
vg
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vg Internal API Reference

Below is an index of all classes, files, and namespaces in `vg`, in alphabetical order.

Useful starting points include `vg::Node`, `vg::Edge`, `vg::Path`, and `vg::Graph`, which define the Protobuf graph data model, and `vg::VG`, which is the main graph class with all the useful graph methods on it.

struct `#include <genotyper.hpp>` **Public Functions**

`vg::Genotyper::Affinity::Affinity()`

`vg::Genotyper::Affinity::Affinity(double affinity, bool is_reverse)`

Public Members

`bool` `vg::Genotyper::Affinity::consistent`

`double` `vg::Genotyper::Affinity::affinity`

`bool` `vg::Genotyper::Affinity::is_reverse`

`double` `vg::Genotyper::Affinity::score`

`double` `vg::Genotyper::Affinity::likelihood_ln`

class `#include <gssw_aligner.hpp>` An ordinary aligner. Inherits from `vg::BaseAligner` **Public Functions**

`Aligner::Aligner(int8_t _match = default_match, int8_t _mismatch = default_mismatch, int8_t _gap_open = default_gap_open, int8_t _gap_extension = default_gap_extension, int8_t _full_length_bonus = default_full_length_bonus, double _gc_content = default_gc_content)`

`vg::Aligner::~~Aligner(void)`

```

void Aligner::align (Alignment &alignment, Graph &g, bool traceback_aln, bool
                    print_score_matrices)
    Store optimal local alignment against a graph in the Alignment object. Gives the full length bonus separately on each end of the alignment. Assumes that graph is topologically sorted by node index.

void Aligner::align_pinned (Alignment &alignment, Graph &g, bool pin_left)

void Aligner::align_pinned_multi (Alignment &alignment, vector<Alignment>
                                &alt_alignments, Graph &g, bool pin_left, int32_t
                                max_alt_alns)

void Aligner::align_global_banded (Alignment &alignment, Graph &g, int32_t
                                band_padding = 0, bool permissive_banding = true)

void Aligner::align_global_banded_multi (Alignment &alignment, vector<Alignment>
                                &alt_alignments, Graph &g, int32_t
                                max_alt_alns, int32_t band_padding = 0,
                                bool permissive_banding = true)

int32_t Aligner::score_exact_match (const Alignment &aln, size_t read_offset, size_t length)
    Compute the score of an exact match in the given alignment, from the given offset, of the given length.

int32_t Aligner::score_exact_match (const string &sequence, const string &base_quality)
    Compute the score of an exact match of the given sequence with the given qualities. Qualities may be ignored by some implementations.

int32_t Aligner::score_exact_match (string::const_iterator seq_begin, string::const_iterator
                                seq_end, string::const_iterator base_qual_begin) const
    Compute the score of an exact match of the given range of sequence with the given qualities. Qualities may be ignored by some implementations.

int32_t Aligner::score_exact_match (const string &sequence) const

int32_t Aligner::score_exact_match (string::const_iterator seq_begin, string::const_iterator
                                seq_end) const

```

Private Functions

```

void Aligner::align_internal (Alignment &alignment, vector<Alignment> *multi_alignments,
                             Graph &g, bool pinned, bool pin_left, int32_t max_alt_alns, bool
                             traceback_aln, bool print_score_matrices)

```

struct Alignments link query strings, such as other genomes or reads, to [Paths](#). **Public Members**

string vg::Alignment::sequence
The sequence that has been aligned.

[Path](#) vg::Alignment::path
The [Path](#) that the sequence follows in the graph it has been aligned to, containing the [Edits](#) that modify the graph to produce the sequence.

string vg::Alignment::name
The name of the sequence that has been aligned. Similar to read name in BAM.

bytes vg::Alignment::quality
The quality scores for the sequence, as values on a 0-255 scale.

`int32 vg::Alignment::mapping_quality`
The mapping quality score for the alignment, in Phreds.

`int32 vg::Alignment::score`
The score for the alignment, in points.

`int32 vg::Alignment::query_position`
The offset in the query at which this *Alignment* occurs.

`string vg::Alignment::sample_name`
The name of the sample that produced the aligned read.

`string vg::Alignment::read_group`
The name of the read group to which the aligned read belongs.

Alignment `vg::Alignment::fragment_prev`
The previous *Alignment* in the fragment. Contains just enough information to locate the full *Alignment*; e.g. contains an *Alignment* with only a name, or only a graph mapping position.

Alignment `vg::Alignment::fragment_next`
Similarly, the next *Alignment* in the fragment.

`bool vg::Alignment::is_secondary`
Flag marking the *Alignment* as secondary. All but one maximal-scoring alignment of a given read in a GAM file must be secondary.

`double vg::Alignment::identity`
Portion of aligned bases that are perfect matches, or 0 if no bases are aligned.

`repeated<Path> vg::Alignment::fragment`
An estimate of the length of the fragment, if this *Alignment* is paired.

`repeated<Locus> vg::Alignment::locus`
The loci that this alignment supports. TODO: get rid of this, we have annotations in our data model again.

`repeated<Position> vg::Alignment::refpos`
Position of the alignment in reference paths embedded in graph.

`bool vg::Alignment::read_paired`
SAMTools-style flags.

`bool vg::Alignment::read_mapped`

`bool vg::Alignment::mate_unmapped`

`bool vg::Alignment::read_on_reverse_strand`

`bool vg::Alignment::mate_on_reverse_strand`

`bool vg::Alignment::soft_clipped`

`bool vg::Alignment::discordant_insert_size`

`double vg::Alignment::uniqueness`
The fraction of bases in the alignment that are covered by MEMs with ≤ 1 total hits in the graph.

`double vg::Alignment::correct`
Correctness metric 1 = perfectly aligned to truth, 0 = not overlapping true alignment.

repeated<int32> vg::Alignment::secondary_score

The ordered list of scores of secondary mappings.

double vg::Alignment::fragment_score

Score under the given fragment model, assume higher is better.

bool vg::Alignment::mate_mapped_to_disjoint_subgraph

string vg::Alignment::fragment_length_distribution

The fragment length distribution under which a paired-end alignment was aligned.

class #include <mapper.hpp>**Public Functions**

vg::AlignmentChainModel::AlignmentChainModel (vector<vector<Alignment>> &bands,
Mapper *mapper, const function<double> const Alignment&,
const Alignment&, const map<string,
vector<pair<size_t, bool>>>&, const
map<string, vector<pair<size_t,
bool>>>&
> &transition_weight, int vertex_band_width = 10, int position_depth = 1, int max_connections = 30

void vg::AlignmentChainModel::score (const set<AlignmentChainModelVertex *> &exclude)

AlignmentChainModelVertex *vg::AlignmentChainModel::max_vertex (void)

vector<Alignment> vg::AlignmentChainModel::traceback (const Alignment &read, int
alt_alns, bool paired, bool
debug)

void vg::AlignmentChainModel::display (ostream &out)

void vg::AlignmentChainModel::clear_scores (void)

Public Members

vector<AlignmentChainModelVertex> vg::AlignmentChainModel::model

map<string, map<int64_t, vector<vector<AlignmentChainModelVertex>::iterator>>> vg::AlignmentChainModel::posi

set<vector<AlignmentChainModelVertex>::iterator> vg::AlignmentChainModel::redundant_vertexes

vector<Alignment> vg::AlignmentChainModel::unaligned_bands

class #include <mapper.hpp>**Public Functions**

vg::AlignmentChainModelVertex::AlignmentChainModelVertex (void)

vg::AlignmentChainModelVertex::AlignmentChainModelVertex (const AlignmentChainModelVertex&)

vg::AlignmentChainModelVertex::AlignmentChainModelVertex (AlignmentChainModelVertex&&)

AlignmentChainModelVertex &vg::AlignmentChainModelVertex::operator= (const AlignmentChainModelVertex&)

```
AlignmentChainModelVertex &vg::AlignmentChainModelVertex::operator=(AlignmentChainModelVertex&&)
virtual vg::AlignmentChainModelVertex::~~AlignmentChainModelVertex()
```

Public Members

```
Alignment *vg::AlignmentChainModelVertex::aln
vector<pair<AlignmentChainModelVertex *, double>> vg::AlignmentChainModelVertex::next_cost
vector<pair<AlignmentChainModelVertex *, double>> vg::AlignmentChainModelVertex::prev_cost
double vg::AlignmentChainModelVertex::weight
double vg::AlignmentChainModelVertex::score
map<string, vector<pair<size_t, bool>>> vg::AlignmentChainModelVertex::positions
int vg::AlignmentChainModelVertex::band_begin
int vg::AlignmentChainModelVertex::band_idx
AlignmentChainModelVertex *vg::AlignmentChainModelVertex::prev
class Public Functions
```

```
bool AlnSorter::mycomparison (const bool &reverse = false)
bool AlnSorter::operator () (const Alignment &a_one, const Alignment &a_two) const
```

Private Members

```
bool AlnSorter::invert
class #include <banded_global_aligner.hpp> Specialized linked list stack that finds and keeps track of the top-scoring non-optimal alignments. Sub-optimal alignments are represented by the locations where their traceback deviates from the optimal traceback, with other steps of the traceback implicitly following the optimal path. New tracebacks can be discovered while performing any of the tracebacks and added to the stack. Public Functions
```

```
BandedGlobalAligner::AltTracebackStack::AltTracebackStack (int64_t
                                                             max_multi_alns,
                                                             int32_t
                                                             empty_score, un-
                                                             ordered_set<BAMatrix
                                                             *>
                                                             &source_node_matrices,
                                                             un-
                                                             ordered_set<BAMatrix
                                                             *>
                                                             &sink_node_matrices,
                                                             int8_t gap_open,
                                                             int8_t gap_extend,
                                                             IntType min_inf)
```

```

BandedGlobalAligner::AltTracebackStack::~~AltTracebackStack()

void BandedGlobalAligner::AltTracebackStack::get_alignment_start (int64_t
                                                                    &node_id,
                                                                    matrix_t
                                                                    &matrix)
    Get the start position of the current alignment and advance deflection pointer to the first deflection.

bool BandedGlobalAligner::AltTracebackStack::has_next ()
    Are there any more alternate alignments in the stack?

void BandedGlobalAligner::AltTracebackStack::next_traceback_alignment ()
    Advance to the next alternate trac.

bool BandedGlobalAligner::AltTracebackStack::next_is_empty ()
    Is the next highest scoring alignment an empty path with no DP matrices?

void BandedGlobalAligner::AltTracebackStack::next_empty_alignment (Alignment
                                                                    &align-
                                                                    ment)
    Get the next empty path alignment.

void BandedGlobalAligner::AltTracebackStack::propose_deflection (const
                                                                    IntType
                                                                    score, const
                                                                    int64_t
                                                                    from_node_id,
                                                                    const
                                                                    int64_t
                                                                    row_idx,
                                                                    const
                                                                    int64_t
                                                                    col_idx,
                                                                    const
                                                                    int64_t
                                                                    to_node_id,
                                                                    const
                                                                    matrix_t
                                                                    to_matrix)
    Check if a deflection from the current traceback is better than any alignments currently in the stack and if
    so insert it in the correct position

IntType BandedGlobalAligner::AltTracebackStack::current_traceback_score ()
    Score of the current traceback.

const list<int64_t> &BandedGlobalAligner::AltTracebackStack::current_empty_prefix ()
    The prefix of the current traceback that consists of only empty nodes.

bool BandedGlobalAligner::AltTracebackStack::at_next_deflection (int64_t
                                                                    node_id,
                                                                    int64_t
                                                                    row_idx,
                                                                    int64_t
                                                                    col_idx)
    Are these the coordinates of the next deflection?

BandedGlobalAligner<IntType>::matrix_t BandedGlobalAligner::AltTracebackStack::deflect_to_matrix
    Get the matrix to deflect to and advance to the next deflection.

```

BandedGlobalAligner<IntType>::matrix_t BandedGlobalAligner::AltTracebackStack::deflect_to_matrix

Get the matrix and the node id to deflect to (for use at a node boundary)

Private Functions

```
void BandedGlobalAligner::AltTracebackStack::insert_traceback (const    vec-
                                                                tor<Deflection>
                                                                &trace-
                                                                back_prefix,
                                                                const    Int-
                                                                Type    score,
                                                                const    int64_t
                                                                from_node_id,
                                                                const    int64_t
                                                                row_idx,
                                                                const    int64_t
                                                                col_idx,
                                                                const    int64_t
                                                                to_node_id,
                                                                const    matrix_t
                                                                to_matrix,
                                                                const
                                                                list<int64_t>
                                                                &empty_node_prefix)
```

Internal method for propose_deflection.

Private Members

```
template<>
int64_t vg::BandedGlobalAligner<IntType>::AltTracebackStack::max_multi_alns
    Maximum number of alternate alignments to keep track of (including the optimal alignment)
```

```
template<>
list<tuple<vector<Deflection>, IntType, list<int64_t>>> vg::BandedGlobalAligner<IntType>::AltTracebackStack
    List of tuples that contain the scores of alternate alignments, the places where their traceback deviates from
    the optimum (Deflections), and all empty nodes that occur at the suffix of the traceback (if any). Maintains
    an invariant where stack is sorted in descending score order.
```

```
template<>
list<list<int64_t>> vg::BandedGlobalAligner<IntType>::AltTracebackStack::empty_full_paths
    All of the paths through the graph that take only empty nodes.
```

```
template<>
int32_t vg::BandedGlobalAligner<IntType>::AltTracebackStack::empty_score
```

```
template<>
list<tuple<vector<Deflection>, IntType, list<int64_t>>>::iterator vg::BandedGlobalAligner<IntType>::AltTracebackStack
    Pointer to the traceback directions for the alignment we are currently tracing back.
```

```
template<>
vector<Deflection>::iterator vg::BandedGlobalAligner<IntType>::AltTracebackStack::curr_deflxn
    Pointer to the next deviation from the optimal traceback we will take.
```

struct *#include <genome_state.hpp>* Inherits from *vg::GenomeStateCommand* **Public Functions**

GenomeStateCommand *vg::AppendHaplotypeCommand::execute(*GenomeState* &state)

const
Execute this command on the given state and return the reverse command. Generally ends up calling a command-type-specific method on the *GenomeState* that does the actual work.

virtual vg::AppendHaplotypeCommand::~AppendHaplotypeCommand()

Public Members

vector<*handle_t*> vg::AppendHaplotypeCommand::haplotype

We just feed in a full traversal from one end of a telomere pair to the other. Must start and end on the boundary nodes of telomere snarls. TODO: unary telomeres will work strangely. Internally the *GenomeState* has to work out how to divide this into snarls.

struct *#include <genotypekit.hpp>* General interface for an augmented graph. This is a graph that was constructed by adding some read information to an original (“base”) graph. We preserve mappings back to the base graph via translations. Augmented graphs can be made using edit (such as in *vg mod -i*) or pileup. Todo : further abstract to handle graph interface Subclassed by *vg::SupportAugmentedGraph* **Public Functions**

pair<const *Edge* *, bool> vg::AugmentedGraph::base_edge(const *Edge* *augmented_edge)

bool vg::AugmentedGraph::is_novel_node(const *Node* *augmented_node)

bool vg::AugmentedGraph::is_novel_edge(const *Edge* *augmented_edge)

void vg::AugmentedGraph::clear()

Clear the contents.

void vg::AugmentedGraph::augment_from_alignment_edits(vector<*Alignment*> &alignments, bool unique_names = true, bool leave_edits = false)

Construct an augmented graph using edit() on a set of alignments

void vg::AugmentedGraph::load_translations(istream &in_file)

Load the translations from a file

void vg::AugmentedGraph::write_translations(ostream &out_file)

Write the translations to a file

Public Members

VG vg::AugmentedGraph::graph

VG *vg::AugmentedGraph::base_graph

Translator vg::AugmentedGraph::translator

class *#include <banded_global_aligner.hpp>* Translates a traceback path into a *Path* object and stores it in an *Alignment* object **Public Functions**

BandedGlobalAligner::BABuilder::BABuilder(*Alignment* &alignment)

```

BandedGlobalAligner::BABuilder::~~BABuilder()

void BandedGlobalAligner::BABuilder::update_state(matrix_t matrix, Node *node,
                                                    int64_t read_idx, int64_t
                                                    node_idx, bool empty_node_seq
                                                    = false)

```

Add next step in traceback.

```

void BandedGlobalAligner::BABuilder::finalize_alignment(const list<int64_t>
                                                         &empty_prefix)

```

Call after concluding traceback to finish adding edits to alignment.

Private Functions

```

void BandedGlobalAligner::BABuilder::finish_current_edit()
void BandedGlobalAligner::BABuilder::finish_current_node()

```

Private Members

```

template<>
Alignment &vg::BandedGlobalAligner<IntType>::BABuilder::alignment

template<>
list<Mapping> vg::BandedGlobalAligner<IntType>::BABuilder::node_mappings

template<>
list<Edit> vg::BandedGlobalAligner<IntType>::BABuilder::mapping_edits

template<>
matrix_t vg::BandedGlobalAligner<IntType>::BABuilder::matrix_state

template<>
bool vg::BandedGlobalAligner<IntType>::BABuilder::matching

template<>
Node *vg::BandedGlobalAligner<IntType>::BABuilder::current_node

template<>
int64_t vg::BandedGlobalAligner<IntType>::BABuilder::edit_length

template<>
int64_t vg::BandedGlobalAligner<IntType>::BABuilder::edit_read_end_idx
class #include <banded_global_aligner.hpp> Represents the band from the DP matrix for one node in the
graph

```

Public Functions

```

BandedGlobalAligner::BAMatrix::BAMatrix(Alignment &alignment, Node *node, int64_t
                                         top_diag, int64_t bottom_diag, BAMatrix
                                         **seeds, int64_t num_seeds, int64_t cumulative_seq_len)

BandedGlobalAligner::BAMatrix::~~BAMatrix()

```

```
void BandedGlobalAligner::BAMatrix::fill_matrix(int8_t *score_mat, int8_t *nt_table,
                                                int8_t gap_open, int8_t gap_extend,
                                                bool qual_adjusted, IntType
                                                min_inf)
```

Use DP to fill the band with alignment scores.

```
void BandedGlobalAligner::BAMatrix::traceback(BABuilder &builder, AltTraceback-
Stack &traceback_stack, matrix_t
start_mat, int8_t *score_mat, int8_t
*nt_table, int8_t gap_open, int8_t
gap_extend, bool qual_adjusted,
IntType min_inf)
```

Traceback through the band after using DP to fill it.

```
void BandedGlobalAligner::BAMatrix::print_full_matrices()
```

Debugging function.

```
void BandedGlobalAligner::BAMatrix::print_rectangularized_bands()
```

Debugging function.

Private Functions

```
void BandedGlobalAligner::BAMatrix::traceback_internal(BABuilder &builder,
AltTracebackStack
&traceback_stack,
int64_t start_row,
int64_t start_col, ma-
trix_t start_mat, bool
in_lead_gap, int8_t
*score_mat, int8_t
*nt_table, int8_t
gap_open, int8_t
gap_extend, bool
qual_adjusted, IntType
min_inf)
```

```
void BandedGlobalAligner::BAMatrix::print_matrix(matrix_t which_mat)
```

Debugging function.

```
void BandedGlobalAligner::BAMatrix::print_band(matrix_t which_mat)
```

Debugging function.

Private Members

```
template<>
int64_t vg::BandedGlobalAligner<IntType>::BAMatrix::top_diag
```

The diagonals in the DP matrix that the band passes through with the bottom index inclusive.

```
template<>
int64_t vg::BandedGlobalAligner<IntType>::BAMatrix::bottom_diag
```

```
template<>
Node *vg::BandedGlobalAligner<IntType>::BAMatrix::node
```

```

template<>
Alignment &vg::BandedGlobalAligner<IntType>::BAMatrix::alignment

template<>
int64_t vg::BandedGlobalAligner<IntType>::BAMatrix::cumulative_seq_len
    Length of shortest sequence leading to matrix from a source node.

template<>
BAMatrix **vg::BandedGlobalAligner<IntType>::BAMatrix::seeds
    Matrices for nodes with edges into this node.

template<>
int64_t vg::BandedGlobalAligner<IntType>::BAMatrix::num_seeds

template<>
IntType *vg::BandedGlobalAligner<IntType>::BAMatrix::match
    DP matrix.

template<>
IntType *vg::BandedGlobalAligner<IntType>::BAMatrix::insert_col
    DP matrix.

template<>
IntType *vg::BandedGlobalAligner<IntType>::BAMatrix::insert_row
    DP matrix.

```

Friends

friend **vg::BandedGlobalAligner::BAMatrix::BABuilder**

friend **vg::BandedGlobalAligner::BAMatrix::AltTracebackStack**

template <class IntType>

class *#include <banded_global_aligner.hpp>* The outward-facing interface for banded global graph alignment. It computes optimal alignment of a DNA sequence to a DAG with POA. The alignment will start at any source node in the graph and end at any sink node. It is also restricted to falling within a certain diagonal band from the start node. Any signed integer type can be used for the dynamic programming matrices, but there are no checks for overflow.

Public Functions

BandedGlobalAligner::BandedGlobalAligner (Alignment &alignment, Graph &g, int64_t band_padding, bool permissive_banding = false, bool adjust_for_base_quality = false)

Initializes banded alignment

Args: alignment empty alignment with a sequence (and possibly base qualities) g graph to align to band_padding width to expand band by permissive_banding expand band, not necessarily symmetrically, to allow all node paths adjust_for_base_quality perform base quality adjusted alignment (see [QualAd-Aligner](#))

BandedGlobalAligner::BandedGlobalAligner (Alignment &alignment, Graph &g, vector<Alignment> &alt_alignments, int64_t max_multi_alns, int64_t band_padding, bool permissive_banding = false, bool adjust_for_base_quality = false)

Initializes banded multi-alignment, which computes the top scoring alternate alignments in addition to the optimal alignment

Args: alignment empty alignment with a sequence (and possibly base qualities) g graph to align to alt_alignments an empty vector to store alternate alignments in, the first element will be a copy of the primary alignment max_multi_alns the maximum number of alternate alignments (including the primary) band_padding width to expand band by permissive_banding expand band, not necessarily symmetrically, to allow all node paths adjust_for_base_quality perform base quality adjusted alignment (see [QualAdjAligner](#))

BandedGlobalAligner::~BandedGlobalAligner()

void BandedGlobalAligner::align(int8_t *score_mat, int8_t *nt_table, int8_t gap_open, int8_t gap_extend)

Adds path and score to the alignment object given in the constructor. If a multi-alignment vector was also supplied, fills the vector with the top scoring alignments as well.

Note: the score arguments are not <IntType> so that they can interact easily with the [Aligner](#)

Args: score_mat matrix of match/mismatch scores from [Aligner](#) (if performing base quality adjusted alignment, use [QualAdjAligner](#)'s adjusted score matrix) nt_table table of indices by DNA char from [Aligner](#) gap_open gap open penalty from [Aligner](#) (if performing base quality adjusted alignment, use [QualAdjAligner](#)'s scaled penalty) gap_extend gap extension penalty from [Aligner](#) (if performing base quality adjusted alignment, use [QualAdjAligner](#)'s scaled penalty)

Private Types

enum type vg::BandedGlobalAligner::matrix_t

Matrices used in Smith-Waterman-Gotoh alignment algorithm.

Values:

Private Functions

BandedGlobalAligner::BandedGlobalAligner(Alignment &alignment, Graph &g, vector<Alignment> *alt_alignments, int64_t max_multi_alns, int64_t band_padding, bool permissive_banding = false, bool adjust_for_base_quality = false)

Internal constructor that the public constructors funnel into.

void BandedGlobalAligner::traceback(int8_t *score_mat, int8_t *nt_table, int8_t gap_open, int8_t gap_extend, IntType min_inf)

Traceback through dynamic programming matrices to compute alignment.

void BandedGlobalAligner::graph_edge_lists(Graph &g, bool outgoing_edges, vector<vector<int64_t>> &out_edge_list)

Constructor helper function: converts [Graph](#) object into adjacency list representation.

void BandedGlobalAligner::topological_sort(Graph &g, vector<vector<int64_t>> &node_edges_out, vector<Node *> &out_topological_order)

Constructor helper function: compute topological ordering.


```
void BandedGlobalAligner::path_lengths_to_sinks(const string &read, vector<vector<int64_t>>
                                              &node_edges_in, vector<int64_t> &shortest_path_to_sink, vector<int64_t>
                                              &longest_path_to_sink)
```

Constructor helper function: compute the longest and shortest path to a sink for each node.

```
void BandedGlobalAligner::find_banded_paths(const string &read, bool permissive_banding, vector<vector<int64_t>>
                                              &node_edges_in, vector<vector<int64_t>> &node_edges_out,
                                              int64_t band_padding, vector<bool> &node_masked, vector<pair<int64_t,
                                              int64_t>> &band_ends)
```

Constructor helper function: compute which diagonals the bands cover on each node's matrix.

```
void BandedGlobalAligner::shortest_seq_paths(vector<vector<int64_t>>
                                              &node_edges_out, unordered_set<Node
                                              *> &source_nodes, vector<int64_t>
                                              &seq_lens_out)
```

Constructor helper function: compute the shortest path from a source to each node.

Private Members

Alignment &vg::BandedGlobalAligner::alignment

The primary alignment.

vector<*Alignment*> *vg::BandedGlobalAligner::alt_alignments

Vector for alternate alignments, or null if not making any.

int64_t vg::BandedGlobalAligner::max_multi_alns

Number of alignments to compute, including the optimal alignment.

bool vg::BandedGlobalAligner::adjust_for_base_quality

Use base quality adjusted scoring for alignments?

vector<*BAMatrix* *> vg::BandedGlobalAligner::banded_matrices

Dynamic programming matrices for each node.

unordered_map<int64_t, int64_t> vg::BandedGlobalAligner::node_id_to_idx

Map from node IDs to the index used in internal vectors.

vector<*Node* *> vg::BandedGlobalAligner::topological_order

A topological ordering of the nodes.

unordered_set<*Node* *> vg::BandedGlobalAligner::source_nodes

Source nodes in the graph.

unordered_set<*Node* *> vg::BandedGlobalAligner::sink_nodes

Sink nodes in the graph.

class #include <gssw_aligner.hpp> The interface that any *Aligner* should implement, with some default implementations. Subclassed by *vg::Aligner*, *vg::QualAdjAligner* **Public Functions**

double BaseAligner::max_possible_mapping_quality(int length)

```

double BaseAligner::estimate_max_possible_mapping_quality(int length, double
                                                         min_diffs, double
                                                         next_min_diffs)

virtual void vg::BaseAligner::align(Alignment &alignment, Graph &g, bool traceback_aln,
                                   bool print_score_matrices)
    = 0 Store optimal local alignment against a graph in the Alignment object. Gives the full length bonus
    separately on each end of the alignment. Assumes that graph is topologically sorted by node index.

virtual void vg::BaseAligner::align_pinned(Alignment &alignment, Graph &g, bool
                                           pin_left)
    = 0

virtual void vg::BaseAligner::align_pinned_multi(Alignment &alignment, vector<Alignment>
                                                &alt_alignments,
                                                Graph &g, bool pin_left, int32_t
                                                max_alt_alns)
    = 0

virtual void vg::BaseAligner::align_global_banded(Alignment &alignment, Graph &g,
                                                  int32_t band_padding = 0, bool per-
                                                  missive_banding = true)
    = 0

virtual void vg::BaseAligner::align_global_banded_multi(Alignment &alignment,
                                                        vector<Alignment>
                                                        &alt_alignments, Graph
                                                        &g, int32_t max_alt_alns,
                                                        int32_t band_padding = 0,
                                                        bool permissive_banding =
                                                        true)
    = 0

virtual int32_t vg::BaseAligner::score_exact_match(const Alignment &aln, size_t
                                                    read_offset, size_t length)
    = 0 Compute the score of an exact match in the given alignment, from the given offset, of the given length.

virtual int32_t vg::BaseAligner::score_exact_match(const string &sequence, const string
                                                    &base_quality) const
    = 0 Compute the score of an exact match of the given sequence with the given qualities. Qualities may be
    ignored by some implementations.

virtual int32_t vg::BaseAligner::score_exact_match(string::const_iterator seq_begin,
                                                    string::const_iterator
                                                    seq_end, string::const_iterator
                                                    base_qual_begin) const
    = 0 Compute the score of an exact match of the given range of sequence with the given qualities. Qualities
    may be ignored by some implementations.

int32_t BaseAligner::score_gap(size_t gap_length)
    Returns the score of an insert or deletion of the given length.

void BaseAligner::compute_mapping_quality(vector<Alignment> &alignments,
                                          int max_mapping_quality, bool
                                          fast_approximation, double cluster_mq, bool
                                          use_cluster_mq, int overlap_count, double
                                          mq_estimate, double maybe_mq_threshold,
                                          double identity_weight)
    stores  $-10 * \log_{10}(P_{err})$  in alignment mapping_quality field where  $P_{err}$  is the probability that the

```

alignment is not the correct one (assuming that one of the alignments in the vector is correct). alignments must have been created with this [Aligner](#) for quality score to be valid

```
void BaseAligner::compute_paired_mapping_quality (pair<vector<Alignment>, vector<Alignment>> &alignment_pairs, const vector<double> &frag_weights, int max_mapping_quality1, int max_mapping_quality2, bool fast_approximation, double cluster_mq, bool use_cluster_mq, int overlap_count1, int overlap_count2, double mq_estimate1, double mq_estimate2, double maybe_mq_threshold, double identity_weight)
```

same function for paired reads, mapping qualities are stored in both alignments in the pair

```
int32_t BaseAligner::compute_mapping_quality (vector<double> &scores, bool fast_approximation)
```

Computes mapping quality for the optimal score in a vector of scores.

```
double BaseAligner::mapping_quality_score_diff (double mapping_quality) const
```

Returns the difference between an optimal and second-best alignment scores that would result in this mapping quality using the fast mapping quality approximation

```
double BaseAligner::score_to_unnormalized_likelihood_ln (double score)
```

Convert a score to an unnormalized log likelihood for the sequence. Requires log_base to have been set.

```
size_t BaseAligner::longest_detectable_gap (const Alignment &alignment, const string::const_iterator &read_pos) const
```

The longest gap detectable from a read position without soft-clipping.

```
size_t BaseAligner::longest_detectable_gap (const Alignment &alignment) const
```

The longest gap detectable from any read position without soft-clipping.

```
int32_t BaseAligner::score_gappy_alignment (const Alignment &aln, const function<size_t> pos_t, pos_t, size_t
```

> &estimate_distance, bool strip_bonuses = false) Use the score values in the aligner to score the given alignment, scoring gaps caused by jumping between between nodes using a custom gap length estimation function (which takes the from position, the to position, and a search limit in bp that happens to be the read length).

May include full length bonus or not. TODO: bool flags are bad.

```
int32_t BaseAligner::score_ungapped_alignment (const Alignment &aln, bool strip_bonuses = false)
```

Use the score values in the aligner to score the given alignment assuming that there are no gaps between Mappings in the [Path](#)

```
int32_t BaseAligner::remove_bonuses (const Alignment &aln, bool pinned = false, bool pin_left = false)
```

Without necessarily rescoreing the entire alignment, return the score of the given alignment with bonuses removed. Assumes that bonuses are actually included in the score. Needs to know if the alignment was pinned-end or not, and, if so, which end was pinned.

Public Members

```
int8_t *vg::BaseAligner::nt_table
int8_t *vg::BaseAligner::score_matrix
int8_t vg::BaseAligner::match
int8_t vg::BaseAligner::mismatch
int8_t vg::BaseAligner::gap_open
int8_t vg::BaseAligner::gap_extension
int8_t vg::BaseAligner::full_length_bonus
double vg::BaseAligner::log_base
```

Protected Functions

```
vg::BaseAligner::BaseAligner()
BaseAligner::~~BaseAligner()
gssw_graph *BaseAligner::create_gssw_graph(Graph &g)
void vg::BaseAligner::visit_node(gssw_node *node, list<gssw_node *> &sorted_nodes,
                                set<gssw_node *> &unmarked_nodes, set<gssw_node *>
                                &temporary_marks)
void BaseAligner::reverse_graph(Graph &g, Graph &reversed_graph_out)
void BaseAligner::unreverse_graph(Graph &graph)
void BaseAligner::unreverse_graph_mapping(gssw_graph_mapping *gm)
void BaseAligner::gssw_mapping_to_alignment(gssw_graph *graph,
                                             gssw_graph_mapping *gm, Alignment
                                             &alignment, bool pinned, bool pin_left,
                                             bool print_score_matrices = false)
string BaseAligner::graph_cigar(gssw_graph_mapping *gm)
double BaseAligner::maximum_mapping_quality_exact(vector<double> &scaled_scores,
                                                  size_t *max_idx_out)
double BaseAligner::maximum_mapping_quality_approx(vector<double>
                                                  &scaled_scores, size_t
                                                  *max_idx_out)
double BaseAligner::estimate_next_best_score(int length, double min_diffs)
void BaseAligner::init_mapping_quality(double gc_content)
class #include <mapper.hpp> Inherits from vg::Progressive Subclassed by vg::Mapper, vg::MultipathMapper
Public Functions
```

```
vg::BaseMapper::BaseMapper(xg::XG *xidex, gcsa::GCSA *g, gcsa::LCPArray *a)
```

```

vg::BaseMapper::BaseMapper (void)

vg::BaseMapper::~~BaseMapper (void)

double vg::BaseMapper::estimate_gc_content (void)

int vg::BaseMapper::random_match_length (double chance_random)

void vg::BaseMapper::set_alignment_scores (int8_t match, int8_t mismatch, int8_t
                                         gap_open, int8_t gap_extend, int8_t
                                         full_length_bonus)

void vg::BaseMapper::set_fragment_length_distr_params (size_t maxi-
                                                         mum_sample_size =
                                                         1000, size_t rees-
                                                         timation_frequency
                                                         = 1000, double ro-
                                                         bust_estimation_fraction =
                                                         0.95)

void vg::BaseMapper::set_alignment_threads (int new_thread_count)
    Set the alignment thread count, updating internal data structures that are per thread. Note that this resets
    aligner scores to their default values!

void vg::BaseMapper::set_cache_size (int new_cache_size)

bool vg::BaseMapper::has_fixed_fragment_length_distr ()
    Returns true if fragment length distribution has been fixed.

void vg::BaseMapper::force_fragment_length_distr (double mean, double stddev)
    Use the given fragment length distribution parameters instead of estimating them.

vector<MaximalExactMatch> vg::BaseMapper::find_mems_deep (string::const_iterator
                                                         seq_begin,
                                                         string::const_iterator
                                                         seq_end, double &lcp_avg,
                                                         double &fraction_filtered,
                                                         int max_mem_length = 0,
                                                         int min_mem_length = 1,
                                                         int reseed_length = 0, bool
                                                         use_lcp_reseed_heuristic
                                                         = false, bool
                                                         use_diff_based_fast_reseed
                                                         = false, bool in-
                                                         clude_parent_in_sub_mem_count
                                                         = false, bool
                                                         record_max_lcp = false,
                                                         int reseed_below_count =
                                                         0)

vector<MaximalExactMatch> vg::BaseMapper::find_mems_simple (string::const_iterator
                                                           seq_begin,
                                                           string::const_iterator
                                                           seq_end, int
                                                           max_mem_length =
                                                           0, int min_mem_length =
                                                           1, int reseed_length = 0)

```

Public Members

```
int vg::BaseMapper::min_mem_length
int vg::BaseMapper::mem_reseed_length
bool vg::BaseMapper::fast_reseed
double vg::BaseMapper::fast_reseed_length_diff
bool vg::BaseMapper::adaptive_reseed_diff
double vg::BaseMapper::adaptive_diff_exponent
int vg::BaseMapper::hit_max
bool vg::BaseMapper::use_approx_sub_mem_count
bool vg::BaseMapper::strip_bonuses
bool vg::BaseMapper::assume_acyclic
bool vg::BaseMapper::adjust_alignments_for_base_quality
MappingQualityMethod vg::BaseMapper::mapping_quality_method
int vg::BaseMapper::max_mapping_quality
```

Protected Functions

```
void vg::BaseMapper::find_sub_mems (const vector<MaximalExactMatch> &mems, int
                                     mem_idx, string::const_iterator next_mem_end, int
                                     min_mem_length, vector<pair<MaximalExactMatch,
                                     vector<size_t>>> &sub_mems_out)
    Locate the sub-MEMs contained in the last MEM of the mems vector that have ending positions before
    the end the next SMEM, label each of the sub-MEMs with the indices of all of the SMEMs that contain it
```

```
void vg::BaseMapper::find_sub_mems_fast (const vector<MaximalExactMatch>
                                         &mems, int mem_idx, string::const_iterator
                                         next_mem_end, int min_sub_mem_length,
                                         vector<pair<MaximalExactMatch, vector<size_t>>> &sub_mems_out)
    Provides same semantics as find_sub_mems but with a different algorithm. This algorithm uses the
    min_mem_length as a pruning tool instead of the LCP index. It can be expected to be faster when both the
    min_mem_length reasonably large relative to the reseed_length (e.g. 1/2 of SMEM size or similar).
```

```
void vg::BaseMapper::fill_nonredundant_sub_mem_nodes (vector<MaximalExactMatch>
                                                       &parent_mems, vector<pair<MaximalExactMatch,
                                                       vector<size_t>>>::iterator
                                                       sub_mem_records_begin,
                                                       vector<pair<MaximalExactMatch,
                                                       vector<size_t>>>::iterator
                                                       sub_mem_records_end)
    finds the nodes of sub MEMs that do not occur inside parent MEMs, each sub MEM should be associated
    with a vector of the indices of the SMEMs that contain it in the parent MEMs vector
```

```

void vg::BaseMapper::first_hit_positions_by_index(MaximalExactMatch &mem,
                                                  vector<set<pos_t>> &positions_by_index_out)
    fills a vector where each element contains the set of positions in the graph that the MEM touches at that
    index for the first MEM hit in the GCSA array

void vg::BaseMapper::mem_positions_by_index(MaximalExactMatch &mem, pos_t hit_pos,
                                             vector<set<pos_t>> &positions_by_index_out)
    fills a vector where each element contains the set of positions in the graph that the MEM touches at that
    index starting at a given hit

char vg::BaseMapper::pos_char(pos_t pos)

map<pos_t, char> vg::BaseMapper::next_pos_chars(pos_t pos)

set<pos_t> vg::BaseMapper::positions_bp_from(pos_t pos, int distance, bool rev)

set<pos_t> vg::BaseMapper::sequence_positions(const string &seq)

size_t vg::BaseMapper::get_adaptive_min_reseed_length(size_t parent_mem_length)

void vg::BaseMapper::check_mems(const vector<MaximalExactMatch> &mems)

void vg::BaseMapper::init_aligner(int8_t match, int8_t mismatch, int8_t gap_open, int8_t gap_extend,
                                   int8_t full_length_bonus)

void vg::BaseMapper::clear_aligners(void)

BaseAligner *vg::BaseMapper::get_aligner(bool have_qualities = true) const
    Get the appropriate aligner to use, based on adjust_alignments_for_base_quality. By setting have_qualities
    to false, you can force the non-quality-adjusted aligner, for reads that lack quality scores.

QualAdjAligner *vg::BaseMapper::get_qual_adj_aligner() const

Aligner *vg::BaseMapper::get_regular_aligner() const

```

Protected Attributes

```

int vg::BaseMapper::alignment_threads

xg::XG *vg::BaseMapper::xindex

gcsa::GCSA *vg::BaseMapper::gcsa

gcsa::LCPArray *vg::BaseMapper::lcp

FragmentLengthDistribution vg::BaseMapper::fragment_length_distr

```

Protected Static Attributes

```

thread_local vector<size_t> vg::BaseMapper::adaptive_reseed_length_memo

```

Private Members

QualAdjAligner *vg::BaseMapper::qual_adj_aligner

Aligner *vg::BaseMapper::regular_aligner

template <typename *Value*, typename *Parser* = *OptionValueParser*<*Value*>>

class #include <option.hpp> The correct user entry point is one of the *Option*<> specializations, not this class.

Represents a configurable parameter for a class that we might want to expose on the command line.

We need to allow these to be defined with default values in the class's header, but be overridable by simple assignment of a value of the right type. But we also need to be able to interrogate an instance of the class to get all its options that need to be filled in and their help text, and ideally to choose short options to assign to them that don't conflict.

So our approach is to have the class keep track of all its option objects, and to have the options register themselves at construction time with a passed this pointer (since this is in scope in the class body in the header).

Option instances **MUST** exist as MEMBERS of classes that inherit from *Configurable*! They can't live in vectors or anything, or the magic code that tracks them as the enclosing object moves won't work!

We'll have an assignment operator from the wrapped type to make setting options manually easy.

We also have magical conversion to the wrapped type.

We wrap all the type-specific parsing into a parser template. You could specify your own if you want custom parsing logic for like a map or something.

Inherits from *vg::OptionInterface*

Subclassed by *vg::Option*< *Value*, *Parser* >

Public Functions

vg::BaseOption::BaseOption()

No default constructor.

virtual *vg::BaseOption::~~BaseOption*()

Default destructor.

vg::BaseOption::BaseOption(*Configurable* *owner, **const** string &long_opt, **const** string &short_opts, **const** *Value* &default_value, **const** string &description)

Make a new *BaseOption* that lives in a class, with the given name, short option characters, and default value.

BaseOption<*Value*, *Parser*> &vg::BaseOption::operator= (**const** *BaseOption*<*Value*, *Parser*> &other)

Assignment from an *Option* of the correct type.

BaseOption<*Value*, *Parser*> &vg::BaseOption::operator= (**const** *Value* &other)

Assignment from an unwrapped value.

vg::BaseOption::operator Value&()

Conversion to the wrapped type.

virtual const string &vg::BaseOption::get_long_option() **const**

Get the long option text without , like "foos-to-bar".

virtual const string &vg::BaseOption::get_short_options() const

Gets a list of short option characters that the option wants, in priority order. If none of these are available, the option will be automatically assigned some other free character.

virtual const string &vg::BaseOption::get_description() const

Get the description, like “number of foos to bar per frobnitz”.

virtual string vg::BaseOption::get_default_value() const

Get the default value as a string.

virtual bool vg::BaseOption::has_argument() const

Returns true if the option takes an argument, and false otherwise.

virtual void vg::BaseOption::parse()

Called for no-argument options when the parser encounters them.

virtual void vg::BaseOption::parse(const string &arg)

Called for argument-having options when the parser encounters them. The passed reference is only valid during the function call, so the option should make a copy.

Protected Attributes

string vg::BaseOption::long_opt

What is the options’s long option name.

string vg::BaseOption::short_opts

What is the option’s short option name.

string vg::BaseOption::description

How is this option described to the user?

Value vg::BaseOption::value

We keep a value of our chosen type. It just has to be copyable and assignable.

Value vg::BaseOption::default_value

We also keep the default value around, in case we somehow get assigned and then get asked to report our metadata. TODO: do this as a string instead?

struct Summarizes reads that map to single position in the graph. This structure is pretty much identical to a line in Samtools pileup format if qualities set, it must have size = num_bases

Public Members

int32 vg::BasePileup::ref_base

int32 vg::BasePileup::num_bases

string vg::BasePileup::bases

bytes vg::BasePileup::qualities

struct #include <benchmark.hpp> Represents the results of a benchmark run. Tracks the mean and standard deviation of a number of runs of a function under test, interleaved with runs of a standard control function.

Public Functions

double vg::BenchmarkResult::score() const

How many control-standardized “points” do we score?

double vg::BenchmarkResult::score_error() const

What is the uncertainty on the score?

Public Members

size_t vg::BenchmarkResult::runs

How many runs were done.

benchmark vg::BenchmarkResult::test_mean

What was the mean runtime of each test run.

benchmark vg::BenchmarkResult::test_stddev

What was the standard deviation of test run times.

benchmark vg::BenchmarkResult::control_mean

What was the mean runtime of each control run.

benchmark vg::BenchmarkResult::control_stddev

What was the standard deviation of control run times.

string vg::BenchmarkResult::name

What was the name of the test being run.

struct #include <srpe.hpp> **Public Functions**

int vg::BREAKPOINT::total_supports()

bool vg::BREAKPOINT::overlap(*BREAKPOINT* p, int dist)

string vg::BREAKPOINT::to_string()

Public Members

string vg::BREAKPOINT::name

Position vg::BREAKPOINT::position

vector<*BREAKPOINT*> vg::BREAKPOINT::mates

string vg::BREAKPOINT::contig

int64_t vg::BREAKPOINT::start

int64_t vg::BREAKPOINT::upper_bound

int64_t vg::BREAKPOINT::lower_bound

bool vg::BREAKPOINT::isForward

int vg::BREAKPOINT::SV_TYPE

int vg::BREAKPOINT::normal_supports

int vg::BREAKPOINT::tumor_supports

int vg::BREAKPOINT::frag1_supports

int vg::BREAKPOINT::split_supports

int vg::BREAKPOINT::other_supports

struct *#include <cactus.hpp>* **Public Members**

int64_t vg::CactusSide::node

bool vg::CactusSide::is_end

class *#include <genotypekit.hpp>* Class for finding all snarls using the base-level Cactus snarl decomposition interface. Inherits from *vg::SnarlFinder* **Public Functions**

vg::CactusSnarlFinder::CactusSnarlFinder (VG &graph)

Make a new *CactusSnarlFinder* to find snarls in the given graph. We can't filter trivial bubbles because that would break our chains.

Optionally takes a hint path name.

vg::CactusSnarlFinder::CactusSnarlFinder (VG &graph, const string &hint_path)

Make a new *CactusSnarlFinder* with a single hinted path to base the decomposition on.

SnarlManager vg::CactusSnarlFinder::find_snarls ()

Find all the snarls with Cactus, and put them into a *SnarlManager*.

Private Functions

const *Snarl* *vg::CactusSnarlFinder::recursively_emit_snarls (const *Visit* &start, const *Visit* &end, const *Visit* &parent_start, const *Visit* &parent_end, stList *chains_list, stList *unary_snarls_list, *SnarlManager* &destination)

Create a snarl in the given *SnarlManager* with the given start and end, containing the given child snarls in the list of chains of children and the given list of unary children. Recursively creates snarls in the *SnarlManager* for the children. Returns a pointer to the finished snarl in the *SnarlManager*. Start and end may be empty visits, in which case no snarl is created, all the child chains are added as root chains, and null is returned. If parent_start and parent_end are empty Visits, no parent() is added to the produced snarl.

Private Members

VG &vg::CactusSnarlFinder::graph

Holds the vg graph we are looking for sites in.

unordered_set<string> vg::CactusSnarlFinder::hint_paths

Holds the names of reference path hints.

struct *#include <snarls.hpp>* We want to be able to loop over a chain and get iterators to pairs of the snarl and its orientation in the chain. So we define some iterators. **Public Functions**

ChainIterator &vg::ChainIterator::operator++ ()

Advance the iterator.

pair<const *Snarl* *, bool> vg::ChainIterator::operator* () const

Get the snarl we're at and whether it is backward.

`const pair<const Snarl *, bool> *vg::ChainIterator::operator->() const`
Get a pointer to the thing we get when we dereference the iterator.

`bool vg::ChainIterator::operator==(const ChainIterator &other) const`
We need to define comparison because C++ doesn't give it to us for free.

`bool vg::ChainIterator::operator!=(const ChainIterator &other) const`

Public Members

`bool vg::ChainIterator::go_left`
Are we a reverse iterator or not?

`bool vg::ChainIterator::backward`
Is the snarl we are at backward or forward in its chain?

`Chain::const_iterator vg::ChainIterator::pos`
What position in the underlying vector are we in?

`Chain::const_iterator vg::ChainIterator::chain_start`
What are the bounds of that underlying vector?

`Chain::const_iterator vg::ChainIterator::chain_end`

`bool vg::ChainIterator::is_rend`
Since we're using backing random access iterators to provide reverse iterators, we need a flag to see if we are rend (i.e. before the beginning)

`bool vg::ChainIterator::complement`
When dereferencing, should we flip snarl orientations from the orientations they appear at in the chain when read left to right?

`pair<const Snarl *, bool> vg::ChainIterator::scratch`
In order to dereference to a pair with -> we need a place to put the pair so we can have a pointer to it. Gets lazily set to wherever the iterator is pointing when we do ->

`class #include <colors.hpp>Public Functions`

`vg::Colors::Colors (void)`

`vg::Colors::Colors (int seed_val)`

`vg::Colors::~~Colors (void)`

`string vg::Colors::hashed (const string &str)`

`string vg::Colors::random (void)`

Public Members

`const vector<string> vg::Colors::colors`

Private Members

mt19937 vg::Colors::rng

class *#include <option.hpp>* Represents a thing-doing class that has options. You construct the class, configure its options, and then set it going. Subclassed by *vg::SupportCaller* **Public Functions**

void vg::Configurable::register_option (OptionInterface *option)

Each option will call this on construction and register with its owner.

vector<OptionInterface*> vg::Configurable::get_options ()

Get all the options for this class. These pointers are only valid unless or until the underlying *Configurable* object moves or is assigned to.

string vg::Configurable::get_name ()

Get the name of the thing being configured, for titling the help section.

Private Members

vector<ptrdiff_t> vg::Configurable::option_offsets

We really should be using something like CRTP and pointer-to-members on the actual class that's configurable, but for now we'll just exploit int->pointer conversion and store the offset from us in memory to the location of the option in memory. If the option is correctly a member of a class derived from this one, it will work correctly because all instances share the same memory layout for members.

class *#include <option.hpp>* Actual implementation class that connects a bunch of *Configurable* things to getopt. TODO: right now every option must have a long option and a char short option. In theory we can use any int as an ID for a long option. We should support long options with untypeable or non-char option IDs. **Public Functions**

vg::ConfigurableParser::ConfigurableParser (const char *base_short_options
= nullptr, const struct option
*base_long_options = nullptr, func-
tion<void> int

> handle_base_option = [] (int c) {throw runtime_error("Invalid option: "+string(1,(char) c));}) *Constructor* that sets up our magic option assigning code. Makes a parser that will parse the given base Getopt null-terminated long and short options with Getopt and call the given function with each.

The base option handler, if specified, should error on unrecognized options.

void vg::ConfigurableParser::register_configurable (Configurable *configurable)

Register a *Configurable* thing and allocate characters for all its options. The *Configurable* is not allowed to move after registration.

void vg::ConfigurableParser::print_help (ostream &out) const

Print option descriptions for registered Configurables to the given stream.

void vg::ConfigurableParser::parse (int argc, char **argv)

Parse the options with getopt. Uses the existing value of the global optind, and updates the global optind, just as getopt would.

Private Members

vector<struct option> vg::ConfigurableParser::long_options

Holds all the long option structs for options we have.

```
set<int> vg::ConfigurableParser::available_short_options
```

Holds all the available short option characters that have not been assigned. Stored as ints so we can check ints against it safely.

```
string vg::ConfigurableParser::short_options
```

Holds the short options string (with colons) for the short options we have.

```
map<int, OptionInterface*> vg::ConfigurableParser::options_by_code
```

Keep a map from assigned character to actual option.

```
map<OptionInterface*, int> vg::ConfigurableParser::codes_by_option
```

And a reverse map for when we look up assigned codes for printing. TODO: No forgery!

```
set<string> vg::ConfigurableParser::long_options_used
```

And a set of long options used so we can detect collisions.

```
vector<Configurable*> vg::ConfigurableParser::configurables
```

And a vector of Configurables in the order registered so we can interrogate them and group their options when printing help.

```
function<void (int)> vg::ConfigurableParser::handle_base_option
```

Handle an option not assigned to an *Option* object.

class *#include <genotypekit.hpp>* Represents a strategy for computing consistency between Alignments and SnarlTraversals. Determines whether a read is consistent with a *SnarlTraversal* or not (but has access to all the *SnarlTraversals*). Polymorphic base class/interface. Subclassed by *vg::SimpleConsistencyCalculator* **Public Functions**

```
virtual vg::ConsistencyCalculator::~~ConsistencyCalculator()
```

```
virtual vector<bool> vg::ConsistencyCalculator::calculate_consistency(const
                                                                    Snarl
                                                                    &site,
                                                                    const
                                                                    vec-
                                                                    tor<SnarlTraversal>
                                                                    &traver-
                                                                    sals,
                                                                    const
                                                                    Align-
                                                                    ment
                                                                    &read)
                                                                    const
```

= 0 Return true or false for each traversal of the site, depending on if the read is consistent with it or not.

struct *#include <constructor.hpp>* Represents a constructed region of the graph along a single linear sequence. Contains the protobuf *Graph* holding all the created components (which may be too large to serialize), a set of node IDs whose left sides need to be connected to when you connect to the start of the chunk, and a set of node IDs whose right sides need to be connected to when you connect to the end of the chunk. *Node* ordering is restricted: if there is a single source, it must be the very first node in the graph with ID 1, and if there is a single sink it must be the very last node in the graph with ID max_id. Additionally, single sources and single sinks must be visited by only a single path, the reference path. The overall reference path must also always be path 0. Also, all mappings in all paths must be full-length matches on the forward strand, and they must be sorted by rank. Ranks must be filled and start with rank 1 in each path. **Public Members**

```
Graph vg::ConstructedChunk::graph
```

```
id_t vg::ConstructedChunk::max_id
```

```
set<id_t> vg::ConstructedChunk::left_ends
```

```
set<id_t> vg::ConstructedChunk::right_ends
```

class *#include <constructor.hpp>* Inherits from *vg::Progressive*, *vg::NameMapper* **Public Functions**

```
ConstructedChunk vg::Constructor::construct_chunk (string reference_sequence, string
                                                    reference_path_name,          vec-
                                                    tor<vcflib::Variant>          variants,
                                                    size_t chunk_offset) const
```

Construct a *ConstructedChunk* of graph from the given piece of sequence, with the given name, applying the given variants. The variants need to be sorted by start position, and have their start positions set to be ZERO- BASED. However, they also need to have their start positions relative to the global start of the contig, so that hash-based names come out right for them. They also need to not overlap with any variants not in the vector we have (i.e. we need access to all overlapping variants for this region). The variants must not extend beyond the given sequence, though they can abut its edges.

Variants in the vector may not use symbolic alleles.

chunk_offset gives the global 0-based position at which this chunk starts in the reference contig it is part of, which is used to correctly place variants.

```
void vg::Constructor::construct_graph (string vcf_contig, FastaReference &refer-
                                                    ence, VcfBuffer &variant_source, const
                                                    vector<FastaReference *> &insertion, func-
                                                    tion<void>) Graph&
```

> *callback* Construct a graph for the given VCF contig name, using the given reference and the variants from the given buffered VCF file. Emits a sequence of *Graph* chunks, which may be too big to serealize directly.

Doesn't handle any of the setup for VCF indexing. Just scans all the variants that can come out of the buffer, so make sure indexing is set on the file first before passing it in.

```
void vg::Constructor::construct_graph (const vector<FastaReference *> &references,
                                                    const vector<vcflib::VariantCallFile *> &vari-
                                                    ant_files, const vector<FastaReference *> &inser-
                                                    tions, function<void>) Graph&
```

> *callback* Construct a graph using the given FASTA references and VCFLib VCF files. The VCF files are assumed to be grouped by contig and then sorted by position within the contig, such that each contig is present in only one file. If multiple FASTAs are used, each contig must be present in only one FASTA file. Reference and VCF vectors may not contain nulls.

Public Members

```
bool vg::Constructor::flat
```

```
bool vg::Constructor::alt_paths
```

```
bool vg::Constructor::do_svs
```

```
bool vg::Constructor::alts_as_loci
```

```
bool vg::Constructor::greedy_pieces
```

```
bool vg::Constructor::chain_deletions
```

```
bool vg::Constructor::warn_on_lowercase

size_t vg::Constructor::max_node_size

size_t vg::Constructor::vars_per_chunk

size_t vg::Constructor::bases_per_chunk

set<string> vg::Constructor::allowed_vcf_names

map<string, pair<size_t, size_t>> vg::Constructor::allowed_vcf_regions
```

Protected Attributes

```
set<string> vg::Constructor::symbolic_allele_warnings
```

Remembers which unusable symbolic alleles we've already emitted a warning about during construction.

```
id_t vg::Constructor::max_id
```

All chunks are generated with IDs starting at 1, but graphs emitted from `construct_graph` need to have the IDs rewritten so they don't overlap. Moreover, multiple calls to `construct_graph` need to not have conflicting IDs, because some `construct_graph` implementations call other ones. What we do for now is globally track the max ID already used, so all calls to `construct_graph` follow a single ID ordering.

Private Members

```
unordered_set<string> vg::Constructor::warned_sequences
```

What sequences have we warned about containing lowercase characters?

Private Static Functions

```
void vg::Constructor::trim_to_variable (vector<list<vcflib::VariantAllele>>
                                       &parsed_alleles)

    Given a vector of lists of VariantAllele edits, trim in from the left and right, leaving a core of edits bounded by edits that actually change the reference in at least one allele.

    Postcondition: either all lists of VariantAlleles are empty, or at least one begins with a non-match and at least one ends with a non-match.

void vg::Constructor::condense_edits (list<vcflib::VariantAllele> &parsed_allele)

    Given a list of VariantAllele edits, condense adjacent perfect match edits to be maximally long.

pair<int64_t, int64_t> vg::Constructor::get_bounds (const                                vec-
                                                  tor<list<vcflib::VariantAllele>>
                                                  &trimmed_variant)

    Given a vector of lists of VariantAllele edits that have been trimmed with trim_to_variable() above, one per non-reference alt for a variant, return the position of the first variable base, and the position of the last variable base. If there's no variable-region, the result is max int64_t and -1, and if there's a 0-length variable region, the result is the base after it and the base before it.
```

```
struct #include <readfilter.hpp>Public Functions
```

```
vg::ReadFilter::Counts::Counts()

Counts &vg::ReadFilter::Counts::operator+= (const Counts &other)
```


Public Members

```
vector<size_t> vg::ReadFilter::Counts::read
vector<size_t> vg::ReadFilter::Counts::filtered
vector<size_t> vg::ReadFilter::Counts::min_score
vector<size_t> vg::ReadFilter::Counts::max_overhang
vector<size_t> vg::ReadFilter::Counts::min_end_matches
vector<size_t> vg::ReadFilter::Counts::min_mapq
vector<size_t> vg::ReadFilter::Counts::split
vector<size_t> vg::ReadFilter::Counts::repeat
vector<size_t> vg::ReadFilter::Counts::defray
struct Public Functions
```

```
bool custom_aln_sort_key::operator() (const Alignment a_one, const Alignment a_two)
struct Public Functions
```

```
bool custom_pos_sort_key::operator() (const Position lhs, const Position rhs)
class #include <deconstructor.hpp>Public Functions
```

```
vg::Deconstructor::Deconstructor()
vg::Deconstructor::~Deconstructor()

pair<bool, vector<string>> vg::Deconstructor::get_alleles (vector<SnarlTraversal> travs,
                                                         string refpath, vg::VG *graph)
    Takes in a vector of snarltraversals returns their sequences as a vector<string> returns a boolean hasRef
    if a reference path is present, hasRef is set to true and the first string in the vector is the reference allele
    otherwise, hasRef is set to false and all strings are alt alleles.

void vg::Deconstructor::deconstruct (string refpath, vg::VG *graph)
void vg::Deconstructor::deconstruct (vector<string> refpaths, vg::VG *graph)
    Convenience wrapper function for deconstruction of multiple paths.
```

Public Members

```
map<string, PathIndex*> vg::Deconstructor::pindexes
```

Private Members

```
bool vg::Deconstructor::headered
```

class *#include <banded_global_aligner.hpp>* Represents a deviation from the optimal traceback that a sub-optimal traceback takes. **Public Functions**

```
BandedGlobalAligner::AltTracebackStack::Deflection::Deflection(const
                                                                int64_t
                                                                from_node_id,
                                                                const
                                                                int64_t
                                                                row_idx,
                                                                const
                                                                int64_t
                                                                col_idx,
                                                                const
                                                                int64_t
                                                                to_node_id,
                                                                const
                                                                matrix_t
                                                                to_matrix)

BandedGlobalAligner::AltTracebackStack::Deflection::~Deflection()
```

Public Members

```
template<>
const int64_t vg::BandedGlobalAligner<IntType>::AltTracebackStack::Deflection::from_node_id
    Node ID where deflection occurs.
```

```
template<>
const int64_t vg::BandedGlobalAligner<IntType>::AltTracebackStack::Deflection::row_idx
    Coordinate from rectangularized band (not original matrix) where deflection occurs.
```

```
template<>
const int64_t vg::BandedGlobalAligner<IntType>::AltTracebackStack::Deflection::col_idx
    Coordinate from rectangularized band (not original matrix) where deflection occurs.
```

```
template<>
const int64_t vg::BandedGlobalAligner<IntType>::AltTracebackStack::Deflection::to_node_id
    Node to deflect to.
```

```
template<>
const matrix_t vg::BandedGlobalAligner<IntType>::AltTracebackStack::Deflection::to_matrix
    Dynamic programming matrix deflect to.
```

struct *#include <genome_state.hpp>* Inherits from *vg::GenomeStateCommand* **Public Functions**

```
GenomeStateCommand *vg::DeleteHaplotypeCommand::execute(GenomeState &state)
                                                                const
```

Execute this command on the given state and return the reverse command. Generally ends up calling a command-type-specific method on the *GenomeState* that does the actual work.

```
virtual vg::DeleteHaplotypeCommand::~DeleteHaplotypeCommand()
```

Public Members

`unordered_map<const Snarl *, vector<size_t>> vg::DeleteHaplotypeCommand::deletions`

For each snarl, delete the haplotype in each overall lane in the vector. You must specify out the deletions for all the snarls in a haplotype; we won't automatically go and find the children if you just list to delete from the parents. Deletions happen from begin to end through each vector. Lane numbers for a given snarl must be strictly decreasing.

class `#include <srpe.hpp>` Overview: Use the GAM/GAM index and a filter to locate Alignments which may indicate the presence of structural variants at a given site. Signatures include: Deletions/Insertions: Stacked soft clips (tips) Inversions: mismatched P/E reads (&& > rather than the expected (> <) Duplications: Read depth signals Translocations: Distant read pairs **Public Functions**

`vg::DepthMap::DepthMap (int64_t sz)`

`vg::DepthMap::DepthMap ()`

`vg::DepthMap::DepthMap (vg::VG *graph)`

`int8_t vg::DepthMap::get_depth (int64_t node_id, int64_t offset)`

`void vg::DepthMap::set_depth (int64_t node_id, int64_t offset, int8_t d)`

`void vg::DepthMap::increment_depth (int64_t node_id, int64_t offset)`

`void vg::DepthMap::fill_depth (const vg::Path &p)`

Public Members

`int8_t *vg::DepthMap::depths`

Map <node_id : offset : depth> or Map <*SnarlTraversal* : support count>

`uint64_t vg::DepthMap::size`

`map<int64_t, uint64_t> vg::DepthMap::node_pos`

`vg::VG *vg::DepthMap::g_graph`

struct `#include <cluster.hpp>` **Public Functions**

`vg::OrientedDistanceClusterer::DPSCScoreComparator::DPSCScoreComparator ()`

`vg::OrientedDistanceClusterer::DPSCScoreComparator::DPSCScoreComparator (const
vec-
tor<ODNode>
&nodes)`

`vg::OrientedDistanceClusterer::DPSCScoreComparator::~~DPSCScoreComparator ()`

`bool vg::OrientedDistanceClusterer::DPSCScoreComparator::operator () (const
size_t
i, const
size_t j)`

Private Members

const `vector<ODNode>` &vg::OrientedDistanceClusterer::DPScoreComparator::**nodes**
struct `Edges` describe linkages between nodes. They are bidirected, connecting the end (default) or start of the “from” node to the start (default) or end of the “to” node. **Public Members**

`int64` vg::Edge::**from**
 ID of upstream node.

`int64` vg::Edge::**to**
 ID of downstream node.

`bool` vg::Edge::**from_start**
 If the edge leaves from the 5’ (start) of a node.

`bool` vg::Edge::**to_end**
 If the edge goes to the 3’ (end) of a node.

`int32` vg::Edge::**overlap**
 Length of overlap between the connected *Nodes*.

struct Keep pileup-like record for reads that span edges. **Public Members**

Edge vg::EdgePileup::**edge**

`int32` vg::EdgePileup::**num_reads**
 total reads mapped

`int32` vg::EdgePileup::**num_forward_reads**
 number of reads mapped on forward strand

`bytes` vg::EdgePileup::**qualities**
struct Edits describe how to generate a new string from elements in the graph. To determine the new string, just walk the series of edits, stepping from_length distance in the basis node, and to_length in the novel element, replacing from_length in the basis node with the sequence. There are several types of *Edit*:
matches: from_length == to_length; sequence is empty *snps*: from_length == to_length; sequence = alt
deletions: to_length == 0 && from_length > to_length; sequence is empty *insertions*: from_length < to_length; sequence = alt

Public Members

`int32` vg::Edit::**from_length**
 Length in the target/ref sequence that is removed.

`int32` vg::Edit::**to_length**
 Length in read/alt of the sequence it is replaced with.

