
MakersMotorControl Library Documentation

Release 1.0

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CircuitPython helper for Circuit Playground Express/Crickit motor control

Examples of products to use this library with:

- [Circuit Playground Express](#)
- [Adafruit CRICKIT for Circuit Playground Express](#)

CHAPTER 1

Dependencies

This driver depends on:

- [Adafruit CircuitPython with Crickit support](#)

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).

CHAPTER 2

Usage Example

```
import time
import makers_motor_control

motors = makers_motor_control.MotorControl()

motors.set_throttle(0.0, 0.0)

while True:
    motors.set_throttle(0.5, 0.5, 0.25, True) # forward
    motors.set_throttle(-0.5, -0.5, 0.25, True) # backward
    motors.set_throttle(0.0, 0.5, 0.25, True) # left
    motors.set_throttle(0.5, 0.0, 0.25, True) # right

    time.sleep(5.0)
```


CHAPTER 3

Contributing

Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.

4.1 Zip release files

To build this library locally you'll need to install the `circuitpython-build-tools` package.

```
python3 -m venv .env
source .env/bin/activate
pip install circuitpython-build-tools
```

Once installed, make sure you are in the virtual environment:

```
source .env/bin/activate
```

Then run the build:

```
circuitpython-build-bundles --filename_prefix makers-circuitpython-motor-control --
↳library_location .
```

4.2 Sphinx documentation

Sphinx is used to build the documentation based on rST files and comments in the code. First, install dependencies (feel free to reuse the virtual environment from above):

```
python3 -m venv .env
source .env/bin/activate
pip install Sphinx sphinx-rtd-theme
```

Now, once you have the virtual environment activated:

```
cd docs
sphinx-build -E -W -b html . _build/html
```

This will output the documentation to `docs/_build/html`. Open the `index.html` in your browser to view them. It will also (due to `-W`) error out on any warning like Travis will. This is a good way to locally verify it will pass.

5.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/motor_control_simpletest.py

```
1  """Motor control test"""
2  import time
3  import makers_motor_control
4
5  motors = makers_motor_control.MotorControl()
6
7  motors.set_throttle(0.0, 0.0)
8
9  while True:
10     motors.set_throttle(0.5, 0.5, 0.25, True) # forward
11     motors.set_throttle(-0.5, -0.5, 0.25, True) # backward
12     motors.set_throttle(0.0, 0.5, 0.25, True) # left
13     motors.set_throttle(0.5, 0.0, 0.25, True) # right
14
15     time.sleep(5.0)
```

5.2 makers_motor_control

- Author(s): Frank Morton

5.2.1 Implementation Notes

Hardware:

- [Circuit Playground Express](#)
- [Adafruit CRICKIT for Circuit Playground Express](#)

Software and Dependencies:

- Adafruit CircuitPython firmware for the supported boards: <https://github.com/adafruit/circuitpython/releases>

class makers_motor_control.**MotorControl**

Crickit motor control helper class

set_throttle (*left_throttle, right_throttle, delay=0.0, stop_after_moving=False*)

Set the motor throttles

stop_motors ()

Stop both motors

CHAPTER 6

Indices and tables

- `genindex`
- `modindex`
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