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# **polyhedron***potential Documentation*

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**Shankar Kulumani**

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## INSTALLATION

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# CHAPTER 1

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## Meshes

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This module provides a MeshData class for defining a Surface\_Mesh and performing related operations.

### **class MeshData**

Class to hold a polyhedron mesh.

This is a wrapper of the Surface\_mesh from CGAL and is the foundation used for the asteroid polyhedron potential model.

**Author** Shankar Kulumani

**Version** 28 October 2018

### **Public Functions**

**void update\_mesh (const Eigen::Ref<const Eigen::MatrixXd> &V, const Eigen::Ref<const Eigen::MatrixXi> &F)**

Completely update the mesh with new vertices and faces. This will also completely regenerate the mesh properties

**Return** void

**Author** Shankar Kulumani

**Version** 9 June 2018

#### **Parameters**

- V: Eigen matrix with the vertices
- F: Eigen matrix with teh faces

**build\_edge\_factor (const Eigen::Ref<const Eigen::Vector3d> &pos)**

Build the per edge factor L for the polyhedron potential model

**Return** bool Success if true

**Author** Shankar Kulumani

**Version** 28 October 2018

**Parameters**

- pos: Position of test point

**build\_face\_factor (const Eigen::Ref<const Eigen::Vector3d> &pos)**

Build the per face factor w for the polyhedron potential model

**Return** bool success if true

**Author** Shankar Kulumani

**Version** 28 October 2018

**Parameters**

- pos: Position of test point

**get\_verts (void) const**

Return the vertices of the mesh as an Eigen array

**Return** vertices Eigen arrays for the mesh nx3

**Author** Shankar Kulumani

**Version** 28 October 2018

Eigen::Matrix<int, Eigen::Dynamic, 3> **get\_faces (void) const**

Return the faces of the mesh as an eigen array

**Return** faces Eigen array for the faces of the mesh nx3

**Author** Shankar Kulumani

**Version** 28 October 2018

std::size\_t **number\_of\_vertices (void) const**

Return the number of vertices of the mesh

**Return** num\_vert Return the number of vertices

**Author** Shankar Kulumani

**Version** 28 October 2018

std::size\_t **number\_of\_edges (void) const**

Return number of edges of the mesh

**Return** num\_edge Number of edges

**Author** Shankar Kulumani

**Version** 28 October 2018

std::size\_t **number\_of\_faces (void) const**

Return number of faces of the mesh

**Return** num\_face Number of faces

**Author** Shankar Kulumani

**Version** 28 October 2018

```
std::size_t number_of_halfedges (void) const
```

Return number of halfedges of the mesh

**Return** num\_half Number of halfedges

**Author** Shankar Kulumani

**Version** 28 October 2018

```
Mesh::Vertex_range vertices (void) const
```

Return vertex range for iteration

**Return** Vertex\_range Range of vertices of the mesh

**Author** Shankar Kulumani

**Version** 28 October 2018

```
Mesh::Face_range faces (void) const
```

Return face range for iteration

**Return** Face\_range Range of faces of the mesh

**Author** Shankar Kulumani

**Version** 28 October 2018

```
Mesh::Edge_range edges (void) const
```

Return edge range for iteration

**Return** Edge\_range Range of edges of the mesh

**Author** Shankar Kulumani

**Version** 28 October 2018

```
Mesh::Halfedge_range halfedges (void) const
```

Return halfedge range for iteration

**Return** Halfedge\_range Range of halfedges of the mesh

**Author** Shankar Kulumani

**Version** 28 October 2018

```
bool refine_faces (const std::vector<Face_index> &face_vec, std::vector<Face_index>
&new_faces, std::vector<Vertex_index> &new_vertices, const int &density = 4.0)
```

Given a set of faces, this will refine them by adding new faces/ vertices within them. The new faces and vertices are returned. The surface mesh member variable is updated.