`string` vg::Edit::**sequence**
 The replacement sequence, if different from the original sequence.

struct `#include <pileup_augmenter.hpp>` **Public Functions**

vg::NodeDivider::Entry::Entry(*Node* *r = 0, `vector<StrandSupport>` sup_r = `vector<StrandSupport>()`, *Node* *a1 = 0, `vector<StrandSupport>` sup_a1 = `vector<StrandSupport>()`, *Node* *a2 = 0, `vector<StrandSupport>` sup_a2 = `vector<StrandSupport>()`)

```

Node *&vg::NodeDivider::Entry::operator[] (int i)
vector<StrandSupport> &vg::NodeDivider::Entry::sup (int i)

```

Public Members

```

Node *vg::NodeDivider::Entry::ref
Node *vg::NodeDivider::Entry::alt1
Node *vg::NodeDivider::Entry::alt2
vector<StrandSupport> vg::NodeDivider::Entry::sup_ref
vector<StrandSupport> vg::NodeDivider::Entry::sup_alt1
vector<StrandSupport> vg::NodeDivider::Entry::sup_alt2
class #include <multipath_mapper.hpp>Public Members

```

```

string::const_iterator vg::ExactMatchNode::begin
string::const_iterator vg::ExactMatchNode::end
Path vg::ExactMatchNode::path

```

```

vector<pair<size_t, size_t>> vg::ExactMatchNode::edges
class #include <genotypekit.hpp> Inherits from vg::TraversalFinder Public Functions

```

```

vg::ExhaustiveTraversalFinder::ExhaustiveTraversalFinder (VG          &graph,
                                                             SnarlManager
                                                             &snarl_manager,
                                                             bool          in-
                                                             clude_reversing_traversals
                                                             = false)

vg::ExhaustiveTraversalFinder::~~ExhaustiveTraversalFinder ()

vector<SnarlTraversal> vg::ExhaustiveTraversalFinder::find_traversals (const
                                                                    Snarl
                                                                    &site)

    Exhaustively enumerate all traversals through the site. Only valid for acyclic Snarls.

```

Private Functions

```

void vg::ExhaustiveTraversalFinder::stack_up_valid_walks (NodeTraversal
                                                         walk_head,          vec-
                                                         tor<NodeTraversal>
                                                         &stack)

void vg::ExhaustiveTraversalFinder::add_traversals (vector<SnarlTraversal>
                                                    &traversals,          Node-
                                                    Traversal          traversal_start,
                                                    set<NodeTraversal>
                                                    &stop_at, set<NodeTraversal>
                                                    &yield_at)

```

Private Members

`VG &vg::ExhaustiveTraversalFinder::graph`

`SnarlManager &vg::ExhaustiveTraversalFinder::snarl_manager`

`bool vg::ExhaustiveTraversalFinder::include_reversing_traversals`

struct `#include <feature_set.hpp>` Represents a *Feature* that occurs on a path between two inclusive coordinates. Carries along all the extra feature data that BED files store. **Public Members**

`string vg::FeatureSet::Feature::path_name`

What *Path* is the feature on?

`size_t vg::FeatureSet::Feature::first`

What is the first base's position on that path, inclusive?

`size_t vg::FeatureSet::Feature::last`

What is the last base's position on the path, inclusive?

`string vg::FeatureSet::Feature::feature_name`

What is the feature name?

`vector<string> vg::FeatureSet::Feature::extra_data`

What extra BED data should we bring along with this feature? TODO: BED blocks are not parsed and updated, but they should be.

class `#include <feature_set.hpp>` Stores a bunch of features defined on paths, as would be found in a BED file, and listens for messages describing edits to the paths that the features are on. *Edit* operations are of the form “On path X, range Y to Z has been replaced with a segment of length W”. Updates the positions and boundaries of features appropriately. Originally designed to allow BED files to be carried through “vg simplify”, but could be used for other annotation liftover tasks. **Public Functions**

`void vg::FeatureSet::load_bed(istream &in)`

Read features from the given BED stream. Adds them to the collection of loaded features.

`void vg::FeatureSet::save_bed(ostream &out) const`

Save features to the given BED stream.

`void vg::FeatureSet::on_path_edit(const string &path, size_t start, size_t old_length, size_t new_length)`

Notify the *FeatureSet* that, at the given path, from the given start position, the given number of bases have been replaced with the other given number of bases. Can handle pure inserts, pure deletions, length-preserving substitutions, and general length-changing substitutions.

Updates the contained features that need to change.

Note that this is currently O(n) in features on the path. TODO: come up with a truly efficient algorithm to back this using some kind of skip list or rope or something.

`const vector<FeatureSet::Feature> &vg::FeatureSet::get_features(const string &path) const`

Get the features on a path. Generally used for testing.

Private Members

`map<string, vector<Feature>> vg::FeatureSet::features`

Stores all the loaded features by path name.

class #include <filter.hpp>Public Functions

```
vg::Filter::Filter()
```

```
vg::Filter::~~Filter()
```

```
bool vg::Filter::perfect_filter(Alignment &aln)
```

```
bool vg::Filter::anchored_filter(Alignment &aln)
```

```
bool vg::Filter::mark_sv_alignments(Alignment &a, Alignment &b)
```

```
bool vg::Filter::mark_smallVariant_alignments(Alignment &a, Alignment &b)
```

```
Alignment vg::Filter::depth_filter(Alignment &aln)
```

```
Alignment vg::Filter::qual_filter(Alignment &aln)
```

Looks for Alignments that have large overhangs at the end of them.

Default behavior: if an alignment has a right- or left- clip that is longer than the maximum allowed, return an empty alignment.

Inverse Behavior: if the alignment has a clip that is larger than the maximum allowed at either end, return the alignment. CLI: `vg filter -d 10 -q 40 -r -R -r`: track depth of both novel variants and those in the graph. `-R`: remove edits that fail the filter (otherwise toss the whole alignment)

```
Alignment vg::Filter::coverage_filter(Alignment &aln)
```

```
Alignment vg::Filter::avg_qual_filter(Alignment &aln)
```

```
Alignment vg::Filter::percent_identity_filter(Alignment &aln)
```

Filter reads that are less than <PCTID> reference. I.E. if a read matches the reference along 80% of its length, and your cutoff is 90% PCTID, throw it out.

```
bool vg::Filter::soft_clip_filter(Alignment &aln)
```

```
bool vg::Filter::unmapped_filter(Alignment &aln)
```

```
bool vg::Filter::split_read_filter(Alignment &aln)
```

Split reads map to two separate paths in the graph OR vastly separated non-consecutive nodes in a single path.

They're super important for detecting structural variants, so we may want to filter them out or collect only split reads.

```
Alignment vg::Filter::path_divergence_filter(Alignment &aln)
```

Looks for alignments that transition from one path to another over their length. This may occur for one of several reasons:

1. The read covers a translocation
2. The read looks a lot like two different (but highly-similar paths)
3. The read is shattered (e.g. as in chromothripsis)

Default behavior: if the *Alignment* is path divergent, return an empty *Alignment*, else return *aln* Inverse behavior: if the *Alignment* is path divergent, return *aln*, else return an empty *Alignment*

```
Alignment vg::Filter::reversing_filter(Alignment &aln)
```

Looks for alignments that change direction over their length. This may happen because of:

1. *Mapping* artifacts
2. Cycles
3. Highly repetitive regions
4. Inversions (if you're lucky enough)

Default behavior: if the *Alignment* reverses, return an empty *Alignment*. inverse behavior: if the *Alignment* reverses, return the *Alignment*.

```
vector<Alignment> vg::Filter::remap (Alignment &aln)
```

```
vector<Alignment> vg::Filter::remap (string seq)
```

```
bool vg::Filter::is_left_clipped (Alignment &a)
```

```
pair<Alignment, int> vg::Filter::refactor_split_alignment (Alignment &a)
```

```
Alignment vg::Filter::path_length_filter (Alignment &aln)
```

```
bool vg::Filter::one_end_anchored_filter (Alignment &aln_first, Alignment  
                                         &aln_second)
```

```
bool vg::Filter::interchromosomal_filter (Alignment &aln_first, Alignment  
                                         &aln_second)
```

```
bool vg::Filter::insert_size_filter (Alignment &aln_first, Alignment &aln_second)
```

```
bool vg::Filter::pair_orientation_filter (Alignment &aln_first, Alignment  
                                         &aln_second)
```

```
pair<Alignment, Alignment> vg::Filter::deletion_filter (Alignment &aln_first, Alignment  
                                                       &aln_second)
```

```
pair<Locus, Locus> vg::Filter::insertion_filter (Alignment &aln_first, Alignment  
                                                &aln_second)
```

Filters insertion-characterizing reads based upon discordant pairs (fragment length too short) one-end anchored / softclipped portions and read depth, one day

```
pair<Locus, Locus> vg::Filter::duplication_filter (Alignment &aln_first, Alignment  
                                                  &aln_second)
```

Find reads that support duplications

```
bool vg::Filter::inversion_filter (Alignment &aln_first, Alignment &aln_second)
```

Find reads that support inversions split reads discordant insert size bad orientation instead of -> <- we'll see <- <- or -> ->

```
pair<Locus, Locus> vg::Filter::breakend_filter (Alignment &aln_first, Alignment  
                                                &aln_second)
```

split reads or discordant reads/insert size may indicate a breakend but not a clean SV type we'd like to report all possible breakends, even if that don't match an SV type very well.

```
void vg::Filter::set_min_depth (int depth)
```

```
void vg::Filter::set_min_qual (int qual)
```

```
void vg::Filter::set_min_percent_identity (double pct_id)
```

```
void vg::Filter::set_avg (bool do_avg)
```

```
void vg::Filter::set_filter_matches (bool fm)
```



```

void vg::Filter::set_remove_failing_edits (bool fm)
void vg::Filter::set_soft_clip_limit (int max_clip)
void vg::Filter::set_split_read_limit (int split_limit)
void vg::Filter::set_window_length (int window_length)
void vg::Filter::set_my_vg (vg::VG *vg)
void vg::Filter::set_my_xg_idx (xg::XG *xg_idx)
void vg::Filter::set_inverse (bool do_inv)
void vg::Filter::init_mapper ()
void vg::Filter::fill_node_to_position (string pathname)
int64_t vg::Filter::distance_between_positions (Position first, Position second)
string vg::Filter::get_clipped_seq (Alignment &a)
int64_t vg::Filter::get_clipped_ref_position (Alignment &a)
Position vg::Filter::get_clipped_position (Alignment &a)
Alignment vg::Filter::remove_clipped_portion (Alignment &a)

```

Public Members

```

vg::VG *vg::Filter::my_vg
xg::XG *vg::Filter::my_xg_index
gcsa::GCSA *vg::Filter::gcsa_ind
gcsa::LCPArray *vg::Filter::lcp_ind
Mapper *vg::Filter::my_mapper
map<int64_t, int64_t> vg::Filter::node_to_position
unordered_map<string, unordered_map<string, int>> vg::Filter::pos_to_edit_to_depth
unordered_map<int, int> vg::Filter::pos_to_qual
bool vg::Filter::inverse
bool vg::Filter::do_remap
bool vg::Filter::remove_failing_edits
bool vg::Filter::filter_matches
bool vg::Filter::use_avg
int vg::Filter::min_depth
int vg::Filter::min_qual

```

```
int vg::Filter::min_cov
int vg::Filter::window_length
int vg::Filter::qual_offset
int vg::Filter::soft_clip_limit
int vg::Filter::split_read_limit
double vg::Filter::min_percent_identity
double vg::Filter::min_avg_qual
int vg::Filter::max_path_length
int vg::Filter::my_max_distance
float vg::Filter::insert_mean
float vg::Filter::insert_sd
class #include <genotypekit.hpp> This genotype prior calculator has a fixed prior for homozygous genotypes
and a fixed prior for hets. Inherits from vg::GenotypePriorCalculator Public Functions
```

```
virtual vg::FixedGenotypePriorCalculator::~FixedGenotypePriorCalculator()
double vg::FixedGenotypePriorCalculator::calculate_log_prior(const Genotype
                                                             &genotype)
    Return the log prior of the given genotype.
    TODO: ploidy priors on nested sites???
```

Public Members

```
double vg::FixedGenotypePriorCalculator::homozygous_prior_ln
double vg::FixedGenotypePriorCalculator::heterozygous_prior_ln
class #include <flow_sort.hpp> Public Functions

vg::FlowSort::FlowSort(VG &vg)

std::unique_ptr<list<NodeTraversal>> vg::FlowSort::max_flow_sort(const string &ref_name,
                                                                bool isGrooming =
                                                                true)

void vg::FlowSort::fast_linear_sort(const string &ref_name, bool isGrooming = true)
void vg::FlowSort::flow_sort_nodes(list<NodeTraversal> &sorted_nodes, const string
                                &ref_name, bool isGrooming)
int vg::FlowSort::get_node_degree(WeightedGraph &wg, id_t node_id)
void vg::FlowSort::update_in_out_edges(EdgeMapping &edges_in, EdgeMapping
                                       &edges_out, Edge *e)
void vg::FlowSort::erase_in_out_edges(EdgeMapping &edges_in, EdgeMapping
                                       &edges_out, Edge *e)
```

```

void vg::FlowSort::reverse_edge (Edge *&e)

void vg::FlowSort::reverse_from_start_to_end_edge (Edge *&e)

id_t vg::FlowSort::from_simple_reverse (Edge *&e)

id_t vg::FlowSort::from_simple_reverse_orientation (Edge *&e)

id_t vg::FlowSort::to_simple_reverse (Edge *&e)

id_t vg::FlowSort::to_simple_reverse_orientation (Edge *&e)

vector<set<id_t>> vg::FlowSort::get_cc_in_wg (EdgeMapping &edges_in, EdgeMapping
&edges_out, const set<id_t> &all_nodes,
id_t start_ref_node)

void vg::FlowSort::groom_components (EdgeMapping &edges_in, EdgeMapping &edges_out,
set<id_t> &isolated_nodes, set<id_t> &main_nodes,
map<id_t, set<Edge *>> &minus_start, map<id_t,
set<Edge *>> &minus_end)

id_t vg::FlowSort::get_next_node_recalc_degrees (WeightedGraph &wg,
std::vector<std::set<id_t>> &de-
grees, std::set<id_t> &sources, id_t
node)

id_t vg::FlowSort::find_max_node (std::vector<std::set<id_t>> nodes_degree)

bool vg::FlowSort::bfs (set<id_t> &nodes, map<id_t, map<id_t, int>> &edge_weight, id_t s, id_t
t, map<id_t, id_t> &parent)

void vg::FlowSort::dfs (set<id_t> &nodes, id_t s, set<id_t> &visited, map<id_t, map<id_t, int>>
&edge_weight)

void vg::FlowSort::find_in_out_web (list<NodeTraversal> &sorted_nodes, Growth
&in_out_growth, WeightedGraph &weighted_graph,
set<id_t> &unsorted_nodes, id_t start_node, bool
in_out, int count)

void vg::FlowSort::process_in_out_growth (EdgeMapping &edges_out_nodes, id_t cur-
rent_id, Growth &in_out_growth, Weighted-
Graph &weighted_graph, set<id_t> &visited,
list<NodeTraversal> &sorted_nodes, bool
reverse, set<id_t> &unsorted_nodes, bool
in_out, int count)

void vg::FlowSort::mark_dfs (EdgeMapping &graph_matrix, id_t s, set<id_t> &new_nodes,
set<id_t> &visited, bool reverse, set<id_t> &nodes, set<id_t>
&backbone)

vector<pair<id_t, id_t>> vg::FlowSort::min_cut (map<id_t, map<id_t, int>> &graph_weight,
set<id_t> &nodes, id_t s, id_t t, EdgeMapping
&edges_out_nodes, set<Edge *> &in_joins)

void vg::FlowSort::remove_edge (EdgeMapping &nodes_to_edges, id_t node, id_t to, bool re-
verse)

```

Public Static Attributes

```
const size_t vg::FlowSort::DEFAULT_PATH_WEIGHT
```

Private Members

VG &vg::FlowSort::vg

class *#include <mapper.hpp>* **Public Functions**

vg::FragmentLengthDistribution::FragmentLengthDistribution (size_t *maximum_sample_size*,
size_t *reestimation_frequency*,
double *robust_estimation_fraction*)

Initialize distribution

Args: *maximum_sample_size* sample size at which reestimation stops *reestimation_frequency* update running estimate after this many samples *robust_estimation_fraction* robustly estimate using this fraction of samples

vg::FragmentLengthDistribution::FragmentLengthDistribution (void)

vg::FragmentLengthDistribution::~~FragmentLengthDistribution ()

void vg::FragmentLengthDistribution::force_parameters (double *mean*, double *std-dev*)

Instead of estimating anything, just use these parameters.

void vg::FragmentLengthDistribution::register_fragment_length (int64_t *length*)

Record an observed fragment length.

double vg::FragmentLengthDistribution::mean () **const**

Robust mean of the distribution observed so far.

double vg::FragmentLengthDistribution::stdev () **const**

Robust standard deviation of the distribution observed so far.

bool vg::FragmentLengthDistribution::is_finalized () **const**

Returns true if the maximum sample size has been reached, which finalizes the distribution estimate

size_t vg::FragmentLengthDistribution::max_sample_size () **const**

Returns the max sample size up to which the distribution will continue to reestimate parameters

size_t vg::FragmentLengthDistribution::curr_sample_size () **const**

Returns the number of samples that have been collected so far.

multiset<double>::const_iterator vg::FragmentLengthDistribution::measurements_begin () **const**

Begin iterator to the measurements that the distribution has used to estimate the parameters

multiset<double>::const_iterator vg::FragmentLengthDistribution::measurements_end () **const**

End iterator to the measurements that the distribution has used to estimate the parameters

Private Functions

void vg::FragmentLengthDistribution::estimate_distribution ()

Private Members

multiset<double> vg::FragmentLengthDistribution::lengths

bool vg::FragmentLengthDistribution::is_fixed

double vg::FragmentLengthDistribution::robust_estimation_fraction

size_t vg::FragmentLengthDistribution::maximum_sample_size

size_t vg::FragmentLengthDistribution::reestimation_frequency

double vg::FragmentLengthDistribution::mu

double vg::FragmentLengthDistribution::sigma

class *#include <mapper.hpp>* Keeps track of statistics about fragment length within the *Mapper* class. Belongs to a single thread. **Public Functions**

void vg::FragmentLengthStatistics::record_fragment_configuration (const
Alignment
&aln1,
const
Alignment
&aln2,
Mapper
*mapper)

string vg::FragmentLengthStatistics::fragment_model_str (void)

void vg::FragmentLengthStatistics::save_frag_lens_to_alns (*Alignment* &aln1,
Alignment &aln2,
const map<string,
int64_t> &ap-
prox_frag_lengths,
bool is_consistent)

double vg::FragmentLengthStatistics::fragment_length_stdev (void)

double vg::FragmentLengthStatistics::fragment_length_mean (void)

double vg::FragmentLengthStatistics::fragment_length_pdf (double length)

double vg::FragmentLengthStatistics::fragment_length_pval (double length)

bool vg::FragmentLengthStatistics::fragment_orientation (void)

bool vg::FragmentLengthStatistics::fragment_direction (void)

Public Members

double vg::FragmentLengthStatistics::cached_fragment_length_mean

double vg::FragmentLengthStatistics::cached_fragment_length_stdev

bool vg::FragmentLengthStatistics::cached_fragment_orientation_same

bool vg::FragmentLengthStatistics::cached_fragment_direction

```
int64_t vg::FragmentLengthStatistics::since_last_fragment_length_estimate
int64_t vg::FragmentLengthStatistics::fragment_model_update_interval
deque<double> vg::FragmentLengthStatistics::fragment_lengths
deque<bool> vg::FragmentLengthStatistics::fragment_orientations
deque<bool> vg::FragmentLengthStatistics::fragment_directions
int64_t vg::FragmentLengthStatistics::fragment_max
int64_t vg::FragmentLengthStatistics::fragment_size
double vg::FragmentLengthStatistics::fragment_sigma
int64_t vg::FragmentLengthStatistics::fragment_length_cache_size
float vg::FragmentLengthStatistics::perfect_pair_identity_threshold
bool vg::FragmentLengthStatistics::fixed_fragment_model
class #include <gamsorter.hpp> Public Functions
```

```
void GAMSorter::sort (vector<Alignment> &alns)
void GAMSorter::paired_sort (string gamfile)
void GAMSorter::write_temp (vector<Alignment> &alns)
void GAMSorter::stream_sort (string gamfile)
void GAMSorter::dumb_sort (string gamfile)
bool GAMSorter::min_aln_first (Alignment &a, Alignment &b)
Position GAMSorter::get_min_position (Alignment a)
Position GAMSorter::get_min_position (Path p)
void GAMSorter::write_index (string gamfile, string outfile, bool isSorted = false)
bool GAMSorter::equal_to (Position a, Position b)
bool GAMSorter::less_than (Position a, Position b)
bool GAMSorter::greater_than (Position a, Position b)
```

Private Members

```
map<int, int> vg::GAMSorter::split_to_split_size
vector<string> vg::GAMSorter::tmp_filenames
vector<ifstream*> vg::GAMSorter::tmp_files
int vg::GAMSorter::max_buf_size
```

`unordered_map<string, Alignment> vg::GAMSorter::pairs`

We want to keep pairs together, with the lowest-coordinate pair coming first. If one read is unmapped, it follows its partner in the sorted GAM file. Pairs with two unmapped reads are considered the highest-mapped in the graph, i.e. they come at the end of a sorted GAM file.

Since we can't hash alignments, we store both mates in the unordered map by name.

`unordered_map<string, pair<Alignment, Alignment>> vg::GAMSorter::paired_pairs`

class `#include <genome_state.hpp>` Define a way to represent a phased set of haplotypes on a graph that is under consideration as a variant calling solution. There should only be one of these for any genotyping run; operations all mutate the single copy and, if you don't like the result, can be rolled back by doing the reverse mutation. **Public Functions**

`void vg::GenomeState::dump() const`

Dump internal state to cerr.

`vg::GenomeState::GenomeState(const SnarlManager &manager, const HandleGraph *graph, const unordered_set<pair<const Snarl *, const Snarl *>> telomeres)`

Make a new *GenomeState* on the given *SnarlManager*, managing snarls in the given graph, with the given telomere pairs. Each telomere can appear in only one pair.

`const NetGraph *vg::GenomeState::get_net_graph(const Snarl *snarl)`

`DeleteHaplotypeCommand vg::GenomeState::append_haplotype(const AppendHaplotypeCommand &c)`

Create a haplotype and return a command to delete it.

`SwapHaplotypesCommand vg::GenomeState::swap_haplotypes(const SwapHaplotypesCommand &c)`

Swap two haplotypes and return a command to swap them back.

`ReplaceLocalHaplotypeCommand vg::GenomeState::replace_snarl_haplotype(const ReplaceSnarlHaplotypeCommand &c)`

Replace part(s) of some haplotype(s) with other material.

`DeleteHaplotypeCommand vg::GenomeState::insert_haplotype(const InsertHaplotypeCommand &c)`

Insert a haplotype and return a command to delete it.

`InsertHaplotypeCommand vg::GenomeState::delete_haplotype(const DeleteHaplotypeCommand &c)`

Delete a haplotype and return a command to insert it.

`ReplaceLocalHaplotypeCommand vg::GenomeState::replace_local_haplotype(const ReplaceLocalHaplotypeCommand &c)`

Replace part(s) of some haplotype(s) with other material.

```

GenomeStateCommand *vg::GenomeState::execute(GenomeStateCommand *command)
    Execute a command. Return a new heap-allocated command that undoes the command being executed.
    Frees the passed command. TODO: does that make sense?

size_t vg::GenomeState::count_haplotypes(const pair<const Snarl *, const Snarl *>
                                           &telomere_pair) const
    Count the number of haplotypes connecting the given pair of telomeres. It must be a pair of telomeres
    actually passed during construction.

size_t vg::GenomeState::count_haplotypes(const Snarl *snarl) const
    Count the number of haplotypes within a given snarl.

void vg::GenomeState::trace_haplotype(const pair<const Snarl *, const Snarl *>
                                       &telomere_pair, size_t overall_lane, const func-
                                       tion<void> const handle_t&
                                       > &iteratee) const
    Trace the haplotype starting at the given start telomere snarl with the given overall lane.
    Calls the callback with each backing HandleGraph handle.

```

Protected Functions

```
void vg::GenomeState::insert_handles(const vector<handle_t> &to_add, unordered_map<const Snarl *, vector<size_t>> &lanes_added, size_t top_lane = numeric_limits<size_t>::max())
```

We have a generic stack-based handle-vector-to-per-snarl-haplotypes insertion walker function. The handles to add have to span one or more entire snarls, and we specify the lane in the spanned snarls to put them in.

Protected Attributes

```
unordered_set<pair<const Snarl *, const Snarl *>> vg::GenomeState::telomeres
```

We keep track of pairs of telomere snarls. The haplotypes we work on connect a left telomere and its corresponding right telomere. We can traverse the snarl decomposition from one telomere to the other either following chains or following paths inside of some snarl we are in. The start snarl of a pair must be in its local forward orientation.

```
unordered_map<const Snarl *, NetGraph> vg::GenomeState::net_graphs
```

We precompute all the net graphs and keep them around.

```
unordered_map<const Snarl *, SnarlState> vg::GenomeState::state
```

We have a state for every snarl, which depends on the corresponding net graph.

```
const HandleGraph *vg::GenomeState::backing_graph
```

We remember the backing graph, because sometimes we need to translate from backing graph handles to IDs and orientations to look up snarls.

```
const SnarlManager &vg::GenomeState::manager
```

We keep a reference to the *SnarlManager* that knows what children are where and which snarl we should look at next after leaving a previous snarl.

struct *#include <genome_state.hpp>* Represents a modification of a *GenomeState*. We use a command pattern to enable undo-ability. Applying a command always returns a command that will undo what you did. Sub-classed by *vg::AppendHaplotypeCommand*, *vg::DeleteHaplotypeCommand*, *vg::InsertHaplotypeCommand*, *vg::ReplaceLocalHaplotypeCommand*, *vg::ReplaceSnarlHaplotypeCommand*, *vg::SwapHaplotypesCommand*

Public Functions

virtual *vg::GenomeStateCommand::~~GenomeStateCommand()*

virtual *GenomeStateCommand* **vg::GenomeStateCommand::execute (GenomeState &state)*

const
= 0Execute this command on the given state and return the reverse command. Generally ends up calling a command-type-specific method on the *GenomeState* that does the actual work.

struct Describes a genotype at a particular locus. **Public Members**

repeated<int32> *vg::Genotype::allele*

These refer to the offsets of the alleles in the *Locus* object.

bool *vg::Genotype::is_phased*

double *vg::Genotype::likelihood*

double *vg::Genotype::log_likelihood*

Likelihood natural logged.

double *vg::Genotype::log_prior*

Prior natural logged.

double *vg::Genotype::log_posterior*

Posterior natural logged (unnormalized).

class *#include <genotypekit.hpp>* Represents a strategy for calculating genotype likelihood for a (nested) Site. Polymorphic base class/interface. **Public Functions**

virtual *vg::GenotypeLikelihoodCalculator::~~GenotypeLikelihoodCalculator()*

```

virtual double vg::GenotypeLikelihoodCalculator::calculate_log_likelihood(const
    Snarl
    &site,
    const
    vec-
    tor<SnarlTraversal>
    &traver-
    sals,
    const
    Geno-
    type
    &geno-
    type,
    const
    vec-
    tor<vector<bool>>
    &con-
    sis-
    ten-
    cies,
    const
    vec-
    tor<Support>
    &sup-
    ports,
    const
    vec-
    tor<Alignment
    *>
    &reads)

```

= 0 Return the log likelihood of the given genotype.

class *#include <genotypekit.hpp>* Represents a strategy for assigning genotype priors. Polymorphic base class/interface. Subclassed by *vg::FixedGenotypePriorCalculator* **Public Functions**

```

virtual vg::GenotypePriorCalculator::~~GenotypePriorCalculator()

```

```

virtual double vg::GenotypePriorCalculator::calculate_log_prior(const Genotype
    &genotype)

```

= 0 Return the log prior of the given genotype.

TODO: ploidy priors on nested sites???

class *#include <genotyper.hpp>* Class to hold on to genotyping parameters and genotyping functions. **Public Functions**

```

void vg::Genotyper::run(AugmentedGraph &graph, vector<Alignment> &alignments, ostream
    &out, string ref_path_name, string contig_name = "", string sam-
    ple_name = "", string augmented_file_name = "", bool subset_graph =
    false, bool show_progress = false, bool output_vcf = false, bool out-
    put_json = false, int length_override = 0, int variant_offset = 0)

```

```

int vg::Genotyper::alignment_qual_score(VG &graph, const Snarl *snarl, const Align-
    ment &alignment)

```

Given an *Alignment* and a *Snarl*, compute a phred score for the quality of the alignment's bases within the snarl overall (not counting the start and end nodes), which is supposed to be interpretable as the probability

that the call of the sequence is wrong (to the degree that it would no longer support the alleles it appears to support).

In practice we're just going to average the quality scores for all the bases interior to the snarl (i.e. not counting the start and end nodes).

If the alignment doesn't have base qualities, or no qualities are available for bases internal to the snarl, returns a default value.

```
list<Mapping> vg::Genotyper::get_traversal_of_snarl (VG &graph, const Snarl *snarl,
                                                    const SnarlManager &manager,
                                                    const Path &path)
```

Given a path (which may run either direction through a snarl, or not touch the ends at all), collect a list of NodeTraversals in order for the part of the path that is inside the snarl, in the same orientation as the path.

```
string vg::Genotyper::traversals_to_string (VG &graph, const list<Mapping> &path)
```

Make a list of NodeTraversals into the string they represent.

```
vector<list<Mapping>> vg::Genotyper::get_paths_through_snarl (VG &graph, const
                                                            Snarl *snarl,
                                                            const SnarlManager &manager,
                                                            const map<string,
                                                            Alignment *>
                                                            &reads_by_name)
```

For the given snarl, emit all subpaths with unique sequences that run from start to end, out of the paths in the graph. Uses the map of reads by name to determine if a path is a read or a real named path. *Paths* through the snarl supported only by reads are subject to a min recurrence count, while those supported by actual embedded named paths are not.

```
string vg::Genotyper::get_qualities_in_snarl (VG &graph, const Snarl *snarl, const
                                             Alignment &alignment)
```

Get all the quality values in the alignment between the start and end nodes of a snarl. Handles alignments that enter the snarl from the end, and alignments that never make it through the snarl.

If we run out of qualities, or qualities aren't present, returns no qualities.

If an alignment goes through the snarl multiple times, we get all the qualities from when it is in the snarl.

Does not return qualities on the start and end nodes. May return an empty string.

```
map<Alignment *, vector<Genotyper::Affinity>> vg::Genotyper::get_affinities (VG
                                                                    &graph,
                                                                    const
                                                                    map<string,
                                                                    Align-
                                                                    ment
                                                                    *>
                                                                    &reads_by_name,
                                                                    const
                                                                    Snarl
                                                                    *snarl,
                                                                    const
                                                                    Snarl-
                                                                    Manager
                                                                    &man-
                                                                    ager,
                                                                    const vec-
                                                                    tor<list<Mapping>>
                                                                    &super-
                                                                    bub-
                                                                    ble_paths)
```

Get the affinity of all the reads relevant to the superbubble to all the paths through the superbubble.

Affinity is a double out of 1.0. Higher is better.

```
map<Alignment *, vector<Genotyper::Affinity>> vg::Genotyper::get_affinities_fast (VG
                                                                    &graph,
                                                                    const
                                                                    map<string,
                                                                    Align-
                                                                    ment
                                                                    *>
                                                                    &reads_by_name,
                                                                    const
                                                                    Snarl
                                                                    *snarl,
                                                                    const
                                                                    Snarl-
                                                                    Man-
                                                                    ager
                                                                    &man-
                                                                    ager,
                                                                    const
                                                                    vec-
                                                                    tor<list<Mapping>>
                                                                    &su-
                                                                    per-
                                                                    bub-
                                                                    ble_paths,
                                                                    bool
                                                                    al-
                                                                    low_internal_alignments
                                                                    =
                                                                    false)
```

Get affinities as above but using only string comparison instead of alignment. Affinities are 0 for mismatch and 1 for a perfect match.

```
Locus vg::Genotyper::genotype_snarl(VG &graph, const Snarl *snarl, const vector<list<Mapping>> &superbubble_paths, const map<Alignment *, vector<Affinity>> &affinities)
```

Compute annotated genotype from affinities and superbubble paths. Needs access to the graph so it can chop up the alignments, which requires node sizes.

```
double vg::Genotyper::get_genotype_log_likelihood(VG &graph, const Snarl *snarl, const vector<int> &genotype, const vector<pair<Alignment *, vector<Affinity>>> &alignment_consistency)
```

Compute the probability of the observed alignments given the genotype.

Takes a genotype as a vector of allele numbers, and support data as a collection of pairs of Alignments and vectors of bools marking whether each alignment is consistent with each allele.

Alignments should have had their quality values trimmed down to just the part covering the superbubble.

Returns a natural log likelihood.

```
double vg::Genotyper::get_genotype_log_prior(const vector<int> &genotype)
```

Compute the prior probability of the given genotype.

Takes a genotype as a vector of allele numbers. It is not guaranteed that allele 0 corresponds to any notion of primary reference-ness.

Returns a natural log prior probability.

TODO: add in strand bias

```
vector<vcflib::Variant> vg::Genotyper::locus_to_variant(VG &graph, const Snarl *snarl, const SnarlManager &manager, const PathIndex &index, vcflib::VariantCallFile &vcf, const Locus &locus, const string &sample_name = "SAMPLE")
```

Make a VCFLib variant from a called *Locus*. Depends on an index of the reference path we want to call against.

Returns 0 or more variants we can articulate from the superbubble. Sometimes if we can't make a variant for the superbubble against the reference path, we'll emit 0 variants.

```
void vg::Genotyper::write_vcf_header(std::ostream &stream, const std::string &sample_name, const std::string &contig_name, size_t contig_size)
```

Make a VCF header

```
vcflib::VariantCallFile *vg::Genotyper::start_vcf(std::ostream &stream, const PathIndex &index, const string &sample_name, const string &contig_name, size_t contig_size)
```

Start VCF output to a stream. Returns a VCFLib VariantCallFile that needs to be deleted.

```

pair<pair<int64_t, int64_t>, bool> vg::Genotyper::get_snarl_reference_bounds (const
                                                                    Snarl
                                                                    *snarl,
                                                                    const
                                                                    PathIn-
                                                                    dex
                                                                    &in-
                                                                    dex,
                                                                    const
                                                                    Han-
                                                                    dle-
                                                                    Graph
                                                                    *graph)

```

Utility function for getting the reference bounds (start and past-end) of a snarl with relation to a given reference index in the given graph. Computes bounds of the variable region, not including the fixed start and end node lengths. Also returns whether the reference path goes through the snarl forwards (false) or backwards (true).

```

void vg::Genotyper::report_snarl (const Snarl *snarl, const SnarlManager &manager, const
                                                                    PathIndex *index, VG &graph)

```

Tell the statistics tracking code that a snarl exists. We can do things like count up the snarl length in the reference and so on. Called only once per snarl, but may be called on multiple threads simultaneously.

```

void vg::Genotyper::report_snarl_traversal (const Snarl *snarl, const SnarlManager
                                                                    &manager, const string &read_name, VG
                                                                    &graph)

```

Tell the statistics tracking code that a read traverses a snarl completely. May be called multiple times for a given read and snarl, and may be called in parallel.

```

void vg::Genotyper::print_statistics (ostream &out)

```

Print snarl statistics to the given stream.

```

void vg::Genotyper::edge_allele_labels (const VG &graph, const Snarl *snarl, const
                                                                    vector<list<NodeTraversal>> &superbub-
                                                                    ble_paths, unordered_map<pair<NodeTraversal,
                                                                    NodeTraversal>,
                                                                    unordered_set<size_t>,
                                                                    hash_oriented_edge> *out_edge_allele_sets)

```

```

void vg::Genotyper::allele_ambiguity_log_probs (const VG &graph, const
                                                                    Snarl *snarl, const vec-
                                                                    tor<list<NodeTraversal>> &su-
                                                                    perbubble_paths, const un-
                                                                    ordered_map<pair<NodeTraversal,
                                                                    NodeTraversal>,
                                                                    un-
                                                                    ordered_set<size_t>,
                                                                    hash_oriented_edge>
                                                                    &edge_allele_sets, vec-
                                                                    tor<unordered_map<vector<size_t>,
                                                                    double,
                                                                    hash_ambiguous_allele_set>>
                                                                    *out_allele_ambiguity_probs)

```

Public Members

```

size_t vg::Genotyper::max_path_search_steps

```

```

int vg::Genotyper::unfold_max_length
int vg::Genotyper::dagify_steps
double vg::Genotyper::max_het_bias
bool vg::Genotyper::use_mapq
bool vg::Genotyper::realign_indels
int vg::Genotyper::default_sequence_quality
int vg::Genotyper::min_recurrence
int vg::Genotyper::min_consistent_per_strand
double vg::Genotyper::min_score_per_base
double vg::Genotyper::diploid_prior_logprob
double vg::Genotyper::het_prior_logprob
double vg::Genotyper::haploid_prior_logprob
double vg::Genotyper::deleted_prior_logprob
double vg::Genotyper::polyploid_prior_success_logprob
Translator vg::Genotyper::translator
unordered_map<size_t, size_t> vg::Genotyper::snarl_reference_length_histogram
unordered_map<const Snarl *, set<string>> vg::Genotyper::snarl_traversals
unordered_set<const Snarl *> vg::Genotyper::all_snarls
Aligner vg::Genotyper::normal_aligner
QualAdjAligner vg::Genotyper::quality_aligner

```

Public Static Functions

```

bool vg::Genotyper::mapping_enters_side(const Mapping &mapping, const handle_t
                                         &side, const HandleGraph *graph)

```

Check if a mapping corresponds to the beginning or end of snarl by making sure it crosses the given side in the expected direction. The handle should be forward for the left side and reverse for the right side.

```

bool vg::Genotyper::mapping_exits_side(const Mapping &mapping, const handle_t &side,
                                         const HandleGraph *graph)

```

struct *Graphs* are collections of nodes and edges. They can represent subgraphs of larger graphs or be wholly-self-sufficient. Protobuf memory limits of 67108864 bytes mean we typically keep the size of them small generating graphs as collections of smaller subgraphs. **Public Members**

```

repeated<Node> vg::Graph::node
    The Nodes that make up the graph.

```

```

repeated<Edge> vg::Graph::edge
    The Edges that connect the Nodes in the graph.

```

repeated<*Path*> vg::Graph::path

A set of named *Paths* that visit sequences of oriented *Nodes*.

class *#include <graph_synchronizer.hpp>* Let threads get exclusive locks on subgraphs of a vg graph, for reading and editing. When a subgraph is locked, a copy is accessible through the lock object and the underlying graph can be edited (through the lock) without affecting any other locked subgraphs. A thread may only hold a lock on a single subgraph at a time. Trying to lock another subgraph while you already have a subgraph locked is likely to result in a deadlock. **Public Functions**

vg::GraphSynchronizer::GraphSynchronizer (*VG* &graph)

Create a *GraphSynchronizer* for synchronizing on parts of the given graph.

const string &vg::GraphSynchronizer::get_path_sequence (const string &path_name)

Since internally we keep *PathIndexes* for paths in the graph, we expose this method for getting the strings for paths.

void vg::GraphSynchronizer::with_path_index (const string &path_name, const function<void> const *PathIndex*&

> &to_run We can actually let users run whatever function they want with an exclusive handle on a *PathIndex*, with the guarantee that the graph won't change while they're working.

Protected Functions

PathIndex &vg::GraphSynchronizer::get_path_index (const string &path_name)

Get the index for the given path name. *Lock* on the indexes and graph must be held already.

void vg::GraphSynchronizer::update_path_indexes (const vector<*Translation*> &translations)

Update all the path indexes according to the given translations. *Lock* on the indexes and graph must be held already.

Protected Attributes

VG &vg::GraphSynchronizer::graph

The graph we manage.

mutex vg::GraphSynchronizer::whole_graph_lock

We use this to lock the whole graph, for when we're exploring and trying to lock a context, or for when we're making an edit, or for when we're trying to lock a context, or for when we're working with the *PathIndexes*. It's only ever held during functions in this class or internal classes (monitor-style), so we don't need it to be a recursive mutex.

condition_variable vg::GraphSynchronizer::wait_for_region

We have one condition variable where we have blocked all the threads that are waiting to lock subgraphs but couldn't the first time because we ran into already locked nodes. When nodes get unlocked, we wake them all up, and they each grab the mutex and check, one at a time, to see if they can have all their nodes this time.

map<string, *PathIndex*> vg::GraphSynchronizer::indexes

We need indexes of all the paths that someone might want to use as a basis for locking. This holds a *PathIndex* for each path we touch by path name.

set<*id_t*> vg::GraphSynchronizer::locked_nodes

This holds all the node IDs that are currently locked by someone.

struct *#include <flow_sort.hpp>* **Public Functions**

```
vg::FlowSort::Growth::Growth()
```

Public Members

```
set<id_t> vg::FlowSort::Growth::nodes
```

```
set<id_t> vg::FlowSort::Growth::backbone
```

```
list<id_t> vg::FlowSort::Growth::ref_path
```

struct #include <handle.hpp> A handle is 8 (assuming `id_t` is still `int64_t`) opaque bytes. A handle refers to an oriented node. Two handles are equal iff they refer to the same orientation of the same node in the same graph. Handles have no ordering, but can be hashed. **Public Members**

```
char vg::handle_t::data[sizeof(id_t)]
```

class `#include <handle.hpp>` This is the interface that a graph that uses handles needs to support. It is also the interface that users should code against. Subclassed by `vg::MutableHandleGraph`, `vg::NetGraph`, `xg::XG`

Public Functions

```
virtual handle_t vg::HandleGraph::get_handle(const id_t &node_id, bool is_reverse = false)  
    const  
    = OLook up the handle for the node with the given ID in the given orientation.
```

```
virtual id_t vg::HandleGraph::get_id(const handle_t &handle) const
    = 0
```

Get the ID from a handle.

```
virtual bool vg::HandleGraph::get_is_reverse (const handle_t &handle) const
    = 0Get the orientation of a handle.
```

```
virtual handle_t vg::HandleGraph::flip(const handle_t &handle) const
= 0; Invert the orientation of a handle (potentially without getting its ID)
```

```
virtual size_t vg::HandleGraph::get_length(const handle_t &handle) const
= 0; // Get the length of a node.
```

```
virtual string vg : : HandleGraph : : get_sequence (const handle_t &handle) const
= 0; Get the sequence of a node, presented in the handle's local forward orientation.
```

```
virtual bool vg::HandleGraph::follow_edges(const handle_t &handle, bool go_left, const
                                         function<bool> const handle_t&
                                         > &iteratee) const = 0
```

Loop over all the handles to next/previous (right/left) nodes. Passes them to a callback which returns false to stop iterating and true to continue. Returns true if we finished and false if we stopped early.

```
virtual void vg::HandleGraph::for_each_handle(const function<bool> const handle_t&
    > &iteratee const = 0) Loop over all the nodes in the graph in their local forward orientations, in their
    internal stored order. Stop if the iteratee returns false.
```

```
virtual size_t vg::HandleGraph::node_size() const
    = 0Return the number of nodes in the graph TODO: can't be node_count because XG has a field named
    node_count.
```

template <typename T>

`auto vg::HandleGraph::follow_edges (const handle_t &handle, bool go_left, T &&iteratee)`

const
Loop over all the handles to next/previous (right/left) nodes. Works with a callback that just takes all the handles and returns void. MUST be pulled into implementing classes with `using` in order to work!

template <typename T>

`auto vg::HandleGraph::for_each_handle (T &&iteratee) const`

Loop over all the nodes in the graph in their local forward orientations, in their internal stored order. Works with void-returning iteratees. MUST be pulled into implementing classes with `using` in order to work!

`handle_t vg::HandleGraph::get_handle (const Visit &visit) const`

Get a handle from a *Visit* Protobuf object. Must be using'd to avoid shadowing.

`Visit vg::HandleGraph::to_visit (const handle_t &handle) const`

Get a Protobuf *Visit* from a handle.

`handle_t vg::HandleGraph::forward (const handle_t &handle) const`

Get the locally forward version of a handle.

`pair<handle_t, handle_t> vg::HandleGraph::edge_handle (const handle_t &left, const handle_t &right) const`

class `#include <phased_genome.hpp>` Specialized linked list that tracks a walk through the variation graph and maintains an index of sites. **Public Functions**

`vg::PhasedGenome::Haplotype::Haplotype (NodeTraversal node_traversal)`

Construct a haplotype with a single node.

template <typename NodeTraversalIterator>

`vg::PhasedGenome::Haplotype::Haplotype (NodeTraversalIterator first, NodeTraversalIterator last)`

Construct a haplotype with an iterator that yields NodeTraversals.

`vg::PhasedGenome::Haplotype::~~Haplotype ()`

`PhasedGenome::HaplotypeNode *vg::PhasedGenome::Haplotype::append_left (NodeTraversal node_traversal)`

Add a haplotype node for this node traversal to left end of haplotype and return new node. Does not maintain indices; intended for use by the *PhasedGenome* for initial haplotype build.

`PhasedGenome::HaplotypeNode *vg::PhasedGenome::Haplotype::append_right (NodeTraversal node_traversal)`

Add a haplotype node for this node traversal to right end of haplotype and return new node. Does not maintain indices; intended for use by the *PhasedGenome* for initial haplotype build.

Private Members

`PhasedGenome::HaplotypeNode *vg::PhasedGenome::Haplotype::left_telomere_node`

Leftmost node in walk.

`PhasedGenome::HaplotypeNode *vg::PhasedGenome::Haplotype::right_telomere_node`

Rightmost node in walk.

`unordered_map<const Snarl *, pair<HaplotypeNode *, HaplotypeNode *>> vg::PhasedGenome::Haplotype::sites`

Index of the location in the haplotype of nested sites. Locations of sites are stored as the nodes on haplotype that correspond to the start and end node of the site. The pair of haplotype nodes is stored in left-to-right order along the haplotype (i.e. .first->prev and .second->next are outside the bubble).

Friends

friend `vg::PhasedGenome::Haplotype::PhasedGenome`

friend `vg::PhasedGenome::Haplotype::HaplotypeNode`

struct `#include <phased_genome.hpp>` A node in walk through the graph taken by a haplotype. **Public Functions**

`vg::PhasedGenome::HaplotypeNode::HaplotypeNode` (*NodeTraversal* *node_traversal*,
HaplotypeNode **next*, *HaplotypeNode* **prev*)

Constructor.

`vg::PhasedGenome::HaplotypeNode::~~HaplotypeNode()`
Destructor.

Public Members

NodeTraversal `vg::PhasedGenome::HaplotypeNode::node_traversal`
Node and strand.

HaplotypeNode `*vg::PhasedGenome::HaplotypeNode::next`
Next node in walk.

HaplotypeNode `*vg::PhasedGenome::HaplotypeNode::prev`
Previous node in walk.

template `<>`
struct

class `std::hash<const vg::Snarl>`
`#include <snarls.hpp>` hash function for Snarls

Public Functions

`size_t std::hash::operator()` (`const vg::Snarl &snarl`) `const`
template `<typename A, typename B>`
struct
class `std::hash<pair<A, B>>`
`#include <hash_map_set.hpp>`

Public Functions

`size_t std::hash::operator()` (`const pair<A, B> &x`) `const`
`size_t std::hash::operator()` (`const pair<A, B> &x`) `const`
template `<typename... TT>`
struct
class `std::hash<std::tuple<TT...>>`
`#include <hash_map.hpp>`

Public Functions

```
size_t std::hash::operator() (std::tuple<TT...> const &tt) const
template <>
struct
class std::hash<vg::handle_t>
#include <handle.hpp> Define hashes for handles.
```

Public Functions

```
size_t std::hash::operator() (const vg::handle_t &handle) const
template <>
struct
class std::hash<vg::NodeSide>
#include <nodeside.hpp> Hash functor to hash NodeSides. We need to implement a hash function for these
if we want to be able to use them in keys in hash maps.
```

Public Functions

```
size_t std::hash::operator() (const vg::NodeSide &item) const
Produce a hash of a NodeSide.
template <>
struct
class std::hash<vg::NodeTraversal>
#include <nodetraversal.hpp> hash function for NodeTraversals
```

Public Functions

```
size_t std::hash::operator() (const vg::NodeTraversal &trav) const
struct #include <genotyper.hpp>Public Functions

size_t vg::Genotyper::hash_ambiguous_allele_set::operator() (const      vec-
                                                                tor<size_t> &am-
                                                                biguous_set)
                                                                const
template <typename K, typename V>
class #include <hash_map.hpp> Inherits from google::dense_hash_map< K, V >
```

Public Functions

```
vg::hash_map::hash_map()
template <typename K, typename V>
class #include <hash_map_set.hpp> Inherits from google::sparse_hash_map< K, V >
```

Public Functions

```
xg::hash_map::hash_map()
```

```

template <typename K, typename V>
    class
class vg::hash_map<K *, V>
    #include <hash_map.hpp> Inherits from google::dense_hash_map< K *, V >

```

Public Functions

```

vg::hash_map::hash_map()
template <typename K, typename V>
    class
class xg::hash_map<K *, V>
    #include <hash_map_set.hpp> Inherits from google::sparse_hash_map< K *, V >

```

Public Functions

```

xg::hash_map::hash_map()
struct #include <genotyper.hpp>Public Functions

size_t vg::Genotyper::hash_node_traversal::operator() (const NodeTraversal
&node_traversal) const
struct #include <genotyper.hpp>Public Functions

size_t vg::Genotyper::hash_oriented_edge::operator() (const pair<const NodeTraver-
sal, const NodeTraversal>
&edge) const
template <typename K>
class #include <hash_map_set.hpp> Inherits from google::sparse_hash_set< K >

```

Public Functions

```

xg::hash_set::hash_set()
template <typename K>
    class
class xg::hash_set<K *>
    #include <hash_map_set.hpp> Inherits from google::sparse_hash_set< K * >

```

Public Functions

```

xg::hash_set::hash_set()
class #include <homogenizer.hpp>Public Functions

void Homogenizer::homogenize (vg::VG *graph, xg::XG *xindex, gcsa::GCSA *gcsa_index,
                             gcsa::LCPArray *lcp_index, Paths p, int kmer_size)
    Locates tips in the graph and tries to generate a single edge / node to represent them. This edge is then
    added, the offending sequences are remapped, and the process is repeated until the graph becomes stable.

void Homogenizer::homogenize (vg::VG *graph, xg::XG *xindex, gcsa::GCSA *gcsa_index,
                             gcsa::LCPArray *lcp_index, vg::Index reads_index)

```

Private Functions

`vector<vg::id_t> Homogenizer::find_tips (vg::VG *graph)`
Find tips (nodes with an indegree/outdegree of 0 in the graph)

`vector<vg::id_t> Homogenizer::find_non_ref_tips (vg::VG *graph)`
Find non-ref tips

`int vg::Homogenizer::remap (vector<Alignment> reads, vg::VG graph)`
remap a set of Alignments to the graph

`void Homogenizer::cut_tips (vg::VG *graph)`
Remove all tips from the graph. WARNING: may cut head/tail nodes.

`void Homogenizer::cut_tips (vector<id_t> tip_ids, vg::VG *graph)`
Remove specific nodes and their edges from the graph

`void Homogenizer::cut_nonref_tips (vg::VG *graph)`
Remove non-reference tips from the graph.

Private Members

Translator `vg::Homogenizer::translator`
struct `#include <utility.hpp>` **Public Functions**

`vg::IncrementIter::IncrementIter (size_t number)`

IncrementIter `&vg::IncrementIter::operator= (const IncrementIter &other)`

`bool vg::IncrementIter::operator== (const IncrementIter &other) const`

`bool vg::IncrementIter::operator!= (const IncrementIter &other) const`

IncrementIter `vg::IncrementIter::operator++ ()`

IncrementIter `vg::IncrementIter::operator++ (int)`

`size_t vg::IncrementIter::operator* ()`

Private Members

`size_t vg::IncrementIter::current`
class `#include <index.hpp>` **Public Functions**

`vg::Index::Index (void)`

`vg::Index::Index (string &name)`

`vg::Index::~~Index (void)`

`rocksdb::Options vg::Index::GetOptions (bool read_only)`

`void vg::Index::open (const std::string &dir, bool read_only = false)`

```

void vg::Index::open_read_only (string &dir)

void vg::Index::open_for_write (string &dir)

void vg::Index::open_for_bulk_load (string &dir)

void vg::Index::reset_options (void)

void vg::Index::flush (void)

void vg::Index::compact (void)

void vg::Index::close (void)

void vg::Index::load_graph (VG &graph)

void vg::Index::dump (std::ostream &out)

void vg::Index::for_all (std::function<void> string&, string&
    > lambda)

void vg::Index::for_range (string &key_start, string &key_end, std::function<void> string&,
    string&
    > lambda)

void vg::Index::put_node (const Node *node)

void vg::Index::put_edge (const Edge *edge)

void vg::Index::batch_node (const Node *node, rocksdb::WriteBatch &batch)

void vg::Index::batch_edge (const Edge *edge, rocksdb::WriteBatch &batch)

void vg::Index::put_kmer (const string &kmer, const int64_t id, const int32_t pos)

void vg::Index::batch_kmer (const string &kmer, const int64_t id, const int32_t pos,
    rocksdb::WriteBatch &batch)

void vg::Index::put_metadata (const string &tag, const string &data)

void vg::Index::put_node_path (int64_t node_id, int64_t path_id, int64_t path_pos, bool back-
    ward, const Mapping &mapping)

void vg::Index::put_path_position (int64_t path_id, int64_t path_pos, bool backward, int64_t
    node_id, const Mapping &mapping)

void vg::Index::put_mapping (const Mapping &mapping)

void vg::Index::put_alignment (const Alignment &alignment)

void vg::Index::put_base (int64_t aln_id, const Alignment &alignment)

void vg::Index::put_traversal (int64_t aln_id, const Mapping &mapping)

void vg::Index::cross_alignment (int64_t aln_id, const Alignment &alignment)

rocksdb::Status vg::Index::get_node (int64_t id, Node &node)

rocksdb::Status vg::Index::get_edge (int64_t from, bool from_start, int64_t to, bool to_end, Edge
    &edge)

rocksdb::Status vg::Index::get_metadata (const string &key, string &data)

```

```
int vg::Index::get_node_path(int64_t node_id, int64_t path_id, int64_t &path_pos, bool
                             &backward, Mapping &mapping)

void vg::Index::get_mappings(int64_t node_id, vector<Mapping> &mappings)

void vg::Index::get_alignments(int64_t node_id, vector<Alignment> &alignments)

void vg::Index::get_alignments(int64_t id1, int64_t id2, vector<Alignment> &alignments)

void vg::Index::for_alignment_in_range(int64_t id1, int64_t id2, std::function<void> const
                                       Alignment&
                                       > lambda)

void vg::Index::for_alignment_to_node(int64_t node_id, std::function<void> const Align-
                                     ment&
                                     > lambda)

void vg::Index::for_alignment_to_nodes(const vector<int64_t> &ids,
                                       std::function<void> const Alignment&
                                       > lambda)

void vg::Index::for_base_alignments(const set<int64_t> &aln_ids,
                                    std::function<void> const Alignment&
                                    > lambda)

const string vg::Index::key_for_node(int64_t id)

const string vg::Index::key_for_edge_on_start(int64_t node_id, int64_t other, bool back-
                                              ward)

const string vg::Index::key_for_edge_on_end(int64_t node_id, int64_t other, bool back-
                                             ward)

const string vg::Index::key_prefix_for_edges_on_node_start(int64_t node)

const string vg::Index::key_prefix_for_edges_on_node_end(int64_t node)

const string vg::Index::key_for_kmer(const string &kmer, int64_t id)

const string vg::Index::key_prefix_for_kmer(const string &kmer)

const string vg::Index::key_for_metadata(const string &tag)

const string vg::Index::key_for_path_position(int64_t path_id, int64_t path_pos, bool
                                              backward, int64_t node_id)

const string vg::Index::key_for_node_path_position(int64_t node_id, int64_t path_id,
                                                    int64_t path_pos, bool backward)

const string vg::Index::key_prefix_for_node_path(int64_t node_id, int64_t path_id)

const string vg::Index::key_for_mapping_prefix(int64_t node_id)

const string vg::Index::key_for_mapping(const Mapping &mapping)

const string vg::Index::key_for_alignment_prefix(int64_t node_id)

const string vg::Index::key_for_alignment(const Alignment &alignment)

const string vg::Index::key_for_base(int64_t aln_id)

const string vg::Index::key_prefix_for_traversal(int64_t node_id)
```

```

const string vg::Index::key_for_traversal (int64_t aln_id, const Mapping &mapping)

void vg::Index::parse_node (const string &key, const string &value, int64_t &id, Node &node)

void vg::Index::parse_edge (const string &key, const string &value, char &type, int64_t &id1,
                           int64_t &id2, Edge &edge)

void vg::Index::parse_edge (const string &key, char &type, int64_t &node_id, int64_t
                           &other_id, bool &backward)

void vg::Index::parse_kmer (const string &key, const string &value, string &kmer, int64_t &id,
                           int32_t &pos)

void vg::Index::parse_node_path (const string &key, const string &value, int64_t &node_id,
                                int64_t &path_id, int64_t &path_pos, bool &backward,
                                Mapping &mapping)

void vg::Index::parse_path_position (const string &key, const string &value, int64_t
                                    &path_id, int64_t &path_pos, bool &backward,
                                    int64_t &node_id, Mapping &mapping)

void vg::Index::parse_mapping (const string &key, const string &value, int64_t &node_id,
                              uint64_t &nonce, Mapping &mapping)

void vg::Index::parse_alignment (const string &key, const string &value, int64_t &node_id,
                                uint64_t &nonce, Alignment &alignment)

void vg::Index::parse_base (const string &key, const string &value, int64_t &aln_id, Alignment
                            &alignment)

void vg::Index::parse_traversal (const string &key, const string &value, int64_t &node_id,
                                int16_t &rank, bool &backward, int64_t &aln_id)

string vg::Index::entry_to_string (const string &key, const string &value)

string vg::Index::graph_entry_to_string (const string &key, const string &value)

string vg::Index::kmer_entry_to_string (const string &key, const string &value)

string vg::Index::position_entry_to_string (const string &key, const string &value)

string vg::Index::metadata_entry_to_string (const string &key, const string &value)

string vg::Index::node_path_to_string (const string &key, const string &value)

string vg::Index::path_position_to_string (const string &key, const string &value)

string vg::Index::mapping_entry_to_string (const string &key, const string &value)

string vg::Index::alignment_entry_to_string (const string &key, const string &value)

string vg::Index::base_entry_to_string (const string &key, const string &value)

string vg::Index::traversal_entry_to_string (const string &key, const string &value)

void vg::Index::get_context (int64_t id, VG &graph)

void vg::Index::expand_context (VG &graph, int steps)

void vg::Index::get_range (int64_t from_id, int64_t to_id, VG &graph)

```

```
void vg::Index::for_graph_range (int64_t from_id, int64_t to_id, function<void> string&,
                                > lambda
void vg::Index::get_connected_nodes (VG &graph)
void vg::Index::get_edges_of (int64_t node, vector<Edge> &edges)
void vg::Index::get_edges_on_end (int64_t node, vector<Edge> &edges)
void vg::Index::get_edges_on_start (int64_t node, vector<Edge> &edges)
void vg::Index::get_nodes_next (int64_t node, bool backward, vector<pair<int64_t, bool>>
                                &destinations)
void vg::Index::get_nodes_prev (int64_t node, bool backward, vector<pair<int64_t, bool>>
                                &destinations)
void vg::Index::get_path (VG &graph, const string &name, int64_t start, int64_t end)
void vg::Index::node_path_position (int64_t id, string &path_name, int64_t &position, bool
                                    &backward, int64_t &offset)
pair<list<pair<int64_t, bool>>, pair<int64_t, bool>> vg::Index::get_nearest_node_prev_path_member (int64_t
                                                                                                  node_id,
                                                                                                  bool
                                                                                                  back-
                                                                                                  ward,
                                                                                                  int64_t
                                                                                                  path_id,
                                                                                                  int64_t
                                                                                                  &path_id,
                                                                                                  bool
                                                                                                  &rel-
                                                                                                  a-
                                                                                                  tive_orie
                                                                                                  int
                                                                                                  max_ste
                                                                                                  =
                                                                                                  4)
pair<list<pair<int64_t, bool>>, pair<int64_t, bool>> vg::Index::get_nearest_node_next_path_member (int64_t
                                                                                                  node_id,
                                                                                                  bool
                                                                                                  back-
                                                                                                  ward,
                                                                                                  int64_t
                                                                                                  path_id,
                                                                                                  int64_t
                                                                                                  &path_id,
                                                                                                  bool
                                                                                                  &rel-
                                                                                                  a-
                                                                                                  tive_orie
                                                                                                  int
                                                                                                  max_ste
                                                                                                  =
                                                                                                  4)
```

```

bool vg::Index::get_node_path_relative_position(int64_t node_id, bool backward,
                                                int64_t path_id,
                                                list<pair<int64_t, bool>>
                                                &path_prev, int64_t &prev_pos,
                                                bool &prev_orientation,
                                                list<pair<int64_t, bool>>
                                                &path_next, int64_t &next_pos,
                                                bool &next_orientation)

Mapping vg::Index::path_relative_mapping(int64_t node_id, bool backward, int64_t
                                         path_id, list<pair<int64_t, bool>>
                                         &path_prev, int64_t &prev_pos, bool
                                         &prev_orientation, list<pair<int64_t,
                                         bool>> &path_next, int64_t &next_pos,
                                         bool &next_orientation)

void vg::Index::path_layout(map<string, pair<pair<int64_t, bool>, pair<int64_t, bool>>>
                           &layout, map<string, int64_t> &lengths)

pair<int64_t, bool> vg::Index::path_first_node(int64_t path_id)

pair<int64_t, bool> vg::Index::path_last_node(int64_t path_id, int64_t &path_length)

void vg::Index::get_kmer_subgraph(const string &kmer, VG &graph)

uint64_t vg::Index::approx_size_of_kmer_matches(const string &kmer)

void vg::Index::approx_sizes_of_kmer_matches(const vector<string> &kmers, vector<uint64_t> &sizes)

void vg::Index::for_kmer_range(const string &kmer, function<void> string&, string&
                              > lambda)

void vg::Index::get_kmer_positions(const string &kmer, map<int64_t, vector<int32_t>>
                                   &positions)

void vg::Index::get_kmer_positions(const string &kmer, map<string, vector<pair<int64_t,
                                   int32_t>>> &positions)

void vg::Index::prune_kmers(int max_kb_on_disk)

void vg::Index::remember_kmer_size(int size)

set<int> vg::Index::stored_kmer_sizes(void)

void vg::Index::store_batch(map<string, string> &items)

void vg::Index::kmer_matches(std::string &kmer, std::set<int64_t> &node_ids,
                             std::set<int64_t> &edge_ids)

string vg::Index::first_kmer_key(const string &kmer)

pair<int64_t, int64_t> vg::Index::compare_kmers(Index &other)

int64_t vg::Index::get_max_path_id(void)

void vg::Index::put_max_path_id(int64_t id)

int64_t vg::Index::new_path_id(const string &name)

string vg::Index::path_name_prefix(const string &name)

```

```
string vg::Index::path_id_prefix (int64_t id)

void vg::Index::put_path_id_to_name (int64_t id, const string &name)

void vg::Index::put_path_name_to_id (int64_t id, const string &name)

string vg::Index::get_path_name (int64_t id)

int64_t vg::Index::get_path_id (const string &name)

void vg::Index::load_paths (VG &graph)

void vg::Index::store_paths (VG &graph)

void vg::Index::store_path (VG &graph, const Path &path)

map<string, int64_t> vg::Index::paths_by_id (void)

void vg::Index::for_each_mapping (function<void> const Mapping&
    > lambda)

void vg::Index::for_each_alignment (function<void> const Alignment&
    > lambda)

char vg::Index::graph_key_type (const string &key)
```

Public Members

```
string vg::Index::name

char vg::Index::start_sep

char vg::Index::end_sep

int vg::Index::threads

rocksdb::DB *vg::Index::db

rocksdb::Options vg::Index::db_options

rocksdb::WriteOptions vg::Index::write_options

rocksdb::ColumnFamilyOptions vg::Index::column_family_options

bool vg::Index::bulk_load

std::atomic<uint64_t> vg::Index::next_nonce

class #include <index.hpp> Inherits from exception Public Functions
```

```
vg::indexOpenException::indexOpenException (string message = "")
```

Private Functions

```
virtual const char *vg::indexOpenException::what () const
```

Private Members

string vg::indexOpenException::message

struct #include <genome_state.hpp> Inherits from vg::GenomeStateCommand **Public Functions**

GenomeStateCommand *vg::InsertHaplotypeCommand::execute (GenomeState &state)

const
Execute this command on the given state and return the reverse command. Generally ends up calling a command-type-specific method on the *GenomeState* that does the actual work.

virtual vg::InsertHaplotypeCommand::~InsertHaplotypeCommand()

Public Members

unordered_map<const Snarl *, vector<vector<pair<handle_t, size_t>>>> vg::InsertHaplotypeCommand::insertion

For each snarl, holds several haplotype traversals. The handles in each traversal are annotated with their local lane assignments. This annotation lets the command be basically an undelete, because we can exactly reverse a delete. Insertions are applied from begin to end within each vector. Lane numbers for a given forward handle must strictly increase between vectors and within vectors.

struct #include <pileup_augmenter.hpp> **Public Members**

Node *vg::PileupAugmenter::InsertionRecord::node

StrandSupport vg::PileupAugmenter::InsertionRecord::sup

int64_t vg::PileupAugmenter::InsertionRecord::orig_id

int vg::PileupAugmenter::InsertionRecord::orig_offset

struct We need to suppress overlapping variants, but interval trees are hard to write. This accomplishes the collision check with a massive bit vector. **Public Functions**

vg::IntervalBitfield::IntervalBitfield (size_t length)
Make a new *IntervalBitfield* covering a region of the specified length.

bool vg::IntervalBitfield::collides (size_t start, size_t pastEnd)
Scan for a collision (O(n) in interval length)

void vg::IntervalBitfield::add (size_t start, size_t pastEnd)
Take up an interval.

