
AdafruitDRV2605 Library Documentation

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Contents

1	Dependencies	3
2	Usage Example	5
3	Contributing	7
4	Building locally	9
5	Table of Contents	11
5.1	Simple test	11
5.2	adafruit_drv2605	12
6	Indices and tables	15
	Python Module Index	17

CircuitPython module for the DRV2605 haptic feedback motor driver.

CHAPTER 1

Dependencies

This driver depends on:

- [Adafruit CircuitPython](#)
- [Bus Device](#)

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).

CHAPTER 2

Usage Example

See `examples/drv2605_simpletest.py` for a demo of the usage.

CHAPTER 3

Contributing

Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.

CHAPTER 4

Building locally

To build this library locally you'll need to install the `circuitpython-build-tools` package.

```
python3 -m venv .env
source .env/bin/activate
pip install circuitpython-build-tools
```

Once installed, make sure you are in the virtual environment:

```
source .env/bin/activate
```

Then run the build:

```
circuitpython-build-bundles --filename_prefix adafruit-circuitpython-drv2605 --
↳library_location .
```


5.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/drv2605_simpletest.py

```
1  # Simple demo of the DRV2605 haptic feedback motor driver.
2  # Will play all 117 effects in order for about a half second each.
3  # Author: Tony DiCola
4  import time
5
6  import board
7  import busio
8
9  import adafruit_drv2605
10
11
12 # Initialize I2C bus and DRV2605 module.
13 i2c = busio.I2C(board.SCL, board.SDA)
14 drv = adafruit_drv2605.DRV2605(i2c)
15
16 # Main loop runs forever trying each effect (1-117).
17 # See table 11.2 in the datasheet for a list of all the effect names and IDs.
18 # http://www.ti.com/lit/ds/symlink/drv2605.pdf
19 effect_id = 1
20 while True:
21     print('Playing effect #{0}'.format(effect_id))
22     drv.sequence[0] = adafruit_drv2605.Effect(effect_id) # Set the effect on slot 0.
23     # You can assign effects to up to 7 different slots to combine
24     # them in interesting ways. Index the sequence property with a
25     # slot number 0 to 6.
26     # Optionally, you can assign a pause to a slot. E.g.
27     # drv.sequence[1] = adafruit_drv2605.Pause(0.5) # Pause for half a second
```

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```
28 drv.play() # Play the effect.
29 time.sleep(0.5)
30 # Increment effect ID and wrap back around to 1.
31 effect_id += 1
32 if effect_id > 117:
33     effect_id = 1
```

5.2 adafruit_drv2605

CircuitPython module for the DRV2605 haptic feedback motor driver. See examples/simpletest.py for a demo of the usage.

- Author(s): Tony DiCola

class `adafruit_drv2605.DRV2605` (*i2c*, *address=90*)
TI DRV2605 haptic feedback motor driver module.

library

The library selected for waveform playback. Should be a value of:

- `LIBRARY_EMPTY`: Empty
- `LIBRARY_TS2200A`: TS2200 library A (the default)
- `LIBRARY_TS2200B`: TS2200 library B
- `LIBRARY_TS2200C`: TS2200 library C
- `LIBRARY_TS2200D`: TS2200 library D
- `LIBRARY_TS2200E`: TS2200 library E
- `LIBRARY_LRA`: LRA library

See the datasheet for the meaning and description of effects in each library.

mode

The mode of the chip. Should be a value of:

- `MODE_INTTRIG`: Internal triggering, vibrates as soon as you call `play()`. Default mode.
- `MODE_EXTTRIGEDGE`: External triggering, edge mode.
- `MODE_EXTTRIGLVL`: External triggering, level mode.
- `MODE_PWMANALOG`: PWM/analog input mode.
- `MODE_AUDIOVIBE`: Audio-to-vibration mode.
- `MODE_REALTIME`: Real-time playback mode.
- `MODE_DIAGNOS`: Diagnostics mode.
- `MODE_AUTOCAL`: Auto-calibration mode.

See the datasheet for the meaning of modes beyond `MODE_INTTRIG`.

play()

Play back the select effect(s) on the motor.

sequence

List-like sequence of waveform effects. Get or set an effect waveform for slot 0-6 by indexing the sequence property with the slot number. A slot must be set to either an Effect() or Pause() class. See the datasheet for a complete table of effect ID values and the associated waveform / effect.

E.g. 'slot_0_effect = drv.sequence[0]', 'drv.sequence[0] = Effect(88)'

set_waveform (*effect_id*, *slot=0*)

Select an effect waveform for the specified slot (default is slot 0, but up to 7 effects can be combined with slot values 0 to 6). See the datasheet for a complete table of effect ID values and the associated waveform / effect.

stop ()

Stop vibrating the motor.

use_ERM ()

Use an eccentric rotating mass motor (the default).

use_LRM ()

Use a linear resonance actuator motor.

class adafruit_drv2605.**Effect** (*effect_id*)
DRV2605 waveform sequence effect.

id

Effect ID.

raw_value

Raw effect ID.

class adafruit_drv2605.**Pause** (*duration*)
DRV2605 waveform sequence timed delay.

duration

Pause duration in seconds.

raw_value

Raw pause duration.

CHAPTER 6

Indices and tables

- `genindex`
- `modindex`
- `search`

a

`adafruit_drv2605`, 12

A

`adafruit_drv2605` (*module*), 12

D

`DRV2605` (*class in adafruit_drv2605*), 12

`duration` (*adafruit_drv2605.Pause attribute*), 13

E

`Effect` (*class in adafruit_drv2605*), 13

I

`id` (*adafruit_drv2605.Effect attribute*), 13

L

`library` (*adafruit_drv2605.DRV2605 attribute*), 12

M

`mode` (*adafruit_drv2605.DRV2605 attribute*), 12

P

`Pause` (*class in adafruit_drv2605*), 13

`play()` (*adafruit_drv2605.DRV2605 method*), 12

R

`raw_value` (*adafruit_drv2605.Effect attribute*), 13

`raw_value` (*adafruit_drv2605.Pause attribute*), 13

S

`sequence` (*adafruit_drv2605.DRV2605 attribute*), 12

`set_waveform()` (*adafruit_drv2605.DRV2605 method*), 13

`stop()` (*adafruit_drv2605.DRV2605 method*), 13

U

`use_ERM()` (*adafruit_drv2605.DRV2605 method*), 13

`use_LRM()` (*adafruit_drv2605.DRV2605 method*), 13