This tends to make a very craggly shape. Better to use remesh instead

**Return** new\_faces Vector of new faces

**Return** new\_vertices Vector of new vertices

**Author** Shankar Kulumani

**Version** 10 June 2018

#### Parameters

- face\_vec: Vector of faces to refine
- density: integer defining the density control factor

**remesh\_faces** (**const** std::vector<Face\_index> &face\_vec, **const** double &target\_edge\_length,  
**const** int &number\_of\_iterations = 3)

Perform isotropic remeshing of the desired faces of the mesh.

**Return** bool True if success

**Author** Shankar Kulumani

**Version** 28 October 2018

#### Parameters

- face\_vec: Vector of faces to remesh
- target\_edge\_length: Target length of the new edges
- number\_of\_iterations: Iterations for isotropic\_remeshing

std::vector<Face\_index> **faces\_in\_fov** (**const** Eigen::Ref<**const** Eigen::Vector3d> &pos, **const** double &max\_fov = 0.52)

Find the faces that are within a FOV of the current position

**Return** face\_vec Vector of face indices

**Author** Shankar Kulumani

**Version** 11 June 2018

#### Parameters

- pos: Position of spacecraft in the asteroid fixed frame

std::vector<Face\_index> **vertices\_in\_fov** (**const** Eigen::Ref<**const** Eigen::Vector3d> &pos,  
**const** double &max\_fov = 0.52)

Find the vertices that are within a FOV of the current position

**Return** vertex\_vec Vector of vertex indices

**Author** Shankar Kulumani

**Version** 28 October 2018

#### Parameters

- pos: Position of spacecraft in the asteroid fixed frame

```
Eigen::Matrix<double, Eigen::Dynamic, 3> refine_faces_in_view(const Eigen::Ref<const
    Eigen::Vector3d> &pos,
    const double &max_fov =
    0.52)
```

Use the refinement function for the faces within a certain angle of the position

**Return** Face\_centers get the center of the new faces in view

**Author** Shankar Kulumani

**Version** 28 October 2018

#### Parameters

- pos: Eigen vector for position
- max\_fov: Maximum cosine(angle) for faces to refine

```
bool remesh_faces_in_view(const Eigen::Ref<const Eigen::Vector3d> &pos, const double
    &max_fov = 0.52, const double &edge_length = 0.01)
```

Use isotropic remeshing to remesh the faces that are in view of the point

**Return** bool Success if true

**Author** Shankar Kulumani

**Version** 28 October 2018

#### Parameters

- pos: Position vector
- max\_fov: Field of view to use to compute the faces in view
- edge\_length: Target edge length for the new faces

```
template <typename Index>
```

```
Eigen::RowVector3d get_vertex(const Index &index) const
```

Get the desired vertex given an index

**Return** vertex Eigen array of the specific vertex

**Author** Shankar Kulumani

**Version** 28 October 2018

#### Parameters

- Index: Index of vertex to get

```
bool set_vertex(const Vertex_index &vd, const Eigen::Ref<const Eigen::Vector3d> &vec)
```

Update the position of a single vertex and recompute the affected mesh properties

**Return** bool True if good

**Author** Shankar Kulumani

**Version** 9 June 2018

#### Parameters

- vd: Vertex index to modify
- vec: Eigen vector of the new vertex position

```
template <typename Index>
Eigen::RowVector3i get_face_vertices(const Index &index) const
    Get the vertex indecies of all vertices in the face
```

**Return** row a row vector of indices

**Author** Shankar Kulumani

**Version** 6 June 2018

#### Parameters

- *index*: A face index (basically an integer)

```
Eigen::VectorXd get_all_face_area(void) const
    Get the area of each face of the mesh
```

**Return** Vector of all face areas

**Author** Shankar Kulumani

**Version** 12 June 2018

#### Parameters

- *void*: none

### Public Members

Mesh **surface\_mesh**  
Surface\_mesh object

## CHAPTER 2

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### Indices and tables

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