Public Members

vector<bool> vg::IntervalBitfield::used

class #include <phased_genome.hpp> Unidirectional iterator to obtain the NodeTraversals of a haplotype. Can be come invalid if the *PhasedGenome* is edited while iterating. **Public Functions**

vg::PhasedGenome::iterator::iterator ()
Default constructor.

vg::PhasedGenome::iterator::iterator (const iterator &other)
Copy constructor.

```
vg::PhasedGenome::iterator::~~iterator()
    Destructor.

iterator &vg::PhasedGenome::iterator::operator=(const iterator &other)

bool vg::PhasedGenome::iterator::operator==(const iterator &other) const

bool vg::PhasedGenome::iterator::operator!=(const iterator &other) const

iterator vg::PhasedGenome::iterator::operator++()

iterator vg::PhasedGenome::iterator::operator++(int)

NodeTraversal vg::PhasedGenome::iterator::operator*()

int vg::PhasedGenome::iterator::which_haplotype()
```

Private Functions

```
vg::PhasedGenome::iterator::iterator(size_t rank, int haplotype_number, HaplotypeNode *haplo_node)
```

Private Members

```
size_t vg::PhasedGenome::iterator::rank
    Ordinal position along the haplotype (to distinguish the same node with multiple copies)

int vg::PhasedGenome::iterator::haplotype_number
    The ID of the haplotype.

HaplotypeNode *vg::PhasedGenome::iterator::haplo_node
    The position along the haplotype.
```

Friends

```
friend vg::PhasedGenome::iterator::PhasedGenome

friend vg::PhasedGenome::iterator::Haplotype
class #include <cluster.hpp> Actual iterator class. Public Functions
```

```
ShuffledPairs::iterator &vg::ShuffledPairs::iterator::operator++()
    Advance to the next pair.

pair<size_t, size_t> vg::ShuffledPairs::iterator::operator*() const
    Get the pair pointed to.

bool vg::ShuffledPairs::iterator::operator==(const iterator &other) const
    see if two iterators are equal.

bool vg::ShuffledPairs::iterator::operator!=(const iterator &other) const
    see if two iterators are not equal.

vg::ShuffledPairs::iterator::iterator(const iterator &other)

iterator &vg::ShuffledPairs::iterator::operator=(const iterator &other)
```

Private Functions

```
vg::ShuffledPairs::iterator::iterator (const ShuffledPairs &iteratee, size_t start_at)
```

Private Members

```
size_t vg::ShuffledPairs::iterator::permutation_idx
```

```
size_t vg::ShuffledPairs::iterator::permuted
```

```
const ShuffledPairs &vg::ShuffledPairs::iterator::iteratee
```

Friends

```
friend vg::ShuffledPairs::iterator::ShuffledPairs
```

```
class Inherits from exception Public Functions
```

```
j2pb_error::j2pb_error (const std::string &e)
```

```
j2pb_error::j2pb_error (const FieldDescriptor *field, const std::string &e)
```

```
virtual j2pb_error::~j2pb_error ()
```

```
virtual const char *j2pb_error::what () const
```

Private Members

```
std::string j2pb_error::_error
```

```
struct Public Functions
```

```
json_autoptr::json_autoptr (json_t *json)
```

```
json_autoptr::~json_autoptr ()
```

```
json_t *json_autoptr::release ()
```

Public Members

```
json_t *json_autoptr::ptr
```

```
template <class T>
```

```
class #include <json2pb.h>
```

Public Functions

```
JSONStreamHelper::JSONStreamHelper (const std::string &file_name)
```

```
JSONStreamHelper::~JSONStreamHelper ()
```

```
std::function<bool (T&)> JSONStreamHelper::get_read_fn
```

```
int64_t JSONStreamHelper::write (std::ostream &out, bool json_out = false, int64_t buf_size =
                                1000)
```

Private Members

```
FILE *JSONStreamHelper::_fp
```

```
class #include <index.hpp> Inherits from exception Private Functions
```

```
virtual const char *vg::keyNotFoundException::what () const
```

```
struct Used to serialize kmer matches. Public Members
```

```
string vg::KmerMatch::sequence
```

```
int64 vg::KmerMatch::node_id
```

```
sint32 vg::KmerMatch::position
```

```
bool vg::KmerMatch::backward
```

If true, this kmer is backwards relative to its node, and position counts from the end of the node.

```
struct #include <vg.hpp> We create a struct that represents each kmer record we want to send to gcsa2 Public Members
```

```
string vg::KmerPosition::kmer
```

```
string vg::KmerPosition::pos
```

```
set<char> vg::KmerPosition::prev_chars
```

```
set<char> vg::KmerPosition::next_chars
```

```
set<string> vg::KmerPosition::next_positions
```

```
struct Support pinned to a location, which can be either a node or an edge. Public Members
```

```
Support vg::LocationSupport::support
```

The support.

```
oneof vg::LocationSupport::oneof_location
```

The location.

```
int64 vg::LocationSupport::node_id
```

```
class #include <graph_synchronizer.hpp> This represents a request to lock a particular context on a particular GraphSynchronizer. It fulfils the BasicLockable concept requirements, so you can wait on it with std::unique_lock. Public Functions
```

```
vg::GraphSynchronizer::Lock::Lock (GraphSynchronizer &synchronizer, const string
                                   &path_name, size_t path_offset, size_t context_bases,
                                   bool reflect)
```

Create a request to lock a certain radius around a certain position along a certain path in the graph controlled by the given synchronizer.

```
vg::GraphSynchronizer::Lock::Lock(GraphSynchronizer &synchronizer, const string
                                &path_name, size_t start, size_t past_end)
```

Create a request to lock a certain range of a certain path, from start to end. The start and end positions must line up with the boundaries of nodes in the graph. Also locks attached things that can be reached by paths of the same length or shorter. Note that the range must be nonempty.

```
void vg::GraphSynchronizer::Lock::lock()
```

Block until a lock is obtained.

```
void vg::GraphSynchronizer::Lock::unlock()
```

If a lock is held, unlock it.

```
VG &vg::GraphSynchronizer::Lock::get_subgraph()
```

May only be called when locked. Grab the subgraph that was extracted when the lock was obtained. Does not contain any path information.

```
pair<NodeSide, NodeSide> vg::GraphSynchronizer::Lock::get_endpoints() const
```

May only be called when locked. Returns the pair of NodeSides corresponding to the start and end positions used when the lock was created.

May only be called on locks that lock a start to end range.

```
set<NodeSide> vg::GraphSynchronizer::Lock::get_peripheral_attachments(NodeSide
                                                                    graph_side)
```

Get the NodeSides for nodes not in the extracted subgraph but in its periphery that are attached to the given *NodeSide* in the subgraph.

```
vector<Translation> vg::GraphSynchronizer::Lock::apply_edit(const Path &path,
                                                            set<NodeSide> &dangling)
```

May only be called when locked. Apply an edit against the base graph and return the resulting translation. Note that this updates only the underlying *VG* graph, not the copy of the locked subgraph stored in the lock. Also note that the edit may only edit locked nodes.

Edit operations will create new nodes, and cannot delete nodes or apply changes (other than dividing and connecting) to existing nodes.

Any new nodes created are created already locked.

Any new nodes created on the left of the alignment (and any existing nodes visited) will be attached to the given “dangling” NodeSides. The set will be populated with the NodeSides for the ends of nodes created/visited at the end of the alignment.

```
vector<Translation> vg::GraphSynchronizer::Lock::apply_edit(const Path &path)
```

May only be called when locked. Apply a path as an edit to the base graph, leaving new nodes at the ends of the path unattached on their outer sides.

```
vector<Translation> vg::GraphSynchronizer::Lock::apply_full_length_edit(const
                                                                    Path
                                                                    &path)
```

May only be called when locked. Apply a path as an edit to the base graph, attaching the outer sides of any newly created nodes to the sides in the periphery attached to the extraction start and end sides, respectively. The lock must have been obtained on a range, rather than a radius.

The alignment must be in the local forward orientation of the graph for this to make sense.

Protected Attributes

GraphSynchronizer &vg::GraphSynchronizer::Lock::synchronizer

This points back to the synchronizer we synchronize with when we get locked.

string vg::GraphSynchronizer::Lock::path_name

size_t vg::GraphSynchronizer::Lock::path_offset

size_t vg::GraphSynchronizer::Lock::context_bases

bool vg::GraphSynchronizer::Lock::reflect

size_t vg::GraphSynchronizer::Lock::start

size_t vg::GraphSynchronizer::Lock::past_end

VG vg::GraphSynchronizer::Lock::subgraph

This is the subgraph that got extracted during the locking procedure.

pair<*NodeSide*, *NodeSide*> vg::GraphSynchronizer::Lock::endpoints

These are the endpoints that the subgraph was extracted between, if applicable.

set<*id_t*> vg::GraphSynchronizer::Lock::periphery

These are the nodes connected to the subgraph but not actually available for editing. We just need no one else to edit them.

map<*NodeSide*, set<*NodeSide*>> vg::GraphSynchronizer::Lock::peripheral_attachments

This connects internal NodeSides to NodeSides of nodes on the periphery.

set<*id_t*> vg::GraphSynchronizer::Lock::locked_nodes

This is the set of nodes that this lock has currently locked.

struct Describes a genetic locus with multiple possible alleles, a genotype, and observational support. **Public Members**

string vg::Locus::name

A locus may have an identifying name.

repeated<*Path*> vg::Locus::allele

These are all the alleles at the locus, not just the called ones. Note that a primary reference allele may or may not appear.

repeated<*Support*> vg::Locus::support

These supports are per-allele, matching the alleles above.

repeated<*Genotype*> vg::Locus::genotype

sorted by likelihood or posterior the first one is the “call”

Support vg::Locus::overall_support

We also have a *Support* for the locus overall, because reads may have supported multiple alleles and we want to know how many total there were.

repeated<double> vg::Locus::allele_log_likelihood

We track the likelihood of each allele individually, in addition to genotype likelihoods. Stores the likelihood natural logged.

class *#include <mapper.hpp>* Inherits from *vg::BaseMapper* **Public Functions**

```

vg::Mapper::Mapper (xg::XG *xidex, gcsa::GCSA *g, gcsa::LCPArray *a)

vg::Mapper::Mapper (void)

vg::Mapper::~Mapper (void)

map<string, vector<size_t>> vg::Mapper::node_positions_in_paths (gcsa::node_type
                                                                node)

double vg::Mapper::graph_entropy (void)

map<string, vector<pair<size_t, bool>>> vg::Mapper::alignment_initial_path_positions (const
                                                                                      Align-
                                                                                      ment
                                                                                      &aln)

void vg::Mapper::annotate_with_initial_path_positions (Alignment &aln)

void vg::Mapper::annotate_with_initial_path_positions (vector<Alignment>
                                                       &alns)

bool vg::Mapper::alignments_consistent (const map<string, double> &pos1, const
                                         map<string, double> &pos2, int frag-
                                         ment_size_bound)

bool vg::Mapper::pair_consistent (Alignment &aln1, Alignment &aln2, double pval)
    use the fragment length annotations to assess if the pair is consistent or not

pair<bool, bool> vg::Mapper::pair_rescue (Alignment &mate1, Alignment &mate2, int
                                         match_score, int full_length_bonus, bool trace-
                                         back)
    use the fragment configuration statistics to rescue more precisely

Alignment vg::Mapper::realign_from_start_position (const Alignment &aln, int extra,
                                                    int iteration)
    assuming the read has only been score-aligned, realign from the end position backwards

set<MaximalExactMatch *> vg::Mapper::resolve_paired_mems (vector<MaximalExactMatch>
                                                         &mems1,          vec-
                                                         tor<MaximalExactMatch>
                                                         &mems2)

vector<Alignment> vg::Mapper::mems_id_clusters_to_alignments (const Alignment
                                                             &alignment, vec-
                                                             tor<MaximalExactMatch>
                                                             &mems, int addi-
                                                             tional_multimaps)

set<const vector<MaximalExactMatch> *> vg::Mapper::clusters_to_drop (const          vec-
                                                                    tor<vector<MaximalExactMatch>>
                                                                    &clusters)

Alignment vg::Mapper::mems_to_alignment (const Alignment &aln,          vec-
                                         tor<MaximalExactMatch> &mems)

Alignment vg::Mapper::mem_to_alignment (MaximalExactMatch &mem)

```

```

int32_t vg::Mapper::score_alignment (const Alignment &aln, bool use_approx_distance =
                                     false)
    Use the scoring provided by the internal aligner to re-score the alignment, scoring gaps between nodes
    using graph distance from the XG index. Can use either approximate or exact (with approximate fallback)
    XG-based distance estimation. Will strip out bonuses if the appropriate Mapper flag is set.

void vg::Mapper::remove_full_length_bonuses (Alignment &aln)
    Given an alignment scored with full length bonuses on, subtract out the full length bonus if it was applied.

Alignment vg::Mapper::patch_alignment (const Alignment &aln, int max_patch_length)

VG vg::Mapper::cluster_subgraph_strict (const Alignment &aln, const vector<MaximalExactMatch> &mems)

Alignment vg::Mapper::align_cluster (const Alignment &aln, const vector<MaximalExactMatch> &mems, bool traceback)

double vg::Mapper::compute_uniqueness (const Alignment &aln, const vector<MaximalExactMatch> &mems)

Alignment vg::Mapper::align_maybe_flip (const Alignment &base, Graph &graph, bool flip,
                                         bool traceback, bool banded_global = false)

bool vg::Mapper::adjacent_positions (const Position &pos1, const Position &pos2)

int64_t vg::Mapper::get_node_length (int64_t node_id)

bool vg::Mapper::check_alignment (const Alignment &aln)

VG vg::Mapper::alignment_subgraph (const Alignment &aln, int context_size = 1)

Alignment vg::Mapper::align (const string &seq, int kmer_size = 0, int stride = 0, int
                             max_mem_length = 0, int band_width = 1000)

Alignment vg::Mapper::align (const Alignment &read, int kmer_size = 0, int stride = 0, int
                             max_mem_length = 0, int band_width = 1000)

vector<Alignment> vg::Mapper::align_multi (const Alignment &aln, int kmer_size = 0,
                                          int stride = 0, int max_mem_length = 0, int
                                          band_width = 1000)

pair<vector<Alignment>, vector<Alignment>> vg::Mapper::align_paired_multi (const
                                                                           Alignment
                                                                           &read1,
                                                                           const
                                                                           Alignment
                                                                           &read2,
                                                                           bool
                                                                           &queued_resolve_later,
                                                                           int
                                                                           max_mem_length
                                                                           = 0, bool
                                                                           only_top_scoring_pair
                                                                           = false,
                                                                           bool
                                                                           retry-
                                                                           ing
                                                                           =
                                                                           false)

Alignment vg::Mapper::subject_alignment (const Alignment &source, set<string>
                                         &path_names, string &path_name, int64_t
                                         &path_pos, bool &path_reverse, int window)

```

```

double vg::Mapper::compute_cluster_mapping_quality(const          vec-
                                                    tor<vector<MaximalExactMatch>>
                                                    &clusters, int read_length)

double vg::Mapper::estimate_max_possible_mapping_quality(int  length,  double
                                                         min_diffs,    double
                                                         next_min_diffs)

double vg::Mapper::max_possible_mapping_quality(int length)

int64_t vg::Mapper::graph_distance(pos_t pos1, pos_t pos2, int64_t maximum = 1e3)

int64_t vg::Mapper::graph_mixed_distance_estimate(pos_t pos1, pos_t pos2, int64_t
                                                    maximum)

int64_t vg::Mapper::approx_distance(pos_t pos1, pos_t pos2)

int64_t vg::Mapper::approx_position(pos_t pos)

int64_t vg::Mapper::approx_alignment_position(const Alignment &aln)
    returns approximate position of alignment start in xindex or -1.0 if alignment is unmapped

map<string, vector<pair<size_t, bool>>> vg::Mapper::alignment_path_offsets(const
                                                    Alignment
                                                    &aln, bool
                                                    just_min =
                                                    true, bool
                                                    nearby  =
                                                    false)

map<string, vector<pair<size_t, bool>>> vg::Mapper::alignment_refpos_to_path_offsets(const
                                                    Align-
                                                    ment
                                                    &aln)

Position vg::Mapper::alignment_end_position(const Alignment &aln)

int64_t vg::Mapper::approx_fragment_length(const Alignment &aln1, const Alignment
                                                    &aln2)
    returns approximate distance between alignment starts or -1.0 if not possible to determine

pos_t vg::Mapper::likely_mate_position(const Alignment &aln, bool is_first)

vector<pos_t> vg::Mapper::likely_mate_positions(const Alignment &aln, bool is_first)

id_t vg::Mapper::node_approximately_at(int64_t approx_pos)

Alignment vg::Mapper::walk_match(const string &seq, pos_t pos)

vector<Alignment> vg::Mapper::walk_match(const Alignment &base, const string &seq, pos_t
                                                    pos)

vector<Alignment> vg::Mapper::mem_to_alignments(MaximalExactMatch &mem)

map<string, int64_t> vg::Mapper::min_pair_fragment_length(const Alignment &aln1,
                                                         const Alignment &aln2)

double vg::Mapper::average_node_length(void)

```

Public Members

```
vector<pair<Alignment, Alignment>> vg::Mapper::imperfect_pairs_to_retry
bool vg::Mapper::debug
int vg::Mapper::min_cluster_length
int vg::Mapper::context_depth
int vg::Mapper::max_attempts
int vg::Mapper::thread_extension
int vg::Mapper::max_target_factor
size_t vg::Mapper::max_query_graph_ratio
int vg::Mapper::max_multimaps
int vg::Mapper::softclip_threshold
int vg::Mapper::max_softclip_iterations
float vg::Mapper::min_identity
int vg::Mapper::min_banded_mq
int vg::Mapper::extra_multimaps
int vg::Mapper::min_multimaps
int vg::Mapper::band_multimaps
double vg::Mapper::maybe_mq_threshold
int vg::Mapper::max_cluster_mapping_quality
bool vg::Mapper::use_cluster_mq
double vg::Mapper::identity_weight
bool vg::Mapper::always_rescue
bool vg::Mapper::include_full_length_bonuses
bool vg::Mapper::simultaneous_pair_alignment
int vg::Mapper::max_band_jump
float vg::Mapper::drop_chain
float vg::Mapper::mq_overlap
int vg::Mapper::mate_rescues
double vg::Mapper::pair_rescue_hang_threshold
double vg::Mapper::pair_rescue_retry_threshold
FragmentLengthStatistics vg::Mapper::frag_stats
```

Private Functions

```
Alignment vg::Mapper::align_to_graph(const Alignment &aln, Graph &graph, size_t
max_query_graph_ratio, bool traceback, bool
pinned_alignment = false, bool pin_left = false, bool
global = false, bool keep_bonuses = true)
```

```
vector<Alignment> vg::Mapper::align_multi_internal (bool compute_unpaired_qualities,
const Alignment &aln, int
kmer_size, int stride, int
max_mem_length, int band_width,
double &cluster_mq, int
keep_multimaps = 0, int ad-
ditional_multimaps = 0, vec-
tor<MaximalExactMatch> *re-
stricted_mems = nullptr)
```

```
void vg::Mapper::compute_mapping_qualities (vector<Alignment> &alns, double clus-
ter_mq, double mq_estimate, double
mq_cap)
```

```
void vg::Mapper::compute_mapping_qualities (pair<vector<Alignment>, vec-
tor<Alignment>> &pair_alns, double
cluster_mq, double mq_estimate1, double
mq_estimate2, double mq_cap1, double
mq_cap2)
```

```
vector<Alignment> vg::Mapper::score_sort_and_deduplicate_alignments (vector<Alignment>
&all_alns,
const
Alignment
&original_alignment)
```

```
void vg::Mapper::filter_and_process_multimaps (vector<Alignment> &all_alns, int to-
tal_multimaps)
```

```
vector<Alignment> vg::Mapper::make_bands (const Alignment &read, int band_width, vec-
tor<pair<int, int>> &to_strip)
```

```
vector<Alignment> vg::Mapper::align_banded (const Alignment &read, int kmer_size = 0,
int stride = 0, int max_mem_length = 0, int
band_width = 1000)
```

```
vector<Alignment> vg::Mapper::align_mem_multi (const Alignment &aln, vec-
tor<MaximalExactMatch> &mems, double
&cluster_mq, double lcp_avg, double
fraction_filtered, int max_mem_length,
int keep_multimaps, int addi-
tional_multimaps)
```

struct A *Mapping* defines the relationship between a node in system and another entity. An empty edit list implies complete match, however it is preferred to specify the full edit structure. as it is more complex to handle special cases. **Public Members**

Position vg::Mapping::position

The position at which the first *Edit*, if any, in the *Mapping* starts. Inclusive.

repeated<*Edit*> vg::Mapping::edit

The series of *Edits* to transform to region in read/alt.

int64 vg::Mapping::rank

The 1-based rank of the mapping in its containing path.

template <class From, class To>

class

Public Functions

vg::NGSSimulator::MarkovDistribution::MarkovDistribution (size_t seed)

void vg::NGSSimulator::MarkovDistribution::record_transition (From from, To to)
record a transition from the input data

void vg::NGSSimulator::MarkovDistribution::finalize ()
indicate that there is no more data and prepare for sampling

To vg::NGSSimulator::MarkovDistribution::sample_transition (From from)
sample according to the training data

Private Members

default_random_engine vg::NGSSimulator::MarkovDistribution::prng

unordered_map<From, uniform_int_distribution<size_t>> vg::NGSSimulator::MarkovDistribution::samplers

unordered_map<To, size_t> vg::NGSSimulator::MarkovDistribution::column_of

vector<To> vg::NGSSimulator::MarkovDistribution::value_at

unordered_map<From, vector<size_t>> vg::NGSSimulator::MarkovDistribution::cond_distrs
class #include <mem.hpp>

Public Functions

vg::MaximalExactMatch::MaximalExactMatch (string::const_iterator b,
string::const_iterator e, gcsa::range_type r,
size_t m = 0)

string vg::MaximalExactMatch::sequence (void) const

int vg::MaximalExactMatch::length (void) const

size_t vg::MaximalExactMatch::count_Ns (void) const

vg::MaximalExactMatch::MaximalExactMatch (void)

vg::MaximalExactMatch::MaximalExactMatch (const MaximalExactMatch&)

vg::MaximalExactMatch::MaximalExactMatch (MaximalExactMatch&&)

MaximalExactMatch &vg::MaximalExactMatch::operator= (const MaximalExactMatch&)

MaximalExactMatch &vg::MaximalExactMatch::operator= (MaximalExactMatch&&)

Public Members

```
string::const_iterator vg::MaximalExactMatch::begin
string::const_iterator vg::MaximalExactMatch::end
gcsa::range_type vg::MaximalExactMatch::range
size_t vg::MaximalExactMatch::match_count
int vg::MaximalExactMatch::fragment
bool vg::MaximalExactMatch::primary
std::vector<gcsa::node_type> vg::MaximalExactMatch::nodes
map<string, vector<pair<size_t, bool>>> vg::MaximalExactMatch::positions
```

Friends

```
bool operator==(const MaximalExactMatch &m1, const MaximalExactMatch &m2)
bool operator<(const MaximalExactMatch &m1, const MaximalExactMatch &m2)
ostream &operator<<(ostream &out, const MaximalExactMatch &m)
class #include <cluster.hpp>Public Functions
```

```
vg::MEMChainModel::MEMChainModel(const vector<size_t> &aln_lengths, const vector<vector<MaximalExactMatch>> &matches, const function<int64_t> pos_t
> &approx_position, const function<map<string, vector<pair<size_t, bool>>> pos_t> &path_position,
const function<double> const MaximalExactMatch&, const MaximalExactMatch&> &transition_weight,
int band_width = 10, int position_depth = 1, int max_connections = 20)

void vg::MEMChainModel::score(const set<MEMChainModelVertex*> &exclude)
MEMChainModelVertex *vg::MEMChainModel::max_vertex(void)

vector<vector<MaximalExactMatch>> vg::MEMChainModel::traceback(int alt_alns, bool
paired, bool debug)

void vg::MEMChainModel::display(ostream &out)
void vg::MEMChainModel::clear_scores(void)
```

Public Members

```
vector<MEMChainModelVertex> vg::MEMChainModel::model
map<string, map<int64_t, vector<vector<MEMChainModelVertex>::iterator>>> vg::MEMChainModel::positions
set<vector<MEMChainModelVertex>::iterator> vg::MEMChainModel::redundant_vertexes
class #include <cluster.hpp>Public Functions

vg::MEMChainModelVertex::MEMChainModelVertex(void)
```

```
vg::MEMChainModelVertex::MEMChainModelVertex(const MEMChainModelVertex&)\nvg::MEMChainModelVertex::MEMChainModelVertex(MEMChainModelVertex&&)\nMEMChainModelVertex &vg::MEMChainModelVertex::operator=(const MEMChainMod-\nelVertex&)\nMEMChainModelVertex &vg::MEMChainModelVertex::operator=(MEMChainModelVertex&&)\nvirtual vg::MEMChainModelVertex::~~MEMChainModelVertex()
```

Public Members

MaximalExactMatch vg::MEMChainModelVertex::mem

vector<pair<MEMChainModelVertex*, double>> vg::MEMChainModelVertex::next_cost

vector<pair<MEMChainModelVertex*, double>> vg::MEMChainModelVertex::prev_cost

double vg::MEMChainModelVertex::weight

double vg::MEMChainModelVertex::score

MEMChainModelVertex*vg::MEMChainModelVertex::prev

struct A subgraph of the unrolled *Graph* in which each non-branching path is associated with an alignment of part of the read and part of the graph such that any path through the *MultipathAlignment* indicates a valid alignment of a read to the graph **Public Members**

string vg::MultipathAlignment::sequence

bytes vg::MultipathAlignment::quality

string vg::MultipathAlignment::name

string vg::MultipathAlignment::sample_name

string vg::MultipathAlignment::read_group

repeated<Subpath> vg::MultipathAlignment::subpath

non-branching paths of the multipath alignment, each containing an alignment of part of the sequence to a *Graph* IMPORTANT: downstream applications will assume these are stored in topological order

int32 vg::MultipathAlignment::mapping_quality

-10 * log₁₀(probability of mismapping)

repeated<uint32> vg::MultipathAlignment::start

optional: indices of Subpaths that align the beginning of the read (i.e. source nodes)

string vg::MultipathAlignment::paired_read_name

class #include <multipath_mapper.hpp>Public Functions

```
vg::MultipathAlignmentGraph::MultipathAlignmentGraph (VG      &vg,      const
                                                    MultipathMap-
                                                    per::memcluster_t
                                                    &hits,      const      un-
                                                    ordered_map<id_t,
                                                    pair<id_t, bool>> &pro-
                                                    jection_trans, SnarlMan-
                                                    ager      *cutting_snarls
                                                    =      nullptr,      int64_t
                                                    max_snarl_cut_size      =
                                                    5)
```

```
vg::MultipathAlignmentGraph::~MultipathAlignmentGraph ()
```

```
void vg::MultipathAlignmentGraph::topological_sort (vector<size_t> &order_out)
    Fills input vector with node indices of a topological sort.
```

```
void vg::MultipathAlignmentGraph::remove_transitive_edges (const vector<size_t>
                                                            &topologi-
                                                            cal_order)
    Removes all transitive edges from graph (reduces to minimum equivalent graph) Note: reorders internal
    representation of adjacency lists
```

```
void vg::MultipathAlignmentGraph::prune_to_high_scoring_paths (const Alignment &align-
                                                                ment,      const
                                                                BaseAligner
                                                                *aligner,
                                                                double MultipathAlign-
                                                                mentGraph,
                                                                const      vec-
                                                                tor<size_t>
                                                                &topologi-
                                                                cal_order)
    Removes nodes and edges that are not part of any path that has an estimated score within some amount of
    the highest scoring path
```

```
void vg::MultipathAlignmentGraph::reorder_adjacency_lists (const vector<size_t>
                                                            &order)
    Reorders adjacency list representation of edges so that they follow the indicated ordering of their target
    nodes
```

Public Members

```
vector<ExactMatchNode> vg::MultipathAlignmentGraph::match_nodes
class #include <multipath_mapper.hpp> Inherits from vg::BaseMapper Public Types
```

using We often pass around clusters of MEMs and their graph positions.

using This represents a graph for a cluster, and holds a pointer to the actual extracted graph, a list of assigned MEMs, and the number of bases of read coverage that that MEM cluster provides (which serves as a priority).

Public Functions

```
vg::MultipathMapper::MultipathMapper(xg::XG *xg_index, gcsa::GCSA *gcsa_index,
                                       gcsa::LCPArray *lcp_array, SnarlManager
                                       *snarl_manager = nullptr)
```

```
vg::MultipathMapper::~MultipathMapper()
```

```
void vg::MultipathMapper::multipath_map(const Alignment &alignment, vector<MultipathAlignment>
                                       &multipath_alns_out, size_t max_alt_mappings)
```

Map read in alignment to graph and make multipath alignments.

```
void vg::MultipathMapper::multipath_map_paired(const Alignment &alignment1,
                                                const Alignment &alignment2,
                                                vector<pair<MultipathAlignment,
                                                MultipathAlignment>> &multipath_aln_pairs_out,
                                                vector<pair<Alignment, Alignment>>
                                                &ambiguous_pair_buffer, size_t
                                                max_alt_mappings)
```

Map a paired read to the graph and make paired multipath alignments. Assumes reads are on the same strand of the DNA/RNA molecule. If the fragment length distribution is still being estimated and the pair cannot be mapped unambiguously, adds the reads to a buffer for ambiguous pairs and does not output any multipath alignments.

```
bool vg::MultipathMapper::validate_multipath_alignment(const MultipathAlignment
                                                        &multipath_aln)
const
```

Debugging function to check that multipath alignment meets the formalism's basic invariants. Returns true if multipath alignment is valid, else false. Does not validate alignment score.

```
void vg::MultipathMapper::set_automatic_min_clustering_length(double random_mem_probability
                                                                = 0.5)
```

Sets the minimum clustering MEM length to the approximate length that a MEM would have to be to have at most the given probability of occurring in random sequence of the same size as the graph

Public Members

```
int64_t vg::MultipathMapper::max_snarl_cut_size
```

```
int32_t vg::MultipathMapper::band_padding
```

```
size_t vg::MultipathMapper::max_expected_dist_approx_error
```

```
int32_t vg::MultipathMapper::num_alt_alns
```

```
double vg::MultipathMapper::mem_coverage_min_ratio
```

```
double vg::MultipathMapper::max_suboptimal_path_score_ratio
```

```
size_t vg::MultipathMapper::num_mapping_attempts
```

```
double vg::MultipathMapper::log_likelihood_approx_factor
```

```
size_t vg::MultipathMapper::min_clustering_mem_length
```

```
size_t vg::MultipathMapper::max_p_value_memo_size
```

Protected Functions

```
void vg::MultipathMapper::multipath_map_internal(const Alignment &alignment,
                                                  MappingQualityMethod mapq_method,
                                                  vector<MultipathAlignment>
                                                  &multipath_alns_out, size_t
                                                  max_alt_mappings)
```

Wrapped internal function that allows some code paths to circumvent the current mapping quality method option.

```
void vg::MultipathMapper::attempt_unpaired_multipath_map_of_pair(const Alignment
                                                                    &alignment1,
                                                                    const Alignment
                                                                    &alignment2,
                                                                    vector<pair<MultipathAlignment,
                                                                    MultipathAlignment>>
                                                                    &multipath_aln_pairs_out,
                                                                    vector<pair<Alignment,
                                                                    Alignment>>
                                                                    &ambiguous_pair_buffer)
```

Before the fragment length distribution has been estimated, look for an unambiguous mapping of the reads using the single ended routine. If we find one record the fragment length and report the pair, if we don't find one, add the read pair to a buffer instead of the output vector.

```
bool vg::MultipathMapper::attempt_rescue(const MultipathAlignment &multipath_aln,
                                          const Alignment &other_aln, bool rescue_forward,
                                          MultipathAlignment &rescue_multipath_aln)
```

Extracts a section of graph at a distance from the *MultipathAlignment* based on the fragment length distribution and attempts to align the other paired read to it. If rescuing forward, assumes the provided *MultipathAlignment* is the first read and vice versa if rescuing backward. Rescue constructs a conventional local alignment with gssw and converts the *Alignment* to a *MultipathAlignment*. The *MultipathAlignment* will be stored in the object passed by reference as an argument.

```
void vg::MultipathMapper::align_to_cluster_graphs (const Alignment &alignment,
                                                    MappingQualityMethod mapq_method,
                                                    vector<clustergraph_t>
                                                    &cluster_graphs,          vector<MultipathAlignment>
                                                    &multipath_alns_out,      size_t
                                                    max_alt_mappings)
```

After clustering MEMs, extracting graphs, and assigning hits to cluster graphs, perform multipath alignment

```
void vg::MultipathMapper::align_to_cluster_graph_pairs (const Alignment &alignment1, const Alignment
                                                         &alignment2,          vector<clustergraph_t>
                                                         &cluster_graphs1,  vector<clustergraph_t>
                                                         &cluster_graphs2,  vector<pair<pair<size_t,
                                                         size_t>,          int64_t>>
                                                         &cluster_pairs,    vector<pair<MultipathAlignment,
                                                         MultipathAlignment>>
                                                         &multipath_aln_pairs_out,
                                                         size_t
                                                         max_alt_mappings)
```

After clustering MEMs, extracting graphs, assigning hits to cluster graphs, and determining which cluster graph pairs meet the fragment length distance constraints, perform multipath alignment

```
bool vg::MultipathMapper::align_to_cluster_graphs_with_rescue (const Alignment &alignment1, const
                                                                Alignment
                                                                &alignment2,  vector<clustergraph_t>
                                                                &cluster_graphs1,
                                                                vector<clustergraph_t>
                                                                &cluster_graphs2,
                                                                vector<pair<MultipathAlignment,
                                                                MultipathAlignment>>
                                                                &multipath_aln_pairs_out,
                                                                size_t
                                                                max_alt_mappings)
```

Align the read ends independently, but also try to form rescue alignments for each from the other. Return true if output obeys pair consistency and false otherwise.

```

auto vg::MultipathMapper::query_cluster_graphs (const Alignment &alignment,
                                                const vector<MaximalExactMatch>
                                                &mems, const vector<memcluster_t>
                                                &clusters)

```

Extracts a subgraph around each cluster of MEMs that encompasses any graph position reachable (according to the *Mapper*'s aligner) with local alignment anchored at the MEMs. If any subgraphs overlap, they are merged into one subgraph. Returns a vector of all the merged cluster subgraphs, their MEMs assigned from the mems vector according to the MEMs' hits, and their read coverages in bp. The caller must delete the *VG* objects produced!

```

void vg::MultipathMapper::split_multicomponent_alignments (vector<MultipathAlignment>
                                                           &multi-
                                                           path_alns_out)

```

const
If there are any MultipathAlignments with multiple connected components, split them up and add them to the return vector

```

void vg::MultipathMapper::split_multicomponent_alignments (vector<pair<MultipathAlignment,
                                                                    MultipathAlign-
                                                                    ment>> &multi-
                                                                    path_aln_pairs_out,
                                                                    vec-
                                                                    tor<pair<pair<size_t,
                                                                    size_t>, int64_t>>
                                                                    &cluster_pairs)

```

const
If there are any MultipathAlignments with multiple connected components, split them up and add them to the return vector, also measure the distance between them and add a record to the cluster pairs vector

```

void vg::MultipathMapper::multipath_align (const Alignment &alignment, VG *vg, mem-
                                           cluster_t &graph_mems, MultipathAlign-
                                           ment &multipath_aln_out) const

```

Make a multipath alignment of the read against the indicated graph and add it to the list of multimappings.

```

void vg::MultipathMapper::strip_full_length_bonuses (MultipathAlignment &multi-
                                                       path_aln) const

```

Remove the full length bonus from all source or sink subpaths that received it.

```

void vg::MultipathMapper::sort_and_compute_mapping_quality (vector<MultipathAlignment>
                                                            &multipath_alns,
                                                            MappingQual-
                                                            ityMethod
                                                            mapq_method)

```

const
Sorts mappings by score and store mapping quality of the optimal alignment in the *MultipathAlignment* object.

```

void vg::MultipathMapper::sort_and_compute_mapping_quality (vector<pair<MultipathAlignment,
                                                                    MultipathAlign-
                                                                    ment>> &multi-
                                                                    path_aln_pairs,
                                                                    vec-
                                                                    tor<pair<pair<size_t,
                                                                    size_t>, int64_t>>
                                                                    &cluster_pairs)

```

const
Sorts mappings by score and store mapping quality of the optimal alignment in the *MultipathAlignment*

object If there are ties between scores, breaks them by the expected distance between pairs as computed by the `OrientedDistanceClusterer::cluster_pairs` function (modified `cluster_pairs` vector)

```
double vg::MultipathMapper::fragment_length_log_likelihood(int64_t length) const
```

Computes the log-likelihood of a given fragment length in the trained distribution.

```
bool vg::MultipathMapper::likely_mismatching(const MultipathAlignment &multi-path_aln)
```

Would an alignment this good be expected against a graph this big by chance alone.

```
size_t vg::MultipathMapper::score_pseudo_length(int32_t score) const
```

A scaling of a score so that it approximately follows the distribution of the longest match in p-value test.

```
double vg::MultipathMapper::random_match_p_value(size_t match_length, size_t read_length)
```

The approximate p-value for a match length of the given size against the current graph.

```
int64_t vg::MultipathMapper::distance_between(const MultipathAlignment &multi-path_aln_1, const MultipathAlignment &multipath_aln_2) const
```

Compute the approximate distance between two multipath alignments.

```
bool vg::MultipathMapper::are_consistent(const MultipathAlignment &multi-path_aln_1, const MultipathAlignment &multipath_aln_2) const
```

Are two multipath alignments consistently placed based on the learned fragment length distribution?

```
bool vg::MultipathMapper::is_consistent(int64_t distance) const
```

Is this a consistent inter-pair distance based on the learned fragment length distribution?

```
double vg::MultipathMapper::read_coverage_z_score(int64_t coverage, const Alignment &alignment) const
```

Computes the Z-score of the number of matches against an equal length random DNA string.

```
bool vg::MultipathMapper::share_start_position(const MultipathAlignment &multi-path_aln_1, const MultipathAlignment &multipath_aln_2) const
```

Return true if any of the initial positions of the source Subpaths are shared between the two multipath alignments

Protected Attributes

```
SnarlManager *vg::MultipathMapper::snarl_manager
```

Protected Static Functions

```
int64_t vg::MultipathMapper::read_coverage(const memcluster_t &mem_hits)
```

Computes the number of read bases a cluster of MEM hits covers.

Protected Static Attributes

```
thread_local unordered_map<pair<size_t, size_t>, double> vg::MultipathMapper::p_value_memo
```


class *#include <handle.hpp>* This is the interface for a handle graph that supports modification. Inherits from *vg::HandleGraph* Subclassed by *vg::VG* **Public Functions**

virtual *handle_t* *vg::MutableHandleGraph::create_handle* (const string &*sequence*)
= 0Create a new node with the given sequence and return the handle.

virtual void *vg::MutableHandleGraph::destroy_handle* (const *handle_t* &*handle*)
= 0Remove the node belonging to the given handle and all of its edges. Does not update any stored paths.

virtual void *vg::MutableHandleGraph::create_edge* (const *handle_t* &*left*, const *handle_t* &*right*)
= 0Create an edge connecting the given handles in the given order and orientations. Ignores existing edges.

virtual void *vg::MutableHandleGraph::destroy_edge* (const *handle_t* &*left*, const *handle_t* &*right*)
= 0Remove the edge connecting the given handles in the given order and orientations. Ignores nonexistent edges. Does not update any stored paths.

virtual void *vg::MutableHandleGraph::swap_handles* (const *handle_t* &*a*, const *handle_t* &*b*)
= 0Swap the nodes corresponding to the given handles, in the ordering used by *for_each_handle* when looping over the graph. Other handles to the nodes being swapped must not be invalidated. If a swap is made while *for_each_handle* is running, it affects the order of the handles traversed during the current traversal (so swapping an already seen handle to a later handle's position will make the seen handle be visited again and the later handle not be visited at all).

virtual *handle_t* *vg::MutableHandleGraph::apply_orientation* (const *handle_t* &*handle*)
= 0Alter the node that the given handle corresponds to so the orientation indicated by the handle becomes the node's local forward orientation. Rewrites all edges pointing to the node and the node's sequence to reflect this. Invalidates all handles to the node (including the one passed). Returns a new, valid handle to the node in its new forward orientation. Note that it is possible for the node's ID to change. Does not update any stored paths.

virtual vector<*handle_t*> *vg::MutableHandleGraph::divide_handle* (const *handle_t* &*handle*, const vector<size_t> &*offsets*)
= 0Split a handle's underlying node at the given offsets in the handle's orientation. Returns all of the handles to the parts. Other handles to the node being split may be invalidated. The split pieces stay in the same local forward orientation as the original node, but the returned handles come in the order and orientation appropriate for the handle passed in. Updates stored paths.

pair<*handle_t*, *handle_t*> *vg::MutableHandleGraph::divide_handle* (const *handle_t* &*handle*, size_t *offset*)
Specialization of *divide_handle* for a single division point.

class *#include <name_mapper.hpp>* Class to do name mapping (or to mix in and provide name mapping functionality to other classes. Subclassed by *vg::Constructor*, *vg::VariantAdder* **Public Functions**

void *vg::NameMapper::add_name_mapping* (const string &*vcf_name*, const string &*fasta_name*)
Add a name mapping between a VCF contig name and a FASTA sequence name or graph path name. Both must be unique.

string *vg::NameMapper::vcf_to_fasta* (const string &*vcf_name*) const
Convert the given VCF contig name to a FASTA sequence or graph path name, through the rename mappings.

```
string vg::NameMapper::fasta_to_vcf(const string &fasta_name) const
```

Convert the given FASTA sequence name or graph path name to a VCF contig name, through the rename mappings.

Protected Attributes

```
map<string, string> vg::NameMapper::vcf_to_fasta_renames
```

This map maps from VCF sequence names to FASTA sequence names. If a VCF sequence name doesn't appear in here, it gets passed through unchanged.

```
map<string, string> vg::NameMapper::fasta_to_vcf_renames
```

This is the reverse map from FASTA sequence name to VCF sequence name.

class *#include <nested_traversal_finder.hpp>* This *TraversalFinder* emits at least one traversal representing every node, edge, or child *Snarl*. Only works on ultrabubbles, and so does not handle cycles. Inherits from *vg::TraversalFinder* **Public Functions**

```
vg::NestedTraversalFinder::NestedTraversalFinder(SupportAugmentedGraph
                                                  &augmented, SnarlManager
                                                  &snarl_manager)
```

```
virtual vg::NestedTraversalFinder::~NestedTraversalFinder()
```

```
vector<SnarlTraversal> vg::NestedTraversalFinder::find_traversals(const Snarl
                                                                &site)
```

Find traversals to cover the nodes, edges, and children of the snarl. Always emits the primary path traversal first, if applicable.

Public Members

```
bool vg::NestedTraversalFinder::verbose
```

Should we emit verbose debugging info?

Protected Functions

```
pair<Support, vector<Visit>> vg::NestedTraversalFinder::find_bubble(Node *node,
                                                                    Edge *edge,
                                                                    const Snarl
                                                                    *child, const
                                                                    Snarl &site)
```

Given an edge or node or child snarl in the augmented graph, look out from the edge or node or child in both directions to find a shortest bubble connecting the start and end of the given site.

Exactly one of edge and node and child must be non-null.

Return the found traversal as a vector of Visits, including anchoring Visits to the site's start and end nodes. Also return the minimum support found on any edge or node in the bubble that is not contained within a child.

If there is no path with any support, returns a zero *Support* and a possibly empty *Path*.

```
Support vg::NestedTraversalFinder::min_support_in_path(const vector<Visit>
                                                         &path)
```

Get the minimum support of all nodes and edges used in the given path that are not inside child snarls.

```
set<pair<size_t, list<Visit>>> vg::NestedTraversalFinder::search_left (const Visit
                                                                    &root, const
                                                                    Snarl &site)
```

Do a breadth-first search left from the given node traversal, and return lengths (in visits) and paths starting at the given node and ending on the given indexed path. Refuses to visit nodes with no support.

Lengths are included so that shorter paths sort first.

```
set<pair<size_t, list<Visit>>> vg::NestedTraversalFinder::search_right (const Visit
                                                                    &root, const
                                                                    Snarl &site)
```

Do a breadth-first search right from the given node traversal, and return lengths (in visits) and paths starting at the given node and ending on the given indexed path.

Lengths are included so that shorter paths sort first.

```
size_t vg::NestedTraversalFinder::bp_length (const list<Visit> &path)
```

Get the length of a path through nodes and child sites, in base pairs. Ignores any bases inside child sites.

Protected Attributes

```
SupportAugmentedGraph &vg::NestedTraversalFinder::augmented
```

The annotated, augmented graph we're finding traversals in.

```
SnarlManager &vg::NestedTraversalFinder::snarl_manager
```

The *SnarlManager* managing the snarls we use.

class *#include <snarls.hpp>* Allow traversing a graph of nodes and child snarl chains within a snarl within another *HandleGraph*. Uses its own internal child index because it's used in the construction of snarls to feed to *SnarlManagers*. Assumes that the chains we get from Cactus are in a consistent order, so the start of the first snarl is the very first thing in the chain, and the end of the last snarl is the very last. We adapt the handle graph abstraction as follows: A chain becomes a single node with the ID and local forward orientation of its first snarl's start. A chain node connects on its left to everything connected to its first start and on its right to everything connected to its last end. A unary snarl becomes a single node, too. It is identified by its boundary node's ID. If you're not using internal connectivity, a chain node or a unary snarl node behaves just like an ordinary node. If you are using internal connectivity, edges are slightly faked: A chain node also sees out its right everything that is out its left if it has a left-left connected snarl before any disconnected snarl. And similarly for the mirror case. All the edges on either side of a unary snarl node are the same. In this part of the code we talk about "heads" (the inward-facing base graph handles used to represent child snarls/chains), and "tails" (the inward-facing ending handles of child chains). Inherits from *vg::HandleGraph* **Public Functions**

```
template <typename ChainContainer>
```

```
vg::NetGraph::NetGraph (const Visit &start, const Visit &end, const ChainContainer
                        &child_chains_mixed, const HandleGraph *graph, bool
                        use_internal_connectivity = false)
```

Make a new *NetGraph* for the given snarl in the given backing graph, using the given chains as child chains. Unary snarls are stored as single-snarl chains just like other trivial chains.

```
template <typename ChainContainer, typename SnarlContainer>
```

```
vg::NetGraph::NetGraph (const Visit &start, const Visit &end, const ChainContainer
                        &child_chains, const SnarlContainer &child_unary_snarls, const Han-
                        dleGraph *graph, bool use_internal_connectivity = false)
```

Make a net graph from the given chains and unary snarls (as pointers) in the given backing graph.

```
vg::NetGraph::NetGraph (const Visit &start, const Visit &end, const vector<vector<Snarl>>
                        &child_chains, const vector<Snarl> &child_unary_snarls, const Han-
                        dleGraph *graph, bool use_internal_connectivity = false)
```

Make a net graph from the given chains and unary snarls (as raw values) in the given backing graph.

Mostly for testing.

handle_t vg::NetGraph::get_handle (const *id_t* &node_id, bool is_reverse = false) const

Look up the handle for the node with the given ID in the given orientation.

id_t vg::NetGraph::get_id (const *handle_t* &handle) const

Get the ID from a handle.

bool vg::NetGraph::get_is_reverse (const *handle_t* &handle) const

Get the orientation of a handle.

handle_t vg::NetGraph::flip (const *handle_t* &handle) const

Invert the orientation of a handle (potentially without getting its ID)

size_t vg::NetGraph::get_length (const *handle_t* &handle) const

Get the length of a node.

string vg::NetGraph::get_sequence (const *handle_t* &handle) const

Get the sequence of a node, presented in the handle's local forward orientation.

bool vg::NetGraph::follow_edges (const *handle_t* &handle, bool go_left, const func-
tion<bool> const &iteratee)

Loop over all the handles to next/previous (right/left) nodes. Passes them to a callback which returns false to stop iterating and true to continue. Returns true if we finished and false if we stopped early.

void vg::NetGraph::for_each_handle (const function<bool> const &iteratee)

Loop over all the nodes in the graph in their local forward orientations, in their internal stored order. Stop if the iteratee returns false.

size_t vg::NetGraph::node_size () const

Return the number of nodes in the graph.

const *handle_t* &vg::NetGraph::get_start () const

Get the inward-facing start handle for this net graph. Useful when working with traversals.

const *handle_t* &vg::NetGraph::get_end () const

Get the outward-facing end handle for this net graph. Useful when working with traversals.

bool vg::NetGraph::is_child (const *handle_t* &handle) const

Returns true if the given handle represents a meta-node for a child chain or unary snarl, and false if it is a normal node actually in the net graph snarl's contents.

handle_t vg::NetGraph::get_inward_backing_handle (const *handle_t* &child_handle)
const

Get the handle in the backing graph reading into the child chain or unary snarl in the orientation represented by this handle to a node representing a child chain or unary snarl.

Protected Functions

vg::NetGraph::NetGraph (const *Visit* &start, const *Visit* &end, const *HandleGraph* *graph, bool
use_internal_connectivity = false)

Make a *NetGraph* without filling in any of the child indexes.

void vg::NetGraph::add_unary_child (const *Snarl* *unary)

Add a unary child snarl to the indexes.

`void vg::NetGraph::add_chain_child(const Chain &chain)`
 Add a chain of one or more non-unary snarls to the index.

Protected Attributes

`const HandleGraph *vg::NetGraph::graph`

`handle_t vg::NetGraph::start`

`handle_t vg::NetGraph::end`

`bool vg::NetGraph::use_internal_connectivity`

`unordered_set<handle_t> vg::NetGraph::unary_boundaries`

`unordered_map<handle_t, handle_t> vg::NetGraph::chain_end_rewrites`

`unordered_map<handle_t, handle_t> vg::NetGraph::chain_ends_by_start`

`unordered_map<id_t, tuple<bool, bool, bool>> vg::NetGraph::connectivity`

`class #include <sampler.hpp>` Class that simulates reads with alignments to a graph that mimic the error profile of NGS sequencing data. **Public Functions**

`vg::NGSSimulator::NGSSimulator(xg::XG &xg_index, const string &ngs_fastq_file, bool interleaved_fastq = false, const vector<string> &source_paths = {}, double substitution_polymorphism_rate = 0.001, double indel_polymorphism_rate = 0.0002, double indel_error_proportion = 0.01, double insert_length_mean = 1000.0, double insert_length_stdev = 75.0, double error_multiplier = 1.0, bool retry_on_Ns = true, size_t seed = 0)`

Initialize simulator. FASTQ file will be used to train an error distribution. Most reads in the FASTQ should be the same length. Polymorphism rates apply uniformly along a read, whereas errors are distributed as indicated by the learned distribution. The simulation can also be restricted to named paths in the graph.

`Alignment vg::NGSSimulator::sample_read()`

Sample an individual read and alignment.

`pair<Alignment, Alignment> vg::NGSSimulator::sample_read_pair()`

Sample a pair of reads and alignments.

Private Functions

`vg::NGSSimulator::NGSSimulator(void)`

`void vg::NGSSimulator::record_read_quality(const Alignment &aln, bool read_2 = false)`
 Add a quality string to the training data.

`void vg::NGSSimulator::record_read_pair_quality(const Alignment &aln_1, const Alignment &aln_2)`
 Add a pair of quality strings to the training data.

`void vg::NGSSimulator::finalize()`
 Indicate that there is no more training data.

string vg::NGSSimulator::sample_read_quality()

Get a quality string that mimics the training data.

pair<string, string> vg::NGSSimulator::sample_read_quality_pair()

Get a pair of quality strings that mimic the training data.

string vg::NGSSimulator::sample_read_quality_internal (uint8_t first, vector<MarkovDistribution<uint8_t, uint8_t>> &transition_distrs)

Wrapped internal function for quality sampling.

void vg::NGSSimulator::sample_read_internal (Alignment &aln, size_t &offset, bool &is_reverse, pos_t &curr_pos, const string &source_path)

Internal method called by paired and unpaired samplers for both whole- graph and path sources. Offset and is_reverse are only used (and drive the iteration and update of curr_pos) in path node. Otherwise, in whole graph mode, they are ignored and curr_pos is used to traverse the graph directly.

void vg::NGSSimulator::sample_start_pos (size_t &offset, bool &is_reverse, pos_t &pos, string &source_path)

Sample an appropriate starting position according to the mode. Updates the arguments.

pos_t vg::NGSSimulator::sample_start_graph_pos()

Get a random position in the graph.

tuple<size_t, bool, pos_t, string> vg::NGSSimulator::sample_start_path_pos()

Get a random position along the source path.

string vg::NGSSimulator::get_read_name()

Get an unclashing read name.

bool vg::NGSSimulator::advance (size_t &offset, bool &is_reverse, pos_t &pos, char &graph_char, const string &source_path)

Move forward one position in either the source path or the graph, depending on mode. Update the arguments. Return true if we can't because we hit a tip or false otherwise

bool vg::NGSSimulator::advance_by_distance (size_t &offset, bool &is_reverse, pos_t &pos, size_t distance, const string &source_path)

Move forward a certain distance in either the source path or the graph, depending on mode. Update the arguments. Return true if we can't because we hit a tip or false otherwise

bool vg::NGSSimulator::advance_on_path (size_t &offset, bool &is_reverse, pos_t &pos, char &graph_char, const string &source_path)

Move forward one position in the source path, return true if we can't because we hit a tip or false otherwise

bool vg::NGSSimulator::advance_on_path_by_distance (size_t &offset, bool &is_reverse, pos_t &pos, size_t distance, const string &source_path)

Move forward a certain distance in the source path, return true if we can't because we hit a tip or false otherwise

bool vg::NGSSimulator::advance_on_graph (pos_t &pos, char &graph_char)

Move forward one position in the graph along a random path, return true if we can't because we hit a tip or false otherwise

```

bool vg::NGSSimulator::advance_on_graph_by_distance (pos_t &pos, size_t distance)
    Move forward a certain distance in the graph along a random path, return true if we can't because we hit a
    tip or false otherwise

pos_t vg::NGSSimulator::walk_backwards (const Path &path, size_t distance)
    Returns the position a given distance from the end of the path, walking backwards.

void vg::NGSSimulator::apply_deletion (Alignment &aln, const pos_t &pos)
    Add a deletion to the alignment.

void vg::NGSSimulator::apply_insertion (Alignment &aln, const pos_t &pos)
    Add an insertion to the alignment.

void vg::NGSSimulator::apply_aligned_base (Alignment &aln, const pos_t &pos, char
                                           graph_char, char read_char)
    Add a match/mismatch to the alignment.

```

Private Members

```

unordered_map<char, string> vg::NGSSimulator::mutation_alphabets
    Remainder of the alphabet after removing a given character.

vector<double> vg::NGSSimulator::phred_prob
    Memo for Phred -> probability conversion.

vector<MarkovDistribution<uint8_t, uint8_t>> vg::NGSSimulator::transition_distrs_1
    A Markov distribution for each read position.

vector<MarkovDistribution<uint8_t, uint8_t>> vg::NGSSimulator::transition_distrs_2
    A second set of Markov distributions for the second read in a pair.

MarkovDistribution<uint8_t, pair<uint8_t, uint8_t>> vg::NGSSimulator::joint_initial_distr
    A distribution for the joint initial qualities of a read pair.

xg::XG &vg::NGSSimulator::xg_index

LRUCache<id_t, Node> vg::NGSSimulator::node_cache

LRUCache<id_t, vector<Edge>> vg::NGSSimulator::edge_cache

default_random_engine vg::NGSSimulator::prng

discrete_distribution vg::NGSSimulator::path_sampler

vector<uniform_int_distribution<size_t>> vg::NGSSimulator::start_pos_samplers

uniform_int_distribution<uint8_t> vg::NGSSimulator::strand_sampler

uniform_int_distribution<size_t> vg::NGSSimulator::background_sampler

uniform_int_distribution<size_t> vg::NGSSimulator::mut_sampler

uniform_real_distribution<double> vg::NGSSimulator::prob_sampler

normal_distribution<double> vg::NGSSimulator::insert_sampler

const double vg::NGSSimulator::sub_poly_rate

```



```
const double vg::NGSSimulator::indel_poly_rate
const double vg::NGSSimulator::indel_error_prop
const double vg::NGSSimulator::insert_mean
const double vg::NGSSimulator::insert_sd
size_t vg::NGSSimulator::sample_counter
size_t vg::NGSSimulator::seed
const bool vg::NGSSimulator::retry_on_Ns
vector<string> vg::NGSSimulator::source_paths
    Restrict reads to just these paths (path-only mode) if nonempty.
```

Private Static Attributes

```
const string vg::NGSSimulator::alphabet
    DNA alphabet.
class #include <banded_global_aligner.hpp> This gets thrown when the aligner can't find any valid alignment
in the band that was requested. Inherits from exception Private Functions
```

```
const char *NoAlignmentInBandException::what() const
```

Private Static Attributes

```
const string NoAlignmentInBandException::message
struct Nodes store sequence data. Public Members
```

```
string vg::Node::sequence
    Sequence of DNA bases represented by the Node.
```

```
string vg::Node::name
    A name provides an identifier.
```

```
int64 vg::Node::id
    Each Node has a unique positive nonzero ID within its Graph.
```

```
struct #include <pileup_augmenter.hpp> Public Types
```

```
enum type vg::NodeDivider::EntryCat
    Values:
    = 0
```

```
typedef
typedef
```


Public Functions

```
void vg::NodeDivider::add_fragment (const Node *orig_node, int offset, Node *subnode, EntryCat cat, vector<StrandSupport> sup)

NodeDivider::Entry vg::NodeDivider::break_end (const Node *orig_node, VG *graph, int offset, bool left_side)

list<Mapping> vg::NodeDivider::map_node (int64_t node_id, int64_t start_offset, int64_t length, bool reverse)

void vg::NodeDivider::clear ()
```

Public Members

```
NodeHash vg::NodeDivider::index

int64_t *vg::NodeDivider::_max_id

struct Public Types
```

```
typedef
```

Public Functions

```
NodeLengthBuffer::NodeLengthBuffer (const xg::XG &xg_index)

size_t NodeLengthBuffer::operator () (xg::id_t id)
```

Public Members

```
const xg::XG &NodeLengthBuffer::index

std::vector<entry_type> NodeLengthBuffer::buffer

std::hash<xg::id_t> NodeLengthBuffer::hash
```

Public Static Attributes

```
const size_t NodeLengthBuffer::BUFFER_SIZE

struct Collect pileup records by node. Saves some space and hashing over storing individually, assuming not too sparse and avg. node length more than couple bases the ith BasePileup in the array corresponds to the position at offset i. Public Members
```

```
int64 vg::NodePileup::node_id

repeated<BasePileup> vg::NodePileup::base_pileup
```

class *#include <nodeside.hpp>* Represents one side of a *Node*, identified by ID, for the purposes of indexing edges. TODO: duplicates much of the functionality of *NodeTraversal*, and causes API duplication to accommodate both. There should only be one. **Public Functions**

```
vg::NodeSide::NodeSide (id_t node, bool is_end = false)
    Create a NodeSide for the given side of the given Node. We need this to be a converting constructor so we
    can represent the empty and deleted item keys in a pair_hash_map.
```

```
vg::NodeSide::NodeSide ()
    Create a NodeSide for no Node.
```

```
bool vg::NodeSide::operator== (const NodeSide &other) const
    Equality operator.
```

```
bool vg::NodeSide::operator!= (const NodeSide &other) const
    Inequality operator.
```

```
bool vg::NodeSide::operator< (const NodeSide &other) const
    Comparison operator for sets and maps.
```

```
NodeSide vg::NodeSide::flip (void) const
    Reverse complement the node side, obtaining the other side of the same Node.
```

```
Visit vg::NodeSide::to_visit () const
    Convert to a Visit.
```

Public Members

```
id_t vg::NodeSide::node
    What Node are we a side of?
```

```
bool vg::NodeSide::is_end
    Are we the end side? Or the start side?
```

Public Static Functions

```
static pair<NodeSide, NodeSide> vg::NodeSide::pair_from_edge (Edge *e)
    Make an edge into a canonically ordered pair of NodeSides.
```

```
static pair<NodeSide, NodeSide> vg::NodeSide::pair_from_edge (const Edge &e)
    Make an edge into a canonically ordered pair of NodeSides.
```

```
static pair<NodeSide, NodeSide> vg::NodeSide::pair_from_start_edge (id_t start_id, const
                                                                    pair<id_t,    bool>
                                                                    &oriented_other)
    Make a canonically ordered pair of NodeSides from an edge off of the start of a node, to another node in
    the given relative orientation.
```

```
static pair<NodeSide, NodeSide> vg::NodeSide::pair_from_end_edge (id_t end_id,    const
                                                                    pair<id_t,    bool>
                                                                    &oriented_other)
    Make a canonically ordered pair of NodeSides from an edge off of the end of a node, to another node in
    the given relative orientation.
```

class *#include <nodetraversal.hpp>* Represents a node traversed in a certain orientation. The default orientation is start to end, but if `backward` is set, represents the node being traversed end to start. A list of these can serve as an edit-free version of a path, especially if supplemented with a length and an initial node offset. A path node has a left and a right side, which are the start and end of the node if it is forward, or the end and start of the node if it is backward. **Public Functions**

```
vg::NodeTraversal::NodeTraversal (Node *node, bool backward = false)
```

Make a *NodeTraversal* that traverses the given *Node* in the given orientation. We don't want *Node*'s to turn into *NodeTraversals* when we aren't expecting it, so this is explicit.

```
vg::NodeTraversal::NodeTraversal ()
```

Create a *NodeTraversal* of no node.

```
bool vg::NodeTraversal::operator== (const NodeTraversal &other) const
```

Equality operator.

```
bool vg::NodeTraversal::operator!= (const NodeTraversal &other) const
```

Inequality operator.

```
bool vg::NodeTraversal::operator< (const NodeTraversal &other) const
```

Comparison operator for sorting in sets and maps. Make sure to sort by node ID and not pointer value, because people will expect that.

```
NodeTraversal vg::NodeTraversal::reverse (void) const
```

Reverse complement the node traversal, returning a traversal of the same node in the opposite direction.

