
dpcluster Documentation

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dpcluster is a package for grouping together (clustering) vectors. It automatically chooses the number of clusters that fits the data best. Specifically, it models the data as a Dirichlet Process mixture in the exponential family. For a tutorial see “[Dirichlet Process](#)” by [Y.W. Teh \(2010\)](#). Currently the only distribution implemented is the multivariate Gaussian with a Normal-Inverse-Wishart conjugate prior but extensions to other distributions are possible.

Two inference algorithms are implemented:

- Variational inference as described in “[Variational Inference for Dirichlet Process Mixtures](#)” by [Blei et al. \(2006\)](#). This is a batch algorithm that requires storing all data in memory.
- An experimental on-line inference algorithm that requires only $O(\log(n))$ memory where n is the total number of observations.

To install locally run:

```
python setup.py install --user
```


CHAPTER 1

Usage

Here is a simple example to demonstrate clustering a number of random points in the plane:

```
>>> from dpcluster import *
>>> n = 10
>>> data = np.random.normal(size=2*n).reshape(-1,2)
>>> vdp = VDP(GaussianNIW(2))
>>> vdp.batch_learn(vdp.distr.sufficient_stats(data))
>>> plt.scatter(data[:,0],data[:,1])
>>> vdp.plot_clusters(slc=np.array([0,1]))
>>> plt.show()
```

Running this might produce 2-3 clusters depending on the randomly generated data. The adaptive nature of the Dirichlet Process mixture model becomes apparent when we increase the number of data points from $n = 10$ to $n = 500$. In this case the clustering algorithm will likely explain the data using only one cluster.

CHAPTER 2

ToDo

- Implement more clustering algorithms e.g. based on Gibbs sampling, expectation propagation, stochastic gradient descent.
- Implement more clustering distributions.
- Re-implement algorithms to take advantage of multi-core or GPU computing.

dpcluster Package

algorithms Module

class `dpcluster.algorithms.OfflineVDP` (*distr*, *w*=0.1, *k*=25, *tol*=0.001, *max_items*=100)
Experimental online clustering algorithm.

Parameters

- **distr** – likelihood-prior distribution pair governing clusters. For now the only option is using a instance of `dpcluster.distributions.GaussianNIW`.
- **w** – non-negative prior weight. The prior has as much influence as *w* data points.
- **k** – maximum number of clusters.
- **tol** – convergence tolerance.
- **max_items** – maximum queue length.

get_model ()

Get current model.

Returns instance of `dpcluster.algorithms.VDP`

put (*r*, *s*=0)

Append data.

Parameters **r** – sufficient statistics of data to be appended.

Basic usage example:

```
>>> distr = GaussianNIW(data.shape[2])
>>> x = distr.sufficient_stats(data)
>>> vdp = OfflineVDP(distr)
>>> vdp.put(x)
>>> print vdp.get_model().cluster_parameters()
```

```
class dpcluster.algorithms.Predictor(model, ix, iy)
```

```
    distr_fit(*args)
    precomp(*args)
    predict(*args)
    predict_old(z, lgh=(True, True, False), full_var=False)
```

```
class dpcluster.algorithms.PredictorKL(model, ix, iy)
```

```
    predict(*args)
    predict_old(z, lgh=(True, True, False), full_var=False)
```

```
class dpcluster.algorithms.VDP(distr, w=0.1, k=50, tol=1e-05, max_iters=10000)
```

Bases: object

Variational Dirichlet Process clustering algorithm following “[Variational Inference for Dirichlet Process Mixtures](#)” by Blei et al. (2006).

Parameters

- **distr** – likelihood-prior distribution pair governing clusters. For now the only option is using a instance of `dpcluster.distributions.GaussianNIW`.
- **w** – non-negative prior weight. The prior has as much influence as w data points.
- **k** – maximum number of clusters.
- **tol** – convergence tolerance.

```
batch_learn(x, verbose=False, sort=True)
```

Learn cluster from data. This is a batch algorithm that required all data be loaded in memory.

Parameters

- **x** – sufficient statistics of the data to be clustered. Can be obtained from raw data by calling `dpcluster.distributions.ConjugatePair.sufficient_stats()`
- **verbose** – print progress report
- **sort** – algorithm optimization. Sort clusters at every step.

Basic usage example:

```
>>> distr = GaussianNIW(data.shape[2])
>>> x = distr.sufficient_stats(data)
>>> vdp = VDP(distr)
>>> vdp.batch_learn(x)
>>> print vdp.cluster_parameters()
```

```
cluster_parameters()
```

Returns Cluster parameters.

```
cluster_sizes()
```

Returns Data weight assigned to each cluster.

```
conditional_expectation(*args)
```

```
conditional_ll(x, cond)
    Conditional log likelihood.
```

Parameters

- **x** – sufficient statistics of data.
- **cond** – slice representing variables to condition on

conditional_variance (*x, iy, ix, ret_ll_gr_hs=(True, False, False)*)

ll (*x, ret_ll_gr_hs=(True, False, False)*)

Compute the log likelihoods (ll) of data with respect to the trained model.

Parameters

- **x** – sufficient statistics of the data.
- **ret_ll_gr_hs** – what to return: likelihood, gradient, hessian. Derivatives taken with respect to data, not sufficient statistics.

marginal (**args*)

plot_clusters (***kwargs*)

Asks each cluster to plot itself. For Gaussian multidimensional clusters pass `slc=np.array([i, j])` as an argument to project clusters on the plane defined by the *i*'th and *j*'th coordinate.

pseudo_resp (**args*)

pseudo_resp_cache (**args*)

resp (**args*)

resp_cache (**args*)

var_cond_exp (*x, iy, ix, ret_ll_gr_hs=(True, False, False), full_var=False*)

distributions Module

class `dpcluster.distributions.ConjugatePair` (*evidence_distr, prior_distr, prior_param*)

Conjugate prior-evidence pair of distributions in the exponential family. Conjugacy means that the posterior has the same form as the prior with updated parameters.

