output at specified x values. In addition to housing the matrices containing the x and y data, the class also provides a simple function call to store new data and resizes the output grids dynamically.

Parameters *nsaves* – Number of anticipated save points, used for calculating value of x at which integrand will be evaluated and saved.

init (*neqn, xlo, xhi, dtype=<type 'numpy.float64'>*)

Setup routine, which creates the output arrays. If *nsaves* was provided at class initialization, the positions at which the integrand will be saved are also calculated.

Parameters

- **neqn** – Number of equations, or the number of y values at each x .
- **xlo** – Lower bound of integration (start point.)
- **xhi** – Upper bound of integration (stop point.)
- **dtype** – Data type of each y . Any Python data type is acceptable.

out (*nstp, x, y, s, h*)

nstp is current step number, current values are x & y , Stepper is s and step size is h

class `pynlo.util.ode_solve.steppers.StepperBase` (*yy, dydxx, xx, atoll, rtoll, dense*)

class `pynlo.util.ode_solve.steppers.ODEint` (*ystartt, xx1, xx2, atol, rtol, h1, hminn, outt, stepper_class, RHS_class, dense=True, dtype=None*)

1.1.6 Dormand-Prince 853 Stepper

class `pynlo.util.ode_solve.dopr853.StepperDopr853` (*yy, dydxx, xx, atoll, rtoll, dens*)
Bases: `pynlo.util.ode_solve.steppers.StepperBase`

1.1.7 Fiber Class

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