Public Members

```
Node *vg::NodeTraversal::node
```

What *Node* is being traversed?

```
bool vg::NodeTraversal::backward
```

In what orientation is it being traversed?

class *#include <cluster.hpp>* **Public Functions**

```
vg::OrientedDistanceClusterer::OEdge::OEdge (size_t to_idx, int32_t weight)
```

```
vg::OrientedDistanceClusterer::OEdge::OEdge ()
```

```
vg::OrientedDistanceClusterer::OEdge::~~OEdge ()
```

Public Members

```
size_t vg::OrientedDistanceClusterer::OEdge::to_idx
```

Index of the node that the edge points to.

```
int32_t vg::OrientedDistanceClusterer::OEdge::weight
```

Weight for dynamic programming.

class *#include <cluster.hpp>* **Public Functions**

```
vg::OrientedDistanceClusterer::ODNode::ODNode (const MaximalExactMatch &mem,
pos_t start_pos, int32_t score)
```

```
vg::OrientedDistanceClusterer::ODNode::ODNode()
vg::OrientedDistanceClusterer::ODNode::~~ODNode()
```

Public Members

```
const MaximalExactMatch *vg::OrientedDistanceClusterer::ODNode::mem

pos_t vg::OrientedDistanceClusterer::ODNode::start_pos
    Position of GCSA hit in the graph.

int32_t vg::OrientedDistanceClusterer::ODNode::score
    Score of the exact match this node represents.

int32_t vg::OrientedDistanceClusterer::ODNode::dp_score
    Score used in dynamic programming.

vector<ODEdge> vg::OrientedDistanceClusterer::ODNode::edges_from
    Edges from this node that are colinear with the read.

vector<ODEdge> vg::OrientedDistanceClusterer::ODNode::edges_to
    Edges to this node that are colinear with the read.
template <typename Value, typename Parser = OptionValueParser<Value>>
class #include <option.hpp> Represents an option for a type with no extra methods.
Inherits from vg::BaseOption< Value, Parser >
```

Public Functions

```
vg::Option::Option()

virtual vg::Option::~~Option()
template <typename Item, typename Parser>
class
class vg::Option<vector<Item>, Parser>
    #include <option.hpp> Specialize and add vector methods. TODO: magically autodetect if a container type has
    things and expose them. TODO: switch to operator* and operator->.
Inherits from vg::BaseOption< vector< Item >, Parser >
```

Public Types

```
using
```

Public Functions

```
using vg::Option<vector<Item>, Parser>::Value = vector<Item>                                vg::Option::Opti

virtual vg::Option::~~Option()

size_t vg::Option::size() const
```

```

bool vg::Option::empty() const

Value::value_type &vg::Option::at(size_t i)

const Value::value_type &vg::Option::at(size_t i) const

Value::iterator vg::Option::begin()

Value::iterator vg::Option::end()

Value::const_iterator vg::Option::begin() const

```

```
Value::const_iterator vg::Option::end() const
```

class *#include <option.hpp>* All of the option templates inherit from this base class, which the command-line parser uses to feed them strings. Subclassed by *vg::BaseOption< bool, OptionValueParser< bool > >*, *vg::BaseOption< double, OptionValueParser< double > >*, *vg::BaseOption< int64_t, OptionValueParser< int64_t > >*, *vg::BaseOption< size_t, OptionValueParser< size_t > >*, *vg::BaseOption< string, OptionValueParser< string > >*, *vg::BaseOption< vector< Item >, Parser >*, *vg::BaseOption< vector< size_t >, OptionValueParser< vector< size_t > > >*, *vg::BaseOption< vector< string >, OptionValueParser< vector< string > > >*, *vg::BaseOption< Value, Parser >* **Public Functions**

```
virtual const string &vg::OptionInterface::get_long_option() const
    = 0Get the long option text without , like “foos-to-bar”.
```

```
virtual const string &vg::OptionInterface::get_short_options() const
    = 0Gets a list of short option characters that the option wants, in priority order. If none of these are available, the option will be automatically assigned some other free character.
```

```
virtual const string &vg::OptionInterface::get_description() const
    = 0Get the description, like “number of foos to bar per frobnitz”.
```

```
virtual string vg::OptionInterface::get_default_value() const
    = 0Get the default value as a string. May be generated on the fly.
```

```
virtual bool vg::OptionInterface::has_argument() const
    = 0Returns true if the option takes an argument, and false otherwise.
```

```
virtual void vg::OptionInterface::parse()
    = 0Called for no-argument options when the parser encounters them.
```

```
virtual void vg::OptionInterface::parse(const string &arg)
    = 0Called for argument-having options when the parser encounters them. The passed reference is only valid during the function call, so the option should make a copy.
```

```
virtual vg::OptionInterface::~~OptionInterface()
    Everyone needs a virtual destructor!
```

```
template <typename Value>
```

```
class #include <option.hpp> This class holds static methods explaining how to parse a type.
```

Public Functions

```
template <>
```

```
bool vg::OptionValueParser::has_argument()
    Bool options don't need arguments.
```

```
template <>
```

```
void vg::OptionValueParser::parse_default (const bool &default_value, bool &value)
```

When someone gives a bool option they mean to invert its default value.

```
template <>
```

```
void vg::OptionValueParser::parse (const string &arg, bool &value)
```

If someone gives a value to a bool, explode.

```
template <>
```

```
string vg::OptionValueParser::unparse (const bool &value)
```

Represent default values for bools as true and false.

Public Static Functions

```
static bool vg::OptionValueParser::has_argument ()
```

Return true if we need an argument and false otherwise.

```
static void vg::OptionValueParser::parse_default (const Value &default_value, Value  
                                                  &value)
```

Parse from no argument, but a default value.

```
static void vg::OptionValueParser::parse (const string &arg, Value &value)
```

Parse from an argument.

```
static string vg::OptionValueParser::unparse (const Value &value)
```

Stringify a default value.

```
template <typename Item>
```

```
class
```

```
class vg::OptionValueParser<vector<Item>>
```

```
#include <option.hpp> For vector options, we recurse.
```

Public Static Functions

```
static bool vg::OptionValueParser::has_argument ()
```

Return true if we need an argument and false otherwise.

```
static void vg::OptionValueParser::parse_default (const vector<Item> &default_value,  
                                                  vector<Item> &value)
```

Parse from no argument, but a default value.

```
static void vg::OptionValueParser::parse (const string &arg, vector<Item> &value)
```

Parse from an argument.

```
static string vg::OptionValueParser::unparse (const vector<Item> &value)
```

Stringify a default value.

```
class #include <cluster.hpp> Public Types
```

using Each hit contains a pointer to the original MEM and the position of that particular hit in the graph.

using Each cluster is a vector of hits.

using A memo for the results of *XG::oriented_paths_of_node*.

using A memo for the results of *XG::get_handle*.

Public Functions

```
vg::OrientedDistanceClusterer::OrientedDistanceClusterer (const Align-
ment &align-
ment, const vector<MaximalExactMatch>
&mems, const
QualAdjAligner
&aligner, xg::XG
*xgindex, size_t
max_expected_dist_approx_error
= 8, size_t
min_mem_length
= 1,
node_occurrence_on_paths_memo_t
*paths_of_node_memo
= nullptr, han-
dle_memo_t
*handle_memo
= nullptr)
```

Constructor using *QualAdjAligner*, optionally memoizing succinct data structure operations.

```
vg::OrientedDistanceClusterer::OrientedDistanceClusterer (const Align-
ment &align-
ment, const vector<MaximalExactMatch>
&mems, const
Aligner &aligner,
xg::XG *xgin-
dex, size_t
max_expected_dist_approx_error
= 8, size_t
min_mem_length
= 1,
node_occurrence_on_paths_memo_t
*paths_of_node_memo
= nullptr, han-
dle_memo_t
*handle_memo
= nullptr)
```

Constructor using *Aligner*, optionally memoizing succinct data structure operations.

```
vector<OrientedDistanceClusterer::cluster_t> vg::OrientedDistanceClusterer::clusters (int32_t
max_qual_score
=
60,
int32_t
log_likelihood_approx
=
0)
```

Returns a vector of clusters. Each cluster is represented a vector of MEM hits. Each hit contains a pointer to the original MEM and the position of that particular hit in the graph.

Public Static Functions

```
vector<pair<pair<size_t, size_t>, int64_t>> vg::OrientedDistanceClusterer::pair_clusters (const  
    Align-  
    ment  
    &align-  
    ment_1,  
    const  
    Align-  
    ment  
    &align-  
    ment_2,  
    const  
    vec-  
    tor<cluster_t  
    *>  
    &left_clusters,  
    const  
    vec-  
    tor<cluster_t  
    *>  
    &right_clusters,  
    xg::XG  
    *xgin-  
    dex,  
    int64_t  
    min_inter_cluster  
    int64_t  
    max_inter_cluster  
    node_occurrence  
    *paths_of_node_  
    =  
    nullptr,  
    han-  
    dle_memo_t  
    *han-  
    dle_memo  
    =  
    nullptr)
```

Given two vectors of clusters, an xg index, an bounds on the distance between clusters, returns a vector of pairs of cluster numbers (one in each vector) matched with the estimated distance

Private Functions

```
vg::OrientedDistanceClusterer::OrientedDistanceClusterer (const Align-
                                                                ment
                                                                &align-
                                                                ment, const vec-
                                                                tor<MaximalExactMatch>
                                                                &mems, const
                                                                Aligner *aligner,
                                                                const Qual-
                                                                AdjAligner
                                                                *qual_adj_aligner,
                                                                xg::XG *xgin-
                                                                dex, size_t
                                                                max_expected_dist_approx_error,
                                                                size_t
                                                                min_mem_length,
                                                                node_occurrence_on_paths_memo_t
                                                                *paths_of_node_memo,
                                                                handle_memo_t
                                                                *handle_memo)
```

Internal constructor that public constructors filter into.

```
vector<pair<size_t, size_t>> vg::OrientedDistanceClusterer::compute_tail_mem_coverage (const Align-
                                                                                          ment
                                                                                          &align-
                                                                                          ment,
                                                                                          const
                                                                                          vec-
                                                                                          tor<MaximalE
                                                                                          &mems)
```

Returns a vector containing the number of SMEM beginnings to the left and the number of SMEM endings to the right of each read position

```
void vg::OrientedDistanceClusterer::identify_sources_and_sinks (vector<size_t>
                                                                &sources_out,
                                                                vec-
                                                                tor<size_t>
                                                                &sinks_out)
```

Fills input vectors with indices of source and sink nodes.

```
void vg::OrientedDistanceClusterer::connected_components (vector<vector<size_t>>
                                                                &components_out)
```

Identify weakly connected components in the graph.

```
void vg::OrientedDistanceClusterer::topological_order (vector<size_t>
                                                                &or-
                                                                der_out)
```

Fills the input vector with the indices of a topological sort.

```
void vg::OrientedDistanceClusterer::perform_dp ()
```

Perform dynamic programming and store scores in nodes.

Private Members

```
vector<ODNode> vg::OrientedDistanceClusterer::nodes
```

```
const Aligner *vg::OrientedDistanceClusterer::aligner
```

```
const QualAdjAligner *vg::OrientedDistanceClusterer::qual_adj_aligner
```

Private Static Functions

```
unordered_map<pair<size_t, size_t>, int64_t> vg::OrientedDistanceClusterer::get_on_strand_distance_t
```

> *&get_position*, **const** function<int64_t, size_t> *&get_offset*, *node_occurrence_on_paths_memo_t* **paths_of_node_memo* = nullptr, *handle_memo_t* **handle_memo* = nullptr Given a certain number of items, and a callback to get each item's position, and a callback to a fixed offset from that position build a distance forest with trees for items that we can verify are on the same strand of the same molecule.

We use the distance approximation to cluster the MEM hits according to the strand they fall on using the oriented distance estimation function in `xg`.

Returns a map from item pair (lower number first) to distance (which may be negative) from the first to the second along the items' forward strand.

```

void vg::OrientedDistanceClusterer::extend_dist_tree_by_permutations (int64_t
                                                                    max_failed_distance_probes,
                                                                    int64_t
                                                                    max_search_distance_to_parents,
                                                                    size_t
                                                                    decrement_frequency,
                                                                    size_t
                                                                    &num_possible_merges_rejected,
                                                                    Union-Find
                                                                    &component_union_find,
                                                                    unordered_map<pair<size_t,
                                                                    size_t>,
                                                                    int64_t>
                                                                    &recorded_finite_dists,
                                                                    map<pair<size_t,
                                                                    size_t>,
                                                                    size_t>
                                                                    &num_infinite_dists,
                                                                    size_t
                                                                    num_items,
                                                                    xg::XG
                                                                    *xg_index,
                                                                    const
                                                                    function<pos_t> size_t
                                                                    > &get_position, const function<int64_t size_t> &get_offset, node_occurrence_on_paths_memo_t
                                                                    *paths_of_node_memo = nullptr, handle_memo_t *handle_memo = nullptr)
Add edges into the distance
tree by estimating the distance between pairs generated by a high entropy deterministic permutation

```

```

void vg::OrientedDistanceClusterer::extend_dist_tree_by_path_buckets (int64_t
                                                                    max_failed_distance_probes
                                                                    size_t
                                                                    &num_possible_merges_remo
                                                                    Union-
                                                                    Find
                                                                    &com-
                                                                    po-
                                                                    nent_union_find,
                                                                    un-
                                                                    ordered_map<pair<size_t,
                                                                    size_t>,
                                                                    int64_t>
                                                                    &recorded_finite_dists,
                                                                    map<pair<size_t,
                                                                    size_t>,
                                                                    size_t>
                                                                    &num_infinite_dists,
                                                                    size_t
                                                                    num_items,
                                                                    xg::XG
                                                                    *xgin-
                                                                    dex,
                                                                    const
                                                                    func-
                                                                    tion<pos_t> size_t
                                                                    > &get_position, const function<int64_tsize_t> &get_offset, node_occurrence_on_paths_memo_t
                                                                    *paths_of_node_memo = nullptr, handle_memo_t *handle_memo = nullptr)
    Adds edges into the distance
    tree by estimating the distance only between pairs of items that can be directly inferred to share a path
    based on the memo of node occurrences on paths

```

```

vector<unordered_map<size_t, int64_t>> vg::OrientedDistanceClusterer::flatten_distance_tree (size_t
                                                                    num_items,
                                                                    const
                                                                    un-
                                                                    ordered
                                                                    size_t>
                                                                    int64_t,
                                                                    &recon

```

Given a number of nodes, and a map from node pair to signed relative distance on a consistent strand (defining a forrest of trees, as generated by *get_on_strand_distance_tree()*), flatten all the trees.

Returns a vector of maps from node ID to relative position in linear space, one map per input tree.

Assumes all the distances are transitive, even though this isn't quite true in graph space.

class *#include <packer.hpp>* **Public Functions**

```

vg::Packer::Packer (void)

vg::Packer::Packer (xg::XG *idx, size_t bin_size)

vg::Packer::~~Packer (void)

void vg::Packer::merge_from_files (const vector<string> &file_names)

void vg::Packer::merge_from_dynamic (vector<Packer *> &packers)

```

```

void vg::Packer::load_from_file (const string &file_name)

void vg::Packer::save_to_file (const string &file_name)

void vg::Packer::load (istream &in)

size_t vg::Packer::serialize (std::ostream &out, sdsl::structure_tree_node *s = NULL,
                               std::string name = "")

void vg::Packer::make_compact (void)

void vg::Packer::make_dynamic (void)

void vg::Packer::add (const Alignment &aln, bool record_edits = true)

size_t vg::Packer::graph_length (void) const

size_t vg::Packer::position_in_basis (const Position &pos) const

string vg::Packer::pos_key (size_t i) const

string vg::Packer::edit_value (const Edit &edit, bool revcomp) const

vector<Edit> vg::Packer::edits_at_position (size_t i) const

size_t vg::Packer::coverage_at_position (size_t i) const

void vg::Packer::collect_coverage (const Packer &c)

ostream &vg::Packer::as_table (ostream &out, bool show_edits = true)

ostream &vg::Packer::show_structure (ostream &out)

void vg::Packer::write_edits (vector<ofstream*> &out) const

void vg::Packer::write_edits (ostream &out, size_t bin) const

size_t vg::Packer::get_bin_size (void) const

size_t vg::Packer::get_n_bins (void) const

bool vg::Packer::is_dynamic (void)

```

Public Members

```
xg::XG*vg::Packer::xgidx
```

Private Functions

```

void vg::Packer::ensure_edit_tmpfiles_open (void)

void vg::Packer::close_edit_tmpfiles (void)

void vg::Packer::remove_edit_tmpfiles (void)

size_t vg::Packer::bin_for_position (size_t i) const

string vg::Packer::escape_delim (const string &s, char d) const

```

```
string vg::Packer::escape_delims (const string &s) const
string vg::Packer::unescape_delim (const string &s, char d) const
string vg::Packer::unescape_delims (const string &s) const
```

Private Members

```
bool vg::Packer::is_compacted
gcsa::CounterArray vg::Packer::coverage_dynamic
vector<string> vg::Packer::edit_tmpfile_names
vector<ofstream*> vg::Packer::tmpfstreams
size_t vg::Packer::n_bins
size_t vg::Packer::bin_size
size_t vg::Packer::edit_length
size_t vg::Packer::edit_count
dac_vector vg::Packer::coverage_civ
vector<csa_sada<enc_vector<>, 32, 32, sa_order_sa_sampling<>, isa_sampling<>, succinct_byte_alphabet<>>> vg::Packer
char vg::Packer::delim1
char vg::Packer::delim2
class #include <packer.hpp> Inherits from vector< Packer > Private Functions
```

```
void vg::Packers::load (const vector<string> &file_names)
ostream &vg::Packers::as_table (ostream &out)
template <typename K, typename V>
class #include <hash_map.hpp> Inherits from google::dense_hash_map< K, V, std::hash< K > >
```

Public Functions

```
vg::pair_hash_map::pair_hash_map ()
template <typename K, typename V>
class #include <hash_map_set.hpp> Inherits from google::sparse_hash_map< K, V, std::hash< K > >
```

Public Functions

```
xg::pair_hash_map::pair_hash_map ()
template <typename K>
class #include <hash_map_set.hpp> Inherits from google::sparse_hash_set< K, std::hash< K > >
```

Public Functions

`xg::pair_hash_set::pair_hash_set()`

struct *Paths* are walks through nodes defined by a series of *Edits*. They can be used to represent: haplotypes mappings of reads, or alignments, by including edits relationships between nodes annotations from other data sources, such as: genes, exons, motifs, transcripts, peaks

Public Members

`string vg::Path::name`

The name of the path. *Path* names starting with underscore (`_`) are reserved for internal *VG* use.

`repeated<Mapping> vg::Path::mapping`

The *Mappings* which describe the order and orientation in which the *Path* visits *Nodes*.

`bool vg::Path::is_circular`

Set to true if the path is circular.

`int64 vg::Path::length`

Optional length annotation for the *Path*.

class `#include <genotypekit.hpp>` Inherits from `vg::TraversalFinder` **Public Functions**

`vg::PathBasedTraversalFinder::PathBasedTraversalFinder (vg::VG &graph, SnarlManager &sm)`

virtual `vg::PathBasedTraversalFinder::~~PathBasedTraversalFinder()`

`vector<SnarlTraversal> vg::PathBasedTraversalFinder::find_traversals (const Snarl &site)`

Private Members

`vg::VG &vg::PathBasedTraversalFinder::graph`

`SnarlManager &vg::PathBasedTraversalFinder::snarlmanager`

class `#include <chunker.hpp>` Chunk up a graph along a path, using a given number of context expansion steps to fill out the chunks. Most of the work done by existing *xg* functions. For *gams*, the *rocksdb* index is also required. **Public Functions**

`vg::PathChunker::PathChunker (xg::XG *xg = NULL)`

`vg::PathChunker::~~PathChunker()`

`void vg::PathChunker::extract_subgraph (const Region ®ion, int context, int length, bool forward_only, VG &subgraph, Region &out_region)`

Extract subgraph corresponding to given path region into its own *vg* graph, and send it to *out_stream*. The boundaries of the extracted graph (which can be different because we expand context and don't cut nodes) are written to *out_region*. If *forward_only* set, context is only expanded in the forward direction

NOTE: we follow convention of *Region* coordinates being 1-based inclusive.

```
void vg::PathChunker::extract_id_range(vg::id_t start, vg::id_t end, int context, int
                                     length, bool forward_only, VG &subgraph, Re-
                                     gion &out_region)
```

Like above, but use (inclusive) id range instead of region on path.

```
int64_t vg::PathChunker::extract_gam_for_subgraph(VG &subgraph, Index &in-
                                                  dex, ostream *out_stream, bool
                                                  only_fully_contained = false, bool
                                                  search_all_positions = false, bool
                                                  unsorted_index = false)
```

Extract all alignments that touch a node in a subgraph and write them to an output stream using the rocksdb index (and this->gam_buffer_size)

```
int64_t vg::PathChunker::extract_gam_for_ids(vector<vg::id_t> &graph_ids, Index
                                             &index, ostream *out_stream, bool
                                             contiguous_id_range = false, bool
                                             only_fully_contained = false, bool
                                             search_all_positions = false, bool un-
                                             sorted_index = false)
```

More general interface used by above two functions

Public Members

```
xg::XG *vg::PathChunker::xg
```

```
size_t vg::PathChunker::gam_buffer_size
```

struct #include <path_index.hpp> Holds indexes of the reference in a graph: position to node, node to position and orientation, and the full reference string. Also knows about the lengths of nodes on the path, and lets you iterate back and forth over it. **Public Types**

using We keep iterators to node occurrences along the ref path.

Public Functions

```
vg::PathIndex::PathIndex(const Path &path)
    Index just a path.
```

```
vg::PathIndex::PathIndex(const list<Mapping> &mappings)
    Index just a list of mappings.
```

```
vg::PathIndex::PathIndex(const list<Mapping> &mappings, VG &vg)
    Index a list of mappings embedded in the given vg's Paths object, and pull sequence from the given vg.
```

```
vg::PathIndex::PathIndex(const Path &path, const xg::XG &vg)
    Index a path and pull sequence from an XG index.
```

```
vg::PathIndex::PathIndex(VG &vg, const string &path_name, bool extract_sequence = false)
    Make a PathIndex from a path in a graph.
```

```
vg::PathIndex::PathIndex(const xg::XG &index, const string &path_name, bool ex-
    tract_sequence = false)
    Make a PathIndex from a path in an indexed graph.
```


`void vg::PathIndex::update_mapping_positions (VG &vg, const string &path_name)`
 Rebuild the mapping positions map by tracing all the paths in the given graph. TODO: We ought to move this functionality to the *Paths* object and make it use a good datastructure instead of brute force.

NodeSide `vg::PathIndex::at_position (size_t position) const`
 Find what node and orientation covers a position. The position must not be greater than the path length.

`bool vg::PathIndex::path_contains_node (int64_t node_id)`

PathIndex::iterator `vg::PathIndex::begin () const`
 Get the iterator to the first node occurrence on the indexed path.

PathIndex::iterator `vg::PathIndex::end () const`
 Get the iterator to the last node occurrence on the indexed path.

PathIndex::iterator `vg::PathIndex::find_position (size_t position) const`
 Find the iterator at the given position along the ref path. The position must not be greater than the path length.

`size_t vg::PathIndex::node_length (const iterator &here) const`
 Get the length of the node occurrence on the path represented by this iterator.

`pair<size_t, size_t> vg::PathIndex::round_outward (size_t start, size_t past_end) const`
 Given an end-exclusive range on the path, round outward to the nearest node boundary positions.

`void vg::PathIndex::apply_translation (const Translation &translation)`
 Update the index to reflect the changes described by a *Translation*. References to nodes along the “from” path are changed to references to nodes along the “to” path. The translation must contain two paths of equal length, containing only matches. The translation must only divide nodes; it may not join nodes together. The translation must fully account for each old node that it touches (it can’t translate only part of a node). The translation may not re-use the ID from one original node for a piece of a different original node. All the Mappings in the *Translation* must have Edits.

`void vg::PathIndex::apply_translations (const vector<Translation> &translations)`
 Update the index to reflect the changes described by the given collection of Translations. These translations are expected to be in the format produced by *VG::edit()* which is one to *Mapping* per translation. The vector may include both forward and reverse versions of each to node, and may also include translations mapping nodes that did not change to themselves.

Public Members

`map<int64_t, pair<size_t, bool>> vg::PathIndex::by_id`
Index from node ID to first position on the reference string and orientation it occurs there.

`map<size_t, NodeSide> vg::PathIndex::by_start`
Index from start position on the reference to the side of the node that begins there. If it is a right side, the node occurs on the path in a reverse orientation.

`std::string vg::PathIndex::sequence`
 The actual sequence of the path, if desired.

`map<const Mapping *, size_t> vg::PathIndex::mapping_positions`
Index from *Mapping* pointers in a *VG Paths* object to their actual positions along their paths. Pointers may dangle if the vg graph changes the path.

Protected Functions

map<id_t, vector<Mapping>> vg::PathIndex::parse_translation(const Translation &translation)

Convert a *Translation* that partitions old nodes into a map from old node ID to the Mappings that replace it in its forward orientation.

void vg::PathIndex::replace_occurrence(iterator to_replace, const vector<Mapping> &replacements)

Given an iterator into `by_start`, replace the occurrence of the node there with occurrences of the nodes given in the vector of mappings, which partition the forward strand of the node being replaced.

Protected Attributes

size_t vg::PathIndex::last_node_length

This, combined with `by_start`, gets us the length of every node on the indexed path.

map<id_t, vector<iterator>> vg::PathIndex::node_occurrences

This holds all the places that a particular node occurs, in order. TODO: use this to replace by_id

class #include <path.hpp>Public Functions

vg::Paths::Paths(void)

vg::Paths::Paths(const Paths &other)

vg::Paths::Paths(Paths &&other)

Paths &vg::Paths::operator=(const Paths &other)

Paths &vg::Paths::operator=(Paths &&other)

void vg::Paths::sort_by_mapping_rank(void)

void vg::Paths::rebuild_mapping_aux(void)

Reassign ranks and rebuild indexes, treating the mapping lists in `_paths` as the truth.

bool vg::Paths::is_head_or_tail_node(id_t id)

vector<string> vg::Paths::all_path_names(void)

void vg::Paths::make_circular(const string &name)

void vg::Paths::make_linear(const string &name)

void vg::Paths::rebuild_node_mapping(void)

list<Mapping>::iterator vg::Paths::find_mapping(Mapping *m)

list<Mapping>::iterator vg::Paths::remove_mapping(Mapping *m)

list<Mapping>::iterator vg::Paths::insert_mapping(list<Mapping>::iterator w, const string &path_name, const Mapping &m)

pair<Mapping *, Mapping *> vg::Paths::divide_mapping(Mapping *m, const Position &pos)

pair<Mapping *, Mapping *> vg::Paths::divide_mapping(Mapping *m, size_t offset)

```

pair<Mapping *, Mapping *> vg::Paths::replace_mapping (Mapping *m, pair<Mapping, Mapping> n)

void vg::Paths::remove_paths (const set<string> &names)

void vg::Paths::remove_path (const string &name)

void vg::Paths::keep_paths (const set<string> &name)

void vg::Paths::remove_node (id_t id)

bool vg::Paths::has_path (const string &name)

void vg::Paths::to_json (ostream &out)

list<Mapping> &vg::Paths::get_path (const string &name)

list<Mapping> &vg::Paths::get_create_path (const string &name)

list<Mapping> &vg::Paths::create_path (const string &name)

bool vg::Paths::has_mapping (const string &name, size_t rank)

bool vg::Paths::has_node_mapping (id_t id)

bool vg::Paths::has_node_mapping (Node *n)

map<string, set<Mapping *>> &vg::Paths::get_node_mapping (Node *n)

map<string, set<Mapping *>> &vg::Paths::get_node_mapping (id_t id)

map<string, map<int, Mapping *>> &vg::Paths::get_node_mappings_by_rank (id_t id)

map<string, map<int, Mapping *>> &vg::Paths::get_node_mapping_copies_by_rank (id_t
                                                                    id)

Mapping *vg::Paths::traverse_left (Mapping *mapping)

Mapping *vg::Paths::traverse_right (Mapping *mapping)

const string vg::Paths::mapping_path_name (Mapping *m)

set<string> vg::Paths::of_node (id_t id)

map<string, int> vg::Paths::node_path_traversal_counts (id_t id, bool rev = false)

vector<string> vg::Paths::node_path_traversals (id_t id, bool rev = false)

bool vg::Paths::are_consecutive_nodes_in_path (id_t id1, id_t id2, const string
                                                                    &path_name)

vector<string> vg::Paths::over_edge (id_t id1, bool rev1, id_t id2, bool rev2, vector<string> fol-
                                                                    lowing)

vector<string> vg::Paths::over_directed_edge (id_t id1, bool rev1, id_t id2, bool rev2, vec-
                                                                    tor<string> following)

size_t vg::Paths::size (void) const

bool vg::Paths::empty (void) const

void vg::Paths::clear (void)

```

```
void vg::Paths::clear_mapping_ranks (void)

void vg::Paths::compact_ranks (void)

void vg::Paths::load (istream &in)

void vg::Paths::write (ostream &out)

void vg::Paths::to_graph (Graph &g)
    Add all paths into the given Protobuf graph. Creates a new path for every path.

Path vg::Paths::path (const string &name)

void vg::Paths::append_mapping (const string &name, const Mapping &m)

void vg::Paths::append_mapping (const string &name, id_t id, size_t rank = 0, bool is_reverse
                                = false)

void vg::Paths::prepend_mapping (const string &name, const Mapping &m)

void vg::Paths::prepend_mapping (const string &name, id_t id, size_t rank = 0, bool is_reverse
                                = false)

size_t vg::Paths::get_next_rank (const string &name)

void vg::Paths::append (Paths &p)

void vg::Paths::append (Graph &g)

void vg::Paths::extend (Paths &p)

void vg::Paths::extend (const Path &p)

void vg::Paths::for_each (const function<void> const Path&
                        > &lambda)

void vg::Paths::for_each_name (const function<void> const string&
                              > &lambda)

void vg::Paths::for_each_stream (istream &in, const function<void> Path&
                                > &lambda)

void vg::Paths::increment_node_ids (id_t inc)

void vg::Paths::swap_node_ids (hash_map<id_t, id_t> &id_mapping)

void vg::Paths::reassign_node (id_t new_id, Mapping *m)

void vg::Paths::for_each_mapping (const function<void> Mapping *
                                > &lambda)
```

Public Members

```
map<string, list<Mapping>> vg::Paths::_paths

map<Mapping *, list<Mapping>::iterator> vg::Paths::mapping_itr

map<Mapping *, string> vg::Paths::mapping_path

map<string, map<size_t, Mapping *>> vg::Paths::mappings_by_rank
```

```
map<id_t, map<string, set<Mapping *>>> vg::Paths::node_mapping
```

```
set<id_t> vg::Paths::head_tail_nodes
```

```
set<string> vg::Paths::circular
```

class *#include <phased_genome.hpp>* A collection of haplotypes that represent all of the chromosomes of a genome (including phasing) as walks through a variation graph. Designed for fast editing at a site level, so it maintains indices of sites for that purpose. **Public Functions**

```
vg::PhasedGenome::PhasedGenome (SnarlManager &snarl_manager)
    Constructor.
```

```
vg::PhasedGenome::~~PhasedGenome ()
```

```
template <typename NodeTraversalIterator>
```

```
int vg::PhasedGenome::add_haplotype (NodeTraversalIterator first, NodeTraversalIterator
    last)
```

Build a haplotype in place from an iterator that returns *NodeTraversal* objects from its dereference operator (allows construction without instantiating the haplotype elsewhere) returns the numerical id of the new haplotype

note: the haplotype must have at least one node

```
void vg::PhasedGenome::build_indices ()
```

Construct the site ends, node locations, and haplotype site location indices. This method is intended to be called one time after building haplotypes. After this, the are maintained automatically during edit operations.

```
size_t vg::PhasedGenome::num_haplotypes ()
```

```
PhasedGenome::iterator vg::PhasedGenome::begin (int which_haplotype)
```

Unidirectional iterator starting at the left telomere and moving to the right. Requires a haplotype id as input

```
PhasedGenome::iterator vg::PhasedGenome::end (int which_haplotype)
```

Iterator representing the past-the-last position of the given haplotype, with the last position being the right telomere node.

```
void vg::PhasedGenome::swap_alleles (const Snarl &site, int haplotype_1, int haplotype_2)
```

Swap the allele from between two haplotypes, maintaining all indices. If a nested site is being swapped, this method should be called only once for the top-most site. Child sites are swapped along with the top-most site automatically.

```
template <typename NodeTraversalIterator>
```

```
void vg::PhasedGenome::set_allele (const Snarl &site, NodeTraversalIterator first, Node-
    TraversalIterator last, int which_haplotype)
```

Set the allele at a site with an iterator that yields its node sequence. The allele should be provided in the order indicated by the *Snarl* (i.e. from start to end) and it should not include the boundary nodes of the *Snarl*.

Note: This method does not check that the allele path takes only edges that are actually included in the graph, so client must ensure this itself.

```
int32_t vg::PhasedGenome::optimal_score_on_genome (const MultipathAlignment &multi-
    path_aln, VG &graph)
```

Private Functions

```
void vg::PhasedGenome::build_site_indices_internal (const Snarl *snarl)
```

```
void vg::PhasedGenome::insert_left (NodeTraversal node_traversal, HaplotypeNode
                                     *haplo_node)
    Insert a node traversal to the left of this haplotype node and update indices.
```

```
void vg::PhasedGenome::insert_right (NodeTraversal node_traversal, HaplotypeNode
                                     *haplo_node)
    Insert a node traversal to the right of this haplotype node and update indices.
```

```
void vg::PhasedGenome::remove (HaplotypeNode *haplo_node)
    Remove this haplotype node from its haplotype and update indices.
```

```
void vg::PhasedGenome::swap_label (const Snarl &site, Haplotype &haplotype_1, Haplotype
                                   &haplotype_2)
    Update a subsite's location in indices after swapping its parent allele.
```

Private Members

```
SnarlManager &vg::PhasedGenome::snarl_manager
```

```
vector<Haplotype *> vg::PhasedGenome::haplotypes
    All haplotypes in the genome (generally 2 per chromosome)
```

```
unordered_map<int64_t, list<HaplotypeNode *>> vg::PhasedGenome::node_locations
    Index of where nodes from the graph occur in the phased genome.
```

```
unordered_map<int64_t, const Snarl *> vg::PhasedGenome::site_starts
    Index of which nodes are starts of Snarls.
```

```
unordered_map<int64_t, const Snarl *> vg::PhasedGenome::site_ends
    Index of which nodes are ends of Snarls.
```

```
class #include <phase_duplicator.hpp> Transforms complex subregions of a graph into collections of disconnected distinct traversal haplotypes. Requires an xg index with a gPBWT in order to work. Public Functions
```

```
vg::PhaseDuplicator::PhaseDuplicator (const xg::XG &index)
    Make a new PhaseDuplicator backed by the given index with gPBWT.
```

```
pair<Graph, vector<Translation>> vg::PhaseDuplicator::duplicate (const set<id_t> &sub-
                                                                graph, id_t &next_id)
                                                                const
```

Duplicate out the subgraph induced by the given set of node IDs. Border nodes of the subgraph, which edges out to the rest of the graph will be identified, and all unique traversals from one border node to another will be generated as new nodes, with edges connecting them to material outside the graph and Translations embedding them in the original graph.

TODO: also generate one-end-anchored traversals and internal not- attached-to-a-border traversals, because there may be phase breaks in the region.

New IDs will be generated startign with next_id, and next_id will be updated to the next ID after the IDs of all generated material.

TODO: invent some kind of thread safe ID allocator so we can do multiple subgraphs in parallel without renumbering later.

```
vector<pair< xg::XG::thread_t, int>> vg::PhaseDuplicator::list_haplotypes (const
                                                                    set<id_t>
                                                                    &subgraph)
                                                                    const
```

List all the distinct haplotypes within a subgraph and their counts. Reports each haplotype in only one direction.

```
vector<pair< xg::XG::thread_t, int>> vg::PhaseDuplicator::list_haplotypes_through (xg::XG::ThreadMapping
                                                                    start_node,
                                                                    const
                                                                    set<id_t>
                                                                    &sub-
                                                                    graph)
                                                                    const
```

List all the distinct haplotypes going through the given node in the given orientation, and staying within the given subgraph, along with their counts. Some may be suffixes of others.

```
vector<pair< xg::XG::thread_t, int>> vg::PhaseDuplicator::list_haplotypes_from (xg::XG::ThreadMapping
                                                                    start_node,
                                                                    const
                                                                    set<id_t>
                                                                    &sub-
                                                                    graph)
                                                                    const
```

List all the distinct haplotypes actually beginning at the given node in the given orientation, and staying within the given subgraph, along with their counts. Haplotypes that begin and end at the same side may or may not be reported multiple times, in differing orientations.

```
vector<pair< xg::XG::thread_t, int>> vg::PhaseDuplicator::list_haplotypes (xg::XG::ThreadMapping
                                                                    start_node,
                                                                    xg::XG::ThreadSearchState
                                                                    start_state,
                                                                    const
                                                                    set<id_t>
                                                                    &subgraph)
                                                                    const
```

List all the distinct haplotypes beginning at the given node, using the given starting search state, that traverse through the subgraph.

```
set<xg::XG::ThreadMapping> vg::PhaseDuplicator::find_borders (const set<id_t> sub-
                                                                    graph) const
```

Get the traversals that represent the borders of the subgraph, through which we can enter the subgraph.

```
vector<Edge> vg::PhaseDuplicator::find_border_edges (xg::XG::ThreadMapping map-
                                                                    ping, bool on_start, const
                                                                    set<id_t> &subgraph) const
```

Find the edges on the given side of the given oriented ThreadMapping that cross the border of the given subgraph.

Public Static Functions

```
xg::XG::ThreadMapping vg::PhaseDuplicator::traverse_edge (const Edge &e, const
                                                                    xg::XG::ThreadMapping
                                                                    &prev)
```

Follow the given edge from the given node visited in the given orientation, and return the node and orientation we land in.

TODO: I think I may have written this logic already with one of the other two oriented node types (*NodeTraversal* and *NodeSide*).

`xg::XG::thread_t` `vg::PhaseDuplicator::canonicalize(const xg::XG::thread_t &thread)`

Return a copy of the given thread in a canonical orientation (either forward or reverse, whichever compares smaller).

Private Members

`const xg::XG &vg::PhaseDuplicator::index`

What XG index describes the graph we operate on?

`class #include <pictographs.hpp>` **Public Functions**

`vg::Pictographs::Pictographs` (void)

`vg::Pictographs::Pictographs` (int *seed_val*)

`vg::Pictographs::~~Pictographs` (void)

string `vg::Pictographs::hashed` (const string &*str*)

string `vg::Pictographs::hashed_char` (const string &*str*)

string `vg::Pictographs::random` (void)

Public Members

`const string` `vg::Pictographs::symbols`

`const int` `vg::Pictographs::symbol_count`

`const string` `vg::Pictographs::chars`

`const int` `vg::Pictographs::char_count`

Private Members

mt19937 `vg::Pictographs::rng`

`struct` Bundle up *Node* and *Edge* pileups. **Public Members**

repeated<*NodePileup*> `vg::Pileup::node_pileups`

repeated<*EdgePileup*> `vg::Pileup::edge_pileups`

`class #include <pileup_augmenter.hpp>` Super simple graph augmentor/caller. Idea: Independently process *Pileup* records, using simple model to make calls that take into account read errors with diploid assumption. Edges and node positions are called independently for now. Outputs either a sample graph (only called nodes and edges) or augmented graph (include uncalled nodes and edges too). **Public Types**

`typedef`

`typedef`

`typedef`


```
typedef
typedef
```

Public Functions

```
vg::PileupAugmenter::PileupAugmenter(VG *graph, int default_quality = De-
                                     fault_default_quality, int min_aug_support =
                                     Default_min_aug_support)

vg::PileupAugmenter::~~PileupAugmenter()

void vg::PileupAugmenter::clear()

void vg::PileupAugmenter::write_augmented_graph(ostream &out, bool json)

void vg::PileupAugmenter::call_node_pileup(const NodePileup &pileup)

void vg::PileupAugmenter::call_edge_pileup(const EdgePileup &pileup)

void vg::PileupAugmenter::update_augmented_graph()

void vg::PileupAugmenter::map_path(const Path &base_path, list<Mapping> &aug_path,
                                   bool expect_edits)

void vg::PileupAugmenter::apply_mapping_edits(const Mapping &base_mapping,
                                               list<Mapping> &aug_mappings)

void vg::PileupAugmenter::map_paths()

void vg::PileupAugmenter::verify_path(const Path &in_path, const list<Mapping>
                                     &call_path)

void vg::PileupAugmenter::call_base_pileup(const NodePileup &np, int64_t offset, bool
                                           insertions)

void vg::PileupAugmenter::compute_top_frequencies(const BasePileup &bp,
                                                  const vector<pair<int64_t,
int64_t>> &base_offsets, string
&top_base, int &top_count, int
&top_rev_count, string &sec-
ond_base, int &second_count,
int &second_rev_count, int
&total_count, bool inserts)

double vg::PileupAugmenter::total_base_quality(const BasePileup &pb, const
vector<pair<int64_t, int64_t>>
&base_offsets, const string &val)

void vg::PileupAugmenter::create_node_calls(const NodePileup &np)

void vg::PileupAugmenter::create_augmented_edge(Node *node1, int from_offset, bool
left_side1, bool aug1, Node *node2,
int to_offset, bool left_side2, bool
aug2, char cat, StrandSupport sup-
port)

void vg::PileupAugmenter::annotate_augmented_node(Node *node, char call, Strand-
Support support, int64_t orig_id,
int orig_offset)
```

```
void vg::PileupAugmenter::annotate_augmented_edge(Edge *edge, char call, StrandSupport support)

void vg::PileupAugmenter::annotate_augmented_nodes()

void vg::PileupAugmenter::annotate_non_augmented_nodes()
```

Public Members

```
VG *vg::PileupAugmenter::_graph

SupportAugmentedGraph vg::PileupAugmenter::_augmented_graph

vector<Genotype> vg::PileupAugmenter::_node_calls

vector<pair<StrandSupport, StrandSupport>> vg::PileupAugmenter::_node_supports

vector<Genotype> vg::PileupAugmenter::_insert_calls

vector<pair<StrandSupport, StrandSupport>> vg::PileupAugmenter::_insert_supports

const Node *vg::PileupAugmenter::_node

int64_t vg::PileupAugmenter::_max_id

NodeDivider vg::PileupAugmenter::_node_divider

unordered_set<int64_t> vg::PileupAugmenter::_visited_nodes

unordered_map<pair<NodeSide, NodeSide>, StrandSupport> vg::PileupAugmenter::_called_edges

EdgeHash vg::PileupAugmenter::_augmented_edges

InsertionHash vg::PileupAugmenter::_inserted_nodes

EdgeSupHash vg::PileupAugmenter::_insertion_supports

EdgeSupHash vg::PileupAugmenter::_deletion_supports

int vg::PileupAugmenter::_buffer_size

char vg::PileupAugmenter::_default_quality

int vg::PileupAugmenter::_min_aug_support
```

Public Static Functions

```
static double vg::PileupAugmenter::safe_log(double v)

static bool vg::PileupAugmenter::missing_call(const Genotype &g)

static bool vg::PileupAugmenter::ref_call(const Genotype &g)

static int vg::PileupAugmenter::call_cat(const Genotype &g)
```

Public Static Attributes

```
const double vg::PileupAugmenter::Log_zero
```

```
const char vg::PileupAugmenter::Default_default_quality
```

```
const int vg::PileupAugmenter::Default_min_aug_support
```

class *#include <pileup.hpp>* This is a collection of protobuf *NodePileup* records that are indexed on their position, as well as *EdgePileup* records. *Pileups* can be merged and streamed, and computed from Alignments. The pileup records themselves are essentially protobuf versions of lines in Samtools pileup format, with deletions represented using a graph-based notation. **Public Types**

```
typedef
```

```
typedef
```

Public Functions

```
vg::Pileups::Pileups (VG *graph, int min_quality = 0, int max_mismatches = 1, int window_size  
                    = 0, int max_depth = 1000, bool use_mapq = false)
```

```
vg::Pileups::Pileups (const Pileups &other)  
    copy constructor
```

```
vg::Pileups::Pileups (Pileups &&other)  
    move constructor
```

```
Pileups &vg::Pileups::operator= (const Pileups &other)  
    copy assignment operator
```

```
Pileups &vg::Pileups::operator= (Pileups &&other)  
    move assignment operator
```

```
vg::Pileups::~~Pileups ()  
    delete contents of table
```

```
void vg::Pileups::clear ()
```

```
void vg::Pileups::to_json (ostream &out)  
    write to JSON
```

```
void vg::Pileups::load (istream &in)  
    read from protobuf
```

```
void vg::Pileups::write (ostream &out, uint64_t buffer_size = 5)  
    write to protobuf
```

```
void vg::Pileups::for_each_node_pileup (const function<void> NodePileup&  
    > &lambda) apply function to each pileup in table
```

```
NodePileup *vg::Pileups::get_node_pileup (int64_t node_id)  
    search hash table for node id
```

```
NodePileup *vg::Pileups::get_create_node_pileup (const Node *node)  
    get a pileup. if it's null, create a new one and insert it.
```

`void vg::Pileups::for_each_edge_pileup (const function<void> EdgePileup&
> &lambda`

`EdgePileup *vg::Pileups::get_edge_pileup (pair<NodeSide, NodeSide> sides)`
search hash table for edge id

`EdgePileup *vg::Pileups::get_create_edge_pileup (pair<NodeSide, NodeSide> sides)`
get a pileup. if it's null, create a new one and insert it.

`void vg::Pileups::extend (Pileup &pileup)`

`bool vg::Pileups::insert_node_pileup (NodePileup *pileup)`
insert a pileup into the table. it will be deleted by `~Pileups()`!!! return true if new pileup inserted, false if merged into existing one

`bool vg::Pileups::insert_edge_pileup (EdgePileup *edge_pileup)`

`void vg::Pileups::compute_from_alignment (Alignment &alignment)`
create / update all pileups from a single alignment

`void vg::Pileups::compute_from_edit (NodePileup &pileup, int64_t &node_offset, int64_t
&read_offset, const Node &node, const Align-
ment &alignment, const Mapping &mapping, const
Edit &edit, const Edit *next_edit, const vec-
tor<int> &mismatch_counts, pair<const Mapping
*, int64_t> &last_match, pair<const Mapping *,
int64_t> &last_del, pair<const Mapping *, int64_t>
&open_del)`
create / update all pileups from an edit (called by above). query stores the current position (and nothing else).

`bool vg::Pileups::pass_filter (const Alignment &alignment, int64_t read_offset, int64_t
length, const vector<int> &mismatches) const`
check base quality as well as miss match filter

`Pileups &vg::Pileups::merge (Pileups &other)`
move all entries in other object into this one. if two positions collide, they are merged. other will be left empty. this is returned

`BasePileup &vg::Pileups::merge_base_pileups (BasePileup &p1, BasePileup &p2)`
merge p2 into p1 and return 1. p2 is left an empty husk

`NodePileup &vg::Pileups::merge_node_pileups (NodePileup &p1, NodePileup &p2)`
merge p2 into p1 and return 1. p2 is left an empty husk

`EdgePileup &vg::Pileups::merge_edge_pileups (EdgePileup &p1, EdgePileup &p2)`
merge p2 into p1 and return 1. p2 is left an empty husk

`char vg::Pileups::combined_quality (char base_quality, int map_quality) const`
create combine map quality (optionally) with base quality

Public Members

`VG *vg::Pileups::_graph`

`NodePileupHash vg::Pileups::_node_pileups`
This maps from *Position* to *Pileup*.

EdgePileupHash vg::Pileups::_edge_pileups

int vg::Pileups::_min_quality
Ignore bases with quality less than this.

int vg::Pileups::_max_mismatches
max mismatches within window_size

int vg::Pileups::_window_size
number of bases to scan in each direction for mismatches

int vg::Pileups::_max_depth
prevent giant protobufs

bool vg::Pileups::_use_mapq
toggle whether we incorporate *Alignment.mapping_quality*

uint64_t vg::Pileups::_min_quality_count
Keep count of bases filtered by quality.

uint64_t vg::Pileups::_max_mismatch_count
keep count of bases filtered by mismatches

uint64_t vg::Pileups::_bases_count
overall count for perspective on above

Public Static Functions

void vg::Pileups::count_mismatches (VG &graph, const Path &path, vector<int> &mismatches, bool skipIndels = false)
do one pass to count all mismatches in read, so we can do mismatch filter efficiently in 2nd path. mismatches[i] stores number of mismatches in range (0, i)

static BasePileup *vg::Pileups::get_base_pileup (NodePileup &np, int64_t offset)
get ith *BasePileup* record

static const BasePileup *vg::Pileups::get_base_pileup (const NodePileup &np, int64_t offset)
set)

static BasePileup *vg::Pileups::get_create_base_pileup (NodePileup &np, int64_t offset)
set)
get ith *BasePileup* record, create if doesn't exist

void vg::Pileups::parse_base_offsets (const BasePileup &bp, vector<pair<int64_t, int64_t>> &offsets)
the bases string in *BasePileup* doesn't allow random access. This function will parse out all the offsets of snps, insertions, and deletions into one array, each offset is a pair of indexes in the bases and qualities arrays

void vg::Pileups::casify (string &seq, bool is_reverse)
transform case of every character in string

void vg::Pileups::make_match (string &seq, int64_t from_length, bool is_reverse)
make the sam pileup style token

void vg::Pileups::make_insert (string &seq, bool is_reverse)

```

void vg::Pileups::make_delete(string &seq, bool is_reverse, const pair<const Mapping *,
int64_t> &last_match, const Mapping &mapping, int64_t
node_offset)

void vg::Pileups::make_delete(string &seq, bool is_reverse, int64_t from_id, int64_t
from_offset, bool from_start, int64_t to_id, int64_t to_offset,
bool to_end)

void vg::Pileups::parse_insert(const string &tok, int64_t &len, string &seq, bool
&is_reverse)

void vg::Pileups::parse_delete(const string &tok, bool &is_reverse, int64_t &from_id,
int64_t &from_offset, bool &from_start, int64_t &to_id,
int64_t &to_offset, bool &to_end)

bool vg::Pileups::base_equal(char c1, char c2, bool is_reverse)

char vg::Pileups::extract_match(const BasePileup &bp, int64_t offset)
    get a pileup value on forward strand

string vg::Pileups::extract(const BasePileup &bp, int64_t offset)
    get arbitrary value from offset on forward strand

```

struct #include <vg.hpp> Structure for managing parallel construction of a graph. **Public Functions**

```

vg::VG::Plan::Plan(VG *graph, map<long, vector<vcflib::VariantAllele>> &&alleles,
map<pair<long, int>, vector<bool>> &&phase_visits, map<pair<long,
int>, vector<pair<string, int>>> &&variant_alts, string seq, string name)

```

Public Members

VG *vg::VG::Plan::graph

map<long, vector<vcflib::VariantAllele>> vg::VG::Plan::alleles

map<pair<long, int>, vector<bool>> vg::VG::Plan::phase_visits

map<pair<long, int>, vector<pair<string, int>>> vg::VG::Plan::variant_alts

string vg::VG::Plan::seq

string vg::VG::Plan::name

struct A position in the graph is a node, direction, and offset. The node is stored by ID, and the offset is 0-based and counts from the start of the node in the specified orientation. The direction specifies which orientation of the node we are considering, the forward (as stored) or reverse complement. Example:

```

seq+      G A T T A C A
offset+   → 0 1 2 3 4 5 6 7

seq-      C T A A T G T
offset-   → 0 1 2 3 4 5 6 7

```

Or both at once:

```

offset-    7 6 5 4 3 2 1 0 ←
seq+      G A T T A C A
offset+   → 0 1 2 3 4 5 6 7

```

Public Members

int64 vg::Position::node_id

The *Node* on which the *Position* is.

int64 vg::Position::offset

The offset into that node's sequence at which the *Position* occurs.

bool vg::Position::is_reverse

True if we obtain the original sequence of the path by reverse complementing the mappings.

string vg::Position::name

If the position is used to represent a position against a reference path.

class #include <support_caller.hpp> We use this to represent a contig in the primary path, with its index and coverage info. **Public Functions**

vg::SupportCaller::PrimaryPath::PrimaryPath (SupportAugmentedGraph &augmented,
const string &ref_path_name, size_t
ref_bin_size)

Index the given path in the given augmented graph, and compute all the coverage bin information with the given bin size.

const Support &vg::SupportCaller::PrimaryPath::get_support_at (size_t primary_path_offset)
const

Get the support at the bin appropriate for the given primary path offset.

size_t vg::SupportCaller::PrimaryPath::get_bin_index (size_t primary_path_offset)
const

Get the index of the bin that the given path position falls in.

size_t vg::SupportCaller::PrimaryPath::get_min_bin () const

Get the bin with minimal coverage.

size_t vg::SupportCaller::PrimaryPath::get_max_bin () const

Get the bin with maximal coverage.

const Support &vg::SupportCaller::PrimaryPath::get_bin (size_t bin) const

Get the support in the given bin.

size_t vg::SupportCaller::PrimaryPath::get_total_bins () const

Get the total number of bins that the path is divided into.

Support vg::SupportCaller::PrimaryPath::get_average_support () const

Get the average support over the path.

Support vg::SupportCaller::PrimaryPath::get_total_support () const

Get the total support for the path.

PathIndex &vg::SupportCaller::PrimaryPath::get_index ()

Get the *PathIndex* for this primary path.

const PathIndex &vg::SupportCaller::PrimaryPath::get_index () const

Get the *PathIndex* for this primary path.

const string &vg::SupportCaller::PrimaryPath::get_name () const

Gets the path name we are representing.

Public Static Functions

Support `vg::SupportCaller::PrimaryPath::get_average_support (const map<string, PrimaryPath> &paths)`

Get the average support over a collection of paths.

Protected Attributes

`size_t vg::SupportCaller::PrimaryPath::ref_bin_size`
How wide is each coverage bin along the path?

PathIndex `vg::SupportCaller::PrimaryPath::index`
This holds the index for this path.

`string vg::SupportCaller::PrimaryPath::name`
This holds the name of the path.

`vector<Support> vg::SupportCaller::PrimaryPath::binned_support`
What's the expected in each bin along the path? Coverage gets split evenly over both strands.

`size_t vg::SupportCaller::PrimaryPath::min_bin`
Which bin has min support?

`size_t vg::SupportCaller::PrimaryPath::max_bin`
Which bin has max support?

Support `vg::SupportCaller::PrimaryPath::total_support`
What's the total *Support* over every bin?

class `#include <progressive.hpp>` Inherit from this class to give your class *create_progress()*, *update_progress()*, and *destroy_progress()* methods, and a public *show_progress* field that can be toggled on and off. Must not be destroyed while a progress bar is active. Subclassed by *vg::BaseMapper*, *vg::Constructor*, *vg::Simplifier*, *vg::VariantAdder*, *vg::VG* **Public Functions**

`void vg::Progressive::preload_progress (const string &message)`
If no progress bar is currently displayed, set the message to use for the next progress bar to be created. Does nothing if *show_progress* is false or when a progress bar is displayed.

Public so that users of a class can provide descriptive messages for generic progress operations (like *VG*'s *for_each_kmer_parallel*).

`void vg::Progressive::create_progress (const string &message, long count)`
Create a progress bar showing the given message, with the given number of items to process. Does nothing if *show_progress* is false. Replaces any existing progress bar.

`void vg::Progressive::create_progress (long count)`
Create a progress bar with the given number of items to process, using either a default message, or the message passed to the last *preload_progress* call since a progress bar was destroyed. Does nothing if *show_progress* is false. Replaces any existing progress bar.

`void vg::Progressive::update_progress (long i)`
Update the progress bar, noting that the given number of items have been processed. Does nothing if no progress bar is displayed.


```
void vg::Progressive::increment_progress ()
    Update the progress bar, noting that one additional item has been processed. Does nothing if no progress
    bar is displayed.
```

```
void vg::Progressive::destroy_progress (void)
    Destroy the current progress bar, if it exists.
```

Public Members

```
bool vg::Progressive::show_progress
```

Private Members

```
string vg::Progressive::progress_message
```

```
long vg::Progressive::progress_count
```

```
long vg::Progressive::last_progress
```

```
long vg::Progressive::progress_seen
```

```
ProgressBar *vg::Progressive::progress
```

```
template <typename T>
class #include <stream.hpp>
```

Public Functions

```
stream::ProtobufIterator::ProtobufIterator (std::istream &in)
    Constructor.
```

```
bool stream::ProtobufIterator::has_next ()
```

```
void stream::ProtobufIterator::get_next ()
```

```
T stream::ProtobufIterator::operator* ()
```

Private Functions

```
void stream::ProtobufIterator::handle (bool ok)
```

Private Members

```
T stream::ProtobufIterator::value
```

```
uint64_t stream::ProtobufIterator::where
```

```
uint64_t stream::ProtobufIterator::chunk_count
```

```
uint64_t stream::ProtobufIterator::chunk_idx
```

```
google::protobuf::io::InputStream stream::ProtobufIterator::raw_in
```

google::protobuf::io::GzipInputStream stream::ProtobufIterator::**gzip_in**

google::protobuf::io::CodedInputStream stream::ProtobufIterator::**coded_in**

class *#include <gssw_aligner.hpp>* An aligner that uses read base qualities to adjust its scores and alignments. Inherits from *vg::BaseAligner* **Public Functions**

```
QualAdjAligner::QualAdjAligner(int8_t _match = default_match, int8_t _mismatch = de-
                                fault_mismatch, int8_t _gap_open = default_gap_open,
                                int8_t _gap_extension = default_gap_extension, int8_t
                                _full_length_bonus = default_full_length_bonus, int8_t
                                _max_scaled_score = default_max_scaled_score, uint8_t
                                _max_qual_score = default_max_qual_score, double
                                gc_content = default_gc_content)
```

```
vg::QualAdjAligner::~~QualAdjAligner(void)
```

```
void QualAdjAligner::align(Alignment &alignment, Graph &g, bool traceback_aln, bool
                           print_score_matrices)
```

Store optimal local alignment against a graph in the *Alignment* object. Gives the full length bonus separately on each end of the alignment. Assumes that graph is topologically sorted by node index.

```
void QualAdjAligner::align_global_banded(Alignment &alignment, Graph &g, int32_t
                                           band_padding = 0, bool permissive_banding =
                                           true)
```

```
void QualAdjAligner::align_pinned(Alignment &alignment, Graph &g, bool pin_left)
```

```
void QualAdjAligner::align_global_banded_multi(Alignment &alignment, vector<Alignment>
                                                &alt_alignments, Graph &g, int32_t max_alt_alns,
                                                int32_t band_padding = 0, bool
                                                permissive_banding = true)
```

```
void QualAdjAligner::align_pinned_multi(Alignment &alignment, vector<Alignment>
                                         &alt_alignments, Graph &g, bool pin_left,
                                         int32_t max_alt_alns)
```

```
void vg::QualAdjAligner::init_mapping_quality(double gc_content)
```

```
int32_t QualAdjAligner::score_exact_match(const Alignment &aln, size_t read_offset,
                                           size_t length)
```

Compute the score of an exact match in the given alignment, from the given offset, of the given length.

```
int32_t QualAdjAligner::score_exact_match(const string &sequence, const string
                                           &base_quality) const
```

Compute the score of an exact match of the given sequence with the given qualities. Qualities may be ignored by some implementations.

```
int32_t QualAdjAligner::score_exact_match(string::const_iterator seq_begin,
                                           string::const_iterator seq_end,
                                           string::const_iterator base_qual_begin)
const
```

Compute the score of an exact match of the given range of sequence with the given qualities. Qualities may be ignored by some implementations.

Public Members

uint8_t vg::QualAdjAligner::max_qual_score

int8_t vg::QualAdjAligner::scale_factor

Private Functions

```
void QualAdjAligner::align_internal (Alignment &alignment, vector<Alignment>
                                     *multi_alignments, Graph &g, bool pinned, bool
                                     pin_left, int32_t max_alt_alns, bool traceback_aln,
                                     bool print_score_matrices)
```

class #include <readfilter.hpp>**Public Functions**

int vg::ReadFilter::filter (istream *alignment_stream, xg::XG *index = nullptr)

Filter the alignments available from the given stream, placing them on standard output or in the appropriate file. Returns 0 on success, exit code to use on error.

If an XG index is required, use the specified one. If one is required and not provided, the function will complain and return nonzero.

TODO: Refactor to be less CLI-aware and more modular-y.

bool vg::ReadFilter::trim_ambiguous_ends (xg::XG *index, Alignment &alignment, int k)

Look at either end of the given alignment, up to k bases in from the end. See if that tail of the alignment is mapped such that another embedding in the given graph can produce the same sequence as the sequence along the embedding that the read actually has, and if so trim back the read.

In the case of softclips, the aligned portion of the read is considered, and if trimmign is required, the softclips are hard-clipped off.

Returns true if the read had to be modified, and false otherwise.

MUST NOT be called with a null index.

Public Members

double vg::ReadFilter::min_secondary

double vg::ReadFilter::min_primary

bool vg::ReadFilter::frac_score

bool vg::ReadFilter::sub_score

int vg::ReadFilter::max_overhang

int vg::ReadFilter::min_end_matches

int vg::ReadFilter::context_size

bool vg::ReadFilter::verbose

double vg::ReadFilter::min_mapq

int vg::ReadFilter::repeat_size

```

int vg::ReadFilter::defray_length
int vg::ReadFilter::defray_count
bool vg::ReadFilter::drop_split
int vg::ReadFilter::threads
string vg::ReadFilter::regions_file
string vg::ReadFilter::outbase
bool vg::ReadFilter::append_regions

```

Private Functions

```

bool vg::ReadFilter::has_repeat (Alignment &aln, int k)
    * quick and dirty filter to see if removing reads that can slip around and still map perfectly helps vg call.
    returns true if at either end of read sequence, at least k bases are repetitive, checking repeats of up to size
    2k

bool vg::ReadFilter::trim_ambiguous_end (xg::XG *index, Alignment &alignment, int k)
    Trim only the end of the given alignment, leaving the start alone. Two calls of this implement
    trim_ambiguous_ends above.

bool vg::ReadFilter::is_split (xg::XG *index, Alignment &alignment)
    Return false if the read only follows edges in the xg index, and true if the read is split (or just incorrect)
    and takes edges not in the index.

    Throws an error if no XG index is specified.

```

class `#include <genotypekit.hpp>` Inherits from `vg::TraversalFinder` **Public Functions**

```

vg::ReadRestrictedTraversalFinder::ReadRestrictedTraversalFinder (VG
                                                                &graph,
                                                                Snarl-
                                                                Man-
                                                                ager
                                                                &snarl_manager,
                                                                const
                                                                map<string,
                                                                Align-
                                                                ment *>
                                                                &reads_by_name,
                                                                int
                                                                min_recurrence
                                                                = 2, int
                                                                max_path_search_steps
                                                                = 100)

vg::ReadRestrictedTraversalFinder::~ReadRestrictedTraversalFinder ()

vector<SnarlTraversal> vg::ReadRestrictedTraversalFinder::find_traversals (const
                                                                Snarl
                                                                &site)

```

For the given site, emit all traversals with unique sequences that run from start to end, out of the paths in the graph. Uses the map of reads by name to determine if a path is a read or a real named path. *Paths*

through the site supported only by reads are subject to a min recurrence count, while those supported by actual embedded named paths are not.

Private Members

VG &vg::ReadRestrictedTraversalFinder::graph

SnarlManager &vg::ReadRestrictedTraversalFinder::snarl_manager

const map<string, *Alignment* *> &vg::ReadRestrictedTraversalFinder::reads_by_name

int vg::ReadRestrictedTraversalFinder::min_recurrence

int vg::ReadRestrictedTraversalFinder::max_path_search_steps

struct #include <region.hpp> **Public Members**

string vg::Region::seq

int64_t vg::Region::start

int64_t vg::Region::end

struct #include <genome_state.hpp> We can use this to replace a local haplotype within one or more snarls. We also could just express all the deletions and insertions in terms of this. Inherits from *vg::GenomeStateCommand*

Public Functions

GenomeStateCommand *vg::ReplaceLocalHaplotypeCommand::execute (*GenomeState* &state) const

Execute this command on the given state and return the reverse command. Generally ends up calling a command-type-specific method on the *GenomeState* that does the actual work.

virtual vg::ReplaceLocalHaplotypeCommand::~ReplaceLocalHaplotypeCommand()

Public Members

unordered_map<const *Snarl* *, vector<size_t>> vg::ReplaceLocalHaplotypeCommand::deletions

Holds, for each snarl, the overall lanes that have to be deleted. Each deleted overall lane for a snarl that is still traversed from its parent needs to be replaced in insertions. Deletions happen first.

unordered_map<const *Snarl* *, vector<vector<pair<*handle_t*, size_t>>>> vg::ReplaceLocalHaplotypeCommand::insertions

Holds, for each *Snarl*, the visits and their lane assignments that have to be inserted.

struct #include <genome_state.hpp> Inherits from *vg::GenomeStateCommand* **Public Functions**

GenomeStateCommand *vg::ReplaceSnarlHaplotypeCommand::execute (*GenomeState* &state) const

Execute this command on the given state and return the reverse command. Generally ends up calling a command-type-specific method on the *GenomeState* that does the actual work.

virtual vg::ReplaceSnarlHaplotypeCommand::~ReplaceSnarlHaplotypeCommand()

Public Members

const *Snarl* *vg::ReplaceSnarlHaplotypeCommand::snarl

Which snarl are we working on?

size_t vg::ReplaceSnarlHaplotypeCommand::lane

Which lane in the snarl are we changing?

vector<*handle_t*> vg::ReplaceSnarlHaplotypeCommand::haplotype

What fully specified haplotype should we replace it with? This gets around any problems to do with increases or decreases in the copy numbers of child snarls being underspecified.

class #include <*genotypekit.hpp*> This *TraversalFinder* is derived from the old vg call code, and emits at least one traversal representing every node, and one traversal representing every edge. Inherits from *vg::TraversalFinder* **Public Functions**

vg::RepresentativeTraversalFinder::RepresentativeTraversalFinder (*SupportAugmentedGraph*
&aug-
mented,
Snarl-
Man-
ager
&snarl_manager,
size_t
max_depth,
size_t
max_width,
size_t
max_bubble_paths,
func-
tion<*PathIndex*
*) **const**
Snarl&

> *get_index* = [](const *Snarl* &s){return nullptr;} Make a new *RepresentativeTraversalFinder* to find traversals. Uses the given augmented graph as the graph with coverage annotation, and reasons about child snarls with the given *SnarlManager*. Explores up to max_depth in the BFS search when trying to find its way across snarls, and considers up to max_width search states at a time. When combining search results on either side of a graph element to be represented, thinks about max_bubble_paths combinations.