Parameters

- **evidence_distr** – Evidence distribution. Must be an instance of *ExponentialFamilyDistribution*
- **prior_distr** – Prior distribution. Must be an instance of *ExponentialFamilyDistribution*
- **prior_param** – Prior parameters.

posterior_ll (*x, nu, ret_ll_gr_hs=(True, False, False), usual_x=False*)

Log likelihood (and derivatives) of data under posterior predictive distribution.

Parameters

- **x** – sufficient statistics of data
- **nu** – prior parameters

sufficient_stats (*data*)

sufficient_stats_dim ()

class `dpcluster.distributions.ExponentialFamilyDistribution`

Models a distribution in the exponential family of the form:

$$f(x|\nu) = h(x) \exp(\nu \cdot T(x) - A(\nu))$$

Parameters to be defined in subclasses:

- **h** is the base measure
- **nu** (ν) are the parameters
- **T(x)** are the sufficient statistics of the data
- **A** is the log partition function

ll (*xs, nus, ret_ll_gr_hs=(True, False, False)*)

Log likelihood (and derivatives, optionally) of data under distribution.

Parameters

- **xs** – sufficient statistics of data
- **nus** – parameters of distribution

log_base_measure (*x, ret_ll_gr_hs=(True, False, False)*)

Log of the base measure. To be implemented by subclasses.

Parameters **x** – sufficient statistics of the data.

log_partition (*nu, ret_ll_gr_hs=(True, False, False)*)

Log of the partition function and derivatives with respect to sufficient statistics. To be implemented by subclasses.

Parameters

- **nu** – parameters of the distribution
- **ret_ll_gr_hs** – what to return: log likelihood, gradient, hessian

class `dpcluster.distributions.Gaussian(d)`

Bases: `dpcluster.distributions.ExponentialFamilyDistribution`

Multivariate Gaussian distribution with density:

$$f(x|\mu, \Sigma) = |2\pi\Sigma|^{-1/2} \exp(-(x - \mu)^T \Sigma^{-1} (x - \mu)/2)$$

Natural parameters:

$$\nu = [\Sigma^{-1}\mu, -\Sigma^{-1}/2]$$

Sufficient statistics of data:

$$T(x) = [x, x \cdot x^T]$$

Parameters **d** – dimension.

log_base_measure (*x, ret_ll_gr_hs=(True, True, True)*)

Log base measure.

log_partition (*nus*)

nat2usual (*nus*)

Convert natural parameters to usual parameters

sufficient_stats (*x*)

Sufficient statistics of data. :arg x: data

sufficient_stats_dim()
Dimension of sufficient statistics.

usual2nat (*mus*, *Sgs*)
Convert usual parameters to natural parameters.

class `dpcluster.distributions.GaussianNIW` (*d*)
Bases: `dpcluster.distributions.ConjugatePair`
Gaussian, Normal-Inverse-Wishart conjugate pair.
The predictive posterior is a multivariate t-distribution.

Parameters **d** – dimension

conditional (*args)

conditional_expectation (*args)

conditional_variance (*x*, *nu*, *iy*, *ix*, *ret_ll_gr_hs*=(*True*, *True*, *False*), *full_var*=*True*)

conditionals_cache (*args)

conditionals_cache_bare (*args)

marginal (*nu*, *slc*)

plot (*nu*, *szs*, *slc*, *n*=100)

posterior_ll (*args)

posterior_ll_cache (*args)

sufficient_stats (*data*)

class `dpcluster.distributions.NIW` (*d*)
Bases: `dpcluster.distributions.ExponentialFamilyDistribution`

Normal Inverse Wishart distribution defined by:

$$f(\mu, \Sigma | \mu_0, \Psi, k) = \text{Gaussian}(\mu | \mu_0, \Sigma / k) \cdot \text{Inverse-Wishart}(\Sigma | \Psi, \nu - d - 2)$$

where $\mu, \mu_0 \in R^d$, $\Sigma, \Psi \in R^{d \times d}$, $k \in R$, $\nu > 2d + 1 \in R$

This is an exponential family conjugate prior for the Gaussian.

Parameters **d** – dimension

log_base_measure (*x*, *ret_ll_gr_hs*=(*True*, *True*, *True*))

log_partition (*nu*, *ret_ll_gr_hs*=(*True*, *False*, *False*), *no_k_grad*=*False*)

multipsi (*a*, *d*)

nat2usual (*args)

sufficient_stats (*mus*, *Sgs*)

sufficient_stats_dim ()

usual2nat (*mu0*, *Psi*, *k*, *nu*)

test Module

class `dpcluster.test.Tests` (*methodName*='runTest')
Bases: `unittest.case.TestCase`
gen_data (*A*, *mu*, *n*=10)

```
setUp()  
test_batch_vdp()  
test_gaussian()  
test_gniw()  
test_gniw_conditionals()  
test_ll()  
test_niw()  
test_online_vdp(*args, **kwargs)  
test_predictor(*args, **kwargs)  
test_presp(*args, **kwargs)  
test_resp()  
test_vdp_conditionals()  
dpcluster.test.grad_check(f, x, eps=0.0001)
```


CHAPTER 4

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