Uses the given *get_index* function to try and find a *PathIndex* for a reference path traversing a child snarl.

virtual vg::RepresentativeTraversalFinder::~~RepresentativeTraversalFinder ()

vector<*SnarlTraversal*> vg::RepresentativeTraversalFinder::find_traversals (const
Snarl
&site)

Find traversals to cover the nodes and edges of the snarl. Always emits the primary path traversal first, if applicable.

Public Members

bool vg::RepresentativeTraversalFinder::verbose

Should we emit verbose debugging info?

Protected Functions

Path `vg::RepresentativeTraversalFinder::find_backbone (const Snarl &site)`

Find a *Path* that runs from the start of the given snarl to the end, which we can use to backend our traversals into when a snarl is off the primary path.

pair<*Support*, vector<*Visit*>> `vg::RepresentativeTraversalFinder::find_bubble (Node
*node,
Edge
*edge,
const
Snarl
*snarl,
PathIn-
dex
&in-
dex,
const
Snarl
&site)`

Given an edge or node in the augmented graph, look out from the edge or node or snarl in both directions to find a shortest bubble relative to the path, with a consistent orientation. The bubble may not visit the same node twice.

Exactly one of edge and node and snarl must be not null.

Takes a max depth for the searches producing the paths on each side.

Return the ordered and oriented nodes in the bubble, with the outer nodes being oriented forward along the path for which an index is provided, and with the first node coming before the last node in the reference. Also return the minimum support found on any edge or node in the bubble (including the reference node endpoints and their edges which aren't stored in the path).

Support `vg::RepresentativeTraversalFinder::min_support_in_path (const
list<Visit>
&path)`

Get the minimum support of all nodes and edges in path

set<*pair*<size_t, list<*Visit*>>> `vg::RepresentativeTraversalFinder::bfs_left (Visit
visit,
PathIn-
dex
&in-
dex, bool
stopIfVis-
ited =
false,
const
Snarl
*in_snarl
=
nullptr)`

Do a breadth-first search left from the given node traversal, and return lengths and paths starting at the given node and ending on the given indexed path. Refuses to visit nodes with no support, if support data is available in the augmented graph.

```
set<pair<size_t, list<Visit>>> vg::RepresentativeTraversalFinder::bfs_right (Visit
                                                                    visit,
                                                                    PathIn-
                                                                    dex
                                                                    &in-
                                                                    dex,
                                                                    bool
                                                                    stopIfVis-
                                                                    ited =
                                                                    false,
                                                                    const
                                                                    Snarl
                                                                    *in_snarl
                                                                    =
                                                                    nullptr)
```

Do a breadth-first search right from the given node traversal, and return lengths and paths starting at the given node and ending on the given indexed path. Refuses to visit nodes with no support, if support data is available in the augmented graph.

```
size_t vg::RepresentativeTraversalFinder::bp_length (const list<Visit> &path)
    Get the length of a path through nodes, in base pairs.
```

Protected Attributes

```
SupportAugmentedGraph &vg::RepresentativeTraversalFinder::augmented
    The annotated, augmented graph we're finding traversals in.
```

```
SnarlManager &vg::RepresentativeTraversalFinder::snarl_manager
    The SnarlManager managing the snarls we use.
```

```
function<PathIndex * (const Snarl&)> vg::RepresentativeTraversalFinder::get_index
    We keep around a function that can be used to get an index for the appropriate path to use to scaffold a given site, or null if no appropriate index exists.
```

```
size_t vg::RepresentativeTraversalFinder::max_depth
    What DFS depth should we search to?
```

```
size_t vg::RepresentativeTraversalFinder::max_width
    How many DFS searches should we let there be on the stack at a time?
```

```
size_t vg::RepresentativeTraversalFinder::max_bubble_paths
    How many search intermediates can we allow?
```

```
class #include <sampler.hpp> Generate Alignments (with or without mutations, and in pairs or alone) from an XG index. Public Functions
```

```
vg::Sampler::Sampler (xg::XG *x, int seed = 0, bool forward_only = false, bool allow_Ns = false,
                      const vector<string> &source_paths = {})
```

```
void vg::Sampler::set_source_paths (const vector<string> &source_paths)
    Make a path sampling distribution based on relative lengths.
```

```
pos_t vg::Sampler::position (void)
```

```
string vg::Sampler::sequence (size_t length)
```


Alignment `vg::Sampler::alignment (size_t length)`

Get an alignment against the whole graph, or against the source path if one is selected.

Alignment `vg::Sampler::alignment_to_graph (size_t length)`

Get an alignment against the whole graph.

Alignment `vg::Sampler::alignment_to_path (const string &source_path, size_t length)`

Get an alignment against the currently set source_path.

Alignment `vg::Sampler::alignment_with_error (size_t length, double base_error, double indel_error)`

`vector<Alignment>` `vg::Sampler::alignment_pair (size_t read_length, size_t fragment_length, double fragment_std_dev, double base_error, double indel_error)`

`size_t` `vg::Sampler::node_length (id_t id)`

`char` `vg::Sampler::pos_char (pos_t pos)`

`map<pos_t, char>` `vg::Sampler::next_pos_chars (pos_t pos)`

Alignment `vg::Sampler::mutate (const Alignment &aln, double base_error, double indel_error)`

`vector<Edit>` `vg::Sampler::mutate_edit (const Edit &edit, const pos_t &position, double base_error, double indel_error, const string &bases, uniform_real_distribution<double> &rprob, uniform_int_distribution<int> &rbase)`

Mutate the given edit, producing a vector of edits that should replace it. *Position* is the position of the start of the edit, and is updated to point to the next base after the mutated edit.

`string` `vg::Sampler::alignment_seq (const Alignment &aln)`

`bool` `vg::Sampler::is_valid (const Alignment &aln)`

Return true if the alignment is semantically valid against the XG index we wrap, and false otherwise. Checks from_lengths on mappings to make sure all node bases are accounted for. Won't accept alignments with internal jumps between graph locations or regions; all skipped bases need to be accounted for by deletions.

Public Members

`xg::XG*` `vg::Sampler::xgidx`

`LRUCache<id_t, Node>` `vg::Sampler::node_cache`

`LRUCache<id_t, vector<Edge>>` `vg::Sampler::edge_cache`

`mt19937` `vg::Sampler::rng`

`int64_t` `vg::Sampler::nonce`

`bool` `vg::Sampler::forward_only`

`bool` `vg::Sampler::no_Ns`

`vector<string>` `vg::Sampler::source_paths`

`discrete_distribution` `vg::Sampler::path_sampler`

class *#include <cluster.hpp>* Iterate over pairsets of integers in a pseudorandom but deterministic order. We use the same permutation every time for a given number of items to pair up. **Public Types**

using

Public Functions

`vg::ShuffledPairs::ShuffledPairs (size_t num_items)`
Make a new iterable pairing up the given number of items.

ShuffledPairs::iterator `vg::ShuffledPairs::begin () const`
Get an iterator to the first pair.

ShuffledPairs::iterator `vg::ShuffledPairs::end () const`
Get an iterator to the past-the-end pair.

Private Members

`size_t vg::ShuffledPairs::num_items`

`size_t vg::ShuffledPairs::num_pairs`

`size_t vg::ShuffledPairs::larger_prime`

`size_t vg::ShuffledPairs::primitive_root`

class *#include <genotypekit.hpp>* Inherits from *vg::ConsistencyCalculator* **Public Functions**

`vg::SimpleConsistencyCalculator::~SimpleConsistencyCalculator ()`

`vector<bool> vg::SimpleConsistencyCalculator::calculate_consistency (const`
Snarl
&site,
const
vec-
tor<SnarlTraversal>
&traver-
sals,
const
Align-
ment
&read)
const

Return true or false for each traversal of the site, depending on if the read is consistent with it or not.
class *#include <genotypekit.hpp>* Inherits from *vg::TraversalSupportCalculator* **Public Functions**

`vg::SimpleTraversalSupportCalculator::~SimpleTraversalSupportCalculator ()`

```
vector<Support> vg::SimpleTraversalSupportCalculator::calculate_supports (const
                                                                    Snarl
                                                                    &site,
                                                                    const
                                                                    vec-
                                                                    tor<SnarlTraversal>
                                                                    &traver-
                                                                    sals,
                                                                    const
                                                                    vec-
                                                                    tor<Alignment
                                                                    *>
                                                                    &reads,
                                                                    const
                                                                    vec-
                                                                    tor<vector<bool>>
                                                                    &con-
                                                                    sis-
                                                                    ten-
                                                                    cies)
                                                                    const
```

Return Supports for all the SnarlTraversals, given the reads and their consistency flags.

class *#include <simplifier.hpp>* A class that can be used to simplify a graph, by repeatedly popping leaf bubbles under a certain size. Keeps graph paths and an optional set of BED- like features up to date. TODO: doesn't handle path start and end positions within nodes. Inherits from *vg::Progressive* **Public Functions**

```
vg::Simplifier::Simplifier (VG &graph)
```

Make a simplifier that simplifies the given graph in place.

```
pair<size_t, size_t> vg::Simplifier::simplify_once (size_t iteration = 0)
```

Simplify the graph by one step. Returns the number of nodes deleted and the number of edges deleted. Can be passed an iteration for its progress messages.

```
void vg::Simplifier::simplify ()
```

Simplify the graph until material stops being deleted or the maximum iteration count is reached.

Public Members

```
size_t vg::Simplifier::min_size
```

What's the minimum size of a bubble to keep, in involved bases? Everything smaller will get squished away.

```
size_t vg::Simplifier::max_iterations
```

How many iterations of simplification should we allow in a *simplify()* call?

```
bool vg::Simplifier::drop_hairpin_paths
```

Should we simplify bubbles where paths come in and leave through the entrance node (and delete those paths) (true)? Or should we leave those bubbles unsimplified?

```
FeatureSet vg::Simplifier::features
```

Stores the features in the graph, and gets updated as simplification proceeds. The user should load the features in and pull them out.

Protected Attributes

VG &vg::Simplifier::graph

Holds a reference to the graph we're simplifying.

SnarlManager vg::Simplifier::site_manager

This keeps track of the sites to simplify.

TrivialTraversalFinder vg::Simplifier::traversal_finder

This is used to find traversals of those sites.

struct Describes a subgraph that is connected to the rest of the graph by two nodes. **Public Members**

SnarlType vg::Snarl::type

What type of snarl is this?

Visit vg::Snarl::start

Visits that connect the *Snarl* to the rest of the graph.

points *INTO* the snarl

Visit vg::Snarl::end

points *OUT OF* the snarl

Snarl vg::Snarl::parent

If this *Snarl* is nested in another, this field should be filled in with a *Snarl* that has the start and end visits filled in (other information is optional/extraneous)

string vg::Snarl::name

Allows snarls to be named, e.g. by the hash of the VCF variant they come from.

bool vg::Snarl::start_self_reachable

Indicate whether there is a reversing path contained in the *Snarl* from either the start to itself or the end to itself

bool vg::Snarl::end_self_reachable

bool vg::Snarl::start_end_reachable

Indicate whether the start of the *Snarl* is connected through to the end.

bool vg::Snarl::directed_acyclic_net_graph

Indicate whether the snarl's net graph is free of directed cycles.

class #include <genotypekit.hpp> Represents a strategy for finding (nested) sites in a vg graph that can be described by snarls. Polymorphic base class/interface. Subclassed by *vg::CactusSnarlFinder* **Public Functions**

virtual vg::SnarlFinder::~~SnarlFinder()

virtual *SnarlManager* vg::SnarlFinder::find_snarls()

= 0Run a function on all root-level NestedSites in parallel. Site trees are passed by value so they have a clear place to live during parallel operations.

class #include <snarls.hpp> A structure to keep track of the tree relationships between Snarls and perform utility algorithms on them **Public Functions**

template <typename SnarlIterator>

vg::SnarlManager::SnarlManager(SnarlIterator begin, SnarlIterator end)

Construct a *SnarlManager* for the snarls returned by an iterator Also covers iterators of chains of snarls.

```

vg::SnarlManager::SnarlManager (istream &in)
    Construct a SnarlManager for the snarls contained in an input stream.

vg::SnarlManager::SnarlManager ()
    Default constructor.

vg::SnarlManager::~~SnarlManager ()
    Destructor.

vg::SnarlManager::SnarlManager (const SnarlManager &other)
    Cannot be copied because of all the internal pointer indexes.

SnarlManager &vg::SnarlManager::operator= (const SnarlManager &other)

vg::SnarlManager::SnarlManager (SnarlManager &&other)
    Can be moved.

SnarlManager &vg::SnarlManager::operator= (SnarlManager &&other)

const vector<const Snarl *> &vg::SnarlManager::children_of (const Snarl *snarl) const
    Returns a vector of pointers to the children of a Snarl. If given null, returns the top-level root snarls.

const Snarl *vg::SnarlManager::parent_of (const Snarl *snarl) const
    Returns a pointer to the parent of a Snarl or nullptr if there is none.

const Snarl *vg::SnarlManager::into_which_snarl (int64_t id, bool reverse) const
    Returns the Snarl that a traversal points into at either the start or end, or nullptr if the traversal does not
    point into any Snarl. Note that Snarls store the end Visit pointing out of rather than into the Snarl, so they
    must be reversed to query it.

const Snarl *vg::SnarlManager::into_which_snarl (const Visit &visit) const
    Returns the Snarl that a Visit points into. If the Visit contains a Snarl rather than a node ID, returns a
    pointer the managed version of that snarl.

const Chain *vg::SnarlManager::chain_of (const Snarl *snarl) const
    Get the Chain that the given snarl participates in. Instead of asking this class to walk the chain for you, use
    ChainIterators on this chain.

bool vg::SnarlManager::in_nontrivial_chain (const Snarl *here) const
    Return true if a Snarl is part of a nontrivial chain of more than one snarl.

const deque<Chain> &vg::SnarlManager::chains_of (const Snarl *snarl) const
    Get all the snarls in all the chains under the given parent snarl. If the parent snarl is null, gives the top-level
    chains that connect and contain the top-level root snarls. Unary snarls and snarls in trivial chains will be
    presented as their own chains. Snarls are not necessarily oriented appropriately given their ordering in the
    chain. Useful for making a net graph.

NetGraph vg::SnarlManager::net_graph_of (const Snarl *snarl, const HandleGraph *graph,
                                         bool use_internal_connectivity = true) const
    Get the net graph of the given Snarl's contents, using the given backing HandleGraph. If
    use_internal_connectivity is false, each chain and unary child snarl is treated as an ordinary node which
    is assumed to be only traversable from one side to the other. Otherwise, traversing the graph works like it
    would if you actually went through the internal graphs fo child snarls.

bool vg::SnarlManager::is_leaf (const Snarl *snarl) const
    Returns true if snarl has no children and false otherwise.

bool vg::SnarlManager::is_root (const Snarl *snarl) const
    Returns true if snarl has no parent and false otherwise.

```

const vector<const *Snarl* *> &vg::SnarlManager::top_level_snarls() **const**

Returns a reference to a vector with the roots of the *Snarl* trees.

void vg::SnarlManager::flip(const *Snarl* *snarl)

Reverses the orientation of a snarl.

const *Snarl* *vg::SnarlManager::add_snarl(const *Snarl* &new_snarl)

Add the given snarl to the *SnarlManager* as neither a root nor a child of any other snarl. The snarl must eventually either be added to a parent snarl or as a root snarl through *add_chain()* or it will not be visible.

void vg::SnarlManager::add_chain(const Chain &new_chain, const *Snarl* *chain_parent)

Add the given chain of snarls that have already been added with *add_snarl()*. Parents the chain to the given parent snarl, also added with *add_snarl()*. If the parent is null, makes the chain a root chain and all of its snarls root snarls. Note that the chains are allowed to be reallocated until the last child chain of a snarl is added.

pair<unordered_set<*Node* *>, unordered_set<*Edge* *>> vg::SnarlManager::shallow_contents(const *Snarl* *snarl, VG &graph, bool include_boundary_nodes) **const**

Returns the Nodes and Edges contained in this *Snarl* but not in any child Snarls (always includes the Nodes that form the boundaries of child Snarls, optionally includes this *Snarl*'s own boundary Nodes)

pair<unordered_set<*Node* *>, unordered_set<*Edge* *>> vg::SnarlManager::deep_contents(const *Snarl* *snarl, VG &graph, bool include_boundary_nodes) **const**

Returns the Nodes and Edges contained in this *Snarl*, including those in child Snarls (optionally includes *Snarl*'s own boundary Nodes)

vector<*Visit*> vg::SnarlManager::visits_left(const *Visit* &visit, VG &graph, const *Snarl* *in_snarl) **const**

Look left from the given visit in the given graph and gets all the attached Visits to nodes or snarls.

vector<*Visit*> vg::SnarlManager::visits_right(const *Visit* &visit, VG &graph, const *Snarl* *in_snarl) **const**

Look left from the given visit in the given graph and gets all the attached Visits to nodes or snarls.

unordered_map<pair<int64_t, bool>, const *Snarl* *> vg::SnarlManager::snarl_boundary_index() **const**

Returns a map from all *Snarl* boundaries to the *Snarl* they point into. Note that this means that end boundaries will be reversed.

unordered_map<pair<int64_t, bool>, const *Snarl* *> vg::SnarlManager::snarl_start_index() **const**

Returns a map from all *Snarl* start boundaries to the *Snarl* they point into.

`unordered_map<pair<int64_t, bool>, const Snarl *> vg::SnarlManager::snarl_end_index()` **const**
 Returns a map from all *Snarl* end boundaries to the *Snarl* they point into. Note that this means that end boundaries will be reversed.

`void vg::SnarlManager::for_each_top_level_snarl (const function<void> const Snarl *
 > &lambda const` Execute a function on all top level sites.

`void vg::SnarlManager::for_each_snarl_preorder (const function<void> const Snarl *
 > &lambda const` Execute a function on all sites in a preorder traversal.

`void vg::SnarlManager::for_each_top_level_snarl_parallel (const function<void> const Snarl *
 > &lambda const` Execute a function on all top level sites in parallel.

`void vg::SnarlManager::for_each_snarl_parallel (const function<void> const Snarl *
 > &lambda const` Execute a function on all sites in parallel.

`const Snarl *vg::SnarlManager::manage (const Snarl ¬_owned) const`
 Given a *Snarl* that we don't own (like from a *Visit*), find the pointer to the managed copy of that *Snarl*.

Private Types

`using` Define the key type.

Private Functions

`SnarlManager::key_t vg::SnarlManager::key_form (const Snarl *snarl) const`
 Converts *Snarl* to the form used as keys in internal data structures.

`void vg::SnarlManager::build_indexes ()`
 Builds tree indexes after Snarls have been added to the snarls vector.

`deque<Chain> vg::SnarlManager::compute_chains (const vector<const Snarl *> &input_snarls)`
 Actually compute chains for a set of already indexed snarls, which is important when chains were not provided. Returns the chains.

`Visit vg::SnarlManager::next_snarl (const Visit &here) const`
 Get a *Visit* to the snarl coming after the given *Visit* to a snarl, or a *Visit* with no *Snarl* no next snarl exists. Accounts for snarls' orientations.

`Visit vg::SnarlManager::prev_snarl (const Visit &here) const`
 Get a *Visit* to the snarl coming before the given *Visit* to a snarl, or a *Visit* with no *Snarl* no previous snarl exists. Accounts for snarls' orientations.

`const Snarl *vg::SnarlManager::snarl_sharing_start (const Snarl *here) const`
 Get the *Snarl*, if any, that shares this *Snarl*'s start node as either its start or its end. Does not count this snarl, even if this snarl is unary. Basic operation used to traverse a chain. Caller must account for snarls' orientations within a chain.

`const Snarl *vg::SnarlManager::snarl_sharing_end (const Snarl *here) const`
 Get the *Snarl*, if any, that shares this *Snarl*'s end node as either its start or its end. Does not count this snarl, even if this snarl is unary. Basic operation used to traverse a chain. Caller must account for snarls' orientations within a chain.

Private Members

`deque<Snrarl> vg::SnrarlManager::snarls`

Master list of the snarls in the graph. Use a deque so pointers never get invalidated but we still have some locality.

`vector<const Snrarl*> vg::SnrarlManager::roots`

Roots of snarl trees.

`deque<Chain> vg::SnrarlManager::root_chains`

Chains of root-level snarls. Uses a deque so Chain* pointers don't get invalidated.

`unordered_map<key_t, vector<const Snrarl*>> vg::SnrarlManager::children`

Map of snarls to the child snarls they contain.

`unordered_map<key_t, deque<Chain>> vg::SnrarlManager::child_chains`

Map of snarls to the child chains they contain Uses a deque so Chain* pointers don't get invalidated.

`unordered_map<key_t, const Snrarl*> vg::SnrarlManager::parent`

Map of snarls to their parent snarls.

`unordered_map<key_t, const Chain*> vg::SnrarlManager::parent_chain`

Map of snarls to the chain each appears in.

`unordered_map<key_t, Snrarl*> vg::SnrarlManager::self`

Map of snarl keys to the pointer to the managed copy in the snarls vector. Is non-const so we can do flip nicely.

`unordered_map<pair<int64_t, bool>, const Snrarl*> vg::SnrarlManager::snarl_into`

Map of node traversals to the snarls they point into.

class `#include <genome_state.hpp>` Represents the state of a snarl: zero or more haplotypes traversing its *NetGraph*. Only admits full-length traversals of a snarl from start to end. Every traversing haplotype is assigned a “lane” number at which it traverses the snarl. Lane is the same looking backward or forward through the snarl. Within each child snarl or child node, the traversal is also assigned a lane. The lane assignments at the start and end nodes are the same, and define the lane assignments for the overall snarl. Traversals can be inserted at any lane number in any internal node. **Public Functions**

`vg::SnrarlState::SnrarlState(const NetGraph*graph)`

Create a *SnrarlState* that uses the given net graph.

`void vg::SnrarlState::dump() const`

Dump internal state to cerr.

`size_t vg::SnrarlState::size() const`

How many haplotypes traverse this snarl?

`void vg::SnrarlState::trace(size_t overall_lane, bool backward, const function<void> const
handle_t&, size_t`

`> &iteratee` **const** Trace the haplotype in eh given overall lane in the given orientation. Yields the oriented handles visited and the per-forward-handle lane assignments.

`void vg::SnrarlState::insert(const vector<pair<handle_t, size_t>> &haplotype)`

Insert the given traversal of this snarl from start to end, with the given lane assignments for each oriented handle. If handles to the same node or child snarl appear more than once, their lane numbers must be strictly increasing.


```
const vector<pair<handle_t, size_t>> &vg::SnarlState::append(const vector<handle_t>
&haplotype, bool backward =
false)
```

Insert the given traversal of this snarl from start to end or end to start (as determined by the backward flag), assigning each visit to a handle to the next available lane. Returns the haplotype annotated with lane assignments. If handles to the same node or child snarl appear more than once, their lane numbers will be strictly increasing.

```
const vector<pair<handle_t, size_t>> &vg::SnarlState::insert(size_t overall_lane, const
vector<handle_t> &haplotype,
bool backward = false)
```

Insert the given traversal of this snarl from start to end or end to start (as determined by the backward flag), assigning it to the given overall lane. Returns the haplotype annotated with lane assignments for all the internal handles. If the internal handles represent child snarls, this can be used to recurse down and insert traversals of them at the right lanes. If handles to the same node or child snarl appear more than once, their assigned lane numbers will be strictly increasing. Returns the haplotype annotated with lane assignments.

```
vector<pair<handle_t, size_t>> vg::SnarlState::erase(size_t overall_lane)
```

Erase the traversal of this haplotype in the given overall lane. Shifts everything in a higher lane 1 rank down. Returns the erased haplotype and its old lane assignments.

```
void vg::SnarlState::swap(size_t lane1, size_t lane2)
```

Swap the traversals of this haplotype in the two given overall lanes. Internal lane assignments (as are used by child snarls) are not affected.

Protected Attributes

```
vector<vector<pair<handle_t, size_t>>> vg::SnarlState::haplotypes
```

```
unordered_map<handle_t, vector<decltype(haplotypes)::value_type::iterator>> vg::SnarlState::net_node_lanes
```

```
const NetGraph *vg::SnarlState::graph
```

We need to keep track of the net graph, because we may need to traverse haplotypes forward or reverse and we need to flip things.

struct Describes a walk through a *Snarl* where each step is given as either a node or a child *Snarl* (leaving the walk through the child *Snarl* to another *SnarlTraversal*)

Public Members

```
repeated<Visit> vg::SnarlTraversal::visits
```

Steps of the walk through a *Snarl*, including the start and end nodes. If the traversal includes a *Visit* that represents a *Snarl*, both the node entering the *Snarl* and the node leaving the *Snarl* should be included in the traversal.

```
string vg::SnarlTraversal::name
```

The name of the traversal can be used for a variant allele id (e.g. <parentSnarlHash>_0, <parentSnarlHash>_1... or by some other arbitrary annotation, unique or non-unique, e.g. deleteterious, gain_of_function, etc., though these will be lost in any indices).

```
class #include <srpe.hpp>Public Functions
```

```
void vg::SRPE::call_svcs_paired_end(vg::VG *graph, ifstream &gamstream, vec-
tor<BREAKPOINT> &bps, string repath = "")
```

```
void vg::SRPE::call_svcs_split_read(vg::VG *graph, ifstream &gamstream, vec-
tor<BREAKPOINT> &bps, string repath = "")
```

```
void vg::SRPE::call_svcs (string graphfile, string gamfile, string repath)
```

```
double vg::SRPE::discordance_score (vector<Alignment> alns, VG *subgraph)

void vg::SRPE::aln_to_bseq (Alignment &a, bseq1_t *read)

void vg::SRPE::assemble (vector<Alignment> alns, vector<fml_utg_t> &unitigs)
    function assemble inputs: a vector of Alignments to be assembled (based on their sequences) outputs:

void vg::SRPE::assemble (string refpath, int64_t start_pos, int64_t end_pos, vector<fml_utg_t>
    &unitigs)

void vg::SRPE::assemble (int64_t node_id, int64_t offset, int window_size)
```

Public Members

```
vector<string> vg::SRPE::ref_names

map<string, PathIndex> vg::SRPE::pindexes

vector<pair<int, int>> vg::SRPE::intervals

bool vg::SRPE::overlapping_refs

DepthMap vg::SRPE::depth

vg::Filter vg::SRPE::ff

map<string, Alignment> vg::SRPE::name_to_aln

map<string, string> vg::SRPE::aln_to_mate

vg::VG *vg::SRPE::graph

int vg::SRPE::max_reads
class #include <ssw_aligner.hpp>
```

Public Functions

```
vg::SSWAligner::SSWAligner (uint8_t _match = 1, uint8_t _mismatch = 4, uint8_t _gap_open =
    6, uint8_t _gap_extension = 1)

vg::SSWAligner::~~SSWAligner (void)

Alignment vg::SSWAligner::align (const string &query, const string &ref)

Alignment vg::SSWAligner::ssw_to_vg (const StripedSmithWaterman::Alignment &ssw_aln,
    const string &query, const string &ref)

void vg::SSWAligner::PrintAlignment (const StripedSmithWaterman::Alignment &align-
    ment)
```

Public Members

```
uint8_t vg::SSWAligner::match

uint8_t vg::SSWAligner::mismatch

uint8_t vg::SSWAligner::gap_open

uint8_t vg::SSWAligner::gap_extension
```

struct *#include <suffix_tree.hpp>* A node of a suffix tree corresponding a substring of the string **Public Functions**

`vg::SuffixTree::STNode::STNode (int64_t first, int64_t last)`
Constructor.

`vg::SuffixTree::STNode::~~STNode ()`

`int64_t vg::SuffixTree::STNode::length (int64_t phase)`
 The length of the the node during a phase of construction.

`int64_t vg::SuffixTree::STNode::final_index (int64_t phase)`
 The last index contained on the this node during a phase of construction.

Public Members

`unordered_map<char, STNode*> vg::SuffixTree::STNode::children`
 Edges down the tree.

`int64_t vg::SuffixTree::STNode::first`
 First index of string on this node.

`int64_t vg::SuffixTree::STNode::last`
 Last index of string on this node, inclusive (-1 indicates end sentinel during consruction)

struct *#include <pileup_augmenter.hpp>* **Public Functions**

`vg::StrandSupport::StrandSupport (int f = 0, int r = 0, double q = 0)`

`bool vg::StrandSupport::operator< (const StrandSupport &other) const`

`bool vg::StrandSupport::operator>= (const StrandSupport &other) const`

`bool vg::StrandSupport::operator== (const StrandSupport &other) const`

`StrandSupport vg::StrandSupport::operator- (const StrandSupport &other) const`

`StrandSupport &vg::StrandSupport::operator+= (const StrandSupport &other)`

`int vg::StrandSupport::total ()`

Public Members

`int vg::StrandSupport::fs`

`int vg::StrandSupport::rs`

`double vg::StrandSupport::qual`

template <typename K, typename V>

class *#include <hash_map.hpp>* Inherits from google::dense_hash_map< K, V >

Public Functions

```
vg::string_hash_map::string_hash_map()
template <typename K, typename V>
class #include <hash_map_set.hpp> Inherits from google::sparse_hash_map< K, V >
```

Public Functions

```
xg::string_hash_map::string_hash_map()
template <typename K>
class #include <hash_map_set.hpp> Inherits from google::sparse_hash_set< K >
```

Public Functions

```
xg::string_hash_set::string_hash_set()
class #include <subcommand.hpp> Represents a subcommand with a name, a description, and some functions.
Registers itself on construction in a static registry, and provides static functions for enumerating through that
registry. Public Functions
```

```
vg::subcommand::Subcommand::Subcommand(std::string name, std::string description,
                                         CommandCategory category, int priority,
                                         std::function<int> int, char **)
    > main_function Make and register a subcommand with the given name and description, in the given cate-
    gory, with the given priority (lower is better), which calls the given main function when invoked.
```

```
vg::subcommand::Subcommand::Subcommand(std::string name, std::string description, Com-
                                         mandCategory category, std::function<int> int,
                                         char **)
    > main_function Make and register a subcommand with the given name and description, in the given cate-
    gory, with worst priority, which calls the given main function when invoked.
```

```
vg::subcommand::Subcommand::Subcommand(std::string name, std::string description,
                                         std::function<int> int, char **)
    > main_function Make and register a subcommand with the given name and description, in the WIDGET
    category, with worst priority, which calls the given main function when invoked.
```

```
const std::string &vg::subcommand::Subcommand::get_name() const
    Get the name of a subcommand.
```

```
const std::string &vg::subcommand::Subcommand::get_description() const
    Get the description of a subcommand.
```

```
const CommandCategory &vg::subcommand::Subcommand::get_category() const
    Get the category of a subcommand, which determines who might want to use it and why.
```

```
const int &vg::subcommand::Subcommand::get_priority() const
    Get the priority level of a subcommand (lower is more important).
```

```
const int vg::subcommand::Subcommand::operator() (int argc, char **argv) const
    Run the main function of a subcommand. Return the return code.
```

Public Static Functions

const *Subcommand* *vg::subcommand::Subcommand::get (int argc, char **argv)

Get the appropriate subcommand to handle the given arguments, or nullptr if no matching subcommand is found.

void vg::subcommand::Subcommand::for_each (const std::function<void> const *Subcommand*& > &lambdaCall the given lambda with each known subcommand, in order.

void vg::subcommand::Subcommand::for_each (*CommandCategory* category, const std::function<void> const *Subcommand*& > &lambdaCall the given lambda with each known subcommand in the given category, in order.

Private Functions

const std::function<int (int, char **)> &vg::subcommand::Subcommand::get_main
const Get the main function of a subcommand.

Private Members

std::string vg::subcommand::Subcommand::name

std::string vg::subcommand::Subcommand::description

CommandCategory vg::subcommand::Subcommand::category

int vg::subcommand::Subcommand::priority

std::function<int (int, char **)> vg::subcommand::Subcommand::main_function

Private Static Functions

std::map<std::string, *Subcommand* *> &vg::subcommand::Subcommand::get_registry ()

Since we can't rely on a static member field being constructed before any static code that creates actual subcommands gets run, we rely on keeping the registry in a static variable inside a static method, so it gets constructed on first use. Note that at shutdown some of the pointers in the registry may be to already-deconstructed static objects.

struct A non-branching path of a *MultipathAlignment*. **Public Members**

Path vg::Subpath::path

describes node sequence and edits to the graph sequences

repeated<uint32> vg::Subpath::next

the indices of subpaths in the multipath alignment that are to the right of this path where right is in the direction of the end of the read sequence

int32 vg::Subpath::score

score of this subpath's alignment

class *#include <suffix_tree.hpp>* An implementation of a suffix tree with linear time and space complexity for construction. **Public Functions**

`vg::SuffixTree::SuffixTree (string::const_iterator begin, string::const_iterator end)`

Linear time constructor.

Note: string cannot have null characters, but this is not checked.

`vg::SuffixTree::~~SuffixTree ()`

`size_t vg::SuffixTree::longest_overlap (const string &str)`

Returns the length of the longest prefix of *str* that exactly matches a suffix of the string used to construct the suffix tree.

Note: string cannot have null characters, but this is not checked.

`size_t vg::SuffixTree::longest_overlap (string::const_iterator begin, string::const_iterator end)`

`vector<size_t> vg::SuffixTree::substring_locations (const string &str)`

Returns a vector of all of the indices where a string occurs as a substring of the string used to construct the suffix tree. Indices are ordered arbitrarily.

Note: string cannot have null characters, but this is not checked.

`vector<size_t> vg::SuffixTree::substring_locations (string::const_iterator begin, string::const_iterator end)`

Public Members

`const string::const_iterator vg::SuffixTree::begin`

Beginning of string used to make tree.

`const string::const_iterator vg::SuffixTree::end`

End of string used to make tree.

Private Functions

`char vg::SuffixTree::get_char (size_t i)`

Returns a char of the string or null char at past-the-last index.

`string vg::SuffixTree::to_string ()`

`string vg::SuffixTree::partial_tree_to_string (int64_t phase)`

`string vg::SuffixTree::label_string (unordered_map<char, STNode *> *branch_point)`

`string vg::SuffixTree::node_string (STNode *node, int64_t phase)`

`string vg::SuffixTree::active_point_string (unordered_map<char, STNode *> *active_branch_point, STNode *active_node, int64_t active_length, int64_t phase)`

`string vg::SuffixTree::suffix_links_string (unordered_map<unordered_map<char, STNode *> *, unordered_map<char, STNode *> *> &suffix_links)`

Private Members

list<*STNode*> vg::SuffixTree::**nodes**

All nodes in the tree (in a list to avoid difficulties with pointers and reallocations)

unordered_map<char, *STNode* *> vg::SuffixTree::**root**

The edges from the root node.

struct Aggregates information about the reads supporting an allele. **Public Members**

double vg::Support::**quality**

The overall quality of all the support, as $-10 * \log_{10}(P(\text{all support is wrong}))$

double vg::Support::**forward**

The number of supporting reads on the forward strand (which may be fractional)

double vg::Support::**reverse**

The number of supporting reads on the reverse strand (which may be fractional)

double vg::Support::**left**

TODO: what is this?

double vg::Support::**right**

TODO: What is this?

struct *#include <genotypekit.hpp>* Augmented *Graph* that holds some *Support* annotation data specific to vg call. Inherits from *vg::AugmentedGraph* **Public Functions**

bool vg::SupportAugmentedGraph::**has_supports**()

Return true if we have support information, and false otherwise.

Support vg::SupportAugmentedGraph::**get_support**(*Node* *node)

Get the *Support* for a given *Node*, or 0 if it has no recorded support.

Support vg::SupportAugmentedGraph::**get_support**(*Edge* *edge)

Get the *Support* for a given *Edge*, or 0 if it has no recorded support.

void vg::SupportAugmentedGraph::**clear**()

Clear the contents.

void vg::SupportAugmentedGraph::**load_supports**(istream &in_file)

Read the supports from protobuf.

void vg::SupportAugmentedGraph::**write_supports**(ostream &out_file)

Write the supports to protobuf

Public Members

map<*Node* *, *Support*> vg::SupportAugmentedGraph::**node_supports**

map<*Edge* *, *Support*> vg::SupportAugmentedGraph::**edge_supports**

class *#include <support_caller.hpp>* *SupportCaller*: take an augmented graph from a Caller and produce actual calls in a VCF. Inherits from *vg::Configurable* **Public Functions**

vg::SupportCaller::**SupportCaller**()

Set up to call with default parameters.

```
void vg::SupportCaller::call (SupportAugmentedGraph &augmented, string pileup_filename =
    "")
```

Produce calls for the given annotated augmented graph. If a pileup_filename is provided, the pileup is loaded again and used to add comments describing variants

```
tuple<vector<Support>, vector<size_t>> vg::SupportCaller::get_traversal_supports_and_sizes (SupportA
```

```
&augmented,
SnarlManager
&snarl_manager,
const Snarl
&site,
const vector<SnarlTraversal>
&traversals,
const SnarlTraversal
*minus_traversal =
NULL)
```

Get the support and size for each traversal in a list. Discount support of minus_traversal if it's specified. Use average_support_switch_threshold and use_average_support to decide whether to return min or avg supports

Get the support for each traversal in a list, using average_support_switch_threshold to decide if we use the minimum or average

```
vector<SnarlTraversal> vg::SupportCaller::find_best_traversals (SupportAugmentedGraph
    &augmented,
    SnarlManager
    &snarl_manager,
    TraversalFinder
    *finder,
    const Snarl &site,
    const Support &baseline_support,
    size_t copy_budget,
    function<void> const
    Locus&,
    const Snarl
    *)
```

> emit_locus For the given snarl, find the reference traversal, the best traversal, and the second-best traversal, recursively, if any exist. These traversals will be fully filled in with nodes.

Only snarls which are ultrabubbles can be called.

Expects the given baseline support for a diploid call.

Will not return more than 1 + copy_budget SnarlTraversals, and will return less if some copies are called as having the same traversal.

Does not deduplicate against the ref traversal; it may be the same as the best or second-best.

Uses the given copy number allowance, and emits a *Locus* for this *Snarl* and any child Snarls.

If no path through the *Snarl* can be found, emits no *Locus* and returns no SnarlTraversals.

```
bool vg::SupportCaller::is_reference(const SnarlTraversal &trav, AugmentedGraph
                                   &augmented)
```

Decide if the given *SnarlTraversal* is included in the original base graph (true), or if it represents a novel variant (false).

Looks at the nodes in the traversal, and sees if their calls are CALL_REFERENCE or not.

Handles single-edge traversals.

```
bool vg::SupportCaller::is_reference(const Path &path, AugmentedGraph &augmented)
```

Decide if the given *Path* is included in the original base graph (true) or if it represents a novel variant (false).

Looks at the nodes, and sees if their calls are CALL_REFERENCE or not.

The path can't be empty; it has to be anchored to something (probably the start and end of the snarl it came from).

```
map<string, SupportCaller::PrimaryPath>::iterator vg::SupportCaller::find_path(const
                                                                              Snarl
                                                                              &site,
                                                                              map<string,
                                                                              PrimaryPath>
                                                                              &primary_paths)
```

Find the primary path, if any, that the given site is threaded onto.

TODO: can only work by brute-force search.

Public Members

```
function<double (const Support&)> vg::SupportCaller::support_val
```

Get the amount of support. Can use this function to toggle between unweighted (total from genotypekit) and quality-weighted (support_quality below) in one place.

```
Option<bool> vg::SupportCaller::convert_to_vcf
```

Should we output in VCF (true) or Protobuf *Locus* (false) format?

```
size_t vg::SupportCaller::locus_buffer_size
```

How big should our output buffer be?

```
Option<vector<string>> vg::SupportCaller::ref_path_names
```

What are the names of the reference paths, if any, in the graph?

```
Option<vector<string>> vg::SupportCaller::contig_name_overrides
```

What name should we give each contig in the VCF file? Autodetected from path names if empty or too short.

```
Option<vector<size_t>> vg::SupportCaller::length_overrides
```

What should the total sequence length reported in the VCF header be for each contig? Autodetected from path lengths if empty or too short.

Option<string> `vg::SupportCaller::sample_name`

What name should we use for the sample in the VCF file?

Option<int64_t> `vg::SupportCaller::variant_offset`

How far should we offset positions of variants?

Option<int64_t> `vg::SupportCaller::max_search_depth`

How many nodes should we be willing to look at on our path back to the primary path? Keep in mind we need to look at all valid paths (and all combinations thereof) until we find a valid pair.

Option<int64_t> `vg::SupportCaller::max_search_width`

How many search states should we allow on the DFS stack when searching for traversals?

Option<double> `vg::SupportCaller::min_fraction_for_call`

What fraction of average coverage should be the minimum to call a variant (or a single copy)? Default to 0 because vg call is still applying depth thresholding

Option<double> `vg::SupportCaller::max_het_bias`

What fraction of the reads supporting an alt are we willing to discount? At 2, if twice the reads support one allele as the other, we'll call homozygous instead of heterozygous. At infinity, every call will be heterozygous if even one read supports each allele.

Option<double> `vg::SupportCaller::max_ref_het_bias`

Like above, but applied to ref / alt ratio (instead of alt / ref)

Option<double> `vg::SupportCaller::max_indel_het_bias`

Like the max het bias, but applies to novel indels.

Option<double> `vg::SupportCaller::max_indel_ma_bias`

Like the max het bias, but applies to multiallelic indels.

Option<size_t> `vg::SupportCaller::min_total_support_for_call`

What's the minimum integer number of reads that must support a call? We don't necessarily want to call a SNP as het because we have a single

Option<size_t> `vg::SupportCaller::ref_bin_size`

Bin size used for counting coverage along the reference path. The bin coverage is used for computing the probability of an allele of a certain depth

Option<double> `vg::SupportCaller::expected_coverage`

On some graphs, we can't get the coverage because it's split over parallel paths. Allow overriding here

Option<bool> `vg::SupportCaller::use_average_support`

Should we use average support instead of minimum support for our calculations?

Option<size_t> `vg::SupportCaller::average_support_switch_threshold`

Max traversal length threshold at which we switch from minimum support to average support (so we don't use average support on pairs of adjacent errors and miscall them, but we do use it on long runs of reference inside a deletion where the min support might not be representative.

`size_t` `vg::SupportCaller::max_bubble_paths`

What's the maximum number of bubble path combinations we can explore while finding one with maximum support?

Option<size_t> `vg::SupportCaller::min_mad_for_filter`

what's the minimum ref or alt allele depth to give a PASS in the filter column? Also used as a min actual support for a second-best allele call

```

Option<size_t> vg::SupportCaller::max_dp_for_filter
    what's the maximum total depth to give a PASS in the filter column

Option<double> vg::SupportCaller::max_dp_multiple_for_filter
    what's the maximum total depth to give a PASS in the filter column, as a multiple of the global baseline coverage?

Option<double> vg::SupportCaller::max_local_dp_multiple_for_filter
    what's the maximum total depth to give a PASS in the filter column, as a multiple of the local baseline coverage?

Option<double> vg::SupportCaller::min_ad_log_likelihood_for_filter
    what's the min log likelihood for allele depth assignments to PASS?

Option<bool> vg::SupportCaller::write_trivial_calls

Option<bool> vg::SupportCaller::call_other_by_coverage
    Should we call on nodes/edges outside of snarls by coverage (true), or just assert that primary path things exist and off-path things don't (false)?

Option<bool> vg::SupportCaller::use_support_count
    Use total support count (true) instead of total support quality (false) when choosing top alleles and deciding genotypes based on the biases.

Option<string> vg::SupportCaller::support_file_name
    Path of supports file generated from the PileupAugmenter (via vg augment)

bool vg::SupportCaller::verbose
    print warnings etc. to stderr

```

Public Static Functions

```
static double vg::SupportCaller::support_quality(const Support &support)
struct #include <genome_state.hpp> Inherits from vg::GenomeStateCommand Public Functions
```

GenomeStateCommand *vg::SwapHaplotypesCommand::execute(*GenomeState* &state) const

Execute this command on the given state and return the reverse command. Generally ends up calling a command-type-specific method on the *GenomeState* that does the actual work.

```
virtual vg::SwapHaplotypesCommand::~~SwapHaplotypesCommand()
```

Public Members

```
pair<const Snarl*, const Snarl*> vg::SwapHaplotypesCommand::telomere_pair
```

Work on the given pair of telomeres.

```
pair<size_t, size_t> vg::SwapHaplotypesCommand::to_swap
    Swap the haplotypes at the given ranks.
```

```
struct #include <xg.hpp>Public Functions
```

```
bool xg::XG::ThreadMapping::operator<(const ThreadMapping &other) const
```

We need comparison for deduplication in sets and canonically orienting threads.

Public Members

`int64_t` `xg::XG::ThreadMapping::node_id`

`bool` `xg::XG::ThreadMapping::is_reverse`

struct *#include <xg.hpp>* Represents the search state for the graph PBWT, so that you can continue a search with more of a thread, or backtrack. By default, represents an un-started search (with no first visited side) that can be extended to the whole collection of visits to a side. **Public Functions**

`int64_t` `xg::XG::ThreadSearchState::count()`

`bool` `xg::XG::ThreadSearchState::is_empty()`

Public Members

`int64_t` `xg::XG::ThreadSearchState::current_side`

`int64_t` `xg::XG::ThreadSearchState::range_start`

`int64_t` `xg::XG::ThreadSearchState::range_end`

struct Translations map from one graph to another. A collection of these provides a covering mapping between a from and to graph. If each “from” path through the base graph corresponds to a “to” path in an updated graph, then we can use these translations to project positions, mappings, and paths in the new graph into the old one using the *Translator* interface. **Public Members**

Path `vg::Translation::from`

Path `vg::Translation::to`

class *#include <translator.hpp>* Class to map paths into a base graph found via a set of Translations **Public Functions**

`vg::Translator::Translator` (void)

`vg::Translator::Translator` (istream &*in*)

`vg::Translator::Translator` (const vector<*Translation*> &*trans*)

void `vg::Translator::load` (const vector<*Translation*> &*trans*)

void `vg::Translator::build_position_table` (void)

Translation `vg::Translator::get_translation` (const *Position* &*position*)

`bool` `vg::Translator::has_translation` (const *Position* &*position*, bool *ignore_strand* = true)

Position `vg::Translator::translate` (const *Position* &*position*)

Position `vg::Translator::translate` (const *Position* &*position*, const *Translation* &*translation*)

Edge `vg::Translator::translate` (const *Edge* &*edge*)

Mapping `vg::Translator::translate` (const *Mapping* &*mapping*)

Path `vg::Translator::translate` (const *Path* &*path*)

Alignment vg::Translator::translate (const *Alignment* &aln)

Locus vg::Translator::translate (const *Locus* &locus)

Translation vg::Translator::overlay (const *Translation* &trans)

Public Members

vector<*Translation*> vg::Translator::translations

map<*pos_t*, *Translation* *> vg::Translator::pos_to_trans

class #include <genotypekit.hpp> Represents a strategy for finding traversals of (nested) sites. Polymorphic base class/interface. Subclassed by *vg::ExhaustiveTraversalFinder*, *vg::NestedTraversalFinder*, *vg::PathBasedTraversalFinder*, *vg::ReadRestrictedTraversalFinder*, *vg::RepresentativeTraversalFinder*, *vg::TrivialTraversalFinder* **Public Functions**

virtual vg::TraversalFinder::~~TraversalFinder()

virtual vector<*SnarlTraversal*> vg::TraversalFinder::find_traversals (const *Snarl* &site)
= 0

class #include <genotypekit.hpp> Represents a strategy for calculating Supports for SnarlTraversals. Polymorphic base class/interface. Subclassed by *vg::SimpleTraversalSupportCalculator* **Public Functions**

virtual vg::TraversalSupportCalculator::~~TraversalSupportCalculator()

virtual vector<*Support*> vg::TraversalSupportCalculator::calculate_supports (const *Snarl* &site, const vector<*SnarlTraversal*> &traversals, const vector<*Alignment* *> &reads, const vector<vector<bool>> &consistencies) const
= 0

Return Supports for all the SnarlTraversals, given the reads and their consistency flags.
template <typename T>
struct #include <utility.hpp>

Public Types

typedef

Public Functions

`vg::Tree::Tree (Node *r = 0)`

`vg::Tree::~~Tree ()`

`void vg::Tree::for_each_preorder (function<void> Node *
> lambda`

`void vg::Tree::for_each_postorder (function<void> Node *
> lambda`

Public Members

`Node *vg::Tree::root`
template <typename T>
struct #include <utility.hpp>

Public Functions

`vg::TreeNode::TreeNode ()`

`vg::TreeNode::~~TreeNode ()`

`void vg::TreeNode::for_each_preorder (function<void> TreeNode<T> *
> lambda`

`void vg::TreeNode::for_each_postorder (function<void> TreeNode<T> *
> lambda`

Public Members

`T vg::TreeNode::v`

`vector<TreeNode<T> *> vg::TreeNode::children`

`TreeNode<T> *vg::TreeNode::parent`

class #include <genotypekit.hpp> This traversal finder finds one or more traversals through leaf sites with no children. It uses a depth-first search. It doesn't work on non-leaf sites, and is not guaranteed to find all traversals. Only works on ultrabubbles. Inherits from `vg::TraversalFinder` **Public Functions**

`vg::TrivialTraversalFinder::TrivialTraversalFinder (VG &graph)`

virtual `vg::TrivialTraversalFinder::~~TrivialTraversalFinder ()`

`vector<SnarlTraversal> vg::TrivialTraversalFinder::find_traversals (const Snarl
&site)`

Find at least one traversal of the site by depth first search, if any exist. Only works on sites with no children.

Private Members

VG &vg::TrivialTraversalFinder::graph
struct *#include <utility.hpp>* **Public Functions**

vg::UnionFind::UFNode::UFNode (size_t *index*)

vg::UnionFind::UFNode::~~UFNode ()

Public Members

size_t vg::UnionFind::UFNode::rank

size_t vg::UnionFind::UFNode::size

size_t vg::UnionFind::UFNode::head

unordered_set<size_t> vg::UnionFind::UFNode::children

class *#include <utility.hpp>* A custom Union-Find data structure that supports merging a set of indices in disjoint sets in amortized nearly linear time. This implementation also supports querying the size of the group containing an index in constant time and querying the members of the group containing an index in linear time in the size of the group. **Public Functions**

vg::UnionFind::UnionFind (size_t *size*)
 Construct *UnionFind* for this many indices.

vg::UnionFind::~~UnionFind ()
 Destructor.

size_t vg::UnionFind::size ()
 Returns the number of indices in the *UnionFind*.

size_t vg::UnionFind::find_group (size_t *i*)
 Returns the group ID that index *i* belongs to (can change after calling union)

void vg::UnionFind::union_groups (size_t *i*, size_t *j*)
 Merges the group containing index *i* with the group containing index *j*.

size_t vg::UnionFind::group_size (size_t *i*)
 Returns the size of the group containing index *i*.

vector<size_t> vg::UnionFind::group (size_t *i*)
 Returns a vector of the indices in the same group as index *i*.

vector<vector<size_t>> vg::UnionFind::all_groups ()
 Returns all of the groups, each in a separate vector.

string vg::UnionFind::current_state ()
 A string representation of the current state for debugging.

Private Members

vector<UFGNode> vg::UnionFind::uf_nodes

class #include <variant_adder.hpp> A tool class for adding variants to a *VG* graph. Integrated *NameMapper* provides name translation for the VCF contigs. Inherits from *vg::NameMapper*, *vg::Progressive* **Public Functions**

vg::VariantAdder::VariantAdder(VG &graph)

Make a new *VariantAdder* to add variants to the given graph. Modifies the graph in place.

void vg::VariantAdder::add_variants(vcfliib::VariantCallFile *vcf)

Add in the variants from the given non-null VCF file. The file must be freshly opened. The variants in the file must be sorted.

May be called from multiple threads. Synchronizes internally on the graph.

Alignment vg::VariantAdder::smart_align(vg::VG &graph, pair<NodeSide, NodeSide> endpoints, const string &to_align, size_t max_span)

Align the given string to the given graph, between the given endpoints, using the most appropriate alignment method, depending on the relative sizes involved and whether a good alignment exists. max_span gives the maximum length in the graph that we expect our string to possibly align over (for cases of large deletions, where we might want to follow a long path in the graph).

The endpoints have to be heads/tails of the graph.

Treats N/N substitutions as matches.

TODO: now that we have a smart aligner that can synthesize deletions without finding them with the banded global aligner, do we need max_span anymore?

Mostly exposed for testability.

void vg::VariantAdder::align_ns(vg::VG &graph, Alignment &aln)

Turn any N/N substitutions in the given alignment against the given graph into matches. Modifies the alignment in place.

Public Members

size_t vg::VariantAdder::variant_range

How wide of a range in bases should we look for nearby variants in?

size_t vg::VariantAdder::flank_range

How much additional context should we try and add outside the radius of our group of variants we actually find?

bool vg::VariantAdder::ignore_missing_contigs

Should we accept and ignore VCF contigs that we can't find in the graph?

size_t vg::VariantAdder::max_context_radius

What's the max radius on a variant we can have in order to use that variant as context for another main variant?

size_t vg::VariantAdder::whole_alignment_cutoff

What's the cut-off for the graph's size or the alt's size in bp under which we can just use permissive banding and large band padding? If either is larger than this, we use the pinned-alignment-based do-each-end-and-splice mode.

`size_t vg::VariantAdder::large_alignment_band_padding`

When we're above that cutoff, what amount of band padding can we use looking for an existing version of our sequence?

`double vg::VariantAdder::min_score_factor`

When we're doing a restricted band padding alignment, how good does it have to be, as a fraction of the perfect match score for the whole context, in order to use it?

`size_t vg::VariantAdder::pinned_tail_size`

If the restricted band alignment doesn't find anything, we resort to pinned alignments from the ends and cutting and pasting together. How big should each pinned tail be?

Aligner `vg::VariantAdder::aligner`

We use this *Aligner* to hold the scoring parameters. It may be accessed by multiple threads at once.

`size_t vg::VariantAdder::edge_max`

Sometimes, we have to make Mappers, for graphs too big to safely use our global banded aligner on. If we do that, what max edge crossing limit should we use for simplification?

`size_t vg::VariantAdder::kmer_size`

What base kmer size should we use?

`size_t vg::VariantAdder::doubling_steps`

What number of doubling steps should we use?

`size_t vg::VariantAdder::subgraph_prune`

If nonzero, prune short subgraphs smaller than this before GCSA2-indexing.

`size_t vg::VariantAdder::thin_alignment_cutoff`

`size_t vg::VariantAdder::mapper_alignment_cutoff`

`bool vg::VariantAdder::skip_structural_duplications`

We have code to skip large structural duplications, because aligners won't be able to distinguish the copies. TODO: we want to actually make them into cycles.

`bool vg::VariantAdder::print_updates`

Should we print out periodic updates about the variants we have processed?

Protected Functions

```
set<vector<int>> vg::VariantAdder::get_unique_haplotypes (const          vec-
                                                         tor<vcflib::Variant
                                                         > * >
                                                         &variants,  WindowedVcf-
                                                         Buffer *cache = nullptr)
                                                         const
```

Get all the unique combinations of variant alts represented by actual haplotypes. Arbitrarily phases unphased variants.

Can (and should) take a *WindowedVcfBuffer* that owns the variants, and from which cached pre-parsed genotypes can be extracted.

Returns a set of vectors or one number per variant, giving the alt number (starting with 0 for reference) that appears on the haplotype.

TODO: ought to just take a collection of pre-parsed genotypes, but in an efficient way (a vector of pointers to vectors of sample genotypes?)

```
string vg::VariantAdder::haplotype_to_string(const vector<int> &haplotype, const vector<vcflib::Variant *> &variants)
```

Convert a haplotype on a list of variants into a string. The string will run from the start of the first variant through the end of the last variant.

Can't be const because it relies on non-const operations on the synchronizer.

```
vector<vcflib::Variant *> vg::VariantAdder::filter_local_variants(const vector<vcflib::Variant *> &before, vcflib::Variant *variant, const vector<vcflib::Variant *> &after) const
```

Glom all the given variants into one vector, throwing out variants from the before and after vectors that are too big to be in a context.

Protected Attributes

VG &vg::VariantAdder::graph

The graph we are modifying.

GraphSynchronizer vg::VariantAdder::sync

We keep a *GraphSynchronizer* so we can have multiple threads working on different parts of the same graph.

set<string> vg::VariantAdder::path_names

We cache the set of valid path names, so we can detect/skip missing ones without locking the graph.

Protected Static Functions

```
size_t vg::VariantAdder::get_radius(const vcflib::Variant &variant)
```

Get the radius of the variant around its center: the amount of sequence that needs to be pulled out to make sure you have the ref and all the alts, if they exist. This is just going to be twice the longest of the ref and the alts.

```
size_t vg::VariantAdder::get_center(const vcflib::Variant &variant)
```

Get the center position of the given variant.

```
pair<size_t, size_t> vg::VariantAdder::get_center_and_radius(const vector<vcflib::Variant *> &variants)
```

Get the center and radius around that center needed to extract everything that might be involved in a group of variants.

class *#include <vcf_buffer.hpp>* Provides a one-variant look-ahead buffer on a vcflib::VariantFile. Lets construction functions peek and see if they want the next variant, or lets them ignore it for the next construction function for a different contig to handle. Ought not to be copied. Handles conversion from 1-based vcflib coordinates to 0-based vg coordinates. **Public Functions**

```
vcflib::Variant *vg::VcfBuffer::get()
```

Return a pointer to the buffered variant, or null if no variant is buffered. Pointer is invalidated when the buffer is handled. The variant will have a 0-based start coordinate.

Although the variant is not const, it may not be moved out of or modified in ways that confuse `vcflib`.

`void vg::VcfBuffer::handle_buffer()`

To be called when the buffer is filled. Marks the buffered variant as handled, discarding it, and allowing another to be read.

`void vg::VcfBuffer::fill_buffer()`

Can be called when the buffer is filled or empty. If there is no variant in the buffer, tries to load a variant into the buffer, if one can be obtained from the file.

`bool vg::VcfBuffer::has_tabix() const`

This returns true if we have a tabix index, and false otherwise. If this is false, `set_region` may be called, but will do nothing and return false.

`bool vg::VcfBuffer::set_region(const string &contig, int64_t start = -1, int64_t end = -1)`

This tries to set the region on the underlying `vcflib::VariantCallFile` to the given contig and region, if specified. Coordinates coming in should be 0-based, and will be converted to 1-based internally.

Returns true if the region was successfully set, and false otherwise (for example, if there is not tabix index, or if the given region is not part of this VCF. Note that if there is a tabix index, and `set_region` returns false, the position in the VCF file is undefined until the next successful `set_region` call.

If either of start and end are specified, then both of start and end must be specified.

Discards any variants previously in the buffer.

`vg::VcfBuffer::VcfBuffer(vcflib::VariantCallFile *file = nullptr)`

Make a new *VcfBuffer* buffering the file at the given pointer (which must outlive the buffer, but which may be null).

Protected Attributes

`bool vg::VcfBuffer::has_buffer`

`bool vg::VcfBuffer::safe_to_get`

`vcflib::Variant vg::VcfBuffer::buffer`

`vcflib::VariantCallFile *const vg::VcfBuffer::file`

Private Functions

`vg::VcfBuffer::VcfBuffer(const VcfBuffer &other)`

VcfBuffer &vg::VcfBuffer::operator=(const VcfBuffer &other)

class `#include <genotypekit.hpp>` Represents a strategy for converting *Locus* objects to VCF records. Polymorphic base class/interface. **Public Functions**

virtual `vg::VcfRecordConverter::~VcfRecordConverter()`

virtual `vcflib::Variant vg::VcfRecordConverter::convert(const Locus &locus)`
= 0

class *#include <genotypekit.hpp>* Represents a filter that passes or rejects VCF records according to some criteria. Polymorphic base class/interface. **Public Functions**

virtual `vg::VcfRecordFilter::~~VcfRecordFilter()`

virtual `bool vg::VcfRecordFilter::accept_record(const vcflib::Variant &variant)`
= 0 Returns true if we should keep the given VCF record, and false otherwise.

class *#include <vectorizer.hpp>* **Public Functions**

`Vectorizer::Vectorizer(xg::XG *x)`

`Vectorizer::~~Vectorizer()`

`void Vectorizer::add_bv(bit_vector v)`

`void Vectorizer::add_name(string n)`

`void Vectorizer::emit(ostream &out, bool r_format, bool annotate)`

`bit_vector Vectorizer::alignment_to_onehot(Alignment a)`

`vector<int> Vectorizer::alignment_to_a_hot(Alignment a)`

`vector<double> Vectorizer::alignment_to_custom_score(Alignment a,`
`> lambda std::function<double>) Alignment`

`vector<double> Vectorizer::alignment_to_identity_hot(Alignment a)`

`string Vectorizer::output_wabbit_map()`

template `<typename T>`

`string Vectorizer::format(T v)`

template `<typename T>`

`string Vectorizer::wabbitize(string name, T v)`

Private Members

`xg::XG *Vectorizer::my_xg`

`vector<bit_vector> Vectorizer::my_vectors`

`vector<string> Vectorizer::my_names`

`bool Vectorizer::output_tabbed`

`bool Vectorizer::output_names`

`unordered_map<string, int> Vectorizer::wabbit_map`

class *#include <vg.hpp>* Represents a variation graph. Graphs consist of nodes, connected by edges. Graphs are bidirected and may be cyclic. Nodes carry forward-oriented sequences. Edges are directed, with a “from” and to” node, and are generally used to connect the end of the “from” node to the start of the “to” node. However, edges can connect to either the start or end of either node. Inherits from *vg::Progressive*, *vg::MutableHandleGraph* **Public Functions**

handle_t `vg::VG::get_handle(const id_t &node_id, bool is_reverse) const`

Look up the handle for the node with the given ID in the given orientation.

```

id_t vg::VG::get_id(const handle_t &handle) const
    Get the ID from a handle.

bool vg::VG::get_is_reverse(const handle_t &handle) const
    Get the orientation of a handle.

handle_t vg::VG::flip(const handle_t &handle) const
    Invert the orientation of a handle (potentially without getting its ID)

size_t vg::VG::get_length(const handle_t &handle) const
    Get the length of a node.

string vg::VG::get_sequence(const handle_t &handle) const
    Get the sequence of a node, presented in the handle's local forward orientation.

bool vg::VG::follow_edges(const handle_t &handle, bool go_left, const function<bool> const
                           handle_t &
                           > &iteratee) const
    Loop over all the handles to next/previous (right/left) nodes. Passes them to a callback
    which returns false to stop iterating and true to continue. Returns true if we finished and false if we stopped
    early.

void vg::VG::for_each_handle(const function<bool> const handle_t &
                             > &iteratee) const
    Loop over all the nodes in the graph in their local forward orientations, in their internal
    stored order. Stop if the iteratee returns false.

size_t vg::VG::node_size() const
    Return the number of nodes in the graph.

handle_t vg::VG::create_handle(const string &sequence)
    Create a new node with the given sequence and return the handle.

void vg::VG::destroy_handle(const handle_t &handle)
    Remove the node belonging to the given handle and all of its edges.

void vg::VG::create_edge(const handle_t &left, const handle_t &right)
    Create an edge connecting the given handles in the given order and orientations.

void vg::VG::destroy_edge(const handle_t &left, const handle_t &right)
    Remove the edge connecting the given handles in the given order and orientations.

void vg::VG::swap_handles(const handle_t &a, const handle_t &b)
    Swap the nodes corresponding to the given handles, in the ordering used by for_each_handle when looping
    over the graph. Other handles to the nodes being swapped must not be invalidated.

handle_t vg::VG::apply_orientation(const handle_t &handle)
    Alter the node that the given handle corresponds to so the orientation indicated by the handle becomes the
    node's local forward orientation. Rewrites all edges pointing to the node and the node's sequence to reflect
    this. Invalidates all handles to the node (including the one passed). Returns a new, valid handle to the node
    in its new forward orientation. Note that it is possible for the node's ID to change.

vector<handle_t> vg::VG::divide_handle(const handle_t &handle, const vector<size_t> &off-
                                     sets)
    Split a handle's underlying node at the given offsets in the handle's orientation. Returns all of the handles
    to the parts. Other handles to the node being split may be invalidated. The split pieces stay in the same
    local forward orientation as the original node, but the returned handles come in the order and orientation
    appropriate for the handle passed in.

```

```
void vg::VG::set_edge(Edge *edge)
```

Set the edge indexes through this function. Picks up the sides being connected by the edge automatically, and silently drops the edge if they are already connected.

```
void vg::VG::print_edges(void)
```

```
vector<pair<id_t, bool>> &vg::VG::edges_start(Node *node)
```

Get nodes and backward flags following edges that attach to this node's start.

```
vector<pair<id_t, bool>> &vg::VG::edges_start(id_t id)
```

Get nodes and backward flags following edges that attach to this node's start.

```
vector<pair<id_t, bool>> &vg::VG::edges_end(Node *node)
```

Get nodes and backward flags following edges that attach to this node's end.

```
vector<pair<id_t, bool>> &vg::VG::edges_end(id_t id)
```

Get nodes and backward flags following edges that attach to this node's end.

```
size_t vg::VG::size(void)
```

Number of nodes.

```
size_t vg::VG::length(void)
```

Total sequence length.

```
vg::VG::VG(void)
```

Default constructor.

```
vg::VG::VG(istream &in, bool showp = false, bool warn_on_duplicates = true)
```

Construct from protobufs.

```
vg::VG::VG(function<bool> Graph&
```

> &get_next_graph, bool showp = false, bool warn_on_duplicates = true) Construct from an arbitrary source of *Graph* protobuf messages (which populates the given *Graph* and returns a flag for whether it's valid).

```
vg::VG::VG(set<Node*> &nodes, set<Edge*> &edges)
```

Construct from sets of nodes and edges. For example, from a subgraph of another graph.

```
map<id_t, vcflib::Variant> vg::VG::get_node_id_to_variant(vcflib::VariantCallFile vfile)
```

Takes in a VCF file and returns a map [node] = vcflib::variant. Unfortunately this is specific to a given graph and VCF.

It will need to throw warnings if the node or variant is not in the graph.

This is useful for VCF masking:

```
if map.find(node) then mask variant
```

It's also useful for calling known variants

```
for m in alignment.mappings:
    node = m.Pos.nodeID
    if node in node_to_vcf:
        return (alignment supports variant)
```

It would be nice if this also supported edges (e.g. for inversions/transversions/breakpoints?).

```
void vg::VG::dice_nodes(int max_node_size)
```

Chop up the nodes.

```

void vg::VG::unchop (void)
    Does the reverse combines nodes by removing edges where doing so has no effect on the graph labels.

set<list<NodeTraversal>> vg::VG::simple_components (int min_size = 1)
    Get the set of components that could be merged into single nodes without changing the path space of the
    graph. Emits oriented traversals of nodes, in the order and orientation in which they are to be merged.

set<list<NodeTraversal>> vg::VG::simple_multinode_components (void)
    Get the simple components of multiple nodes.

set<set<id_t>> vg::VG::strongly_connected_components (void)
    Get the strongly connected components of the graph.

set<set<id_t>> vg::VG::multinode_strongly_connected_components (void)
    Get only multi-node strongly connected components.

bool vg::VG::is_acyclic (void)
    Returns true if the graph does not contain cycles.

bool vg::VG::is_directed_acyclic (void)
    Returns true if the graph does not contain a directed cycle (but it may contain a reversing cycle)

bool vg::VG::is_single_stranded (void)
    Return true if there are no reversing edges in the graph.

void vg::VG::keep_multinode_strongly_connected_components (void)
    Remove all elements which are not in a strongly connected component.

bool vg::VG::is_self_looping (Node *node)
    Does the specified node have any self-loops?

set<list<NodeTraversal>> vg::VG::elementary_cycles (void)
    Get simple cycles following Johnson's elementary cycles algorithm.

Node *vg::VG::concat_nodes (const list<NodeTraversal> &nodes)
    Concatenates the nodes into a new node with the same external linkage as the provided component. After
    calling this, paths will be invalid until Paths::compact_ranks() is called.

Node *vg::VG::merge_nodes (const list<Node*> &nodes)
    Merge the nodes into a single node, preserving external linkages. Use the orientation of the first node as
    the basis.

void vg::VG::normalize (int max_iter = 1, bool debug = false)
    Use unchop and sibling merging to simplify the graph into a normalized form.

void vg::VG::bluntify (void)
    Remove redundant overlaps.

VG vg::VG::dagify (uint32_t expand_scc_steps, unordered_map<id_t, pair<id_t, bool>>
    &node_translation, size_t target_min_walk_length = 0, size_t compo-
    nent_length_max = 0)
    Turn the graph into a dag by copying strongly connected components expand_scc_steps times and trans-
    lating the edges in the component to flow through the copies in one direction.

VG vg::VG::backtracking_unroll (uint32_t max_length, uint32_t max_depth, un-
    ordered_map<id_t, pair<id_t, bool>> &node_translation)
    Generate a new graph that unrolls the current one using backtracking. Caution: exponential in branching.

```

VG `vg::VG::unfold` (uint32_t *max_length*, unordered_map<*id_t*, pair<*id_t*, bool>> &*node_translation*)

Ensure that all traversals up to *max_length* are represented as a path on one strand or the other without taking an inverting edge. All inverting edges are converted to non-inverting edges to reverse complement nodes. If no inverting edges are present, the strandedness of all nodes is the same as the input graph. If inverting edges are present, node strandedness is arbitrary.

VG `vg::VG::split_strands` (unordered_map<*id_t*, pair<*id_t*, bool>> &*node_translation*)

Create reverse complement nodes and edges for the entire graph. Doubles the size. Converts all inverting edges into non-inverting edges.

VG `vg::VG::reverse_complement_graph` (unordered_map<*id_t*, pair<*id_t*, bool>> &*node_translation*)

Create the reverse complemented graph with topology preserved. Record translation in provided map.

`void` `vg::VG::identity_translation` (unordered_map<*id_t*, pair<*id_t*, bool>> &*node_translation*)

Record the translation of this graph into itself in the provided map.

unordered_map<*id_t*, pair<*id_t*, bool>> `vg::VG::overlay_node_translations` (const unordered_map<*id_t*, pair<*id_t*, bool>> &*over*, const unordered_map<*id_t*, pair<*id_t*, bool>> &*under*)

Assume two node translations, the over is based on the under; merge them.

`vector<Edge>` `vg::VG::break_cycles` (void)

Use our topological sort to quickly break cycles in the graph, return the edges which are removed. Very non-optimal, but fast.

`void` `vg::VG::remove_non_path` (void)

Remove pieces of the graph which are not part of any path.

`void` `vg::VG::remove_path` (void)

Remove pieces of the graph which are part of some path.

`set<Edge*>` `vg::VG::get_path_edges` (void)

Get all of the edges that are on any path.

`void` `vg::VG::flip_doubly_reversed_edges` (void)

Convert edges that are both from_start and to_end to “regular” ones from end to start.

`void` `vg::VG::from_gfa` (istream &*in*, bool *showp* = false)

Build a graph from a GFA stream.

`void` `vg::VG::from_turtle` (string *filename*, string *baseuri*, bool *showp* = false)

Build a graph from a Turtle stream.

`vg::VG::~~VG` (void)

Destructor.

`vg::VG::VG` (const *VG* &*other*)

Copy constructor.

```

vg::VG::VG(VG &&other)
    Move constructor.

VG &vg::VG::operator=(const VG &other)
    Copy assignment operator.

VG &vg::VG::operator=(VG &&other)
    Move assignment operator.

void vg::VG::build_indexes(void)

void vg::VG::build_node_indexes(void)

void vg::VG::build_edge_indexes(void)

void vg::VG::build_indexes_no_init_size(void)

void vg::VG::build_node_indexes_no_init_size(void)

void vg::VG::build_edge_indexes_no_init_size(void)

void vg::VG::index_paths(void)

void vg::VG::clear_node_indexes(void)

void vg::VG::clear_node_indexes_no_resize(void)

void vg::VG::clear_edge_indexes(void)

void vg::VG::clear_edge_indexes_no_resize(void)

void vg::VG::clear_indexes(void)

void vg::VG::clear_indexes_no_resize(void)

void vg::VG::resize_indexes(void)

void vg::VG::rebuild_indexes(void)

void vg::VG::rebuild_edge_indexes(void)

void vg::VG::merge(Graph &g)
    Literally merge protobufs.

void vg::VG::merge(VG &g)
    Literally merge protobufs.

void vg::VG::clear_paths(void)
    Clear the paths object (which indexes the graph.paths) and the graph paths themselves.

void vg::VG::sync_paths(void)
    Synchronize in-memory indexes and protobuf graph.

void vg::VG::merge_union(VG &g)
    Merge protobufs after removing overlaps. Good when there aren't many overlaps.

void vg::VG::remove_duplicated_in(VG &g)
    Helper to merge_union.

void vg::VG::remove_duplicates(void)
    Remove duplicated nodes and edges.

```

`void vg::VG::prune_complex_paths` (int *length*, int *edge_max*, *Node* **head_node*, *Node* **tail_node*)
Limit the local complexity of the graph, connecting pruned components to a head and tail node depending on the direction which we come into the node when the *edge_max* is passed.

`void vg::VG::prune_short_subgraphs` (size_t *min_size*)

`void vg::VG::serialize_to_ostream` (ostream &*out*, id_t *chunk_size* = 1000)
Write to a stream in chunked graphs.

`void vg::VG::serialize_to_file` (const string &*file_name*, id_t *chunk_size* = 1000)

`id_t vg::VG::max_node_id` (void)
Get the maximum node ID in the graph.

`id_t vg::VG::min_node_id` (void)
Get the minimum node ID in the graph.

`void vg::VG::compact_ids` (void)
Squish the node IDs down into as small a space as possible. Fixes up paths itself.

`void vg::VG::increment_node_ids` (id_t *increment*)
Add the given value to all node IDs. Preserves the paths.

`void vg::VG::decrement_node_ids` (id_t *decrement*)
Subtract the given value from all the node IDs. Must not create a node with 0 or negative IDs. Invalidates the paths.

`void vg::VG::swap_node_id` (id_t *node_id*, id_t *new_id*)
Change the ID of the node with the first id to the second, new ID not used by any node. Invalidates any paths containing the node, since they are not updated.

`void vg::VG::swap_node_id` (*Node* **node*, id_t *new_id*)
Change the ID of the given node to the second, new ID not used by any node. Invalidates the paths. Invalidates any paths containing the node, since they are not updated.

`void vg::VG::extend` (*VG* &*g*, bool *warn_on_duplicates* = false)
Iteratively add when nodes and edges are novel. Good when there are very many overlaps. TODO: If you are using this with warn on duplicates on, and you know there shouldn't be any duplicates, maybe you should use merge instead. This version sorts paths on rank after adding in the path mappings from the other graph.

`void vg::VG::extend` (*Graph* &*graph*, bool *warn_on_duplicates* = false)
This version does not sort path mappings by rank. In order to preserve paths, call *Paths::sort_by_mapping_rank()* and *Paths::rebuild_mapping_aux()* after you are done adding in graphs to this graph.

`void vg::VG::append` (*VG* &*g*)
Add another graph into this graph, attaching tails to heads. Modify ids of the second graph to ensure we don't have conflicts. Then attach tails of this graph to the heads of the other, and extend(*g*).

`void vg::VG::combine` (*VG* &*g*)
Add another graph into this graph. Don't append or join the nodes in the graphs; just ensure that ids are unique, then apply extend.

`void vg::VG::include` (const *Path* &*path*)
Edit the graph to include the path.

`vector<Translation> vg::VG::edit (const vector<Path> &paths)`

Edit the graph to include all the sequence and edges added by the given paths. Can handle paths that visit nodes in any orientation. Returns a vector of Translations, one per node existing after the edit, describing how each new or conserved node is embedded in the old graph. Note that this method sorts the graph and rebuilds the path index, so it should not be called in a loop.

`vector<Translation> vg::VG::edit_fast (const Path &path, set<NodeSide> &dangling)`

Edit the graph to include all the sequences and edges added by the given path. Returns a vector of Translations, one per original-node fragment. Completely novel nodes are not mentioned, and nodes with no Translations are assumed to be carried through unchanged. Invalidates the rank-based *Paths* index. Does not sort the graph. Suitable for calling in a loop. Can attach newly created nodes on the left of the path to the given set of dangling NodeSides, and populates the set at the end with the *NodeSide* corresponding to the end of the path.

`void vg::VG::find_breakpoints (const Path &path, map<id_t, set<pos_t>> &breakpoints)`

Find all the points at which a *Path* enters or leaves nodes in the graph. Adds them to the given map by node ID of sets of bases in the node that will need to become the starts of new nodes.

`map<pos_t, Node*> vg::VG::ensure_breakpoints (const map<id_t, set<pos_t>> &breakpoints)`

Take a map from node ID to a set of offsets at which new nodes should start (which may include 0 and 1-past-the-end, which should be ignored), break the specified nodes at those positions. Returns a map from old node start position to new node pointer in the graph. Note that the caller will have to create and rebuild path rank data.

Returns a map from old node start position to new node. This map contains some entries pointing to null, for positions past the ends of original nodes. It also maps from positions on either strand of the old node to the same new node pointer; the new node's forward strand is always the same as the old node's forward strand.

`map<id_t, set<pos_t>> vg::VG::forwardize_breakpoints (const map<id_t, set<pos_t>> &breakpoints)`

Flips the breakpoints onto the forward strand.

`void vg::VG::add_nodes_and_edges (const Path &path, const map<pos_t, Node*> &node_translation, map<pair<pos_t, string>, vector<Node*>> &added_seqs, map<Node*, Path> &added_nodes, const map<id_t, size_t> &orig_node_sizes, set<NodeSide> &dangling, size_t max_node_size = 1024)`

Given a path on nodes that may or may not exist, and a map from start position in the old graph to a node in the current graph, add all the new sequence and edges required by the path. The given path must not contain adjacent perfect match edits in the same mapping, or any deletions on the start or end of mappings (the removal of which can be accomplished with the *Path::simplify()* function).

Outputs (and caches for subsequent calls) novel node runs in *added_seqs*, and *Paths* describing where novel nodes translate back to in the original graph in *added_nodes*. Also needs a map of the original sizes of nodes deleted from the original graph, for reverse complementing. If *dangling* is nonempty, left edges of nodes created for initial inserts will connect to the specified sides. At the end, *dangling* is populated with the side corresponding to the last edit in the path.

`void vg::VG::add_nodes_and_edges (const Path &path, const map<pos_t, Node*> &node_translation, map<pair<pos_t, string>, vector<Node*>> &added_seqs, map<Node*, Path> &added_nodes, const map<id_t, size_t> &orig_node_sizes, size_t max_node_size = 1024)`

This version doesn't require a set of dangling sides to populate.

```
vector<Translation> vg::VG::make_translation (const map<pos_t, Node*> &node_translation,  
                                              const map<Node *, Path> &added_nodes,  
                                              const map<id_t, size_t> &orig_node_sizes)
```

Produce a graph *Translation* object from information about the editing process.

```
void vg::VG::add_node (const Node &node)
```

Add in the given node, by value.

```
void vg::VG::add_nodes (const vector<Node> &nodes)
```

Add in the given nodes, by value.

```
void vg::VG::add_edge (const Edge &edge)
```

Add in the given edge, by value.

```
void vg::VG::add_edges (const vector<Edge> &edges)
```

Add in the given edges, by value.

```
void vg::VG::add_edges (const vector<Edge*> &edges)
```

Add in the given edges, by value.

```
void vg::VG::add_nodes (const set<Node*> &nodes)
```

Add in the given nodes, by value.

```
void vg::VG::add_edges (const set<Edge*> &edges)
```

Add in the given edges, by value.

```
size_t vg::VG::node_count (void) const
```

Return the number of nodes in the graph.

```
size_t vg::VG::edge_count (void) const
```

Count the number of edges in the graph.

```
id_t vg::VG::total_length_of_nodes (void)
```

Get the total sequence length of nodes in the graph. TODO: redundant with *length()*.

```
int vg::VG::node_rank (Node *node)
```

Get the rank of the node in the protobuf array that backs the graph.

```
int vg::VG::node_rank (id_t id)
```

Get the rank of the node in the protobuf array that backs the graph.

```
int vg::VG::start_degree (Node *node)
```

Get the number of edges attached to the start of a node.

```
int vg::VG::end_degree (Node *node)
```

Get the number of edges attached to the end of a node.

```
int vg::VG::left_degree (NodeTraversal node)
```

Get the number of edges attached to the left side of a *NodeTraversal*.

```
int vg::VG::right_degree (NodeTraversal node)
```

Get the number of edges attached to the right side of a *NodeTraversal*.

```
void vg::VG::edges_of_node (Node *node, vector<Edge*> &edges)
```

Get the edges of the specified node, and add them to the given vector. Guaranteed to add each edge only once per call.

```
vector<Edge*> vg::VG::edges_of (Node *node)
```

Get the edges of the specified node.

```

vector<Edge*> vg::VG::edges_from(Node*node)
    Get the edges from the specified node.

vector<Edge*> vg::VG::edges_to(Node*node)
    Get the edges to the specified node.

void vg::VG::edges_of_nodes(set<Node*> &nodes, set<Edge*> &edges)
    Get the edges of the specified set of nodes, and add them to the given set of edge pointers.

set<NodeSide> vg::VG::sides_to(NodeSide side)
    Get the sides on the other side of edges to this side of the node.

set<NodeSide> vg::VG::sides_from(NodeSide side)
    Get the sides on the other side of edges from this side of the node.

set<NodeSide> vg::VG::sides_from(id_t id)
    Get the sides from both sides of the node.

set<NodeSide> vg::VG::sides_to(id_t id)
    Get the sides to both sides of the node.

set<NodeSide> vg::VG::sides_of(NodeSide side)
    Union of sides_to and sides_from.

set<pair<NodeSide, bool>> vg::VG::sides_context(id_t node_id)
    Get all sides connecting to this node.

bool vg::VG::same_context(id_t id1, id_t id2)
    Use sides_from an sides_to to determine if both nodes have the same context.

bool vg::VG::is_ancestor_prev(id_t node_id, id_t candidate_id)
    Determine if the node is a prev ancestor of this one.

bool vg::VG::is_ancestor_prev(id_t node_id, id_t candidate_id, set<id_t> &seen, size_t steps
                             = 64)
    Determine if the node is a prev ancestor of this one by trying to find it in a given number of steps.

bool vg::VG::is_ancestor_next(id_t node_id, id_t candidate_id)
    Determine if the node is a next ancestor of this one.

bool vg::VG::is_ancestor_next(id_t node_id, id_t candidate_id, set<id_t> &seen, size_t steps
                             = 64)
    Determine if the node is a next ancestor of this one by trying to find it in a given number of steps.

id_t vg::VG::common_ancestor_prev(id_t id1, id_t id2, size_t steps = 64)
    Try to find a common ancestor by walking back up to steps from the first node.

id_t vg::VG::common_ancestor_next(id_t id1, id_t id2, size_t steps = 64)
    Try to find a common ancestor by walking forward up to steps from the first node.

set<NodeTraversal> vg::VG::siblings_to(const NodeTraversal &traversal)
    To-siblings are nodes which also have edges to them from the same nodes as this one.

set<NodeTraversal> vg::VG::siblings_from(const NodeTraversal &traversal)
    From-siblings are nodes which also have edges to them from the same nodes as this one.

set<NodeTraversal> vg::VG::full_siblings_to(const NodeTraversal &trav)
    Full to-siblings are nodes traversals which share exactly the same upstream NodeSides.

```

`set<NodeTraversal> vg::VG::full_siblings_from(const NodeTraversal &trav)`
Full from-siblings are nodes traversals which share exactly the same downstream *NodeSides*.

`set<Node*> vg::VG::siblings_of(Node *node)`
Get general siblings of a node.

`void vg::VG::simplify_siblings(void)`
Remove easily-resolvable redundancy in the graph.

`void vg::VG::simplify_to_siblings(const set<set<NodeTraversal>> &to_sibs)`
Remove easily-resolvable redundancy in the graph for all provided to-sibling sets.

`void vg::VG::simplify_from_siblings(const set<set<NodeTraversal>> &from_sibs)`
Remove easily-resolvable redundancy in the graph for all provided from-sibling sets.

`set<set<NodeTraversal>> vg::VG::transitive_sibling_sets(const set<set<NodeTraversal>> &sibs)`
Remove intransitive sibling sets, such as where (A, B, C) = S1 but C S2.

`set<set<NodeTraversal>> vg::VG::identically_oriented_sibling_sets(const set<set<NodeTraversal>> &sibs)`
Remove sibling sets which don't have identical orientation.

`bool vg::VG::adjacent(const Position &pos1, const Position &pos2)`
Determine if pos1 occurs directly before pos2.

`Node *vg::VG::create_node(const string &seq, id_t id = 0)`
Create a node. Use the *VG* class to generate ids.

`Node *vg::VG::get_node(id_t id)`
Find a particular node.

`void vg::VG::nonoverlapping_node_context_without_paths(Node *node, VG &g)`
Get the subgraph of a node and all the edges it is responsible for (where it has the minimal ID) and add it into the given *VG*.

`void vg::VG::expand_context(VG &g, size_t distance, bool add_paths = true, bool use_steps = true)`
Expand the context of what's already in the given graph by the given distance, either in nodes or in bases. Pulls material from this graph.

`void vg::VG::expand_context_by_steps(VG &g, size_t steps, bool add_paths = true)`
Expand the context of the given graph by the given number of steps.

`void vg::VG::expand_context_by_length(VG &g, size_t length, bool add_paths = true, bool reflect = false, const set<NodeSide> &barriers = set<NodeSide>())`
Expand the context of the given graph by the given number of bases. If reflect is true, bounce off the ends of nodes to get siblings of nodes you came from. Can take a set of NodeSides not to look out from, that act as barriers to context expansion. These barriers will have no edges attached to them in the final graph.

`void vg::VG::destroy_node(Node *node)`
Destroy the node at the given pointer. This pointer must point to a *Node* owned by the graph.

`void vg::VG::destroy_node(id_t id)`
Destroy the node with the given ID.

```

bool vg::VG::has_node(id_t id)
    Determine if the graph has a node with the given ID.

bool vg::VG::has_node(Node *node)
    Determine if the graph contains the given node.

bool vg::VG::has_node(const Node &node)
    Determine if the graph contains the given node.

Node *vg::VG::find_node_by_name_or_add_new(string name)
    Find a node with the given name, or create a new one if none is found.

void vg::VG::for_each_node(function<void> Node *)
    > lambdaRun the given function on every node.

void vg::VG::for_each_node_parallel(function<void> Node *)
    > lambdaRun the given function on every node in parallel.

void vg::VG::for_each_connected_node(Node *node, function<void> Node *)
    > lambdaGo through all the nodes in the same connected component as the given node. Ignores relative
    orientation.

void vg::VG::dfs(const function<void> NodeTraversal
    > &node_begin_fn, const function<void NodeTraversal> &node_end_fn, const function<boolvoid>
    &break_fn, const function<voidEdge *> &edge_fn, const function<voidEdge *> &tree_fn, const
    function<voidEdge *> &edge_curr_fn, const function<voidEdge *> &edge_cross_fn, const vec-
    tor<NodeTraversal> *sources, const unordered_set<NodeTraversal> *sinks

```

Parameters

- node_begin_fn: Called when node orientation is first encountered.
- node_end_fn: Called when node orientation goes out of scope.
- break_fn: Called to check if we should stop the DFS.
- edge_fn: Called when an edge is encountered.
- tree_fn: Called when an edge forms part of the DFS spanning tree.
- edge_curr_fn: Called when we meet an edge in the current tree component.
- edge_cross_fn: Called when we meet an edge in an already-traversed tree component.
- sources: Start only at these node traversals.
- sinks: When hitting a sink, don't keep walking.

Do a DFS search of the bidirected graph. A bidirected DFS starts at some root node, and traverses first all the nodes found reading out the right of that node in their appropriate relative orientations (including the root), and then all the nodes found reading left out of that node in their appropriate orientations (including the root). If any unvisited nodes are left in other connected components, the process will repeat from one such node, until all nodes have been visited in each orientation.

```

void vg::VG::dfs(const function<void> NodeTraversal
    > &node_begin_fn, const function<void NodeTraversal> &node_end_fn, const vector<NodeTraversal>
    *sources = NULL, const unordered_set<NodeTraversal> *sinks = NULLSpecialization of dfs for only
    handling nodes.

void vg::VG::dfs(const function<void> NodeTraversal
    > &node_begin_fn, const function<void NodeTraversal> &node_end_fn, const function<boolvoid>
    &break_fnSpecialization of dfs for only handling nodes + break function.

```


bool `vg::VG::empty` (void)
Is the graph empty?

const `string` `vg::VG::hash` (void)
Generate a digest of the serialized graph.

void `vg::VG::remove_null_nodes` (void)
Remove nodes with no sequence. These are created in some cases during the process of graph construction.

void `vg::VG::remove_node_forwarding_edges` (*Node* **node*)
Remove a node but connect all of its predecessor and successor nodes with new edges.

void `vg::VG::remove_null_nodes_forwarding_edges` (void)
Remove null nodes but connect predecessors and successors, preserving structure.

void `vg::VG::remove_orphan_edges` (void)
Remove edges for which one of the nodes is not present.

void `vg::VG::remove_inverting_edges` (void)
Remove edges representing an inversion and edges on the reverse complement.

bool `vg::VG::has_inverting_edges` (void)
Determine if the graph has inversions.

void `vg::VG::keep_paths` (set<string> &*path_names*, set<string> &*kept_names*)
Keep paths in the given set of path names. Populates *kept_names* with the names of the paths it actually found to keep. The paths specified may not overlap. Removes all nodes and edges not used by one of the specified paths.

void `vg::VG::keep_path` (const `string` &*path_name*)

int `vg::VG::path_edge_count` (list<*NodeTraversal*> &*path*, int32_t *offset*, int *path_length*)
Path stats. Starting from *offset* in the first node, how many edges do we cross? *path* must be nonempty and longer than the given length. *offset* is interpreted as relative to the first node in its on-path orientation, and is inclusive.

int `vg::VG::path_end_node_offset` (list<*NodeTraversal*> &*path*, int32_t *offset*, int *path_length*)
Determine the offset in its last node at which the path starting at this *offset* in its first node ends. *path* must be nonempty and longer than the given length. *offset* is interpreted as relative to the first node in its on-path orientation, and is inclusive. Returned *offset* is remaining unused length in the last node touched.

const `vector`<*Alignment*> `vg::VG::paths_as_alignments` (void)
Convert the stored paths in this graph to alignments.

const `string` `vg::VG::path_sequence` (const *Path* &*path*)
Return sequence string of path.

double `vg::VG::path_identity` (const *Path* &*path1*, const *Path* &*path2*)
Return percent identity between two paths (# matches / (#matches + #mismatches)). Note: uses ssw aligner, so will only work on small paths.

string `vg::VG::trav_sequence` (const *NodeTraversal* &*trav*)
Get the sequence of a *NodeTraversal*.

id_t `vg::VG::get_node_at_nucleotide` (string *pathname*, int *nuc*)
Takes in a pathname and the nucleotide position (like from a vcf) and returns the node id which contains that position.

Edge *vg::VG::create_edge(*Node* *from, *Node* *to, bool from_start = false, bool to_end = false)
 Create an edge. If the given edge cannot be created, returns null. If the given edge already exists, returns the existing edge.

Edge *vg::VG::create_edge(*id_t* from, *id_t* to, bool from_start = false, bool to_end = false)
 Create an edge. If the given edge cannot be created, returns null. If the given edge already exists, returns the existing edge.

Edge *vg::VG::create_edge(*NodeTraversal* left, *NodeTraversal* right)
 Make a left-to-right edge from the left *NodeTraversal* to the right one, respecting orientations. If the given edge cannot be created, returns null. If the given edge already exists, returns the existing edge.

Edge *vg::VG::create_edge(*NodeSide* side1, *NodeSide* side2)
 Make an edge connecting the given sides of nodes. If the given edge cannot be created, returns null. If the given edge already exists, returns the existing edge.

Edge *vg::VG::get_edge(const *NodeSide* &side1, const *NodeSide* &side2)
 Get a pointer to the specified edge. This can take sides in any order.

Edge *vg::VG::get_edge(const pair<*NodeSide*, *NodeSide*> &sides)
 Get a pointer to the specified edge. This can take sides in any order.

Edge *vg::VG::get_edge(const *NodeTraversal* &left, const *NodeTraversal* &right)
 Get the edge connecting the given oriented nodes in the given order.

void vg::VG::destroy_edge(*Edge* *edge)
 Destroy the edge at the given pointer. This pointer must point to an edge owned by the graph.

void vg::VG::destroy_edge(const *NodeSide* &side1, const *NodeSide* &side2)
 Destroy the edge between the given sides of nodes. These can be in either order.

void vg::VG::destroy_edge(const pair<*NodeSide*, *NodeSide*> &sides)
 Destroy the edge between the given sides of nodes. This can take sides in any order.

void vg::VG::unindex_edge_by_node_sides(const *NodeSide* &side1, const *NodeSide* &side2)
 Remove an edge from the node side indexes, so it doesn't show up when you ask for the edges connected to the side of a node. Makes the edge untraversable until the indexes are rebuilt.

void vg::VG::unindex_edge_by_node_sides(*Edge* *edge)
 Remove an edge from the node side indexes, so it doesn't show up when you ask for the edges connected to the side of a node. Makes the edge untraversable until the indexes are rebuilt.

void vg::VG::index_edge_by_node_sides(*Edge* *edge)
 Add an edge to the node side indexes. Doesn't touch the index of edges by node pairs or the graph; those must be updated separately.

bool vg::VG::has_edge(const *NodeSide* &side1, const *NodeSide* &side2)
 Get the edge between the given node sides, which can be in either order.

bool vg::VG::has_edge(const pair<*NodeSide*, *NodeSide*> &sides)
 Determine if the graph has an edge. This can take sides in any order.

bool vg::VG::has_edge(*Edge* *edge)
 Determine if the graph has an edge. This can take sides in any order.

bool vg::VG::has_edge(const *Edge* &edge)
 Determine if the graph has an edge. This can take sides in any order.

```

bool vg::VG::has_inverting_edge (Node *n)
    Determine if the graph has an inverting edge on the given node.

bool vg::VG::has_inverting_edge_from (Node *n)
    Determine if the graph has an inverting edge from the given node.

bool vg::VG::has_inverting_edge_to (Node *n)
    Determine if the graph has an inverting edge to the given node.

void vg::VG::for_each_edge (function<void> Edge *
    > lambda) Run the given function for each edge.

void vg::VG::for_each_edge_parallel (function<void> Edge *
    > lambda) Run the given function for each edge, in parallel.

void vg::VG::circularize (id_t head, id_t tail)
    Circularize a subgraph / path using the head / tail nodes.

void vg::VG::circularize (vector<string> pathnames)

void vg::VG::connect_node_to_nodes (NodeTraversal node, vector<NodeTraversal> &nodes)
    Connect node -> nodes. Connects from the right side of the first to the left side of the second.

void vg::VG::connect_node_to_nodes (Node *node, vector<Node *> &nodes, bool from_start
    = false)
    Connect node -> nodes. You can optionally use the start of the first node instead of the end.

void vg::VG::connect_nodes_to_node (vector<NodeTraversal> &nodes, NodeTraversal node)
    connect nodes -> node. Connects from the right side of the first to the left side of the second.

void vg::VG::connect_nodes_to_node (vector<Node *> &nodes, Node *node, bool to_end =
    false)
    connect nodes -> node.

void vg::VG::divide_node (Node *node, int pos, Node *&left, Node *&right)
    Divide a node at a given internal position. Inserts the new nodes in the correct paths, but can't update the
    ranks, so they need to be cleared and re-calculated by the caller.

void vg::VG::divide_node (Node *node, vector<int> &positions, vector<Node *> &parts)
    Divide a node at a given internal position. This version works on a collection of internal positions, in linear
    time.

void vg::VG::divide_path (map<long, id_t> &path, long pos, Node *&left, Node *&right)
    Divide a path at a position. Also invalidates stored rank information.

void vg::VG::to_dot (ostream &out, vector<Alignment> alignments = {}, vector<Locus> loci
    = {}, bool show_paths = false, bool walk_paths = false, bool anno-
    tate_paths = false, bool show_mappings = false, bool simple_mode = false,
    bool invert_edge_ports = false, bool color_variants = false, bool ultrabub-
    ble_labeling = false, bool skip_missing_nodes = false, bool ascii_labels =
    false, int random_seed = 0)
    Convert the graph to Dot format.

void vg::VG::to_dot (ostream &out, vector<Alignment> alignments = {}, bool show_paths = false,
    bool walk_paths = false, bool annotate_paths = false, bool show_mappings =
    false, bool invert_edge_ports = false, int random_seed = 0, bool color_variants
    = false)
    Convert the graph to Dot format.

```

`void vg::VG::to_gfa (ostream &out)`
 Convert the graph to GFA format.

`void vg::VG::to_turtle (ostream &out, const string &rdf_base_uri, bool precompress)`
 Convert the graph to Turtle format.

`bool vg::VG::is_valid (bool check_nodes = true, bool check_edges = true, bool check_paths = true, bool check_orphans = true)`
 Determine if the graph is valid or not, according to the specified criteria.

`void vg::VG::lazy_sort (void)`
 Topologically order the nodes in the Protobuf graph. Only valid if the graph is a DAG with all no reversing edges or doubly reversing edges. No guarantee of system independent behavior, but significantly faster than `VG::sort()`.

`void vg::VG::swap_nodes (Node *a, Node *b)`
 Swap the given nodes. TODO: what does that mean?

`void vg::VG::force_path_match (void)`
 For each path, assign edits that describe a total match of the mapping to the node.

`void vg::VG::fill_empty_path_mappings (void)`
 For each path, if a mapping has no edits then make it a perfect match against a node. This is the same as `force_path_match`, but only for empty mappings.

Alignment `vg::VG::align (const string &sequence, Aligner *aligner, bool traceback = true, bool acyclic = false, size_t max_query_graph_ratio = 0, bool pinned_alignment = false, bool pin_left = false, bool banded_global = false, size_t band_padding_override = 0, size_t max_span = 0, bool print_score_matrices = false)`
 Align without base quality adjusted scores. Align to the graph. May modify the graph by re-ordering the nodes. May add nodes to the graph, but cleans them up afterward.

Alignment `vg::VG::align (const Alignment &alignment, Aligner *aligner, bool traceback = true, bool acyclic = false, size_t max_query_graph_ratio = 0, bool pinned_alignment = false, bool pin_left = false, bool banded_global = false, size_t band_padding_override = 0, size_t max_span = 0, bool print_score_matrices = false)`
 Align without base quality adjusted scores. Align to the graph. May modify the graph by re-ordering the nodes. May add nodes to the graph, but cleans them up afterward.

Alignment `vg::VG::align (const Alignment &alignment, bool traceback = true, bool acyclic = false, size_t max_query_graph_ratio = 0, bool pinned_alignment = false, bool pin_left = false, bool banded_global = false, size_t band_padding_override = 0, size_t max_span = 0, bool print_score_matrices = false)`
 Align with default *Aligner*. Align to the graph. May modify the graph by re-ordering the nodes. May add nodes to the graph, but cleans them up afterward.

Alignment `vg::VG::align (const string &sequence, bool traceback = true, bool acyclic = false, size_t max_query_graph_ratio = 0, bool pinned_alignment = false, bool pin_left = false, bool banded_global = false, size_t band_padding_override = 0, size_t max_span = 0, bool print_score_matrices = false)`
 Align with default *Aligner*. Align to the graph. May modify the graph by re-ordering the nodes. May add nodes to the graph, but cleans them up afterward.

Alignment `vg::VG::align_qual_adjusted(const Alignment &alignment, QualAdjAligner *qual_adj_aligner, bool traceback = true, bool acyclic = false, size_t max_query_graph_ratio = 0, bool pinned_alignment = false, bool pin_left = false, bool banded_global = false, size_t band_padding_override = 0, size_t max_span = 0, bool print_score_matrices = false)`

Align with base quality adjusted scores. Align to the graph. May modify the graph by re-ordering the nodes. May add nodes to the graph, but cleans them up afterward.

Alignment `vg::VG::align_qual_adjusted(const string &sequence, QualAdjAligner *qual_adj_aligner, bool traceback = true, bool acyclic = false, size_t max_query_graph_ratio = 0, bool pinned_alignment = false, bool pin_left = false, bool banded_global = false, size_t band_padding_override = 0, size_t max_span = 0, bool print_score_matrices = false)`

Align with base quality adjusted scores. Align to the graph. May modify the graph by re-ordering the nodes. May add nodes to the graph, but cleans them up afterward.

`void vg::VG::for_each_kpath(int k, bool path_only, int edge_max, function<void> NodeTraversal > handle_prev_maxed, function<void NodeTraversal> handle_next_maxed, function<voidlist<NodeTraversal>::iterator, list<NodeTraversal>&> lambda)` Calls a function on all node-crossing paths with up to length across node boundaries. Considers each node in forward orientation to produce the kpaths around it.

`void vg::VG::for_each_kpath_parallel(int k, bool path_only, int edge_max, function<void> NodeTraversal > handle_prev_maxed, function<void NodeTraversal> handle_next_maxed, function<voidlist<NodeTraversal>::iterator, list<NodeTraversal>&> lambda)` Calls a function on all kpaths of the given node.

`void vg::VG::for_each_kpath(int k, bool path_only, int edge_max, function<void> NodeTraversal > handle_prev_maxed, function<void NodeTraversal> handle_next_maxed, function<voidsize_t, Path>> lambda)` Calls a function on all node-crossing paths with up to length across node boundaries. Considers each node in forward orientation to produce the kpaths around it.

`void vg::VG::for_each_kpath_parallel(int k, bool path_only, int edge_max, function<void> NodeTraversal > handle_prev_maxed, function<void NodeTraversal> handle_next_maxed, function<voidsize_t, Path>> lambda)` Calls a function on all kpaths of the given node.

`void vg::VG::for_each_kpath_of_node(Node *node, int k, bool path_only, int edge_max, function<void> NodeTraversal > handle_prev_maxed, function<void NodeTraversal> handle_next_maxed, function<voidlist<NodeTraversal>::iterator, list<NodeTraversal>&> lambda)` Calls a function on all kpaths of the given node.

`void vg::VG::for_each_kpath_of_node(Node *n, int k, bool path_only, int edge_max, function<void> NodeTraversal > handle_prev_maxed, function<void NodeTraversal> handle_next_maxed, function<voidsize_t, Path>> lambda)` Calls a function on all kpaths of the given node.

`void vg::VG::kpaths(set<list<NodeTraversal>> &paths, int length, bool path_only, int edge_max, function<void> NodeTraversal > prev_maxed, function<void NodeTraversal> next_maxed)` Get kpaths. TODO: what is this for?

```

void vg::VG::kpaths (vector<Path> &paths, int length, bool path_only, int edge_max, func-
    tion<void> NodeTraversal
    > prev_maxed, function<void NodeTraversal> next_maxed) Get kpaths. TODO: what is this for?

void vg::VG::kpaths_of_node (Node *node, set<list<NodeTraversal>> &paths, int length, bool
    path_only, int edge_max, function<void> NodeTraversal
    > prev_maxed, function<void NodeTraversal> next_maxed) Get kpaths on a particular node. TODO: what
    is this for?

void vg::VG::kpaths_of_node (Node *node, vector<Path> &paths, int length, bool path_only, int
    edge_max, function<void> NodeTraversal
    > prev_maxed, function<void NodeTraversal> next_maxed) Get kpaths on a particular node. TODO: what
    is this for?

void vg::VG::kpaths_of_node (id_t node_id, vector<Path> &paths, int length, bool path_only, int
    edge_max, function<void> NodeTraversal
    > prev_maxed, function<void NodeTraversal> next_maxed) Get kpaths on a particular node. TODO: what
    is this for?

void vg::VG::prev_kpaths_from_node (NodeTraversal node, int length, bool path_only, int
    edge_max, bool edge_bounding, list<NodeTraversal>
    postfix, set<list<NodeTraversal>> &walked_paths,
    const vector<string> &followed_paths, func-
    tion<void> NodeTraversal
    > &maxed_nodes) Given an oriented start node, a length in bp, a maximum number of edges to cross, and
    a stack of nodes visited so far, fill in the set of paths with all the paths starting at the oriented start node
    and going left off its end no longer than the specified length, calling maxed_nodes on nodes which can't
    be visited due to the edge-crossing limit. Produces paths ending with the specified node. TODO: postfix
    should not be (potentially) copied on every call.

void vg::VG::next_kpaths_from_node (NodeTraversal node, int length, bool path_only, int
    edge_max, bool edge_bounding, list<NodeTraversal>
    prefix, set<list<NodeTraversal>> &walked_paths,
    const vector<string> &followed_paths, func-
    tion<void> NodeTraversal
    > &maxed_nodes) Do the same as prec_kpaths_from_node, except going right, producing a path starting
    with the specified node.

void vg::VG::paths_between (Node *from, Node *to, vector<Path> &paths)

void vg::VG::paths_between (id_t from, id_t to, vector<Path> &paths)

void vg::VG::likelihoods (vector<Alignment> &alignments, vector<Path> &paths, vector<long
    double> &likelihoods)

void vg::VG::nodes_prev (NodeTraversal n, vector<NodeTraversal> &nodes)
    Get the nodes attached to the left side of the given NodeTraversal, in their proper orientations.

vector<NodeTraversal> vg::VG::nodes_prev (NodeTraversal n)
    Get the nodes attached to the left side of the given NodeTraversal, in their proper orientations.

set<NodeTraversal> vg::VG::travs_to (NodeTraversal node)
    Get traversals before this node on the same strand. Same as nodes_prev but using set.

void vg::VG::nodes_next (NodeTraversal n, vector<NodeTraversal> &nodes)
    Get the nodes attached to the right side of the given NodeTraversal, in their proper orientations.

vector<NodeTraversal> vg::VG::nodes_next (NodeTraversal n)
    Get the nodes attached to the right side of the given NodeTraversal, in their proper orientations.

```

```

set<NodeTraversal> vg::VG::travs_from (NodeTraversal node)
    Get traversals after this node on the same strand. Same as nodes_next but using set.

set<NodeTraversal> vg::VG::travs_of (NodeTraversal node)
    Get traversals either before or after this node on the same strand.

int vg::VG::node_count_prev (NodeTraversal n)
    Count the nodes attached to the left side of the given NodeTraversal.

int vg::VG::node_count_next (NodeTraversal n)
    Count the nodes attached to the right side of the given NodeTraversal.

Path vg::VG::create_path (const list<NodeTraversal> &nodes)
    Create a path.

Path vg::VG::create_path (const vector<NodeTraversal> &nodes)
    Create a path.

string vg::VG::path_string (const list<NodeTraversal> &nodes)
    Get the string sequence for all the NodeTraversals on the given path.

string vg::VG::path_string (const Path &path)
    Get the string sequence for traversing the given path. Assumes the path covers the entirety of any nodes
    visited. Handles backward nodes.

void vg::VG::expand_path (const list<NodeTraversal> &path, vector<NodeTraversal> &ex-
                        panded)
    Expand a path. TODO: what does that mean?

void vg::VG::node_starts_in_path (const list<NodeTraversal> &path, map<Node *, int>
                        &node_start)
    Fill in the node_start map with the first index along the path at which each node appears. Caller is respon-
    sible for dealing with orientations.

bool vg::VG::nodes_are_perfect_path_neighbors (NodeTraversal left, NodeTraversal
                        right)
    Return true if nodes share all paths and the mappings they share in these paths are adjacent, in the specified
    relative order and orientation.

bool vg::VG::mapping_is_total_match (const Mapping &m)
    Return true if the mapping completely covers the node it maps to and is a perfect match.

map<string, vector<Mapping>> vg::VG::concat_mappings_for_node_pair (id_t id1, id_t
                        id2)
    Concatenate the mappings for a pair of nodes; handles multiple mappings per path.

map<string, vector<Mapping>> vg::VG::concat_mappings_for_nodes (const
                        list<NodeTraversal>
                        &nodes)
    Concatenate mappings for a list of nodes that we want to concatenate. Returns, for each path name, a
    vector of merged mappings, once per path traversal of the run of nodes. Those merged mappings are in
    the orientation of the merged node (so mappings to nodes that are traversed in reverse will have their flags
    toggled). We assume that all mappings on the given nodes are full-length perfect matches, and that all the
    nodes are perfect path neighbors.

void vg::VG::expand_path (list<NodeTraversal> &path, vector<list<NodeTraversal>::iterator>
                        &expanded)
    Expand a path. TODO: what does that mean? These versions handle paths in which nodes can be traversed
    multiple times. Unfortunately since we're throwing non-const iterators around, we can't take the input path
    as const.

```



```
void vg::VG::node_starts_in_path(list<NodeTraversal> &path, map<NodeTraversal *, int>
                                &node_start)
```

Find node starts in a path. TODO: what does that mean? To get the starts out of the map this produces, you need to dereference the iterator and then get the address of the *NodeTraversal* (stored in the list) that you are talking about.

```
void vg::VG::for_each_kmer_parallel(int kmer_size, bool path_only, int edge_max, func-
                                tion<void> string&, list<NodeTraversal>::iterator, int,
                                list<NodeTraversal>&, VG&
                                > lambda, int stride = 1, bool allow_dups = false, bool allow_negatives = false) Call a function for each
                                kmer in the graph, in parallel.
```

```
void vg::VG::for_each_kmer(int kmer_size, bool path_only, int edge_max, func-
                                tion<void> string&, list<NodeTraversal>::iterator, int,
                                list<NodeTraversal>&, VG&
                                > lambda, int stride = 1, bool allow_dups = false, bool allow_negatives = false) Call a function for each
                                kmer in the graph.
```

```
void vg::VG::for_each_kmer_of_node(Node *node, int kmer_size, bool path_only,
                                int edge_max, function<void> string&,
                                list<NodeTraversal>::iterator, int,
                                list<NodeTraversal>&, VG&
                                > lambda, int stride = 1, bool allow_dups = false, bool allow_negatives = false) Call a function for each
                                kmer on a node.
```

```
void vg::VG::kmer_context(string &kmer, int kmer_size, bool path_only, int
                                edge_max, bool forward_only, list<NodeTraversal> &path,
                                list<NodeTraversal>::iterator start_node, int32_t start_offset,
                                list<NodeTraversal>::iterator &end_node, int32_t &end_offset,
                                set<tuple<char, id_t, bool, int32_t>> &prev_positions,
                                set<tuple<char, id_t, bool, int32_t>> &next_positions)
```

For the given kmer of the given length starting at the given offset into the given *Node* along the given path, fill in end_node and end_offset with where the end of the kmer falls (counting from the right side of the *NodeTraversal*), prev_chars with the characters that precede it, next_chars with the characters that follow it, prev_ and next_positions with the ((node ID, orientation), offset) pairs of the places you can come from/go next (from the right end of the kmer). Refuses to follow more than edge_max edges. Offsets are in the path orientation. Meant for gcsa2.

```
void vg::VG::gcsa_handle_node_in_graph(Node *node, int kmer_size, bool path_only,
                                int edge_max, int stride, bool forward_only,
                                Node *head_node, Node *tail_node, func-
                                tion<void> KmerPosition&
```

> lambda) Do the GCSA2 kmers for a node. head_node and tail_node must both be non- null, but only one of those nodes actually needs to be in the graph. They will be examined directly to get their representative characters. They also don't need to be actually owned by the graph; they can be copies.

```
void vg::VG::for_each_gcsa_kmer_position_parallel(int kmer_size, bool path_only,
                                int edge_max, int stride,
                                bool forward_only, id_t
                                &head_id, id_t &tail_id,
                                function<void> KmerPosition&
```

> lambda) Call a function for each GCSA2 kmer position in parallel. GCSA kmers are the kmers in the graph with each node existing in both its forward and reverse-complement orientation. *Node* IDs in the GCSA graph are 2 * original node ID, +1 if the GCSA node represents the reverse complement, and +0 if it does not. Non-reversing edges link the forward copy of the from node to the forward copy of the to node, and similarly for the reverse complement copies, while reversing edges link the forward copy of the from node to the *reverse complement* copy of the to node, and visa versa. This allows us to index both the

forward and reverse strands of every node, and to deal with GCSA's lack of support for reversing edges, with the same trick. Note that `start_tail_id`, if zero, will be replaced with the ID actually used for the start/end node before `lambda` is ever called.

```
void vg::VG::get_gcsa_kmers (int kmer_size, bool path_only, int edge_max, int stride, bool forward_only, const function<void> vector<gcsa::KMer>&, bool > &handle_kmers, id_t &head_id, id_t &tail_id)
    Get the GCSA2 kmers in the graph.
```

```
void vg::VG::write_gcsa_kmers (int kmer_size, bool path_only, int edge_max, int stride, bool forward_only, ostream &out, id_t &head_id, id_t &tail_id)
    Write the GCSA2 kmer file for the graph to the given stream.
```

```
string vg::VG::write_gcsa_kmers_to_tmpfile (int kmer_size, bool paths_only, bool forward_only, id_t &head_id, id_t &tail_id, size_t doubling_steps = 2, size_t size_limit = 200, const string &base_file_name = ".vg-kmers-tmp-")
    Write the GCSA2 kmers to a temp file with the given base. Return the name of the file.
```

```
void vg::VG::build_gcsa_lcp (gcsa::GCSA *gcsa, gcsa::LCPArray *lcp, int kmer_size, bool paths_only, bool forward_only, size_t doubling_steps = 2, size_t size_limit = 200, const string &base_file_name = ".vg-kmers-tmp-")
    Construct the GCSA2 index for this graph.
```

```
void vg::VG::prune_complex (int path_length, int edge_max, Node *head_node, Node *tail_node)
    Take all nodes that would introduce paths of > edge_max edge crossings, remove them, and link their neighbors to head_node or tail_node depending on which direction the path extension was stopped. For pruning graph prior to indexing with gcsa2.
```

```
void vg::VG::prune_complex_with_head_tail (int path_length, int edge_max)
    Wrap the graph with heads and tails before doing the prune. Utility function for preparing for indexing.
```

```
Alignment vg::VG::random_read (size_t read_len, mt19937 &rng, id_t min_id, id_t max_id, bool either_strand)
    Generate random reads. Note that even if either_strand is false, having backward nodes in the graph will result in some reads from the global reverse strand.
```

```
void vg::VG::disjoint_subgraphs (list<VG> &subgraphs)
    Find subgraphs.
```

```
void vg::VG::head_nodes (vector<Node*> &nodes)
    Get the head nodes (nodes with edges only to their right sides). These are required to be oriented forward.
```

```
vector<Node*> vg::VG::head_nodes (void)
    Get the head nodes (nodes with edges only to their right sides). These are required to be oriented forward.
```

```
bool vg::VG::is_head_node (id_t id)
    Determine if a node is a head node.
```

```
bool vg::VG::is_head_node (Node *node)
    Determine if a node is a head node.
```

```
int32_t vg::VG::distance_to_head (NodeTraversal node, int32_t limit = 1000)
    Get the distance in bases from start of node to closest head node of graph, or -1 if that distance exceeds the limit.
```

```
int32_t vg::VG::distance_to_head(NodeTraversal node, int32_t limit, int32_t dist,
                                set<NodeTraversal> &seen)
```

Get the distance in bases from start of node to closest head node of graph, or -1 if that distance exceeds the limit. dist increases by the number of bases of each previous node until you reach the head node seen is a set that holds the nodes that you have already gotten the distance of, but starts off empty

```
vector<Node*> vg::VG::tail_nodes(void)
```

Get the tail nodes (nodes with edges only to their left sides). These are required to be oriented forward.

```
void vg::VG::tail_nodes(vector<Node*> &nodes)
```

Get the tail nodes (nodes with edges only to their left sides). These are required to be oriented forward.

```
bool vg::VG::is_tail_node(id_t id)
```

Determine if a node is a tail node.

```
bool vg::VG::is_tail_node(Node *node)
```

Determine if a node is a tail node.

```
int32_t vg::VG::distance_to_tail(NodeTraversal node, int32_t limit = 1000)
```

Get the distance from tail of node to end of graph, or -1 if limit exceeded.

```
int32_t vg::VG::distance_to_tail(NodeTraversal node, int32_t limit, int32_t dist,
                                set<NodeTraversal> &seen)
```

Get the distance in bases from end of node to closest tail of graph, or -1 if that distance exceeds the limit. dist increases by the number of bases of each next node until you reach the tail node seen is a set that holds the nodes that you have already gotten the distance of, but starts off empty

```
int32_t vg::VG::distance_to_tail(id_t id, int32_t limit = 1000)
```

Get the distance from tail of node to end of graph, or -1 if limit exceeded.

```
void vg::VG::collect_subgraph(Node *node, set<Node*> &subgraph)
```

Collect the subgraph of a *Node*. TODO: what does that mean?

```
Node *vg::VG::join_heads(void)
```

Join head nodes of graph to common null node, creating a new single head.

```
void vg::VG::join_heads(Node *node, bool from_start = false)
```

Join head nodes of graph to specified node. Optionally from the start/to the end of the new node.

```
void vg::VG::join_tails(Node *node, bool to_end = false)
```

Join tail nodes of graph to specified node. Optionally from the start/to the end of the new node.

```
void vg::VG::wrap_with_null_nodes(void)
```

Add singular head and tail null nodes to graph.

```
void vg::VG::add_start_end_markers(int length, char start_char, char end_char, Node
                                   *&start_node, Node *&end_node, id_t start_id = 0,
                                   id_t end_id = 0)
```

Add a start node and an end node, where all existing heads in the graph are connected to the start node, and all existing tails in the graph are connected to the end node. Any connected components in the graph which do not have either are connected to the start at an arbitrary point, and the end node from nodes going to that arbitrary point. If start_node or end_node is null, a new node will be created. Otherwise, the passed node will be used. Note that this visits every node, to make sure it is attached to all connected components. Note that if a graph has, say, heads but no tails, the start node will be attached but the end node will be free-floating.

Public Members

Graph `vg::VG::graph`

Protobuf-based representation.

Paths `vg::VG::paths`

Manages paths of the graph. Initialized by setting `paths._paths = graph.paths`.

`string` `vg::VG::name`

Name of the graph.

id_t `vg::VG::current_id`

Current id for *Node* to be added next.

hash_map<*id_t*, *Node* *> `vg::VG::node_by_id`

Nodes by id.

pair_hash_map<*pair*<*NodeSide*, *NodeSide*>, *Edge* *> `vg::VG::edge_by_sides`

Edges by sides of *Nodes* they connect. Since duplicate edges are not permitted, two edges cannot connect the same pair of node sides. Each edge is indexed here with the smaller *NodeSide* first. The actual node order is recorded in the *Edge* object.

hash_map<*Node* *, *int*> `vg::VG::node_index`

nodes by position in nodes repeated field. this is critical to allow fast deletion of nodes

hash_map<*Edge* *, *int*> `vg::VG::edge_index`

hash_map<*id_t*, *vector*<*pair*<*id_t*, *bool*>>> `vg::VG::edges_on_start`

Stores the destinations and backward flags for edges attached to the starts of nodes (whether that node is “from” or “to”).

hash_map<*id_t*, *vector*<*pair*<*id_t*, *bool*>>> `vg::VG::edges_on_end`

Stores the destinations and backward flags for edges attached to the ends of nodes (whether that node is “from” or “to”).

map<*string*, *SnarlTraversal*> `vg::VG::variant_to_traversal`

Private Functions

`void` `vg::VG::_for_each_kmer` (*int* *kmer_size*, *bool* *path_only*, *int* *edge_max*, *function*<*void*> *string*&, *list*<*NodeTraversal*>::*iterator*, *int*, *list*<*NodeTraversal*>&, *VG*&
> *lambda*, *bool* *parallel*, *int* *stride*, *bool* *allow_dups*, *bool* *allow_negatives*, *Node* **node* = nullptr) Call the given function on each kmer. If *parallel* is specified, goes through nodes one per thread. If *node* is not null, looks only at kmers of that specific node.

Alignment `vg::VG::align` (*const* *Alignment* &*alignment*, *Aligner* **aligner*, *QualAdjAligner* **qual_adj_aligner*, *bool* *traceback* = true, *bool* *acyclic* = false, *size_t* *max_query_graph_ratio* = 0, *bool* *pinned_alignment* = false, *bool* *pin_left* = false, *bool* *banded_global* = false, *size_t* *band_padding_override* = 0, *size_t* *max_span* = 0, *bool* *print_score_matrices* = false)

Private method to funnel other align functions into. *max_span* specifies the min distance to unfold the graph to, and is meant to be the longest path that the specified sequence could cover, accounting for deletions. If it's less than the sequence's length, the sequence's length is used. *band_padding_override* gives the band padding to use for banded global alignment. In banded global mode, if the band padding

override is nonzero, permissive banding is not used, and instead the given band padding is provided. If the band padding override is not provided, the max span is used as the band padding and permissive banding is enabled.

```
void vg::VG::init (void)
    setup, ensures that gssw == NULL on startup
```

Private Members

```
vector<id_t> vg::VG::empty_ids
    Placeholder for functions that sometimes need to be passed an empty vector.
```

```
vector<pair<id_t, bool>> vg::VG::empty_edge_ends
    Placeholder for functions that sometimes need to be passed an empty vector.
```

Private Static Attributes

```
const size_t vg::VG::HIGH_BIT
const size_t vg::VG::LOW_BITS
class #include <vg_set.hpp>Public Functions
```

```
vg::VGset::VGset ()
vg::VGset::VGset (vector<string> &files)
void vg::VGset::transform (std::function<void> VG *
    > lambda)
void vg::VGset::for_each (std::function<void> VG *
    > lambda)
int64_t vg::VGset::merge_id_space (void)
void vg::VGset::to_xg (xg::XG &index, bool store_threads = false)
    Transforms to a succinct, queryable representation.
void vg::VGset::to_xg (xg::XG &index, bool store_threads, const regex &paths_to_take,
    map<string, Path> &removed_paths)
    As above, except paths with names matching the given regex are removed and returned separately by
    inserting them into the provided map.
void vg::VGset::store_in_index (Index &index)
void vg::VGset::store_paths_in_index (Index &index)
void vg::VGset::index_kmers (Index &index, int kmer_size, bool path_only, int edge_max, int
    stride = 1, bool allow_negatives = false)
void vg::VGset::for_each_kmer_parallel (const function<void> string&,
    list<NodeTraversal>::iterator, int,
    list<NodeTraversal>&, VG&
    > &lambda, int kmer_size, bool path_only, int edge_max, int stride, bool allow_dups, bool al-
    low_negatives = false)
```

```
void vg::VGset::write_gcsa_out (ostream &out, int kmer_size, bool path_only, bool forward_only, int64_t head_id = 0, int64_t tail_id = 0)

void vg::VGset::write_gcsa_kmers_binary (ostream &out, int kmer_size, bool path_only, bool forward_only, int64_t head_id = 0, int64_t tail_id = 0)

void vg::VGset::get_gcsa_kmers (int kmer_size, bool path_only, bool forward_only, const function<void> vector<gcsa::KMer>&, bool > &handle_kmers, int64_t head_id = 0, int64_t tail_id = 0)

vector<string> vg::VGset::write_gcsa_kmers_binary (int kmer_size, bool path_only, bool forward_only, int64_t head_id = 0, int64_t tail_id = 0)
```

Public Members

```
vector<string> vg::VGset::filenames

bool vg::VGset::show_progress
```

Private Functions

```
void vg::VGset::for_each_gcsa_kmer_position_parallel (int kmer_size, bool path_only, bool forward_only, int64_t &head_id, int64_t &tail_id, function<void> KmerPosition& > lambda
```

struct Describes a step of a walk through a *Snarl* either on a node or through a child *Snarl*. **Public Members**

```
int64 vg::Visit::node_id
    The node ID or snarl of this step (only one should be given)
```

```
Snarl vg::Visit::snarl
    only needs to contain the start and end Visits
```

```
bool vg::Visit::backward
    Indicates: if node_id is specified reverse complement of node if feature_id is specified traversal of a child snarl entering backwards through end and leaving backwards through start
struct #include <flow_sort.hpp>Public Functions
```

```
void vg::FlowSort::WeightedGraph::construct (FlowSort &fs, const string &ref_name, bool isGrooming = true)
```

Public Members

```
EdgeMapping vg::FlowSort::WeightedGraph::edges_out_nodes
```

```
EdgeMapping vg::FlowSort::WeightedGraph::edges_in_nodes
```

map<Edge *, int> vg::FlowSort::WeightedGraph::edge_weight

class #include <vcf_buffer.hpp> Provides a look-around buffer for VCFs where you can look at each variant in the context of nearby variants. Also caches parsings of genotypes, so you can iterate over genotypes efficiently without parsing them out over and over again. **Public Functions**

vg::WindowedVcfBuffer::WindowedVcfBuffer (vcflib::VariantCallFile *file, size_t window_size)

Make a new *WindowedVcfBuffer* buffering the file at the given pointer (which must outlive the buffer, but which may be null). The VCF in the file must be sorted, but may contain overlapping variants.

bool vg::WindowedVcfBuffer::next ()

Advance to the next variant, making it the current variant. Returns true if a next variant exists, and false if no next variant can be found. Must be called (and return true) before the first call to *get()* after constructing the *WindowedVcfBuffer* or setting the region.

tuple<vector<vcflib::Variant *>, vcflib::Variant *, vector<vcflib::Variant *>> vg::WindowedVcfBuffer::get ()

Get the current variant in its context. Throws an exception if no variant is current. Returns a vector of variants in the window before the current variant, the current variant, and a vector of variants in the window after the current variant.

Pointers will be invalidated upon the next call to *next()* or *set_region()*.

tuple<vector<vcflib::Variant *>, vcflib::Variant *, vector<vcflib::Variant *>> vg::WindowedVcfBuffer::get_nonoverlapping ()

Like *get()*, but elides variants in the context that overlap the current variant, or each other.

const vector<vector<int>> &vg::WindowedVcfBuffer::get_parsed_genotypes (vcflib::Variant *variant)

Given a pointer to a cached variant owned by this *WindowedVcfBuffer* (such as might be obtained from *get()*), return the cached parsed-out genotypes for all the samples, in the order the samples appear in the VCF file.

Returns a reference which is valid until the variant passed in is scrolled out of the buffer.

bool vg::WindowedVcfBuffer::has_tabix () const

This returns true if we have a tabix index, and false otherwise. If this is false, *set_region* may be called, but will do nothing and return false.

bool vg::WindowedVcfBuffer::set_region (const string &contig, int64_t start = -1, int64_t end = -1)

This tries to set the region on the underlying vcflib VariantCallFile to the given contig and region, if specified. Coordinates coming in should be 0-based, and will be converted to 1-based internally.

Returns true if the region was successfully set, and false otherwise (for example, if there is not tabix index, or if the given region is not part of this VCF. Note that if there is a tabix index, and *set_region* returns false, the position in the VCF file is undefined until the next successful *set_region* call.

If either of start and end are specified, then both of start and end must be specified.

Discards any variants previously in the buffer.

Protected Attributes

VcfBuffer vg::WindowedVcfBuffer::reader

size_t vg::WindowedVcfBuffer::window_size

list<unique_ptr<vcflib::Variant>> vg::WindowedVcfBuffer::variants_before

```
list<unique_ptr<vcflib::Variant>> vg::WindowedVcfBuffer::variants_after
unique_ptr<vcflib::Variant> vg::WindowedVcfBuffer::current
map<vcflib::Variant *, vector<vector<int>>> vg::WindowedVcfBuffer::cached_genotypes
vector<size_t> vg::WindowedVcfBuffer::map_order_to_original
```

Protected Static Functions

```
vector<int> vg::WindowedVcfBuffer::decompose_genotype_fast(const string &genotype)
                                                    (type)
    Quickly decompose a genotype without any string copies.
```

Private Functions

```
vg::WindowedVcfBuffer::WindowedVcfBuffer(const WindowedVcfBuffer &other)
WindowedVcfBuffer &vg::WindowedVcfBuffer::operator=(const WindowedVcfBuffer
                                                         &other)
class #include <xg.hpp> Provides succinct storage for a graph, its positional paths, and a set of embedded
threads. Inherits from vg::HandleGraph Public Types
```

```
using
using
```

Public Functions

```
xg::XG::XG(void)
xg::XG::~~XG(void)
xg::XG::XG(istream &in)
xg::XG::XG(Graph &graph)
xg::XG::XG(function<void> function<void>
            Graph&>> get_chunks
xg::XG::XG(const XG &other)
xg::XG::XG(XG &&other)
XG &xg::XG::operator=(const XG &other)
XG &xg::XG::operator=(XG &&other)
void xg::XG::from_stream(istream &in, bool validate_graph = false, bool print_graph = false,
                        bool store_threads = false, bool is_sorted_dag = false)
void xg::XG::from_graph(Graph &graph, bool validate_graph = false, bool print_graph = false,
                        bool store_threads = false, bool is_sorted_dag = false)
```

```

void xg::XG::from_callback (function<void> function<void
    Graph&>> get_chunks, bool validate_graph = false, bool print_graph = false, bool store_threads = false,
    bool is_sorted_dag = false

void xg::XG::build (vector<pair<id_t, string>> &node_label, unordered_map<side_t, vec-
    tor<side_t>> &from_to, unordered_map<side_t, vector<side_t>> &to_from,
    map<string, vector<trav_t>> &path_nodes, bool validate_graph, bool
    print_graph, bool store_threads, bool is_sorted_dag)

void xg::XG::load (istream &in)

size_t xg::XG::serialize (std::ostream &out, sds::structure_tree_node *v = NULL, std::string
    name = "")

const uint64_t *xg::XG::sequence_data (void) const

const size_t xg::XG::sequence_bit_size (void) const

size_t xg::XG::id_to_rank (int64_t id) const

int64_t xg::XG::rank_to_id (size_t rank) const

size_t xg::XG::max_node_rank (void) const

bool xg::XG::has_node (int64_t id) const

int64_t xg::XG::node_at_seq_pos (size_t pos) const
    Get the node ID at the given sequence position. Works in 1-based coordinates.

size_t xg::XG::node_start (int64_t id) const

Node xg::XG::node (int64_t id) const

string xg::XG::node_sequence (int64_t id) const

size_t xg::XG::node_length (int64_t id) const

char xg::XG::pos_char (int64_t id, bool is_rev, size_t off) const

string xg::XG::pos_substr (int64_t id, bool is_rev, size_t off, size_t len = 0) const

size_t xg::XG::node_graph_idx (int64_t id) const

size_t xg::XG::edge_graph_idx (const Edge &edge) const

bool xg::XG::has_edge (int64_t id1, bool is_start, int64_t id2, bool is_end) const
    Returns true if the given edge is present in the given orientation, and false otherwise.

bool xg::XG::has_edge (const Edge &edge) const
    Returns true if the given edge is present in either orientation, and false otherwise.

vector<Edge> xg::XG::edges_of (int64_t id) const

vector<Edge> xg::XG::edges_to (int64_t id) const

vector<Edge> xg::XG::edges_from (int64_t id) const

vector<Edge> xg::XG::edges_on_start (int64_t id) const

vector<Edge> xg::XG::edges_on_end (int64_t id) const

```

Edge `xg::XG::canonicalize (const Edge &edge) const`
Get the rank of the edge, or `numeric_limits<size_t>.max()` if no such edge exists.

Graph `xg::XG::node_subgraph_id (int64_t id) const`
use the unified graph storage to return a node subgraph

Graph `xg::XG::node_subgraph_g (int64_t g) const`
returns the graph with graph offsets rather than ids on edges and nodes

Graph `xg::XG::graph_context_id (const pos_t &pos, int64_t length) const`
provide the graph context up to a given length from the current position; step by nodes

Graph `xg::XG::graph_context_g (const pos_t &pos, int64_t length) const`

Edge `xg::XG::edge_from_encoding (int64_t from, int64_t to, int type) const`
return an edge from the three-part encoding used in the graph vector Edge type encoding: 1: end to start
2: end to end 3: start to start 4: start to end

void `xg::XG::idify_graph (Graph &graph) const`

int `xg::XG::edge_type (bool from_start, bool to_end) const`
a numerical code for the edge type (based on the two reversal flags)

int `xg::XG::edge_type (const Edge &edge) const`

handle_t `xg::XG::get_handle (const id_t &node_id, bool is_reverse) const`
Look up the handle for the node with the given ID in the given orientation.

id_t `xg::XG::get_id (const handle_t &handle) const`
Get the ID from a handle.

bool `xg::XG::get_is_reverse (const handle_t &handle) const`
Get the orientation of a handle.

handle_t `xg::XG::flip (const handle_t &handle) const`
Invert the orientation of a handle (potentially without getting its ID)

size_t `xg::XG::get_length (const handle_t &handle) const`
Get the length of a node.

string `xg::XG::get_sequence (const handle_t &handle) const`
Get the sequence of a node, presented in the handle's local forward orientation.

bool `xg::XG::follow_edges (const handle_t &handle, bool go_left, const function<bool> const
handle_t &
> &iteratee) const` Loop over all the handles to next/previous (right/left) nodes. Passes them to a callback
which returns false to stop iterating and true to continue.

void `xg::XG::for_each_handle (const function<bool> const handle_t &
> &iteratee) const` Loop over all the nodes in the graph in their local forward orientations, in their internal
stored order. Stop if the iteratee returns false.

size_t `xg::XG::node_size () const`
Return the number of nodes in the graph.

void `xg::XG::neighborhood (int64_t id, size_t dist, Graph &g, bool use_steps = true) const`

void `xg::XG::for_path_range (const string &name, int64_t start, int64_t stop, func-
tion<void> int64_t node_id
> lambda, bool is_rev = false) const`

```

void xg::XG::get_path_range (const string &name, int64_t start, int64_t stop, Graph &g, bool
                             is_rev = false) const

void xg::XG::expand_context (Graph &g, size_t dist, bool add_paths = true, bool use_steps =
                             true, bool expand_forward = true, bool expand_backward = true,
                             int64_t until_node = 0) const

void xg::XG::expand_context_by_steps (Graph &g, size_t steps, bool add_paths = true, bool
                                       expand_forward = true, bool expand_backward =
                                       true, int64_t until_node = 0) const

void xg::XG::expand_context_by_length (Graph &g, size_t length, bool add_paths =
                                       true, bool expand_forward = true, bool ex-
                                       pand_backward = true, int64_t until_node = 0)
                                       const

void xg::XG::get_connected_nodes (Graph &g) const

void xg::XG::get_id_range (int64_t id1, int64_t id2, Graph &g) const

void xg::XG::get_id_range_by_length (int64_t id1, int64_t length, Graph &g, bool forward)
                                     const

Path xg::XG::path (const string &name) const

const XGPath &xg::XG::get_path (const string &name) const

size_t xg::XG::path_rank (const string &name) const

size_t xg::XG::max_path_rank (void) const

string xg::XG::path_name (size_t rank) const

vector<size_t> xg::XG::paths_of_node (int64_t id) const

map<string, vector<Mapping>> xg::XG::node_mappings (int64_t id) const

bool xg::XG::path_contains_node (const string &name, int64_t id) const

void xg::XG::add_paths_to_graph (map<int64_t, Node*> &nodes, Graph &g) const

size_t xg::XG::node_occs_in_path (int64_t id, const string &name) const

size_t xg::XG::node_occs_in_path (int64_t id, size_t rank) const

vector<size_t> xg::XG::node_ranks_in_path (int64_t id, const string &name) const

vector<size_t> xg::XG::node_ranks_in_path (int64_t id, size_t rank) const

vector<size_t> xg::XG::position_in_path (int64_t id, const string &name) const

vector<size_t> xg::XG::position_in_path (int64_t id, size_t rank) const

map<string, vector<size_t>> xg::XG::position_in_paths (int64_t id, bool is_rev = false, size_t
                                                         offset = 0) const

map<string, vector<pair<size_t, bool>>> xg::XG::offsets_in_paths (pos_t pos) const

map<string, vector<pair<size_t, bool>>> xg::XG::nearest_offsets_in_paths (pos_t      pos,
                                                                    int64_t
                                                                    max_search)
                                                                    const

```

```
map<string, vector<size_t>> xg::XG::distance_in_paths (int64_t id1, bool is_rev1, size_t offset1, int64_t id2, bool is_rev2, size_t offset2) const
```

```
int64_t xg::XG::min_distance_in_paths (int64_t id1, bool is_rev1, size_t offset1, int64_t id2, bool is_rev2, size_t offset2) const
```

```
int64_t xg::XG::node_at_path_position (const string &name, size_t pos) const
```

Get the ID of the node that covers the given 0-based position along the path.

```
Mapping xg::XG::mapping_at_path_position (const string &name, size_t pos) const
```

Get the Mapping that covers the given 0-based position along the path.

```
size_t xg::XG::node_start_at_path_position (const string &name, size_t pos) const
```

Get the 0-based start position in the path that covers the given 0-based position along the path.

```
pos_t xg::XG::graph_pos_at_path_position (const string &name, size_t pos) const
```

Get the graph position at the given 0-based path position.

```
Alignment xg::XG::target_alignment (const string &name, size_t pos1, size_t pos2, const string &feature) const
```

```
size_t xg::XG::path_length (const string &name) const
```

```
size_t xg::XG::path_length (size_t rank) const
```

```
pair<int64_t, vector<size_t>> xg::XG::nearest_path_node (int64_t id, int max_steps = 16) const
```

```
int64_t xg::XG::min_approx_path_distance (int64_t id1, int64_t id2) const
```

```
pair<pos_t, int64_t> xg::XG::next_path_position (pos_t pos, int64_t max_search) const
```

nearest position that is in a path and the distance between it and the current position

```
bool xg::XG::paths_on_same_component (size_t path_rank_1, size_t path_rank_2) const
```

returns true if the paths are on the same connected component of the graph (constant time)

```
vector<pair<size_t, vector<pair<size_t, bool>>>> xg::XG::oriented_paths_of_node (int64_t id) const
```

returns all of the paths that a node traversal occurs on, the rank of these occurrences on the path and the orientation of the occurrences. false indicates that the traversal occurs in the same orientation as in the path, true indicates.

```
void xg::XG::memoized_oriented_paths_of_node (int64_t id, vector<pair<size_t, vector<pair<size_t, bool>>>> &local_paths_var, vector<pair<size_t, bool>>>> *paths_of_node_ptr_out, unordered_map<id_t, vector<pair<size_t, vector<pair<size_t, bool>>>> *paths_of_node_memo = nullptr) const
```

sets a pointer to a memoized result from oriented_paths_of_node. if no memo is provided, the result will be queried and stored in local_paths_var and the pointer will be set to point to this variable so that no additional code paths are necessary

`handle_t xg::XG::memoized_get_handle(int64_t id, bool rev, unordered_map<pair<int64_t, bool>, handle_t> *handle_memo = nullptr) const`
 returns a the memoized result from `get_handle` if a memo is provided that the result has been queried previously otherwise, returns the result of `get_handle` directly and stores it in the memo if one is provided

`int64_t xg::XG::closest_shared_path_oriented_distance(int64_t id1, size_t offset1, bool rev1, int64_t id2, size_t offset2, bool rev2, size_t max_search_dist = 100, unordered_map<id_t, vector<pair<size_t, vector<pair<size_t, bool>>>> *paths_of_node_memo = nullptr, unordered_map<pair<int64_t, bool>, handle_t> *handle_memo = nullptr) const`
 the oriented distance (positive if pos2 is further along the path than pos1, otherwise negative) estimated by the distance along the nearest shared path to the two positions plus the distance to traverse to that path. returns `numeric_limits<int64_t>::max()` if no pair of nodes that occur same on the strand of a path are reachable within the max search distance (measured in sequence length, not node length).

`vector<tuple<int64_t, bool, size_t>> xg::XG::jump_along_closest_path(int64_t id, bool is_rev, size_t offset, int64_t jump_dist, size_t max_search_dist, unordered_map<id_t, vector<pair<size_t, vector<pair<size_t, bool>>>> *paths_of_node_memo = nullptr, unordered_map<pair<int64_t, bool>, handle_t> *handle_memo = nullptr) const`
 returns a vector of (node id, is reverse, offset) tuples that are found by jumping a fixed oriented distance along path(s) from the given position. if the position is not on a path, searches from the position to a path and adds/subtracts the search distance to the jump depending on the search direction. returns an empty vector if there is no path within the max search distance or if the jump distance goes past the end of the path

`int64_t xg::XG::where_to(int64_t current_side, int64_t visit_offset, int64_t new_side) const`

`int64_t xg::XG::where_to(int64_t current_side, int64_t visit_offset, int64_t new_side, vector<Edge> &edges_into_new, vector<Edge> &edges_out_of_old) const`

`int64_t xg::XG::node_height(ThreadMapping node) const`

`void xg::XG::set_thread_names(const vector<string> &names)`

Replace the existing thread names with the new names. Each name must be unique.

`void xg::XG::insert_thread(const thread_t &t, const string &name)`

Insert a thread. Name must be unique or empty. `bs_bake()` and `tn_bake()` need to be called before queries.

```
void xg::XG::insert_threads_into_dag(const vector<thread_t> &t, const vector<string>
                                   &names)
```

Insert a whole group of threads. Names should be unique or empty (though they aren't used yet). The indexed graph must be a DAG, at least in the subset traversed by the threads. (Reversing edges are fine, but the threads in a node must all run in the same direction.) This uses a special efficient batch insert algorithm for DAGs that lets us just scan the graph and generate nodes' B_s arrays independently. This must be called only once, and no threads can have been inserted previously. Otherwise the gPWT data structures will be left in an inconsistent state.

```
auto xg::XG::extract_threads (bool extract_reverse) const
```

Read all the threads embedded in the graph.

```
thread_t xg::XG::extract_thread (const string &name) const
```

Extract a particular thread by name. Name may not be empty.

```
auto xg::XG::extract_threads_matching (const string &pattern, bool reverse) const
```

Extract a set of threads matching a pattern.

```
XG::thread_t xg::XG::extract_thread (xg::XG::ThreadMapping node, int64_t offset, int64_t
                                   max_length)
```

Extract a particular thread, referring to it by its offset at node; step it out to a maximum of max_length

```
size_t xg::XG::count_matches (const thread_t &t) const
```

Count matches to a subthread among embedded threads.

```
size_t xg::XG::count_matches (const Path &t) const
```

```
void xg::XG::extend_search (ThreadSearchState &state, const thread_t &t) const
```

```
void xg::XG::extend_search (ThreadSearchState &state, const ThreadMapping &t) const
```

Extend a search with the given single *ThreadMapping*.

```
XG::ThreadSearchState xg::XG::select_starting (const ThreadMapping &start) const
```

Select only the threads (if any) starting with a particular *ThreadMapping*, and not those continuing through it.

```
int64_t xg::XG::id_rev_to_side (int64_t id, bool is_rev) const
```

Take a node id and side and return the side id.

```
pair<int64_t, bool> xg::XG::side_to_id_rev (int64_t side) const
```

Take a side and give a node id / rev pair.

```
int64_t xg::XG::threads_starting_on_side (int64_t side) const
```

The number of threads starting at this side.

```
int64_t xg::XG::thread_starting_at (int64_t side, int64_t offset) const
```

Given a side and offset, return the id of the thread starting there (or 0 if none)

```
pair<int64_t, int64_t> xg::XG::thread_start (int64_t thread_id) const
```

Given a thread id and the reverse state get the starting side and offset.

```
string xg::XG::thread_name (int64_t thread_id) const
```

Given a thread id, return its name.

```
pair<int64_t, int64_t> xg::XG::thread_start (int64_t thread_id, bool is_rev) const
```

Gives the thread start for the given thread.

```
vector<int64_t> xg::XG::threads_named_starting (const string &pattern) const
```

Gives the thread ids of those whose names start with this pattern.

XG::ThreadSearchState `xg::XG::select_continuing(const ThreadMapping &start) const`
 Select only the threads (if any) continuing through a particular *ThreadMapping*, and not those starting there.

`void xg::XG::bs_dump(ostream &out) const`

Public Members

`size_t xg::XG::seq_length`

`size_t xg::XG::node_count`

`size_t xg::XG::edge_count`

`size_t xg::XG::path_count`

`char xg::XG::start_marker`

`char xg::XG::end_marker`

Public Static Attributes

`const uint32_t xg::XG::MAX_INPUT_VERSION`

`const uint32_t xg::XG::OUTPUT_VERSION`

Private Types

`using`

Private Functions

`bool xg::XG::edge_filter(int type, bool is_to, bool want_left, bool is_reverse) const`
 This is a utility function for the edge exploration. It says whether we want to visit an edge depending on its type, whether we're the to or from node, whether we want to look left or right, and whether we're forward or reverse on the node.

`bool xg::XG::do_edges(const size_t &g, const size_t &start, const size_t &count, bool is_to, bool want_left, bool is_reverse, const function<bool> const handle_t& > &iteratee) const`

`void xg::XG::index_component_path_sets()`

`void xg::XG::create_succinct_component_path_sets(int_vector<> &path_ranks_iv_out, bit_vector &path_ranks_bv_out) const`

`void xg::XG::unpack_succinct_component_path_sets(const int_vector<> &path_ranks_iv, const bit_vector &path_ranks_bv)`

XG::destination_t `xg::XG::bs_get(int64_t side, int64_t offset) const`

```
size_t xg::XG::bs_rank (int64_t side, int64_t offset, destination_t value) const  
void xg::XG::bs_set (int64_t side, vector<destination_t> new_array)  
void xg::XG::bs_insert (int64_t side, int64_t offset, destination_t value)  
void xg::XG::bs_bake ()  
void xg::XG::tn_bake ()
```

Private Members

```
int_vector xg::XG::g_iv  
    locally traversable graph storage  
  
    Encoding designed for efficient compression, cache locality, and relativistic traversal of the graph.  
  
    node := { header, edges_to, edges_from } header := { node_id, node_start, node_length, edges_to_count,  
    edges_from_count } node_id := integer node_start := integer (offset in s_iv) node_length := integer  
    edges_to_count := integer edges_from_count := integer edges_to := { edge_to, ... } edges_from := {  
    edge_from, ... } edge_to := { offset_to_previous_node, edge_type } edge_to := { offset_to_next_node,  
    edge_type }  
  
bit_vector xg::XG::g_bv  
    delimit node records to allow lookup of nodes in g_civ by rank  
  
rank_support_v<1> xg::XG::g_bv_rank  
  
bit_vector::select_1_type xg::XG::g_bv_select  
  
int_vector xg::XG::s_iv  
  
bit_vector xg::XG::s_bv  
  
rank_support_v<1> xg::XG::s_bv_rank  
  
bit_vector::select_1_type xg::XG::s_bv_select  
  
int_vector xg::XG::i_iv  
  
int64_t xg::XG::min_id  
  
int64_t xg::XG::max_id  
  
int_vector xg::XG::r_iv  
  
int_vector xg::XG::pn_iv  
  
csa_wt xg::XG::pn_csa  
  
bit_vector xg::XG::pn_bv  
  
rank_support_v<1> xg::XG::pn_bv_rank  
  
bit_vector::select_1_type xg::XG::pn_bv_select  
  
int_vector xg::XG::pi_iv  
  
vector<XGPath *> xg::XG::paths
```

```

int_vector xg::XG::np_iv
bit_vector xg::XG::np_bv
rank_support_v<1> xg::XG::np_bv_rank
bit_vector::select_1_type xg::XG::np_bv_select
int_vector xg::XG::h_iv
vlc_vector xg::XG::h_civ
int_vector xg::XG::ts_iv
vlc_vector xg::XG::ts_civ
vector<string> xg::XG::bs_arrays
rank_select_int_vector xg::XG::bs_single_array
csa_bitcompressed xg::XG::tn_csa
sd_vector xg::XG::tn_cbv
sd_vector::rank_1_type xg::XG::tn_cbv_rank
sd_vector::select_1_type xg::XG::tn_cbv_select
vlc_vector xg::XG::tin_civ
vlc_vector xg::XG::tio_civ
wt_int xg::XG::side_thread_wt
string xg::XG::names_str
vector<unordered_set<size_t>> xg::XG::component_path_sets
vector<size_t> xg::XG::component_path_set_of_path

```

Private Static Attributes

```

const int xg::XG::G_NODE_ID_OFFSET
const int xg::XG::G_NODE_SEQ_START_OFFSET
const int xg::XG::G_NODE_LENGTH_OFFSET
const int xg::XG::G_NODE_TO_COUNT_OFFSET
const int xg::XG::G_NODE_FROM_COUNT_OFFSET
const int xg::XG::G_NODE_HEADER_LENGTH
const int xg::XG::G_EDGE_OFFSET_OFFSET
const int xg::XG::G_EDGE_TYPE_OFFSET
const int xg::XG::G_EDGE_LENGTH

```

```
const size_t xg::XG::HIGH_BIT
```

```
const size_t xg::XG::LOW_BITS
```

```
const XG::destination_t xg::XG::BS_SEPARATOR
```

```
const XG::destination_t xg::XG::BS_NULL
```

```
class #include <xg.hpp> Thrown when attempting to interpret invalid data as an XG index. Inherits from runtime_error
```

```
class #include <xg.hpp> Public Functions
```

```
xg::XGPath::XGPath (void)
```

```
xg::XGPath::~~XGPath (void)
```

```
xg::XGPath::XGPath (const string &path_name, const vector<trav_t> &path, size_t node_count, XG &graph, size_t *unique_member_count_out = nullptr)
```

```
xg::XGPath::XGPath (const XGPath &other)
```

```
xg::XGPath::XGPath (XGPath &&other)
```

```
XGPath &xg::XGPath::operator= (const XGPath &other)
```

```
XGPath &xg::XGPath::operator= (XGPath &&other)
```

```
void xg::XGPath::load (istream &in)
```

```
size_t xg::XGPath::serialize (std::ostream &out, sds::structure_tree_node *v = NULL, std::string name = "") const
```

```
Mapping xg::XGPath::mapping (size_t offset) const
```

Public Members

```
rrr_vector xg::XGPath::nodes
```

```
rrr_vector::rank_1_type xg::XGPath::nodes_rank
```

```
rrr_vector::select_1_type xg::XGPath::nodes_select
```

```
wt_gmr xg::XGPath::ids
```

```
sd_vector xg::XGPath::directions
```

```
int_vector xg::XGPath::positions
```

```
int_vector xg::XGPath::ranks
```

```
bit_vector xg::XGPath::offsets
```

```
rank_support_v<1> xg::XGPath::offsets_rank
```

```
bit_vector::select_1_type xg::XGPath::offsets_select
```

```
namespace
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namespace

namespace **Functions**

template <typename T>

bool stream::write(*std::ostream* &out, uint64_t *element_count*, uint64_t *chunk_elements*, const *std::function*<T> uint64_t
> &lambda) Write objects using adaptive chunking. Takes a stream to write to, a total element count to write, a guess at how many elements should be in a chunk, and a function that, given a start element and a length, returns a Protobuf object representing that range of elements.

Adaptively sets the chunk size, in elements, so that no too-large Protobuf records are serialized.

template <typename T>

bool stream::write(*std::ostream* &out, uint64_t *count*, const *std::function*<T> uint64_t
> &lambda)

template <typename T>

bool stream::write_buffered(*std::ostream* &out, *std::vector*<T> &buffer, uint64_t *buffer_limit*)

template <typename T>

void stream::for_each(*std::istream* &in, const *std::function*<void> T&
> &lambda, const *std::function*<voiduint64_t> &handle_count)

template <typename T>

void stream::for_each(*std::istream* &in, const *std::function*<void> T&
> &lambda)

template <typename T>

void stream::for_each_parallel_impl(*std::istream* &in, const *std::function*<void> T&, T&
> &lambda2, const *std::function*<voidT&> &lambda1, const *std::function*<voiduint64_t> &handle_count, const *std::function*<boolvoid> &single_threaded_until_true)

template <typename T>

void stream::for_each_interleaved_pair_parallel(*std::istream* &in, const *std::function*<void> T&, T&
> &lambda2)

template <typename T>

void stream::for_each_interleaved_pair_parallel_after_wait(*std::istream* &in, const *std::function*<void> T&, T&
> &lambda2, const *std::function*<boolvoid> &single_threaded_until_true)

template <typename T>

void stream::for_each_parallel(*std::istream* &in, const *std::function*<void> T&
> &lambda1, const *std::function*<voiduint64_t> &handle_count)

template <typename T>

void stream::for_each_parallel(*std::istream* &in, const *std::function*<void> T&
> &lambda)

template <typename T>

std::pair<*ProtobufIterator*<T>, *ProtobufIterator*<T>> stream::protobuf_iterator_range(*std::istream* &in)

Returns iterators that act like begin() and end() for a stream containing protobuf data.

Variables

```
const size_t stream::MAX_PROTOBUF_SIZE
```

Protobuf will refuse to read messages longer than this size.

```
const size_t stream::TARGET_PROTOBUF_SIZE
```

We aim to generate messages that are this size.

```
namespace Typedefs
```

```
using vg::benchtime = typedef chrono::nanoseconds
```

We define a duration type for expressing benchmark times in.

```
typedef
```

```
typedef
```

```
using vg::real_t = typedef long double
```

```
typedef
```

```
using vg::Chain = typedef vector<const Snarl*>
```

Snarls are defined at the Protobuf level, but here is how we define chains as real objects.

The *SnarlManager* is going to have one official copy of each chain stored, and it will give you a pointer to it on demand.

typedef Represents a *Node* ID. ID type is a 64-bit signed int.

typedef Represents an offset along the sequence of a *Node*. Offsets are size_t.

typedef Represents an oriented position on a *Node*. *Position* type: id, direction, offset.

Enums

```
enum type vg::MappingQualityMethod
```

Values:

```
enum type vg::SnarlType
```

Enumeration of the classifications of snarls.

Values:

= 0

= 1

= 2

Functions

```
int vg::hts_for_each (string &filename, function<void> Alignment&  
> lambda
```

```
int vg::hts_for_each_parallel (string &filename, function<void> Alignment&  
> lambda
```

```
bam_hdr_t *vg::hts_file_header (string &filename, string &header)
```

```

bam_hdr_t *vg::hts_string_header(string &header, map<string, int64_t> &path_length,
                                  map<string, string> &rg_sample)

bool vg::get_next_alignment_from_fastq(gzFile fp, char *buffer, size_t len, Alignment
                                       &alignment)

bool vg::get_next_interleaved_alignment_pair_from_fastq(gzFile fp, char *buffer,
                                                        size_t len, Alignment
                                                        &mate1, Alignment
                                                        &mate2)

bool vg::get_next_alignment_pair_from_fastqs(gzFile fp1, gzFile fp2, char *buffer,
                                              size_t len, Alignment &mate1, Align-
                                              ment &mate2)

size_t vg::fastq_unpaired_for_each_parallel(const string &filename, func-
                                           tion<void> Alignment&
                                           > lambda)

size_t vg::fastq_paired_interleaved_for_each_parallel(const string &filename,
                                                       function<void> Alignment&,
                                                       Alignment&
                                                       > lambda)

size_t vg::fastq_paired_interleaved_for_each_parallel_after_wait(const string
                                                                &file-
                                                                name, func-
                                                                tion<void> Alignment&,
                                                                Align-
                                                                ment&
                                                                > lambda, function<boolvoid> single_threaded_until_true)

size_t vg::fastq_paired_two_files_for_each_parallel(const string &file1,
                                                     const string &file2, func-
                                                     tion<void> Alignment&, Align-
                                                     ment&
                                                     > lambda)

size_t vg::fastq_paired_two_files_for_each_parallel_after_wait(const string
                                                                &file1,
                                                                const string
                                                                &file2, func-
                                                                tion<void> Alignment&,
                                                                Alignment&
                                                                > lambda, function<boolvoid> single_threaded_until_true)

size_t vg::fastq_unpaired_for_each(const string &filename, function<void> Alignment&
                                   > lambda)

size_t vg::fastq_paired_interleaved_for_each(const string &filename, func-
                                              tion<void> Alignment&, Alignment&
                                              > lambda)

size_t vg::fastq_paired_two_files_for_each(const string &file1, const string &file2, func-
                                             tion<void> Alignment&, Alignment&
                                             > lambda)

void vg::parse_rg_sample_map(char *hts_header, map<string, string> &rg_sample)

void vg::write_alignments(std::ostream &out, vector<Alignment> &buf)

```

```
short vg::quality_char_to_short(char c)

char vg::quality_short_to_char(short i)

void vg::alignment_quality_short_to_char(Alignment &alignment)

string vg::string_quality_short_to_char(const string &quality)

void vg::alignment_quality_char_to_short(Alignment &alignment)

string vg::string_quality_char_to_short(const string &quality)

bam1_t *vg::alignment_to_bam(const string &sam_header, const Alignment &alignment, const
                           string &refseq, const int32_t refpos, const bool refrev, const
                           string &cigar, const string &mateseq, const int32_t matepos,
                           const int32_t tlen)

string vg::alignment_to_sam(const Alignment &alignment, const string &refseq, const int32_t
                           refpos, const bool refrev, const string &cigar, const string &mate-
                           seq, const int32_t matepos, const int32_t tlen)

string vg::cigar_string(vector<pair<int, char>> &cigar)

string vg::mapping_string(const string &source, const Mapping &mapping)

void vg::mapping_cigar(const Mapping &mapping, vector<pair<int, char>> &cigar)

string vg::cigar_against_path(const Alignment &alignment, bool on_reverse_strand)

int32_t vg::sam_flag(const Alignment &alignment, bool on_reverse_strand)

Alignment vg::bam_to_alignment(const bam1_t *b, map<string, string> &rg_sample)

int vg::alignment_to_length(const Alignment &a)

int vg::alignment_from_length(const Alignment &a)

Alignment vg::strip_from_start(const Alignment &aln, size_t drop)

Alignment vg::strip_from_end(const Alignment &aln, size_t drop)

Alignment vg::trim_alignment(const Alignment &aln, const Position &pos1, const Position
                             &pos2)

vector<Alignment> vg::alignment_ends(const Alignment &aln, size_t len1, size_t len2)

Alignment vg::alignment_middle(const Alignment &aln, int len)

vector<Alignment> vg::reverse_complement_alignments(const vector<Alignment> &alns,
                                                    const function<int64_t> int64_t
                                                    > &node_length)

Alignment vg::reverse_complement_alignment(const Alignment &aln, const func-
                                           tion<int64_t> id_t
                                           > &node_length)

void vg::reverse_complement_alignment_in_place(Alignment *aln, const func-
                                              tion<int64_t> id_t
                                              > &node_length)

Alignment vg::merge_alignments(const vector<Alignment> &alns, bool debug)
```

```

Alignment &vg::extend_alignment (Alignment &a1, const Alignment &a2, bool debug)

Alignment vg::merge_alignments (const Alignment &a1, const Alignment &a2, bool debug)

void vg::translate_nodes (Alignment &a, const unordered_map<id_t, pair<id_t, bool>> &ids,
                        const std::function<size_t> int64_t
                        > &node_length

void vg::flip_nodes (Alignment &a, const set<int64_t> &ids, const std::function<size_t> int64_t
                    > &node_length

int vg::softclip_start (const Alignment &alignment)

int vg::softclip_end (const Alignment &alignment)

int vg::query_overlap (const Alignment &aln1, const Alignment &aln2)

int vg::edit_count (const Alignment &alignment)

size_t vg::to_length_after_pos (const Alignment &aln, const Position &pos)

size_t vg::from_length_after_pos (const Alignment &aln, const Position &pos)

size_t vg::to_length_before_pos (const Alignment &aln, const Position &pos)

size_t vg::from_length_before_pos (const Alignment &aln, const Position &pos)

const string vg::hash_alignment (const Alignment &aln)

Alignment vg::simplify (const Alignment &a)
    Simplifies the Path in the Alignment. Note that this removes deletions at the start and end of Mappings, so
    code that handles simplified Alignments needs to handle offsets on internal Mappings.

void vg::write_alignment_to_file (const Alignment &aln, const string &filename)

map<id_t, int> vg::alignment_quality_per_node (const Alignment &aln)

string vg::middle_signature (const Alignment &aln, int len)

pair<string, string> vg::middle_signature (const Alignment &aln1, const Alignment &aln2, int
                                         len)

string vg::signature (const Alignment &aln)

pair<string, string> vg::signature (const Alignment &aln1, const Alignment &aln2)

void vg::parse_bed_regions (istream &bedstream, xg::XG *xgindex, vector<Alignment>
                          *out_alignments)

int vg::fastq_for_each (string &filename, function<void> Alignment&
                      > lambda

ostream &vg::operator<< (ostream &out, const BenchmarkResult &result)
    Benchmark results can be output to streams

void vg::benchmark_control ()
    The benchmark control function, designed to take some amount of time that might vary with CPU load.

BenchmarkResult vg::run_benchmark (const string &name, size_t iterations, const func-
                                tion<void> void
                                > &under_test) Run the given function the given number of times, interleaved with runs of the control
                                function, and return a BenchmarkResult describing its performance.

```

```

BenchmarkResult vg::run_benchmark(const string &name, size_t iterations, const func-
    tion<void> void
    > &setup, const function<voidvoid> &under_test) Run a benchmark with a setup function.

Node vg::xg_cached_node(id_t id, xg::XG *xgidx, LRUCache<id_t, Node> &node_cache)

vector<Edge> vg::xg_cached_edges_of(id_t id, xg::XG *xgidx, LRUCache<id_t, vector<Edge>>
    &edge_cache)

vector<Edge> vg::xg_cached_edges_on_start(id_t id, xg::XG *xgidx, LRUCache<id_t, vec-
    tor<Edge>> &edge_cache)

vector<Edge> vg::xg_cached_edges_on_end(id_t id, xg::XG *xgidx, LRUCache<id_t, vec-
    tor<Edge>> &edge_cache)

string vg::xg_cached_node_sequence(id_t id, xg::XG *xgidx, LRUCache<id_t, Node>
    &node_cache)

size_t vg::xg_cached_node_length(id_t id, xg::XG *xgidx, LRUCache<id_t, Node>
    &node_cache)
    Get the length of a Node from an xg::XG index, with cacheing of deserialized nodes.

int64_t vg::xg_cached_node_start(id_t id, xg::XG *xgidx, LRUCache<id_t, int64_t>
    &node_start_cache)
    Get the node start position in the sequence vector.

char vg::xg_cached_pos_char(pos_t pos, xg::XG *xgidx, LRUCache<id_t, Node> &node_cache)
    Get the character at a position in an xg::XG index, with cacheing of deserialized nodes.

map<pos_t, char> vg::xg_cached_next_pos_chars(pos_t pos, xg::XG *xgidx, LRUCache<id_t,
    Node> &node_cache, LRUCache<id_t,
    vector<Edge>> &edge_cache)
    Get the characters at positions after the given position from an xg::XG index, with cacheing of deserialized
    nodes.

set<pos_t> vg::xg_cached_next_pos(pos_t pos, bool whole_node, xg::XG *xgidx, LRU-
    Cache<id_t, Node> &node_cache, LRUCache<id_t, vec-
    tor<Edge>> &edge_cache)

int64_t vg::xg_cached_distance(pos_t pos1, pos_t pos2, int64_t maximum, xg::XG *xgidx,
    LRUCache<id_t, Node> &node_cache, LRUCache<id_t, vec-
    tor<Edge>> &edge_cache)

set<pos_t> vg::xg_cached_positions_bp_from(pos_t pos, int64_t distance, bool rev,
    xg::XG *xgidx, LRUCache<id_t, Node>
    &node_cache, LRUCache<id_t, vec-
    tor<Edge>> &edge_cache)

static void vg::compute_side_components(VG &graph, vector<SideSet> &components,
    Side2Component &side_to_component)

void *vg::mergeNodeObjects(void *a, void *b)

void vg::getReachableBridges2(stCactusEdgeEnd *edgeEnd1, stHash *bridgeEndsToBridgeN-
    odes, stList *bridgeEnds)
    Get the bridge ends that form boundary pairs with edgeEnd1, using the given getBridgeEdgeEndsTo-
    BridgeNodes hash map. Duplicated from the pinchesAndCacti tests.

void vg::getReachableBridges(stCactusEdgeEnd *edgeEnd1, stList *bridgeEnds)
    Get the bridge ends that form boundary pairs with edgeEnd1. Duplicated from the pinchesAndCacti tests.

```

```

void vg::addArbitraryTelomerePair (vector<stCactusEdgeEnd *> ends, stList *telomeres)
    Finds an arbitrary pair of telomeres in a Cactus graph, which are either a pair of bridge edge ends or a
    pair of chain edge ends, oriented such that they form a pair of boundaries.

    Mostly copied from the pinchesAndCacti unit tests.

pair<stCactusGraph *, stList *> vg::vg_to_cactus (VG &graph, const unordered_set<string>
                                                &hint_paths)

VG vg::cactus_to_vg (stCactusGraph *cactus_graph)

VG vg::cactusify (VG &graph)

Graph vg::cluster_subgraph (const xg::XG &xg, const Alignment &aln, const vec-
                           tor<vg::MaximalExactMatch> &mems, double expansion)
    return a subgraph form an xg for a cluster of MEMs from the given alignment

Graph vg::cluster_subgraph (const xg::XG &xg, const Alignment &aln, const vec-
                           tor<MaximalExactMatch> &mems, double expansion = 1.61803)
    return a subgraph form an xg for a cluster of MEMs from the given alignment

template <typename T>
bool vg::convert (const std::string &s, T &r)

template <typename T>
std::string vg::convert (const T &r)

real_t vg::gamma_ln (real_t x)
    Calculate the natural log of the gamma function of the given argument.

real_t vg::factorial_ln (int n)
    Calculate the natural log of the factorial of the given integer. TODO: replace with a cache or giant lookup
    table from Freebayes.

real_t vg::pow_ln (real_t m, int n)
    Raise a log probability to a power

real_t vg::choose_ln (int n, int k)
    Compute the number of ways to select k items from a collection of n distinguishable items, ignoring order.
    Returns the natural log of the (integer) result.

real_t vg::multinomial_choose_ln (int n, vector<int> k)
    Compute the number of ways to select k_1, k_2, ... k_i items into i buckets from a collection of n dis-
    tinguishable items, ignoring order. All of the items have to go into the buckets, so all k_i must sum to
    n. To compute choose you have to call this function with a 2-element vector, to represent the chosen and
    not-chosen buckets. Returns the natural log of the (integer) result.

    TODO: Turns out we don't actually need this for the ambiguous multinomial after all.

real_t vg::poisson_prob_ln (int observed, real_t expected)
    Compute the log probability of a Poisson-distributed process: observed events in an interval where ex-
    pected events happen on average.

template <typename ProbIn>
real_t vg::multinomial_sampling_prob_ln (const vector<ProbIn> &probs, const vector<int>
                                         &obs)
    Get the probability for sampling the counts in obs from a set of categories weighted by the probabilities in
    probs. Works for both double and real_t probabilities. Also works for binomials.

template <typename ProbIn>

```



```
real_t vg::binomial_cmf_ln (ProbIn success_logprob, size_t trials, size_t successes)
```

Compute the probability of having the given number of successes or fewer in the given number of trials, with the given success probability. Returns the resulting log probability.

```
template <typename ProbIn>
```

```
real_t vg::geometric_sampling_prob_ln (ProbIn success_logprob, size_t trials)
```

Get the log probability for sampling the given value from a geometric distribution with the given success log probability. The geometric distribution is the distribution of the number of trials, with a given success probability, required to observe a single success.

```
template <typename Iter>
```

```
bool vg::advance_split (Iter start, Iter end)
```

Given a split of items across a certain number of categories, as ints between the two given bidirectional iterators, advance to the next split and return true. If there is no next split, leave the collection unchanged and return false.

```
template <typename ProbIn>
```

```
real_t vg::multinomial_censored_sampling_prob_ln (const          vector<ProbIn>
                                                  &probs,          const          un-
                                                  ordered_map<vector<bool>,  int>
                                                  &obs)
```

Get the log probability for sampling any actual set of category counts that is consistent with the constraints specified by obs, using the per-category probabilities defined in probs.

Obs maps from a vector of per-category flags (called a “class”) to a number of items that might be in any of the flagged categories.

For example, if there are two equally likely categories, and one item flagged as potentially from either category, the probability of sampling a set of category counts consistent with that constraint is 1. If instead there are three equally likely categories, and one item flagged as potentially from two of the three but not the third, the probability of sampling a set of category counts consistent with that constraint is 2/3.

```
bool vg::edit_is_match (const Edit &e)
```

```
bool vg::edit_is_sub (const Edit &e)
```

```
bool vg::edit_is_insertion (const Edit &e)
```

```
bool vg::edit_is_deletion (const Edit &e)
```

```
pair<Edit, Edit> vg::cut_edit_at_to (const Edit &e, size_t to_off)
```

```
pair<Edit, Edit> vg::cut_edit_at_from (const Edit &e, size_t from_off)
```

```
Edit vg::reverse_complement_edit (const Edit &e)
```

```
bool vg::operator== (const Edit &e1, const Edit &e2)
```

```
double vg::entropy (const string &st)
```

```
double vg::entropy (const char *st, size_t len)
```

```
Support vg::make_support (double forward, double reverse, double quality)
```

TBD Create a *Support* for the given forward and reverse coverage and quality.

```
double vg::total (const Support &support)
```

Get the total read support in a *Support*.

```
Support vg::support_min (const Support &a, const Support &b)
```

Get the minimum support of a pair of Supports, by taking the min in each orientation.

```

Support vg::support_max (const Support &a, const Support &b)
    Get the maximum support of a pair of Supports, by taking the max in each orientation.

Support vg::operator+ (const Support &one, const Support &other)
    Add two Support values together, accounting for strand.

Support &vg::operator+= (Support &one, const Support &other)
    Add in a Support to another.

bool vg::operator< (const Support &a, const Support &b)
    Support less-than, based on total coverage.

bool vg::operator> (const Support &a, const Support &b)
    Support greater-than, based on total coverage.

ostream &vg::operator<< (ostream &stream, const Support &support)
    Allow printing a Support.

string vg::to_vcf_genotype (const Genotype &gt)
    Get a VCF-style 1/2, 1|2|3, etc. string from a Genotype.

template <typename Scalar>
Support vg::operator* (const Support &support, const Scalar &scale)
    Scale a Support by a factor.

template <typename Scalar>
Support &vg::operator*= (Support &support, const Scalar &scale)
    Scale a Support by a factor, in place.

template <typename Scalar>
Support vg::operator* (const Scalar &scale, const Support &support)
    Scale a Support by a factor, the other way

template <typename Scalar>
Support vg::operator/ (const Support &support, const Scalar &scale)
    Divide a Support by a factor.

template <typename Scalar>
Support &vg::operator/= (Support &support, const Scalar &scale)
    Divide a Support by a factor, in place.

string vg::allele_to_string (VG &graph, const Path &allele)
    Turn the given path into an allele. Drops the first and last mappings and looks up the sequences for the
    nodes of the others.

template <typename T>
void vg::set_intersection (const unordered_set<T> &set_1, const unordered_set<T> &set_2,
                          unordered_set<T> *out_intersection)

void vg::sort_by_id_dedup_and_clean (Graph &graph)
    remove duplicates and sort by id

void vg::remove_duplicates (Graph &graph)
    remove duplicate nodes and edges

void vg::remove_duplicate_edges (Graph &graph)
    remove duplicate edges

void vg::remove_duplicate_nodes (Graph &graph)
    remove duplicate nodes

```

```
void vg::remove_orphan_edges (Graph &graph)
    remove edges that link to a node that is not in the graph

void vg::sort_by_id (Graph &graph)
    order the nodes and edges in the graph by id

void vg::sort_nodes_by_id (Graph &graph)
    order the nodes in the graph by id

void vg::sort_edges_by_id (Graph &graph)
    order the edges in the graph by id pairs

bool vg::is_id_sortable (const Graph &graph)
    returns true if the graph is id-sortable (no reverse links)

bool vg::has_inversion (const Graph &graph)
    returns true if we find an edge that may specify an inversion

void vg::flip_doubly_reversed_edges (Graph &graph)
    clean up doubly-reversed edges

int64_t &vg::as_integer (handle_t &handle)
    View a handle as an integer.

const int64_t &vg::as_integer (const handle_t &handle)
    View a const handle as a const integer.

handle_t &vg::as_handle (int64_t &value)
    View an integer as a handle.

const handle_t &vg::as_handle (const int64_t &value)
    View a const integer as a const handle.

bool vg::operator== (const handle_t &a, const handle_t &b)
    Define equality on handles.

bool vg::operator!= (const handle_t &a, const handle_t &b)
    Define inequality on handles.

void vg::node_path_position (int64_t id, string &path_name, int64_t &position, bool backward,
                             int64_t &offset)

void vg::index_positions (VG &graph, map<long, Node *> &node_path, map<long, Edge *>
                           &edge_path)

int vg::sub_overlaps_of_first_aln (const vector<Alignment> &alns, float overlap_fraction)

set<pos_t> vg::gcsa_nodes_to_positions (const vector<gcsa::node_type> &nodes)

const int vg::balanced_stride (int read_length, int kmer_size, int stride)

const vector<string> vg::balanced_kmers (const string &seq, const int kmer_size, const int stride)

pair<int64_t, int64_t> vg::mem_min_oriented_distances (const MaximalExactMatch &m1,
                                                       const MaximalExactMatch &m2)

bool vg::operator== (const MaximalExactMatch &m1, const MaximalExactMatch &m2)

bool vg::operator< (const MaximalExactMatch &m1, const MaximalExactMatch &m2)
```

```

ostream &vg::operator<< (ostream &out, const MaximalExactMatch &mem)

const string vg::mems_to_json (const vector<MaximalExactMatch> &mems)

vector<string::const_iterator> vg::cluster_cover (const vector<MaximalExactMatch> &cluster)

int vg::cluster_coverage (const vector<MaximalExactMatch> &cluster)

bool vg::mems_overlap (const MaximalExactMatch &mem1, const MaximalExactMatch &mem2)

int vg::mems_overlap_length (const MaximalExactMatch &mem1, const MaximalExactMatch
                             &mem2)

bool vg::clusters_overlap_in_read (const vector<MaximalExactMatch> &cluster1, const
                                   vector<MaximalExactMatch> &cluster2)

int vg::clusters_overlap_length (const vector<MaximalExactMatch> &cluster1, const vec-
                                tor<MaximalExactMatch> &cluster2)

vector<pos_t> vg::cluster_nodes (const vector<MaximalExactMatch> &cluster)

bool vg::clusters_overlap_in_graph (const vector<MaximalExactMatch> &cluster1, const
                                   vector<MaximalExactMatch> &cluster2)

void vg::topologically_order_subpaths (MultipathAlignment &multipath_aln)
    Put subpaths in topological order (assumed to be true for other algorithms)

void vg::identify_start_subpaths (MultipathAlignment &multipath_aln)
    Finds the start subpaths (i.e. the source nodes of the multipath DAG) and stores them in the ‘start’ field of
    the MultipathAlignment

int32_t vg::optimal_alignment_internal (const MultipathAlignment &multipath_aln, Align-
                                       ment *aln_out)

void vg::optimal_alignment (const MultipathAlignment &multipath_aln, Alignment &aln_out)
    Stores the highest scoring alignment contained in the MultipathAlignment in an Alignment

    Note: Assumes that each subpath’s Path object uses one Mapping per node and that start subpaths have
    been identified

    Args: multipath_aln multipath alignment to find optimal path through aln_out empty alignment to store
    optimal alignment in (data will be overwritten if not empty)

int32_t vg::optimal_alignment_score (const MultipathAlignment &multipath_aln)
    Returns the score of the highest scoring alignment contained in the MultipathAlignment

    Note: Assumes that each subpath’s Path object uses one Mapping per node and that start subpaths have
    been identified

    Args: multipath_aln multipath alignment to find optimal score in

void vg::rev_comp_subpath (const Subpath &subpath, const function<int64_t> int64_t
                          > &node_length, Subpath &rev_comp_out) Stores the reverse complement of a Subpath in another Subpath

    note: this is not included in the header because reversing a subpath without going through the multipath
    alignment can break invariants related to the edge lists

    Args: subpath subpath to reverse complement node_length a function that returns the length of a node
    sequence from its node ID rev_comp_out empty subpath to store reverse complement in (data will be
    overwritten if not empty)

```

```
void vg::rev_comp_multipath_alignment (const MultipathAlignment &multipath_aln, const
                                     function<int64_t> int64_t
                                     > &node_length, MultipathAlignment &rev_comp_out)
    Stores the reverse complement of a MultipathAlignment
    in another MultipathAlignment
```

Args: multipath_aln multipath alignment to reverse complement node_length a function that returns the length of a node sequence from its node ID rev_comp_out empty multipath alignment to store reverse complement in (some data may be overwritten if not empty)

```
void vg::rev_comp_multipath_alignment_in_place (MultipathAlignment *multipath_aln,
                                               const function<int64_t> int64_t
                                               > &node_length)
    Stores the reverse complement of a MultipathAlignment in another MultipathAlignment
```

Args: multipath_aln multipath alignment to reverse complement in place node_length a function that returns the length of a node sequence from its node ID

```
void vg::to_multipath_alignment (const Alignment &aln, MultipathAlignment &multi-
                                path_aln_out)
    Converts a Alignment into a Multipath alignment with one Subpath and stores it in an object
```

Args: aln alignment to convert multipath_aln empty multipath alignment to store converted alignment in (data may be overwritten if not empty)

```
void vg::transfer_read_metadata (const MultipathAlignment &from, MultipathAlignment
                                &to)
    Copies metadata from an MultipathAlignment object and transfers it to another MultipathAlignment
```

Args: from copy metadata from this to into this

```
void vg::transfer_read_metadata (const Alignment &from, MultipathAlignment &to)
    Copies metadata from an Alignment object and transfers it to a MultipathAlignment
```

Args: from copy metadata from this to into this

```
void vg::transfer_read_metadata (const MultipathAlignment &from, Alignment &to)
    Copies metadata from an MultipathAlignment object and transfers it to a Alignment
```

Args: from copy metadata from this to into this

```
vector<vector<int64_t>> vg::connected_components (const MultipathAlignment &multi-
                                                path_aln)
    Returns a vector whose elements are vectors with the indexes of the Subpaths in each connected component
```

```
void vg::extract_sub_multipath_alignment (const MultipathAlignment &multipath_aln,
                                           const vector<int64_t> &subpath_indexes,
                                           MultipathAlignment &sub_multipath_aln)
    Extract the MultipathAlignment consisting of the Subpaths with the given indexes into a new MultipathAlignment object
```

```
NodeSide vg::node_start (id_t id)
    Produce the start NodeSide of a Node.
```

```
NodeSide vg::node_end (id_t id)
    Produce the end NodeSide of a Node.
```

```
ostream &vg::operator<< (ostream &out, const NodeSide &nodeside)
    Print a NodeSide to a stream.
```

```
ostream &vg::operator<< (ostream &out, const NodeTraversal &nodetraversal)
    Print the given NodeTraversal.
```

```

Path &vg::append_path (Path &a, const Path &b)

int vg::path_to_length (const Path &path)

int vg::path_from_length (const Path &path)

int vg::mapping_to_length (const Mapping &m)

int vg::mapping_from_length (const Mapping &m)

int vg::softclip_start (const Mapping &mapping)

int vg::softclip_end (const Mapping &mapping)

Position vg::first_path_position (const Path &path)

Position vg::last_path_position (const Path &path)

int vg::to_length (const Mapping &m)

int vg::from_length (const Mapping &m)

Path &vg::extend_path (Path &path1, const Path &path2)

Path vg::concat_paths (const Path &path1, const Path &path2)

Path vg::simplify (const Path &p)
    Simplify the path for addition as new material in the graph. Remove any mappings that are merely single
    deletions, merge adjacent edits of the same type, strip leading and trailing deletion edits on mappings, and
    make sure no mappings have missing positions.

Mapping vg::concat_mappings (const Mapping &m, const Mapping &n)

Mapping vg::simplify (const Mapping &m)
    Merge adjacent edits of the same type, strip leading and trailing deletion edits (while updating positions if
    necessary), and makes sure position is actually set.

Mapping vg::merge_adjacent_edits (const Mapping &m)
    Merge adjacent edits of the same type.

Path vg::trim_hanging_ends (const Path &p)

bool vg::mapping_ends_in_deletion (const Mapping &m)

bool vg::mapping_starts_in_deletion (const Mapping &m)

bool vg::mapping_is_total_deletion (const Mapping &m)

bool vg::mapping_is_simple_match (const Mapping &m)

bool vg::path_is_simple_match (const Path &p)

const string vg::mapping_sequence (const Mapping &mp, const string &node_seq)

const string vg::mapping_sequence (const Mapping &mp, const Node &n)

Mapping vg::reverse_complement_mapping (const Mapping &m, const function<int64_t> id_t
    > &node_length

```

```
void vg::reverse_complement_mapping_in_place (Mapping *m, const function<int64_t> id_t
                                             > &node_length

Path vg::reverse_complement_path (const Path &path, const function<int64_t> id_t
                                   > &node_length

void vg::reverse_complement_path_in_place (Path *path, const function<int64_t> id_t
                                           > &node_length

pair<Mapping, Mapping> vg::cut_mapping (const Mapping &m, const Position &pos)

pair<Mapping, Mapping> vg::cut_mapping (const Mapping &m, size_t offset)

pair<Path, Path> vg::cut_path (const Path &path, const Position &pos)

pair<Path, Path> vg::cut_path (const Path &path, size_t offset)

bool vg::maps_to_node (const Path &p, id_t id)

Position vg::path_start (const Path &path)

string vg::path_to_string (Path p)

Position vg::path_end (const Path &path)

bool vg::adjacent_mappings (const Mapping &m1, const Mapping &m2)

bool vg::mapping_is_match (const Mapping &m)

double vg::divergence (const Mapping &m)

double vg::identity (const Path &path)

void vg::decompose (const Path &path, map<pos_t, int> &ref_positions, map<pos_t, Edit> &edits)

double vg::overlap (const Path &p1, const Path &p2)

void vg::translate_node_ids (Path &path, const unordered_map<id_t, id_t> &translator)

void vg::translate_oriented_node_ids (Path &path, const unordered_map<id_t, pair<id_t,
                                                                    bool>> &translator)

pos_t vg::initial_position (const Path &path)

pos_t vg::final_position (const Path &path)

Path vg::path_from_node_traversals (const list<NodeTraversal> &traversals)

Path &vg::increment_node_mapping_ids (Path &p, id_t inc)

const Paths vg::paths_from_graph (Graph &g)

Path vg::merge_adjacent_edits (const Path &m)
    Merge adjacent edits of the same type.

ostream &vg::operator<< (ostream &os, const NodeDivider::NodeMap &nm)

ostream &vg::operator<< (ostream &os, NodeDivider::Entry entry)

ostream &vg::operator<< (ostream &os, const PileupAugmenter::NodeOffSide &no)
```

```

StrandSupport vg::minSup (vector<StrandSupport> &s)

StrandSupport vg::maxSup (vector<StrandSupport> &s)

StrandSupport vg::avgSup (vector<StrandSupport> &s)

StrandSupport vg::totalSup (vector<StrandSupport> &s)

ostream &vg::operator<< (ostream &os, const StrandSupport &sup)

pos_t vg::make_pos_t (const Position &pos)
    Convert a Position to a (much smaller) pos_t.

pos_t vg::make_pos_t (id_t id, bool is_rev, off_t off)
    Create a pos_t from a Node ID, an orientation flag, and an offset.

pos_t vg::make_pos_t (gcsa::node_type node)
    Create a pos_t from a gcsa node.

Position vg::make_position (const pos_t &pos)
    Convert a pos_t to a Position.

Position vg::make_position (id_t id, bool is_rev, off_t off)
    Create a Position from a Node ID, an orientation flag, and an offset.

Position vg::make_position (gcsa::node_type node)
    Make a Position from a gcsa node.

bool vg::is_empty (const pos_t &pos)
    Return true if a pos_t is unset.

id_t vg::id (const pos_t &pos)
    Extract the id of the node a pos_t is on.

bool vg::is_rev (const pos_t &pos)
    Return true if a pos_t is on the reverse strand of its node.

off_t vg::offset (const pos_t &pos)
    Get the offset from a pos_t.

id_t &vg::get_id (pos_t &pos)
    Get a reference to the Node ID of a pos_t.

bool &vg::get_is_rev (pos_t &pos)
    Get a reference to the reverse flag of a pos_t.

off_t &vg::get_offset (pos_t &pos)
    Get a reference to the offset field of a pos_t.

pos_t vg::reverse (const pos_t &pos, size_t node_length)
    Reverse a pos_t and get a pos_t at the same base, going the other direction.

Position vg::reverse (const Position &pos, size_t node_length)
    Reverse a Position and get a Position at the same base, going the other direction.

ostream &vg::operator<< (ostream &out, const pos_t &pos)
    Print a pos_t to a stream.

```

```
pair<int64_t, int64_t> vg::min_oriented_distances (const map<string, vector<pair<size_t,
                                                    bool>>> &path_offsets1, const
                                                    map<string, vector<pair<size_t, bool>>>
                                                    &path_offsets2)
```

Find the min distance in the path offsets where the path orientation is the same and different.

```
void vg::parse_bed_regions (const string &bed_path, vector<Region> &out_regions)
```

```
void vg::parse_region (string &region, Region &out_region)
```

```
pos_t vg::position_at (xg::XG *xgidx, const string &path_name, const size_t &path_offset, bool
                      is_reverse)
```

We have a helper function to convert path positions and orientations to pos_t values.

We have a utility function for turning positions along paths, with orientations, into pos_ts. Remember that pos_t counts offset from the start of the reoriented node, while here we count offset from the beginning of the forward version of the path.

```
bool vg::start_backward (const Chain &chain)
```

Return true if the first snarl in the given chain is backward relative to the chain.

```
bool vg::end_backward (const Chain &chain)
```

Return true if the last snarl in the given chain is backward relative to the chain.

```
Visit vg::get_start_of (const Chain &chain)
```

Get the inward-facing start *Visit* for a chain.

```
Visit vg::get_end_of (const Chain &chain)
```

Get the outward-facing end *Visit* for a chain.

```
ChainIterator vg::chain_begin (const Chain &chain)
```

We define free functions for getting iterators forward and backward through chains.

```
ChainIterator vg::chain_end (const Chain &chain)
```

```
ChainIterator vg::chain_rbegin (const Chain &chain)
```

```
ChainIterator vg::chain_rend (const Chain &chain)
```

```
ChainIterator vg::chain_rcbegin (const Chain &chain)
```

We also define some reverse complement iterators, which go from right to left through the chains, but give us the reverse view. For example, if all the snarls are oriented forward in the chain, we will iterate through the snarls in reverse order, with each individual snarl also reversed.

```
ChainIterator vg::chain_rcend (const Chain &chain)
```

```
ChainIterator vg::chain_begin_from (const Chain &chain, const Snarl *start_snarl, bool
                                   snarl_orientation)
```

We also define a function for getting the *ChainIterator* (forward or reverse complement) for a chain starting with a given snarl in the given inward orientation

```
ChainIterator vg::chain_end_from (const Chain &chain, const Snarl *start_snarl, bool
                                 snarl_orientation)
```

And the end iterator for the chain (forward or reverse complement) viewed from a given snarl in the given inward orientation

```
bool vg::operator== (const Visit &a, const Visit &b)
```

Two Visits are equal if they represent the same traversal of the same *Node* or *Snarl*.

`bool vg::operator!=(const Visit &a, const Visit &b)`

Two Visits are unequal if they are not equal.

`bool vg::operator<(const Visit &a, const Visit &b)`

A *Visit* is less than another *Visit* if it represents a traversal of a smaller node, or it represents a traversal of a smaller snarl, or it represents a traversal of the same node or snarl forward instead of backward.

`ostream &vg::operator<<(ostream &out, const Visit &visit)`

A *Visit* can be printed.

`bool vg::operator==(const SnarlTraversal &a, const SnarlTraversal &b)`

Two SnarlTraversals are equal if their snarls are equal and they have the same number of visits and all their visits are equal.

`bool vg::operator!=(const SnarlTraversal &a, const SnarlTraversal &b)`

Two SnarlTraversals are unequal if they are not equal.

`bool vg::operator<(const SnarlTraversal &a, const SnarlTraversal &b)`

A SnarlTraversal is less than another if it is a traversal of a smaller *Snarl*, or if its list of Visits has a smaller *Visit* first, or if its list of Visits is shorter.

`bool vg::operator==(const Snarl &a, const Snarl &b)`

Two Snarls are equal if their types are equal and their bounding Visits are equal and their parents are equal.

`bool vg::operator!=(const Snarl &a, const Snarl &b)`

Two Snarls are unequal if they are not equal.

`bool vg::operator<(const Snarl &a, const Snarl &b)`

A *Snarl* is less than another *Snarl* if its type is smaller, or its start *Visit* is smaller, or its end *Visit* is smaller, or its parent is smaller.

`ostream &vg::operator<<(ostream &out, const Snarl &snarl)`

A *Snarl* can be printed.

`NodeTraversal vg::to_node_traversal(const Visit &visit, const VG &graph)`

Converts a *Visit* to a *NodeTraversal*. Throws an exception if the *Visit* is of a *Snarl* instead of a *Node*

`NodeTraversal vg::to_rev_node_traversal(const Visit &visit, const VG &graph)`

Converts a *Visit* to a *NodeTraversal* in the opposite orientation. Throws an exception if the *Visit* is of a *Snarl* instead of a *Node*

`NodeSide vg::to_left_side(const Visit &visit)`

Converts a *Visit* to a node or snarl into a *NodeSide* for its left side.

`NodeSide vg::to_right_side(const Visit &visit)`

Converts a *Visit* to a node or snarl into a *NodeSide* for its right side.

`Visit vg::to_visit(const NodeTraversal &node_traversal)`

Converts a *NodeTraversal* to a *Visit*.

`Visit vg::to_visit(const Mapping &mapping)`

Converts a *Mapping* to a *Visit*. The mapping must represent a full node match.

`Visit vg::to_visit(id_t node_id, bool is_reverse)`

Make a *Visit* from a node ID and an orientation.

`Visit vg::to_visit(const Snarl &snarl)`

Make a *Visit* from a snarl to traverse.

Visit `vg::reverse (const Visit &visit)`

Get the reversed version of a visit.

Visit `vg::to_rev_visit (const NodeTraversal &node_traversal)`

Converts a *NodeTraversal* to a *Visit* in the opposite orientation.

Mapping `vg::to_mapping (const Visit &visit, std::function<size_t> id_t`

`> node_length` Converts a *Visit* to a *Mapping*. Throws an exception if the *Visit* is of a *Snarl* instead of a *Node*. Uses a function to get node length.

Mapping `vg::to_mapping (const Visit &visit, VG &vg)`

Converts a *Visit* to a *Mapping*. Throws an exception if the *Visit* is of a *Snarl* instead of a *Node*. Uses a graph to get node length.

`void vg::transfer_boundary_info (const Snarl &from, Snarl &to)`

Copies the boundary Visits from one *Snarl* into another.

NodeTraversal `vg::to_node_traversal (const Visit &visit, VG &graph)`

NodeTraversal `vg::to_rev_node_traversal (const Visit &visit, VG &graph)`

`template <typename T>`

`string vg::to_string_ss (T val)`

`double vg::strand_bias (const Support &support)`

Get the strand bias of a *Support*.

`string vg::char_to_string (const char &letter)`

Make a letter into a full string because apparently that's too fancy for the standard library.

`void vg::write_vcf_header (ostream &stream, const vector<string> &sample_names, const vector<string> &contig_names, const vector<size_t> &contig_sizes, int min_map_for_filter, int max_dp_for_filter, double max_dp_multiple_for_filter, double max_local_dp_multiple_for_filter, double min_ad_log_likelihood_for_filter)`

Write a minimal VCF header for a file with the given samples, and the given contigs with the given lengths.

`bool vg::can_write_alleles (vcflib::Variant &variant)`

Return true if a variant may be output, or false if this variant is valid but the GATK might choke on it.

Mostly used to throw out variants with very long alleles, because GATK has an allele length limit. How alleles that really *are* 1 megabase deletions are to be specified to GATK is left as an exercise to the reader.

`bool vg::mapping_is_perfect_match (const Mapping &mapping)`

Return true if a mapping is a perfect match, and false if it isn't.

`string vg::get_pileup_line (const map<int64_t, NodePileup> &node_pileups, const set<pair<int64_t, size_t>> &refCrossreferences, const set<pair<int64_t, size_t>> &altCrossreferences)`

Given a collection of pileups by original node ID, and a set of original node id:offset cross-references in both ref and alt categories, produce a VCF comment line giving the pileup for each of those positions on those nodes. Includes a trailing newline if nonempty.

TODO: VCF comments aren't really a thing.

`void vg::trace_traversal (const SnarlTraversal &traversal, const Snarl &site, function<void> size_t, id_t`

`> handle_node, function<void> size_t, NodeSide, NodeSide> handle_edge, function<void> size_t, Snarl>`

handle_child Trace out the given traversal, handling nodes, child snarls, and edges associated with particular visit numbers.

```
tuple<Support, Support, size_t> vg::get_traversal_support (SupportAugmentedGraph
                                                         &augmented,      SnarlManager
                                                         &snarl_manager, const Snarl
                                                         &site,      const SnarlTraversal
                                                         &traversal, const SnarlTraversal
                                                         *already_used = nullptr)
```

Get the min support, total support, bp size (to divide total by for average support), and min likelihood for a traversal, optionally special-casing the material used by another traversal. Material used by another traversal only makes half its coverage available to this traversal.

```
bool vg::is_match (const Translation &translation)
```

```
char vg::reverse_complement (const char &c)
```

```
string vg::reverse_complement (const string &seq)
```

```
void vg::reverse_complement_in_place (string &seq)
```

```
bool vg::is_all_n (const string &seq)
```

Return True if the given string is entirely Ns of either case, and false otherwise.

```
int vg::get_thread_count (void)
```

```
std::vector<std::string> &vg::split_delims (const std::string &s, const std::string &delims,
                                           std::vector<std::string> &elems)
```

```
std::vector<std::string> vg::split_delims (const std::string &s, const std::string &delims)
```

```
const std::string vg::shalsum (const std::string &data)
```

```
const std::string vg::shalhead (const std::string &data, size_t head)
```

```
string vg::wrap_text (const string &str, size_t width)
```

```
bool vg::is_number (const std::string &s)
```

```
bool vg::allATGC (const string &s)
```

```
string vg::nonATGCNtoN (const string &s)
```

```
string vg::toUppercase (const string &s)
```

```
string vg::tmpfilename (const string &base)
```

Create a temporary file starting with the given base name.

```
string vg::find_temp_dir ()
```

Find the system temp directory using defaults and environment variables.

```
string vg::tmpfilename ()
```

Create a temporary file in the appropriate system temporary directory.

```
string vg::get_or_make_variant_id (const vcflib::Variant &variant)
```

```
string vg::make_variant_id (const vcflib::Variant &variant)
```

```
double vg::median (std::vector<int> &v)
```

```
vector<size_t> vg::range_vector (size_t begin, size_t end)

void vg::get_input_file (int &optind, int argc, char **argv, function<void> istream&
    > callback)

string vg::get_input_file_name (int &optind, int argc, char **argv)

string vg::get_output_file_name (int &optind, int argc, char **argv)

void vg::get_input_file (const string &file_name, function<void> istream&
    > callback)

double vg::phi (double x1, double x2)

double vg::normal_inverse_cdf (double p)
    Inverse CDF of a standard normal distribution. Must have 0 < quantile < 1.

void vg::create_ref_allele (vcflib::Variant &variant, const std::string &allele)
    Create the reference allele for an empty vcflib Variant, since apparently there's no method for that already.
    Must be called before any alt alleles are added.

int vg::add_alt_allele (vcflib::Variant &variant, const std::string &allele)
    Add a new alt allele to a vcflib Variant, since apparently there's no method for that already.
    If that allele already exists in the variant, does not add it again.
    Returns the allele number (0, 1, 2, etc.) corresponding to the given allele string in the given variant.

double vg::slope (const std::vector<double> &x, const std::vector<double> &y)

double vg::fit_zipf (const vector<double> &y)

size_t vg::integer_power (uint64_t base, uint64_t exponent)
    Computes base^exponent in log(exponent) time.

size_t vg::modular_exponent (uint64_t base, uint64_t exponent, uint64_t modulus)
    Computes base^exponent mod modulus in log(exponent) time without requiring more than 64 bits to represent exponentiated number

bool vg::is_number (const string &s)

double vg::stdev (const std::vector<double> &v)
template <typename T>
double vg::stdev (const T &v)

double vg::add_log (double log_x, double log_y)

double vg::ln_to_log10 (double ln)
    Convert a number ln to the same number log 10.

double vg::log10_to_ln (double l10)
    Convert a number log 10 to the same number ln.

double vg::prob_to_logprob (double prob)

double vg::logprob_to_prob (double logprob)

double vg::logprob_add (double logprob1, double logprob2)

double vg::logprob_invert (double logprob)
```

```

double vg::phred_to_prob (int phred)

double vg::prob_to_phred (double prob)

double vg::phred_to_logprob (int phred)

double vg::logprob_to_phred (double logprob)

double vg::logprob_geometric_mean (double lnprob1, double lnprob2)

double vg::phred_geometric_mean (double phred1, double phred2)
template <typename T>
T vg::normal_pdf (T x, T m, T s)
template <typename T, typename V>
set<T> vg::map_keys_to_set (const map<T, V> &m)
template <typename T>
vector<T> vg::pmax (const std::vector<T> &a, const std::vector<T> &b)
template <typename T>
vector<T> vg::vpmax (const std::vector<std::vector<T>> &vv)
template <typename Collection>
Collection::value_type vg::sum (const Collection &collection)
    Compute the sum of the values in a collection. Values must be default- constructable (like numbers are).
template <typename Collection>
Collection::value_type vg::logprob_sum (const Collection &collection)
    Compute the sum of the values in a collection, where the values are log probabilities and the result is the
    log of the total probability. Items must be convertible to/from doubles for math.
template <template< class T, class A=std::allocator< T >> class Container, typename Input, typename Output>
Container<Output> vg::map_over (const Container<Input> &in, const std::function<Output> const
    Input&
    > &lambda) We have a transforming map function that we can chain.
template <template< class T, class A=std::allocator< T >> class Container, typename Item>
Container<const Item *> vg::pointerfy (const Container<Item> &in)
    We have a wrapper of that to turn a container reference into a container of pointers.

size_t vg::integer_power (size_t x, size_t power)

void vg::genotype_svs (VG *graph, string gamfile, string reffpath)
    Takes a graph and two GAMs, one tumor and one normal Locates existing variation supported by the
    tumor and annotate it with a path Then overlay the normal sample Use a depthmap of snarltraversal trans-
    forms, one for tumor, one for normal which we can use to count the normal and tumor alleles void so-
    matic_genotyper(VG* graph, string tumorgam, string normalgam);

    Do smart augment, maintaining a depth map for tumor/normal perfect matches and then editing in all of
    the SV reads (after normalization) with a T/N_ prefix Then, get our Snarls count reads supporting each
    and genotype void somatic_caller_genotyper(VG* graph, string tumorgam, string normalgam);

void vg::variant_recall (VG *graph, vcflib::VariantCallFile *vars, FastaReference *ref_genome,
    vector<FastaReference *> insertions, string gamfile, bool isIndex)
    run with : vg genotype -L -V v.vcf -I i.fa -R ref.fa

static void vg::triple_to_vg (void *user_data, raptor_statement *triple)

Node vg::xg_node (id_t id, xg::XG *xgidx)

vector<Edge> vg::xg_edges_on_start (id_t id, xg::XG *xgidx)

```

```
vector<Edge> vg::xg_edges_on_end(id_t id, xg::XG *xgidx)

string vg::xg_node_sequence(id_t id, xg::XG *xgidx)

size_t vg::xg_node_length(id_t id, xg::XG *xgidx)
    Get the length of a Node from an xg::XG index, with cacheing of deserialized nodes.

int64_t vg::xg_node_start(id_t id, xg::XG *xgidx)
    Get the node start position in the sequence vector.

char vg::xg_pos_char(pos_t pos, xg::XG *xgidx)
    Get the character at a position in an xg::XG index, with cacheing of deserialized nodes.

map<pos_t, char> vg::xg_next_pos_chars(pos_t pos, xg::XG *xgidx)
    Get the characters at positions after the given position from an xg::XG index, with cacheing of deserialized nodes.

set<pos_t> vg::xg_next_pos(pos_t pos, bool whole_node, xg::XG *xgidx)

int64_t vg::xg_distance(pos_t pos1, pos_t pos2, int64_t maximum, xg::XG *xgidx)

set<pos_t> vg::xg_positions_bp_from(pos_t pos, int64_t distance, bool rev, xg::XG *xgidx)
```

Variables

```
const char *const vg::BAM_DNA_LOOKUP

constexpr size_t vg::spaced_primes[62]

constexpr size_t vg::primitive_roots_of_unity[62]

const map<char, char> vg::COMPLEMENTARY_NUCLEOTIDES

const int8_t vg::default_match

const int8_t vg::default_mismatch

const int8_t vg::default_gap_open

const int8_t vg::default_gap_extension

const int8_t vg::default_full_length_bonus

const int8_t vg::default_max_scaled_score

const uint8_t vg::default_max_qual_score

const double vg::default_gc_content

const int vg::MAX_ALLELE_LENGTH

const double vg::LOG_ZERO

const char vg::complement[256]

const char *vg::VG_VERSION_STRING
```

namespace Enums

enum type `vg::subcommand::CommandCategory`

Defines what kind of command each subcommand is.

Values:

Some commands are part of the main build-graph, align, call variants pipeline.

Some subcommands are important parts of the toolkit/swiss army knife for working with graphs and data.

Some commands are less important but potentially useful widgets that let you do a thing you might need.

Some commands are useful really only for developers.

Functions

```
std::ostream &vg::subcommand::operator<< (std::ostream &out, const CommandCategory
                                         &category)
```

Define a way to print the titles of the different categories.

namespace Functions

```
int vg::unittest::run_unit_tests (int argc, char **argv)
```

Take the original argc and argv from a `vg unittest` command-line call and run the unit tests. We keep this in its own CPP/HPP to keep our unit test library from being a dependency of `main.o` and other real application code.

Passes the args along to the unit test system.

Returns exit code 0 on success, other codes on failure.

namespace Typedefs

```
typedef
```

```
typedef
```

```
typedef
```

Functions

```
id_t xg::side_id (const side_t &side)
```

```
bool xg::side_is_end (const side_t &side)
```

```
side_t xg::make_side (id_t id, bool is_end)
```

```
id_t xg::trav_id (const trav_t &trav)
```

```
bool xg::trav_is_rev (const trav_t &trav)
```

```
int32_t xg::trav_rank (const trav_t &trav)
```

```
trav_t xg::make_trav (id_t id, bool is_rev, int32_t rank)
```

```
int xg::dna3bit (char c)
```

```
char xg::revdna3bit (int i)
```

```
Mapping xg::new_mapping (const string &name, int64_t id, size_t rank, bool is_reverse)

void xg::parse_region (const string &target, string &name, int64_t &start, int64_t &end)

void xg::to_text (ostream &out, Graph &graph)

size_t xg::serialize (XG::rank_select_int_vector &to_serialize, ostream &out,
                      sdslib::structure_tree_node *parent, const std::string name)

void xg::deserialize (XG::rank_select_int_vector &target, istream &in)

bool xg::edges_equivalent (const Edge &e1, const Edge &e2)

bool xg::relative_orientation (const Edge &e1, const Edge &e2)

bool xg::arrive_by_reverse (const Edge &e, int64_t node_id, bool node_is_reverse)

bool xg::depart_by_reverse (const Edge &e, int64_t node_id, bool node_is_reverse)

Edge xg::make_edge (int64_t from, bool from_start, int64_t to, bool to_end)

char xg::reverse_complement (const char &c)

string xg::reverse_complement (const string &seq)

void xg::extract_pos (const string &pos_str, int64_t &id, bool &is_rev, size_t &off)

void xg::extract_pos_substr (const string &pos_str, int64_t &id, bool &is_rev, size_t &off,
                             size_t &len)
```

file **alignment.cpp**

```
#include "alignment.hpp" #include "stream.hpp" #include <regex>
```

file **alignment.hpp**

```
#include <iostream> #include <functional> #include <zlib.h> #include "utility.hpp" #include
"path.hpp" #include "position.hpp" #include "vg.pb.h" #include "xg.hpp" #include "htslib/hfile.h" #include
"htslib/hts.h" #include "htslib/sam.h" #include "htslib/vcf.h"
```

file **banded_global_aligner.cpp**

```
#include "banded_global_aligner.hpp" #include "json2pb.h"
```

file **banded_global_aligner.hpp**

```
#include <stdio.h> #include <ctype.h> #include <iostream> #include <vector> #include <un-
ordered_set> #include <unordered_map> #include <list> #include <exception> #include "vg.pb.h"
```

file **benchmark.cpp**

```
#include "benchmark.hpp" #include <vector> #include <iostream> #include <cassert> #include <nu-
meric> #include <cmath> #include <iomanip>
```

file **benchmark.hpp**

```
#include <chrono> #include <functional> #include <iostream> #include <string> : implementations of bench-
marking functions
```

Contains utilities for running (micro)benchmarks of vg code.

file **bin2ascii.h**

```
#include <string> #include <stdexcept>
```

Defines

```
VG_BIN2ASCII_H_INCLUDED
```


Functions

`std::string hex2bin (const std::string &s)`

`std::string bin2hex (const std::string &s)`

`std::string b64_encode (const std::string &s)`

`std::string b64_decode (const std::string &s)`

file **cached_position.cpp**
#include "cached_position.hpp"

file **cached_position.hpp**
#include "vg.pb.h" #include "types.hpp" #include "xg.hpp" #include "lru_cache.h" #include "utility.hpp" #include "json2pb.h" #include <gcsa/gcsa.h> #include <iostream> Functions for working with cached Positions and pos_ts.

file **cactus.cpp**
#include <unordered_set> #include "cactus.hpp" #include "vg.hpp" #include "algorithms/topological_sort.hpp" #include <unordered_map> #include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/cached_position.hpp" #include "vg.pb.h" #include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/hash_map.hpp" #include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/handle.hpp" #include "algorithms/weakly_connected_components.hpp" #include <vector> #include "algorithms/find_shortest_paths.hpp" #include "sonLib.h" #include "stCactusGraphs.h"

file **cactus.hpp**
#include <vector> #include <map> #include "types.hpp" #include "utility.hpp" #include "node-side.hpp" #include "vg.hpp" #include "sonLib.h" #include "stCactusGraphs.h" **cactus.hpp**: Wrapper utility functions for for pinchesAndCacti

file **chunker.cpp**
#include <iostream> #include <unordered_set> #include "stream.hpp" #include "chunker.hpp"

file **chunker.hpp**
#include <iostream> #include <map> #include <chrono> #include <ctime> #include "lru_cache.h" #include "vg.hpp" #include "xg.hpp" #include "json2pb.h" #include "region.hpp" #include "index.hpp"

file **cluster.cpp**
#include <string> #include <algorithm> #include <utility> #include <cstring> #include "cluster.hpp"

file **cluster.hpp**
#include <gcsa/gcsa.h> #include <gcsa/lcp.h> #include "position.hpp" #include "gssw_aligner.hpp" #include "utility.hpp" #include "mem.hpp" #include "xg.hpp" #include <functional> #include <string> #include <vector> #include <map> Chaining and clustering tools to work with maximal exact matches.

file **colors.hpp**
#include <vector> #include <random>

file **constructor.cpp**
#include "vg.hpp" #include "constructor.hpp" #include <cstdlib> #include <set> #include <tuple> #include <list> #include <algorithm> #include <memory> **constructor.cpp**: contains implementations for vg construction functions.

file **constructor.hpp**
#include <vector> #include <set> #include <map> #include <cstdlib> #include <functional> #include <regex> #include "types.hpp" #include "progressive.hpp" #include "vg.pb.h" #include "Variant.h" #include "Fasta.h" #include "vcf_buffer.hpp" #include "name_mapper.hpp" **constructor.hpp**: defines a tool class used for constructing VG graphs from VCF files.

```
file convert.hpp  
    #include <sstream>
```

```
file deconstructor.cpp  
    #include "deconstructor.hpp"
```

```
file deconstructor.hpp  
    #include <vector>#include <string>#include <sstream>#include <ostream>#include "genotype-  
kit.hpp"#include "path_index.hpp"#include "Variant.h"#include "path.hpp"#include "vg.hpp"#include  
"vg.pb.h"#include "Fasta.h" Deconstruct is getting rewritten. New functionality: -Detect superbubbles and  
bubbles -Fix command line interface. -harmonize on XG / raw graph (i.e. deprecate index) -Use unroll/DAGify  
if needed to avoid cycles
```

Much of this is taken from Brankovic's "Linear-Time Superbubble Identification Algorithm for Genome Assembly"

```
file distributions.hpp  
    #include <map>#include <cmath>#include "utility.hpp"
```

```
file edit.cpp  
    #include "edit.hpp"#include "utility.hpp"
```

```
file edit.hpp  
    #include "vg.pb.h"#include <utility>#include <iostream>#include "json2pb.h"
```

```
file entropy.cpp  
    #include "entropy.hpp"
```

```
file entropy.hpp  
    #include <iostream>#include <set>#include <vector>#include <string>#include <cmath>#include <map>
```

```
file feature_set.cpp  
    #include "feature_set.hpp"#include <sstream>
```

```
file feature_set.hpp  
    #include <string>#include <vector>#include <map>#include <iostream> Defines a FeatureSet class that can  
read and write BED files, and that can keep BED features up to date as paths are edited.
```

```
file filter.cpp  
    #include "filter.hpp"
```

```
file filter.hpp  
    #include <vector>#include <cstdlib>#include <iostream>#include <unordered_map>#include  
<sstream>#include <string>#include <math.h>#include "vg.hpp"#include "mapper.hpp"#include  
"xg.hpp"#include "vg.pb.h" Provides a way to filter Edits contained within Alignments. This can be  
used to clean out sequencing errors and to find high-quality candidates for variant calling.
```

```
file flow_sort.cpp  
    #include "vg.hpp"#include "stream.hpp"#include "gssw_aligner.hpp"#include "vg.pb.h"#include  
"flow_sort.hpp"#include <raptor2/raptor2.h>
```

```
file flow_sort.hpp  
    #include "vg.pb.h"
```

```
file gamsorter.cpp  
    #include "gamsorter.hpp"
```

Variables

```
struct custom_pos_sort_key possortkey
```

```
struct custom_aln_sort_key alnsortkey
```

```
file gamsorter.hpp
```

```
#include "vg.pb.h" #include "stream.hpp" #include <string> #include <queue> #include <sstream> #include
<functional> #include <algorithm> #include <iostream> #include <set> #include <vector> #include
<unordered_map> #include <tuple> #include "google/protobuf/stubs/common.h" #include
"google/protobuf/io/zero_copy_stream.h" #include "google/protobuf/io/zero_copy_stream_impl.h" #include
"google/protobuf/io/gzip_stream.h" #include "google/protobuf/io/coded_stream.h"
```

```
file genome_state.cpp
```

```
#include "genome_state.hpp"
```

```
file genome_state.hpp
```

```
#include "handle.hpp" #include "snarls.hpp" #include <vector> #include <unordered_map> #include <util-
ity> #include <tuple> MCMC-friendly genome state representation.
```

```
file genotypekit.cpp
```

```
#include "genotypekit.hpp" #include "algorithms/topological_sort.hpp" #include "algo-
rithms/is_directed_acyclic.hpp" #include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/handle.hpp"
<unordered_set> #include <vector> #include "cactus.hpp"
```

```
file genotypekit.hpp
```

```
#include <iostream> #include <algorithm> #include <functional> #include <cmath> #include <regex> #include
<limits> #include <unordered_set> #include <unordered_map> #include <list> #include "vg.pb.h" #include
"vg.hpp" #include "translator.hpp" #include "hash_map.hpp" #include "utility.hpp" #include
"types.hpp" #include "distributions.hpp" #include "snarls.hpp" #include "path_index.hpp" #include "son-
Lib.h"
```

```
file genotyper.cpp
```

```
#include <csdint> #include "genotyper.hpp" #include "algorithms/topological_sort.hpp"
```

```
file genotyper.hpp
```

```
#include <iostream> #include <algorithm> #include <functional> #include <numeric> #include
<cmath> #include <limits> #include <unordered_set> #include <unordered_map> #include <regex> #include
<vector> #include <list> #include "vg.pb.h" #include "vg.hpp" #include "translator.hpp" #include "deconstruc-
tor.hpp" #include "srpe.hpp" #include "hash_map.hpp" #include "utility.hpp" #include "types.hpp" #include
"genotypekit.hpp" #include "path_index.hpp" #include "index.hpp" #include "distributions.hpp"
```

```
file graph.cpp
```

```
#include "graph.hpp"
```

```
file graph.hpp
```

```
#include "vg.pb.h" #include "types.hpp" #include <set> #include <algorithm>
```

```
file graph_synchronizer.cpp
```

```
#include "graph_synchronizer.hpp" #include "algorithms/extract_connecting_graph.hpp" #include <un-
ordered_map> #include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/position.hpp" #include
"/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/cached_position.hpp" #include
"/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/handle.hpp" #include
".../vg.pb.h" #include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/hash_map.hpp" #include
<iterator>
```

```
file graph_synchronizer.hpp
```

```
#include "vg.hpp" #include "path_index.hpp" #include <thread> #include <mutex> #include <condi-
tion_variable> : define a GraphSynchronizer that can manage concurrent access and updates to a VG
graph.
```

```
file gssw_aligner.cpp
```

```
#include "gssw_aligner.hpp" #include "json2pb.h"
```

Variables

```
const double quality_scale_factor
```

```
const double exp_overflow_limit
```

file **gssw_aligner.hpp**

```
#include <algorithm>#include <utility>#include <vector>#include <set>#include <string>#include  
<unordered_map>#include "gssw.h"#include "vg.pb.h"#include "vg.hpp"#include "Variant.h"#include  
"Fasta.h"#include "path.hpp"#include "utility.hpp"#include "banded_global_aligner.hpp"
```

file **handle.cpp**

```
#include "handle.hpp"#include "snarls.hpp" Implement handle graph utility methods.
```

file **handle.hpp**

```
#include "types.hpp"#include "vg.pb.h"#include <functional>#include <cstdint>#include <vector> Defines  
a handle type that can refer to oriented nodes of, and be used to traverse, any backing graph implementation.  
Not just an ID or a pos_t because XG (and maybe other implementations) provide more efficient local traversal  
mechanisms if you can skip ID lookups.
```

file **haplotype_extractor.cpp**

```
#include <iostream>#include "vg.hpp"#include "haplotype_extractor.hpp"#include "json2pb.h"#include  
"xg.hpp"
```

Functions

```
void trace_haplotypes_and_paths (xg::XG &index, vg::id_t start_node, int ex-  
tend_distance, Graph &out_graph, map<string, int>  
&out_thread_frequencies, bool expand_graph)
```

```
void output_haplotype_counts (ostream &annotation_ostream, vector<pair<thread_t, int>>  
&haplotype_list, xg::XG &index)
```

```
Graph output_graph_with_embedded_paths (vector<pair<thread_t, int>> &haplotype_list,  
xg::XG &index)
```

```
void output_graph_with_embedded_paths (ostream &subgraph_ostream, vec-  
tor<pair<thread_t, int>> &haplotype_list, xg::XG  
&index, bool json)
```

```
void thread_to_graph_spanned (thread_t &t, Graph &g, xg::XG &index)
```

```
void add_thread_nodes_to_set (thread_t &t, set<int64_t> &nodes)
```

```
void add_thread_edges_to_set (thread_t &t, set<pair<int, int>> &edges)
```

```
void construct_graph_from_nodes_and_edges (Graph &g, xg::XG &index, set<int64_t>  
&nodes, set<pair<int, int>> &edges)
```

```
Path path_from_thread_t (thread_t &t)
```

```
vector<pair<thread_t, int>> list_haplotypes (xg::XG &index, xg::XG::ThreadMapping start_node,  
int extend_distance)
```

file **haplotype_extractor.hpp**

```
#include <cstdio>#include <cstdlib>#include <iostream>#include <vector>#include "vg.pb.h"#include  
"xg.hpp"
```

Typedefs

```
using
```

Functions

```
void trace_haplotypes_and_paths (xg::XG &index,   vg::id_t start_node,   int extend_distance,   Graph &out_graph,   map<string, int> &out_thread_frequencies,   bool expand_graph = true)
```

```
Path path_from_thread_t (thread_t &t)
```

```
vector<pair<thread_t, int>> list_haplotypes (xg::XG &index,   xg::XG::ThreadMapping start_node,   int extend_distance)
```

```
void output_graph_with_embedded_paths (ostream &subgraph_ostream,   vector<pair<thread_t, int>> &haplotype_list,   xg::XG &index,   bool json = true)
```

```
Graph output_graph_with_embedded_paths (vector<pair<thread_t, int>> &haplotype_list,   xg::XG &index)
```

```
void output_haplotype_counts (ostream &annotation_ostream,   vector<pair<thread_t, int>> &haplotype_list,   xg::XG &index)
```

```
void thread_to_graph_spanned (thread_t &t,   Graph &graph,   xg::XG &index)
```

```
void add_thread_nodes_to_set (thread_t &t,   set<int64_t> &nodes)
```

```
void add_thread_edges_to_set (thread_t &t,   set<pair<int, int>> &edges)
```

```
void construct_graph_from_nodes_and_edges (Graph &g,   xg::XG &index,   set<int64_t> &nodes,   set<pair<int, int>> &edges)
```

file **hash_map.hpp**

```
#include "sparsehash/sparse_hash_map"#include "sparsehash/dense_hash_map"#include <tuple>
```

Defines

```
OVERLOAD_PAIR_HASH
```

```
USE_DENSE_HASH
```

file **hash_map_set.hpp**

```
#include "sparsehash/sparse_hash_map"#include "sparsehash/sparse_hash_set"
```

Defines

```
OVERLOAD_PAIR_HASH
```

file **homogenizer.cpp**

```
#include "homogenizer.hpp"
```

file **homogenizer.hpp**

```
#include <iostream>#include <vector>#include "vg.hpp"#include "translator.hpp"#include "filter.hpp"#include "mapper.hpp"#include "vg.pb.h"#include "types.hpp"
```

Defines

```
VG_HOMOGENIZEER
```

file **index.cpp**

```
#include "index.hpp"
```

Defines

S (x)

file **index.hpp**

```
#include <iostream>#include <exception>#include <sstream>#include <climits>#include
"rocksdb/db.h"#include "rocksdb/env.h"#include "rocksdb/options.h"#include
"rocksdb/write_batch.h"#include "rocksdb/memtablerep.h"#include "rocksdb/statistics.h"#include
"rocksdb/cache.h"#include "rocksdb/slice_transform.h"#include "rocksdb/table.h"#include
"rocksdb/filter_policy.h"#include "json2pb.h"#include "vg.hpp"#include "hash_map.hpp"
```

file **json2pb.cpp**

```
#include <errno.h>#include <jansson.h>#include <google/protobuf/message.h>#include
<google/protobuf/descriptor.h>#include <json2pb.h>#include <stdexcept>#include <cstdio>#include
"bin2ascii.h"
```

Defines

json_boolean (val)

_CONVERT (type, ctype, fmt, sfunc, afunc)

_SET_OR_ADD (sfunc, afunc, value)

_CONVERT (type, ctype, fmt, sfunc, afunc)

Functions

static json_t * _pb2json (const Message &msg)

static json_t * _field2json (const Message &msg, const FieldDescriptor *field, size_t index)

static void _json2pb (Message &msg, json_t *root)

static void _json2field (Message &msg, const FieldDescriptor *field, json_t *jf)

void json2pb (Message &msg, const char *buf, size_t size)

void json2pb (Message &msg, FILE *fp)

int json_dump_std_string (const char *buf, size_t size, void *data)

std::string pb2json (const Message &msg)

file **json2pb.h**

```
#include <string>#include <cstdio>#include <functional>#include <vector>#include <stream.hpp>#include
<iostream>
```

Functions

void json2pb (google::protobuf::Message &msg, const char *buf, size_t size)

void json2pb (google::protobuf::Message &msg, FILE *fp)

std::string pb2json (const google::protobuf::Message &msg)

file **main.cpp**

```
#include <iostream>#include <fstream>#include <ctime>#include <cstdio>#include <getopt.h>#include
<sys/stat.h>#include "google/protobuf/stubs/common.h"#include "version.hpp"#include "subcom-
mand/subcommand.hpp"
```

Functions

```
void vg_help (char **argv)
```

```
int main (int argc, char *argv[])
```

file **mapper.cpp**

```
#include <unordered_set>#include "mapper.hpp"#include "algorithms/extract_containing_graph.hpp"#include
<vector>#include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/position.hpp"#include
"/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/xg.hpp"#include
"/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/vg.hpp"#include
"..vg.pb.h"#include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/handle.hpp"#include
"/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/hash_map.hpp"
```

file **mapper.hpp**

```
#include <iostream>#include <map>#include <chrono>#include <ctime>#include "omp.h"#include
"vg.hpp"#include "xg.hpp"#include "index.hpp"#include <gcsa/gcsa.h>#include <gcsa/lcp.h>#include
"alignment.hpp"#include "path.hpp"#include "position.hpp"#include "xg_position.hpp"#include
"lru_cache.h"#include "json2pb.h"#include "entropy.hpp"#include "gssw_aligner.hpp"#include
"mem.hpp"#include "cluster.hpp"#include "graph.hpp"
```

file **mem.cpp**

```
#include <string>#include <algorithm>#include <cstring>#include <sstream>#include "mem.hpp"
```

file **mem.hpp**

```
#include <gcsa/gcsa.h>#include <gcsa/lcp.h>#include "position.hpp"#include "utility.hpp"#include <func-
tional>#include <string>#include <vector>#include <map> Maximal Exact Matches (MEMs) header
```

file **multipath_alignment.cpp**

```
#include "multipath_alignment.hpp"
```

file **multipath_alignment.hpp**

```
#include <stdio.h>#include <vector>#include <list>#include <unordered_map>#include <algo-
rithm>#include "vg.pb.h"#include "path.hpp"#include "alignment.hpp"#include "utility.hpp"
```

file **multipath_mapper.cpp**

```
#include "multipath_mapper.hpp"#include "algorithms/extract_containing_graph.hpp"#include "algo-
rithms/extract_connecting_graph.hpp"#include "algorithms/extract_extending_graph.hpp"#include <un-
ordered_map>#include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/position.hpp"#include
"/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/cached_position.hpp"#include
"..vg.pb.h"#include "/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/hash_map.hpp"#include
"/home/docs/checkouts/readthedocs.org/user_builds/vg/checkouts/latest/src/handle.hpp"#include "algo-
rithms/topological_sort.hpp"#include "algorithms/weakly_connected_components.hpp"
```

file **multipath_mapper.hpp**

```
#include "hash_map.hpp"#include "suffix_tree.hpp"#include "mapper.hpp"#include
"gssw_aligner.hpp"#include "types.hpp"#include "multipath_alignment.hpp"#include "xg.hpp"#include
"vg.pb.h"#include "position.hpp"#include "path.hpp"#include "edit.hpp"#include "snarls.hpp"
```

file **name_mapper.cpp**

```
#include "name_mapper.hpp" : contains implementations for the NameMapper to convert between VCF and
graph/FASTA contig names.
```


file name_mapper.hpp
#include <map>#include <string> *name_mapper.hpp*: defines a class that maps back and forth from VCF-space contig names to graph or FASTA-space contig names.

file nested_traversal_finder.cpp
#include "nested_traversal_finder.hpp" : Contains implementation for a TraversalFinder that works on non-leaf Snarls and produces covering paths.

file nested_traversal_finder.hpp
#include "genotypekit.hpp" : Defines a TraversalFinder that produces covering paths, with an awareness of nested Snarls.

file nodeside.hpp
#include <ostream>#include <utility>#include "vg.pb.h"#include "types.hpp"#include "hash_map.hpp"

file nodetraversal.hpp
#include "vg.pb.h"#include "hash_map.hpp"

file option.cpp
#include <typeinfo>#include <cxxabi.h>#include <cassert>#include "option.hpp" : Definitions for our thing-doer-class-attached option system

file option.hpp
#include <string>#include <vector>#include <set>#include <map>#include <functional>#include <iostream>#include <sstream>#include <getopt.h> : Command-line options that can be attached to configurable thing-doer classes (variant callers, mappers, etc.)

To use: make your configurable object inherit from Configurable, and make all your command-line-option fields into Option<whatever type>.

file packer.cpp
#include "packer.hpp"

file packer.hpp
#include <iostream>#include <map>#include <chrono>#include <ctime>#include "omp.h"#include "xg.hpp"#include "alignment.hpp"#include "path.hpp"#include "position.hpp"#include "json2pb.h"#include "graph.hpp"#include "gcsa/internal.h"#include "xg_position.hpp"#include "utility.hpp"

file path.cpp
#include "path.hpp"#include "stream.hpp"#include "region.hpp"

file path.hpp
#include <iostream>#include <algorithm>#include <functional>#include <set>#include <list>#include <sstream>#include "json2pb.h"#include "vg.pb.h"#include "edit.hpp"#include "hash_map.hpp"#include "utility.hpp"#include "types.hpp"#include "position.hpp"#include "nodetraversal.hpp"

file path_index.cpp
#include "path_index.hpp"

file path_index.hpp
#include <map>#include <utility>#include <string>#include "vg.hpp"#include "xg.hpp" Provides an index for indexing an individual path for fast random access. Stores all the mappings uncompressed in memory.

Used for the reference path during VCF creation and interpretation.

file phase_duplicator.cpp
#include "phase_duplicator.hpp"

file phase_duplicator.hpp
#include <utility>#include <vector>#include <xg.hpp>#include "vg.pb.h"#include "types.hpp" This file contains the PhaseDuplicator, which duplicates and un-crosslinks complex regions of a graph using information about phased traversals.

```

file phased_genome.cpp
    #include "phased_genome.hpp"

file phased_genome.hpp
    #include <stdio.h>#include <cassert>#include <list>#include "vg.pb.h"#include "vg.hpp"#include "node-
traversal.hpp"#include "genotypekit.hpp"#include "hash_map.hpp"#include "snarls.hpp"

file pictographs.hpp
    #include <vector>#include <random>#include <functional>

file pileup.cpp
    #include <cstdlib>#include <stdexcept>#include <regex>#include "json2pb.h"#include
    "pileup.hpp"#include "stream.hpp"

file pileup.hpp
    #include <iostream>#include <algorithm>#include <functional>#include "vg.pb.h"#include
    "vg.hpp"#include "hash_map.hpp"#include "utility.hpp"

file pileup_augmenter.cpp
    #include <cstdlib>#include <stdexcept>#include "json2pb.h"#include "pileup_augmenter.hpp"#include
    "stream.hpp"

file pileup_augmenter.hpp
    #include <iostream>#include <algorithm>#include <functional>#include <cmath>#include <lim-
its>#include <unordered_set>#include <tuple>#include "vg.pb.h"#include "vg.hpp"#include
    "hash_map.hpp"#include "utility.hpp"#include "pileup.hpp"#include "path_index.hpp"#include "geno-
typekit.hpp"#include "option.hpp"

file position.cpp
    #include "position.hpp"

file position.hpp
    #include "vg.pb.h"#include "types.hpp"#include "utility.hpp"#include "json2pb.h"#include
    <gcsa/gcsa.h>#include <iostream> Functions for working with Positions and pos_ts.

file progressive.cpp
    #include "progressive.hpp"#include <iostream>

file progressive.hpp
    #include <string>#include "progress_bar.hpp"

file readfilter.cpp
    #include "readfilter.hpp"#include "IntervalTree.h"#include <fstream>#include <sstream>

file readfilter.hpp
    #include <vector>#include <cstdlib>#include <iostream>#include <string>#include "vg.hpp"#include
    "xg.hpp"#include "vg.pb.h" Provides a way to filter and transform reads, implementing the bulk of the vg
    filter command.

file region.cpp
    #include <iostream>#include <fstream>#include <cassert>#include "region.hpp"

file region.hpp
    #include <string>#include <vector>#include <sstream>#include "xg.hpp"

file sampler.cpp
    #include "sampler.hpp"

file sampler.hpp
    #include <iostream>#include <map>#include <unordered_map>#include <vector>#include
    <sstream>#include <algorithm>#include <chrono>#include <ctime>#include "vg.hpp"#include

```

```
“xg.hpp”#include      “alignment.hpp”#include      “path.hpp”#include      “position.hpp”#include  
“cached_position.hpp”#include “lru_cache.h”#include “json2pb.h”
```

```
file simplifier.cpp  
#include “simplifier.hpp”
```

```
file simplifier.hpp  
#include “progressive.hpp”#include “vg.hpp”#include “vg.pb.h”#include “genotypekit.hpp”#include “util-  
ity.hpp”#include “path.hpp”#include “feature_set.hpp”#include “path_index.hpp” Provides a class for sim-  
plifying graphs by popping bubbles.
```

```
file snarls.cpp  
#include “snarls.hpp”#include “json2pb.h”
```

```
file snarls.hpp  
#include <cstdint>#include <stdio.h>#include <unordered_map>#include <unordered_set>#include  
<fstream>#include <deque>#include “stream.hpp”#include “vg.hpp”#include “handle.hpp”#include  
“vg.pb.h”#include “hash_map.hpp”
```

```
file srpe.cpp  
#include “srpe.hpp”
```

```
file srpe.hpp  
#include <string>#include <cstdint>#include <Variant.h>#include “filter.hpp”#include “index.hpp”#include  
“path_index.hpp”#include “IntervalTree.h”#include “vg.pb.h”#include “fml.h”#include “vg.hpp”#include  
<gcsa/gcsa.h>#include “alignment.hpp”#include “genotypekit.hpp”
```

```
file ssw_aligner.cpp  
#include “ssw_aligner.hpp”
```

```
file ssw_aligner.hpp  
#include <vector>#include <set>#include <string>#include “ssw_cpp.h”#include “vg.pb.h”#include  
“path.hpp”
```

```
file stream.hpp  
#include <cassert>#include <iostream>#include <istream>#include <fstream>#include <func-  
tional>#include <vector>#include <list>#include “google/protobuf/stubs/common.h”#include  
“google/protobuf/io/zero_copy_stream.h”#include “google/protobuf/io/zero_copy_stream_impl.h”#include  
“google/protobuf/io/gzip_stream.h”#include “google/protobuf/io/coded_stream.h”
```

```
file add_main.cpp  
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include “sub-  
command.hpp”#include “./vg.hpp”#include “./variant_adder.hpp” Defines the “vg add” subcommand, which  
adds in variation from a VCF to an existing graph.
```

Functions

```
void help_add(char **argv)
```

```
int main_add(int argc, char **argv)
```

Variables

```
Subcommand vg_add("add", "add variants from a VCF to a graph", main_add)
```

```
file align_main.cpp  
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include “sub-
```

command.hpp”#include ”../vg.hpp” Defines the “vg align” subcommand, which aligns a read against an entire graph.

Functions

```
void help_align (char **argv)
int main_align (int argc, char **argv)
```

Variables

```
Subcommand vg_align("align", "local alignment", main_align)
```

file **annotate_main.cpp**

```
#include "subcommand.hpp"#include "../vg.hpp"#include "../utility.hpp"#include "../mapper.hpp"#include
"../stream.hpp"#include "../alignment.hpp"#include <unistd.h>#include <getopt.h>
```

Functions

```
void help_annotate (char **argv)
int main_annotate (int argc, char **argv)
```

Variables

```
Subcommand vg_annotate("annotate", "annotate alignments with graphs and graphs with ali
```

file **augment_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "sub-
command.hpp"#include "../option.hpp"#include "../vg.hpp"#include "../pileup_augmenter.hpp" Defines the
“vg augment” subcommand, which augments a graph using a GAM as a first step before computing sites and
calling variants.
```

It presently only supports augmentation via pileup (as originally used by vg call).

vg mod -i is an alternative, but as currently implemented it is too expensive. Ideally, a more heuristic/fast implementation would get added as an option here.

The new vg count structure, provided edge/edit/strand/quality is supported, may be an interesting replacement for the current protobuf pileups which ought to go, one way or the other.

Functions

```
Pileups *compute_pileups (VG *graph, const string &gam_file_name, int thread_count, int
min_quality, int max_mismatches, int window_size, int max_depth, bool
use_mapq, bool show_progress)
void augment_with_pileups (PileupAugmenter &augmenter, Pileups &pileups, bool ex-
pect_subgraph, bool show_progress)
void add_trivial_edits (VG &graph)
void help_augment (char **argv, ConfigurableParser &parser)
int main_augment (int argc, char **argv)
```

Variables

Subcommand **vg_augment**("augment","augment a graph from an alignment", PIPELINE, 5, main_

file **benchmark_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "sub-  
command.hpp"#include "../benchmark.hpp"#include "../version.hpp"#include "../vg.hpp"#include  
"../xg.hpp"#include "../algorithms/extract_connecting_graph.hpp"#include "../algo-  
rithms/topological_sort.hpp"#include "../algorithms/weakly_connected_components.hpp" Defines the "vg  
benchmark" subcommand, which runs and reports on microbenchmarks.
```

Functions

void **help_benchmark**(char **argv)

int **main_benchmark**(int argc, char **argv)

Variables

Subcommand **vg_benchmark**("benchmark","run and report on performance benchmarks", DEVELOP

file **bugs_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <stdlib.h>#include <iostream>#include  
"subcommand.hpp" Defines the "vg bugs" subcommand, which shows and opens Github issues.
```

Functions

void **help_bugs**(char **argv)

int **main_bugs**(int argc, char **argv)

Variables

Subcommand **vg_bugs**("bugs","show or create bugs", DEVELOPMENT, main_bugs)

file **call_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "sub-  
command.hpp"#include "../option.hpp"#include "../vg.hpp"#include "../support_caller.hpp" Defines the "vg  
call" subcommand, which calls variation from an augmented graph
```

Functions

void **help_call**(char **argv, ConfigurableParser &parser)

int **main_call**(int argc, char **argv)

Variables

Subcommand **vg_call**("call","call variants on an augmented graph", PIPELINE, 5, main_cal

file **chunk_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <string>#include <vector>#include
<regex>#include "subcommand.hpp"#include "../vg.hpp"#include "../stream.hpp"#include "../util-
ity.hpp"#include "../chunker.hpp"#include "../region.hpp"#include "../haplotype_extractor.hpp"
```

Functions

```
void help_chunk (char **argv)
```

```
int main_chunk (int argc, char **argv)
```

Variables

```
Subcommand vg_chunk("chunk","split graph or alignment into chunks", main_chunk)
```

file **circularize_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcom-
mand.hpp"#include "../vg.hpp" Defines the "vg circularize" subcommand
```

Functions

```
void help_circularize (char **argv)
```

```
int main_circularize (int argc, char **argv)
```

Variables

```
Subcommand vg_circularize("circularize","circularize a path within a graph", main_circ
```

file **compare_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcom-
mand.hpp"#include "../vg.hpp"#include "../index.hpp" Defines the "vg compare" subcommand
```

Functions

```
void help_compare (char **argv)
```

```
int main_compare (int argc, char **argv)
```

Variables

```
Subcommand vg_compare("compare","compare the kmer space of two graphs", main_compare)
```

file **concat_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcom-
mand.hpp"#include "../vg.hpp" Defines the "vg concat" subcommand
```

Functions

```
void help_concat (char **argv)
int main_concat (int argc, char **argv)
```

Variables

```
Subcommand vg_concat ("concat", "concatenate graphs tail-to-head", main_concat)
```

file **construct_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <memory>#include "subcom-
mand.hpp"#include "../stream.hpp"#include "../constructor.hpp"#include "../region.hpp"
```

Functions

```
void help_construct (char **argv)
int main_construct (int argc, char **argv)
```

Variables

```
Subcommand vg_construct ("construct", "graph construction", PIPELINE, 1, main_construct)
```

file **deconstruct_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcom-
mand.hpp"#include "../vg.hpp"#include "../deconstructor.hpp" Defines the "vg deconstruct" subcommand,
which turns graphs back into VCFs.
```

Functions

```
void help_deconstruct (char **argv)
int main_deconstruct (int argc, char **argv)
```

Variables

```
Subcommand vg_deconstruct ("deconstruct", "convert a graph into VCF relative to a referen
```

file **explode_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include "subcommand.hpp"#include
"../vg.hpp"#include "../stream.hpp"#include "../utility.hpp" : break a graph into connected components
```

Functions

```
void help_explode (char **argv)
int main_explode (int argc, char **argv)
```

Variables

Subcommand **vg_explode**("explode","split graph into connected components", main_explode)

file **filter_main.cpp**

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "subcommand.hpp"#include "../vg.hpp"#include "../readfilter.hpp" Defines the "vg filter" subcommand, which filters alignments.

Functions

void **help_filter**(char **argv)

int **main_filter**(int argc, char **argv)

Variables

Subcommand **vg_vectorize**("filter","filter reads", main_filter)

file **find_main.cpp**

#include "subcommand.hpp"#include "../vg.hpp"#include "../utility.hpp"#include "../mapper.hpp"#include "../stream.hpp"#include <unistd.h>#include <getopt.h>

Functions

void **help_find**(char **argv)

int **main_find**(int argc, char **argv)

Variables

Subcommand **vg_msga**("find","use an index to find nodes, edges, kmers, paths, or position", main_find)

file **gamsort_main.cpp**

#include "gamsorter.hpp"#include "stream.hpp"#include <getopt.h>#include "subcommand.hpp"#include "index.hpp"

Functions

void **help_gamsort**(char **argv)

int **main_gamsort**(int argc, char **argv)

Variables

Subcommand **vg_gamsort**("gamsort","Perform naive sorts and indexing on a GAM file.", main_gamsort)

file **genotype_main.cpp**

#include <getopt.h>#include "subcommand.hpp"#include "index.hpp"#include "stream.hpp"#include "genotyper.hpp"#include "genotypekit.hpp"#include "variant_recall.hpp"

Functions

void **help_genotype** (char **argv)

int **main_genotype** (int argc, char **argv)

Variables

Subcommand **vg_genotype** ("genotype", "Genotype (or type) graphs, GAMS, and VCFs.", main_g

file **help_main.cpp**

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <stdlib.h>#include <iostream>#include "subcommand.hpp"#include "../version.hpp" Defines the "vg help" subcommand, which describes subcommands.

Functions

void **help_help** (char **argv)

int **main_help** (int argc, char **argv)

Variables

Subcommand **vg_help** ("help", "show all subcommands", PIPELINE, main_help)

file **ids_main.cpp**

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcommand.hpp"#include "../vg.hpp"#include "../vg_set.hpp"#include "../algorithms/topological_sort.hpp" Defines the "vg ids" subcommand, which modifies node IDs.

Functions

void **help_ids** (char **argv)

int **main_ids** (int argc, char **argv)

Variables

Subcommand **vg_ids** ("ids", "manipulate node ids", TOOLKIT, main_ids)

file **index_main.cpp**

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <string>#include <vector>#include <regex>#include "subcommand.hpp"#include "../vg.hpp"#include "../index.hpp"#include "../stream.hpp"#include "../vg_set.hpp"#include "../utility.hpp"#include "../path_index.hpp"#include <gcsa/gcsa.h>#include <gcsa/algorithms.h>#include <gbwt/dynamic_gbwt.h>

Functions

void **help_index** (char **argv)

xg::XG::ThreadMapping **gbwt_to_thread_mapping** (gbwt::node_type node)


```

gbwt::node_type mapping_to_gbwt (const Mapping &mapping)
gbwt::node_type node_side_to_gbwt (const NodeSide &side)
int main_index (int argc, char **argv)

```

Variables

Subcommand **vg_construct**("index", "index graphs or alignments for random access or mapping")

file **join_main.cpp**

```

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcommand.hpp"#include "../vg.hpp" Defines the "vg join" subcommand, which attaches graphs together.

```

Functions

```

void help_join (char **argv)
int main_join (int argc, char **argv)

```

Variables

Subcommand **vg_join**("join", "combine graphs via a new head", main_join)

file **kmers_main.cpp**

```

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcommand.hpp"#include "../vg.hpp"#include "../vg_set.hpp" Defines the "vg kmers" subcommand, which generates the kmers in a graph.

```

Functions

```

void help_kmers (char **argv)
int main_kmers (int argc, char **argv)

```

Variables

Subcommand **vg_kmers**("kmers", "enumerate kmers of the graph", main_kmers)

file **locify_main.cpp**

```

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcommand.hpp"#include "../vg.hpp"#include "../index.hpp"#include "../convert.hpp" Defines the "vg locify" subcommand

```

Functions

```

void help_locify (char **argv)
int main_locify (int argc, char **argv)

```

Variables

Subcommand **vg_locify**("locify","find loci", main_locify)

file **map_main.cpp**

```
#include "subcommand.hpp"#include "../vg.hpp"#include "../utility.hpp"#include "../mapper.hpp"#include
"../stream.hpp"#include <unistd.h>#include <getopt.h>
```

Functions

void **help_map**(char **argv)

int **main_map**(int argc, char **argv)

Variables

Subcommand **vg_map**("map","MEM-based read alignment", PIPELINE, 3, main_map)

file **mod_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <string>#include <vec-
tor>#include <regex>#include "subcommand.hpp"#include "../vg.hpp"#include "../cactus.hpp"#include
"../stream.hpp"#include "../utility.hpp"#include "../algorithms/topological_sort.hpp"
```

Functions

void **help_mod**(char **argv)

int **main_mod**(int argc, char **argv)

Variables

Subcommand **vg_mod**("mod","filter, transform, and edit the graph", TOOLKIT, main_mod)

file **mpmap_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include "subcommand.hpp"#include "../multi-
path_mapper.hpp"#include "../path.hpp" : multipath mapping of reads to a graph
```

Functions

void **help_mpmap**(char **argv)

int **main_mpmap**(int argc, char **argv)

Variables

Subcommand **vg_mpmap**("mpmap","multipath alignments of reads to a graph", main_mpmap)

file **msga_main.cpp**

```
#include "subcommand.hpp"#include "../vg.hpp"#include "../utility.hpp"#include "../mapper.hpp"#include
"../stream.hpp"#include "../algorithms/topological_sort.hpp"#include <unistd.h>#include <getopt.h>
```

Functions

```
void help_msga (char **argv)
int main_msga (int argc, char **argv)
```

Variables

```
Subcommand vg_msga ("msga", "multiple sequence graph alignment", main_msga)
```

```
file pack_main.cpp
#include "subcommand.hpp" #include "../vg.hpp" #include "../utility.hpp" #include "../packer.hpp" #include
"./stream.hpp" #include <unistd.h> #include <getopt.h>
```

Functions

```
void help_pack (char **argv)
int main_pack (int argc, char **argv)
```

Variables

```
Subcommand vg_pack ("pack", "convert alignments to a compact coverage, edit, and path in
```

```
file paths_main.cpp
#include <omp.h> #include <unistd.h> #include <getopt.h> #include <iostream> #include "subcom-
mand.hpp" #include "../vg.hpp" Defines the "vg paths" subcommand, which reads paths in the graph.
```

Functions

```
void help_paths (char **argv)
int main_paths (int argc, char **argv)
```

Variables

```
Subcommand vg_paths ("paths", "traverse paths in the graph", main_paths)
```

```
file sift_main.cpp
#include <iostream> #include <fstream> #include <ctime> #include <stdio> #include <getopt.h> #include
<functional> #include <omp.h> #include "subcommand.hpp" #include <gcsa/gcsa.h> #include
"stream.hpp" #include "json2pb.h" #include "vg.hpp" #include "vg.pb.h" #include "filter.hpp" #include
"alignment.hpp"
```

Functions

```
void help_sift (char **argv)
int main_sift (int argc, char **argv)
```

Variables

Subcommand **vg_sift**("sift", "Filter Alignments by various metrics related to variant cal

file **sim_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "sub-  
command.hpp"#include "../vg.hpp"#include "../mapper.hpp"#include "../sampler.hpp" Defines the "vg sim"  
subcommand, which generates potential reads from a graph.
```

Functions

```
void help_sim(char **argv)
```

```
int main_sim(int argc, char **argv)
```

Variables

Subcommand **vg_sim**("sim", "simulate reads from a graph", TOOLKIT, main_sim)

file **simplify_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "sub-  
command.hpp"#include "../vg.hpp"#include "../simplifier.hpp"
```

Functions

```
void help_simplify(char **argv)
```

```
int main_simplify(int argc, char **argv)
```

Variables

Subcommand **vg_simplify**("simplify", "graph simplification", main_simplify)

file **snarls_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include  
<regex>#include "subcommand.hpp"#include "../vg.hpp"#include "vg.pb.h"#include "../genotypekit.hpp"
```

Functions

```
void help_snarl(char **argv)
```

```
int main_snarl(int argc, char **argv)
```

Variables

Subcommand **vg_snarl**("snarls", "compute snarls and their traversals", main_snarl)

file **sort_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcom-  
mand.hpp"#include "../vg.hpp"#include "../flow_sort.hpp" Defines the "vg sort" subcommand, which  
sorts graph nodes.
```

Functions

```
void help_sort (char **argv)
int main_sort (int argc, char *argv[])
```

Variables

Subcommand **vg_sort** ("sort", "sort variant graph using max flow algorithm or Eades fast h

```
file srpe_main.cpp
#include <iostream>#include <vector>#include <getopt.h>#include <functional>#include <regex>#include
"subcommand.hpp"#include "srpe.hpp"#include "stream.hpp"#include "index.hpp"#include "po-
sition.hpp"#include "vg.pb.h"#include "path.hpp"#include "genotypekit.hpp"#include "geno-
typer.hpp"#include "path_index.hpp"#include "vg.hpp"#include <math.h>#include "filter.hpp"#include
"utility.hpp"#include "Variant.h"#include "translator.hpp"#include "Fasta.h"#include "IntervalTree.h"
```

Functions

```
void help_srpe (char **argv)
int main_srpe (int argc, char **argv)
```

Variables

Subcommand **vg_srpe** ("srpe", "graph-external SV detection", main_srpe)

```
file stats_main.cpp
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "sub-
command.hpp"#include "../vg.hpp"#include "../distributions.hpp"#include "../genotypekit.hpp" Defines the
"vg stats" subcommand, which evaluates graphs and alignments.
```

Functions

```
void help_stats (char **argv)
int main_stats (int argc, char **argv)
```

Variables

Subcommand **vg_stats** ("stats", "metrics describing graph properties", TOOLKIT, main_stats)

```
file subcommand.cpp
#include "subcommand.hpp"#include <algorithm>#include <utility>#include <vector>#include <limits>
```

```
file subcommand.hpp
#include <map>#include <functional>#include <string>#include <iostream> subcommand.hpp: defines a
system for registering subcommands of the vg command (vg construct, vg view, etc.) at compile time. Re-
places the system of defining two functions and a giant run of if statements in main.cpp.
```

main.cpp does *not* need to include any subcommand headers!

Subcommands are created as static global objects in their own compilation units, which have to be explicitly linked into the binary (they won't be pulled out of a library if nothing references their symbols).

Subcommands are responsible for printing their own help; we can do “vg help” and print all the subcommands that exist (via a help subcommand), but we can't do “vg help subcommand” and have that be equivalent to “vg subcommand -help” (because the help subcommand doesn't know how to get help info on the others).

We have a subcommand importance/category system, so we can tell people about just the main pipeline and keep the subcommands they don't want out of their brains and off their screen.

Subcommands get passed all of argv, so they have to skip past their names when parsing arguments.

To make a subcommand, do something like this in a cpp file in this “subcommand” directory:

```
#include "subcommand.hpp"
using namespace vg::subcommand;

int main_frobnicate(int argc, char** argv) {
    return 0;
}

static Subcommand vg_frobnicate("frobnicate", "frobnicate nodes and edges",
    main_frobnicate);
```

file **subject_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <string>#include <vector>#include
<set>#include "subcommand.hpp"#include "../vg.hpp"#include "../stream.hpp"#include "../util-
ity.hpp"#include "../mapper.hpp"
```

Functions

```
void help_subject (char **argv)
```

```
int main_subject (int argc, char **argv)
```

Variables

```
Subcommand vg_subject("subject", "map alignments onto specific paths", main_subject)
```

file **test_main.cpp**

```
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcom-
mand.hpp"#include "../unittest/driver.hpp" Defines the “vg test” subcommand, which runs unit tests.
```

Functions

```
int main_test (int argc, char **argv)
```

Variables

```
Subcommand vg_test("test", "run unit tests", DEVELOPMENT, main_test)
```

file **trace_main.cpp**

```
#include <getopt.h>#include <string>#include <vector>#include "subcommand.hpp"#include
"../vg.hpp"#include "../haplotype_extractor.hpp"
```

Typedefs

using

Functions

void **help_trace** (char **argv)

int **main_trace** (int argc, char **argv)

Variables

Subcommand **vg_trace**("trace", "trace haplotypes", main_trace)

file **translate_main.cpp**

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcommand.hpp"#include "../vg.hpp"#include "../translator.hpp" Defines the “vg translate” subcommand

Functions

void **help_translate** (char **argv)

int **main_translate** (int argc, char **argv)

Variables

Subcommand **vg_version**("translate", "project alignments and paths through a graph transl.

file **validate_main.cpp**

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcommand.hpp"#include "../vg.hpp" Defines the “vg validate” subcommand

Functions

void **help_validate** (char **argv)

int **main_validate** (int argc, char **argv)

Variables

Subcommand **vg_validate**("validate", "validate the semantics of a graph", DEVELOPMENT, ma

file **vectorize_main.cpp**

#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "subcommand.hpp"#include "../vg.hpp"#include "../vectorizer.hpp"#include "../mapper.hpp" Defines the “vg vectorize” subcommand, which turns graphs into ML vectors.

Functions

```
void help_vectorize (char **argv)
int main_vectorize (int argc, char **argv)
```

Variables

```
Subcommand vg_vectorize("vectorize", "transform alignments to simple ML-compatible vect
```

```
file version_main.cpp
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <iostream>#include "subcom-
mand.hpp"#include "../version.hpp" Defines the "vg version" subcommand, which evaluates graphs and
alignments.
```

Functions

```
void help_version (char **argv)
int main_version (int argc, char **argv)
```

Variables

```
Subcommand vg_version("version", "version information", DEVELOPMENT, main_version)
```

```
file view_main.cpp
#include <omp.h>#include <unistd.h>#include <getopt.h>#include <list>#include <fstream>#include "sub-
command.hpp"#include "../multipath_alignment.hpp"#include "../vg.hpp" Defines the "vg view" subcom-
mand, which converts formats.
```

Functions

```
void help_view (char **argv)
int main_view (int argc, char **argv)
```

Variables

```
Subcommand vg_view("view", "format conversions for graphs and alignments", TOOLKIT, mai
```

```
file xg_main.cpp
#include <omp.h>#include <unistd.h>#include <iostream>#include <fstream>#include
<getopt.h>#include "subcommand.hpp"#include "sdsl/bit_vectors.hpp"#include "../version.hpp"#include
"../stream.hpp"#include "../cpp/vg.pb.h"#include "../xg.hpp"
```

Functions

```
void help_xg (char **argv)
int main_xg (int argc, char **argv)
```


Variables

Subcommand **vg_xg**("xg", "manipulate xg files", main_xg)

```
file suffix_tree.cpp
    #include "suffix_tree.hpp"

file suffix_tree.hpp
    #include <stdio.h>#include <unordered_map>#include <list>#include <vector>#include <sstream>#include
    <iostream>

file support_caller.cpp
    #include <iostream>#include <fstream>#include <sstream>#include <regex>#include
    <set>#include <unordered_set>#include <utility>#include <algorithm>#include <getopt.h>#include
    "vg.hpp"#include "index.hpp"#include "Variant.h"#include "genotypekit.hpp"#include
    "snarls.hpp"#include "path_index.hpp"#include "support_caller.hpp"#include "stream.hpp"#include
    "nested_traversal_finder.hpp"

file support_caller.hpp
    #include <iostream>#include <algorithm>#include <functional>#include <cmath>#include <lim-
    its>#include <unordered_set>#include <tuple>#include "vg.pb.h"#include "vg.hpp"#include
    "hash_map.hpp"#include "utility.hpp"#include "pileup.hpp"#include "path_index.hpp"#include "geno-
    typekit.hpp"#include "option.hpp"

file swap_remove.hpp
    #include <vector>#include <algorithm>
```

Functions

```
template <typename T>
bool swap_remove(std::vector<T> &v, const T &e)
```

```
file translator.cpp
    #include "translator.hpp"#include "stream.hpp"

file translator.hpp
    #include <iostream>#include <algorithm>#include <functional>#include <set>#include <vector>#include
    <list>#include "vg.pb.h"#include "vg.hpp"#include "hash_map.hpp"#include "utility.hpp"#include
    "types.hpp" Defines the Translator, which maps paths on an augmented graph into the base graph de-
    fined by a set of Translations from the augmented graph

file types.hpp
    #include <tuple> Contains typedefs for basic types useful for talking about graphs.

file driver.cpp
    #include "driver.hpp"#include "catch.hpp"#include <sstream>#include <algorithm>#include
    <string>#include <vector>#include <cstdint>#include <iomanip>#include <limits>#include
    <stdint.h>#include <iterator>#include <stdlib.h>#include <cmath>#include <set>#include <stdex-
    cept>#include <iosfwd>#include <streambuf>#include <ostream>#include <fstream>#include <mem-
    ory>#include <cctype>#include <map>#include <ctime>#include <assert.h>#include <signal.h>#include
    <cstdio>#include <iostream>#include <cerrno>#include <unistd.h>#include <sys/time.h>#include
    <cstring>#include <cfloat>
```

Defines

CATCH_CONFIG_RUNNER

file **driver.hpp**

file **utility.cpp**
#include "utility.hpp"

file **utility.hpp**
#include <string>#include <vector>#include <sstream>#include <omp.h>#include <cstring>#include
<algorithm>#include <numeric>#include <cmath>#include <unordered_set>#include <unistd.h>#include
"vg.pb.h"#include "sha1.hpp"#include "Variant.h"

file **variant_adder.cpp**
#include "variant_adder.hpp"#include "mapper.hpp"

file **variant_adder.hpp**
#include "vcf_buffer.hpp"#include "path_index.hpp"#include "vg.hpp"#include "progressive.hpp"#include
"name_mapper.hpp"#include "graph_synchronizer.hpp" *variant_adder.hpp*: defines a tool class used for
adding variants from VCF files into existing graphs.

file **variant_recall.cpp**
#include <stdint>#include "variant_recall.hpp"#include "algorithms/topological_sort.hpp"

file **variant_recall.hpp**
#include <iostream>#include <algorithm>#include <functional>#include <numeric>#include
<cmath>#include <limits>#include <unordered_set>#include <unordered_map>#include <regex>#include
<vector>#include <list>#include "vg.pb.h"#include "vg.hpp"#include "translator.hpp"#include "deconstruc-
tor.hpp"#include "srpe.hpp"#include "hash_map.hpp"#include "utility.hpp"#include "types.hpp"#include
"genotypekit.hpp"#include "path_index.hpp"#include "index.hpp"#include "distributions.hpp"

file **vcf_buffer.cpp**
#include "vcf_buffer.hpp" *constructor.cpp*: contains implementations for vg construction functions.

file **vcf_buffer.hpp**
#include <list>#include <tuple>#include "Variant.h" *vcf_buffer.hpp*: defines a buffer for reading through VCF
files with look-ahead.

file **vectorizer.cpp**
#include "vectorizer.hpp"

file **vectorizer.hpp**
#include <iostream>#include <sstream>#include "sdsl/bit_vectors.hpp"#include <vector>#include <un-
ordered_map>#include "vg.hpp"#include "xg.hpp"#include "vg.pb.h"

file **version.cpp**
#include "version.hpp"#include "vg_git_version.hpp"

Defines

VG_GIT_VERSION

file **version.hpp**

file **vg.cpp**
#include "vg.hpp"#include "stream.hpp"#include "gssw_aligner.hpp"#include "genotypekit.hpp"#include
"algorithms/topological_sort.hpp"#include <raptor2/raptor2.h>#include <stPinchGraphs.h>

file **vg.hpp**
#include <vector>#include <set>#include <string>#include <deque>#include <list>#include <ar-
ray>#include <omp.h>#include <unistd.h>#include <limits.h>#include <algorithm>#include <ran-
dom>#include "gssw.h"#include <gcsa/gcsa.h>#include <gcsa/lcp.h>#include "gssw_aligner.hpp"#include
"ssw_aligner.hpp"#include "region.hpp"#include "path.hpp"#include "utility.hpp"#include

```

“alignment.hpp”#include “vg.pb.h”#include “hash_map.hpp”#include “progressive.hpp”#include
“lru_cache.h”#include “Variant.h”#include “Fasta.h”#include “swap_remove.hpp”#include “pic-
tographs.hpp”#include “colors.hpp”#include “types.hpp”#include “gfakluge.hpp”#include “nodetraver-
sal.hpp”#include “nodeside.hpp”#include “handle.hpp”

```

file **vg.proto**

Variables

syntax

file **vg_set.cpp**

```
#include “vg_set.hpp”#include “stream.hpp”
```

file **vg_set.hpp**

```
#include <set>#include <regex>#include <stdlib.h>#include <gcsa/gcsa.h>#include “vg.hpp”#include “in-
dex.hpp”#include “xg.hpp”
```

file **xg.cpp**

```
#include “xg.hpp”#include “stream.hpp”#include <bitset>#include <arpa/inet.h>
```

file **xg.hpp**

```
#include <iostream>#include <fstream>#include <map>#include <queue>#include <omp.h>#include <un-
ordered_map>#include <unordered_set>#include “cpp/vg.pb.h”#include “sdsl/bit_vectors.hpp”#include
“sdsl/enc_vector.hpp”#include “sdsl/dac_vector.hpp”#include “sdsl/vlc_vector.hpp”#include
“sdsl/wavelet_trees.hpp”#include “sdsl/csa_wt.hpp”#include “sdsl/suffix_arrays.hpp”#include
“hash_map_set.hpp”#include “position.hpp”#include “graph.hpp”#include “path.hpp”#include “han-
dle.hpp”
```

Defines

MODE_DYNAMIC

MODE_SDSL

GPBWT_MODE

file **xg_position.cpp**

```
#include “xg_position.hpp”
```

file **xg_position.hpp**

```
#include “vg.pb.h”#include “types.hpp”#include “xg.hpp”#include “lru_cache.h”#include “util-
ity.hpp”#include “json2pb.h”#include <gcsa/gcsa.h>#include <iostream> Functions for working with
cached Positions and pos_ts.
```

dir **src**

dir **src/subcommand**

dir **src/unittest**

vg is a tool suite for working with **variation graphs**: graph-based data structures used to represent genomic information. These pages document the internals of the vg tool.

User documentation for vg is available at [the vg wiki](#).

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