
StochMCMC.jl Documentation

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Contents

1 Installation	3
1.1 Contents	3
1.2 Indices	13

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Website <https://github.com/alstat/StochMCMC.jl>

A julia package for Stochastic Gradient Markov Chain Monte Carlo. The package is part of my master's thesis entitled **Bayesian Autoregressive Distributed Lag via Stochastic Gradient Hamiltonian Monte Carlo** or **BADL-SGHMC**, under the supervision of **Dr. Joselito C. Magadia** of School of Statistics, University of the Philippines Diliman. This work aims to accommodate other Stochastic Gradient MCMCs in the near future.

CHAPTER 1

Installation

To install the package, run the following

```
Pkg.clone("https://github.com/alstat/StochMCMC.jl")
```

And to load the package, run

```
using StochMCMC
```

Contents

Metropolis-Hasting

Implementation of the Metropolis-Hasting sampler for Bayesian inference.

MH (*logposterior*::Function, *proposal*::Function, *init_est*::Array{Float64}, *d*::Int64)
Construct a Sampler object for Metropolis-Hasting sampling.

Arguments

- *logposterior* : the logposterior of the parameter of interest.
- *proposal* : the proposal distribution for random steps of the MCMC.
- *init_est* : the initial/startng value for the markov chain.
- *d* : the dimension of the posterior distribution.

Value

Returns a MH type object.

Example

In order to illustrate the modeling, the data is simulated from a simple linear regression expectation function. That is the model is given by

```
y_i = w_0 + w_1 x_i + e_i,    e_i ~ N(0, 1 / a)
```

To do so, let $B = [w_0, w_1]' = [.2, -.9]', a = 1 / 5$. Generate 200 hypothetical data:

```
using DataFrames
using Distributions
using Gadfly
using StochMCMC
Gadfly.push_theme(:dark)

srand(123);

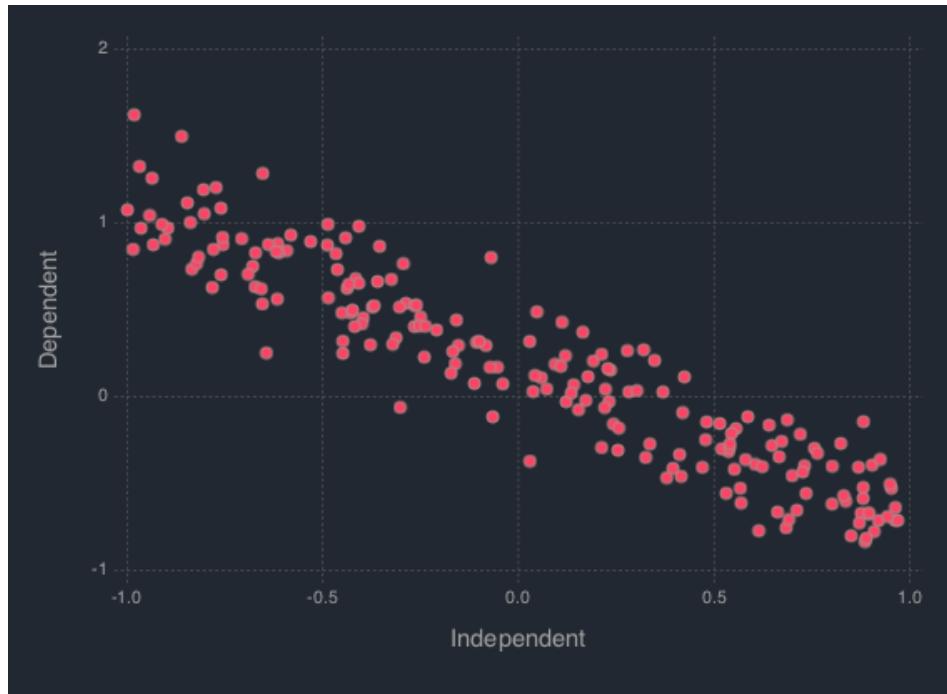
# Define data parameters
w0 = -.3; w1 = -.5; stdev = 5.; a = 1 / stdev

# Generate Hypothetical Data
n = 200;
x = rand(Uniform(-1, 1), n);
A = [ones(length(x)) x];
B = [w0; w1];
f = A * B;
y = f + rand(Normal(0, a), n);

my_df = DataFrame(Independent = round(x, 4), Dependent = round(y, 4));
```

Next is to plot this data which can be done as follows:

```
plot(my_df, x = :Independent, y = :Dependent)
```



In order to proceed with the Bayesian inference, the parameters of the model is considered to be random modeled by a standard Gaussian distribution. That is, $B \sim N(\mathbf{0}, I)$, where $\mathbf{0}$ is the zero vector. The likelihood of the data is given by,

```
L(w | [x, y], b) = _{i=1}^n N([x_i, y_i] | w, b)
```

Thus the posterior is given by,

```
P(w | [x, y]) = P(w) L(w | [x, y], b)
```

To start programming, define the probabilities

```
"""
The log prior function is given by the following codes:
"""

function logprior(theta::Array{Float64}; mu::Array{Float64} = zero_vec,
                    s::Array{Float64} = eye_mat)
    w0_prior = log(pdf(Normal(mu[1, 1], s[1, 1]), theta[1]))
    w1_prior = log(pdf(Normal(mu[2, 1], s[2, 2]), theta[2]))
    w_prior = [w0_prior w1_prior]

    return w_prior |> sum
end

"""
The log likelihood function is given by the following codes:
"""

function loglike(theta::Array{Float64}; alpha::Float64 = a, x::Array{Float64} =
                  x, y::Array{Float64} = y)
    yhat = theta[1] + theta[2] * x

    likhood = Float64[]
    for i in 1:length(yhat)
        push!(likhood, log(pdf(Normal(yhat[i], alpha), y[i])))
    end

    return likhood |> sum
end

"""
The log posterior function is given by the following codes:
"""

function logpost(theta::Array{Float64})
    loglike(theta, alpha = a, x = x, y = y) + logprior(theta, mu = zero_vec, s =
                eye_mat)
end
```

To start the estimation, define the necessary parameters.

```
# Hyperparameters
zero_vec = zeros(2)
eye_mat = eye(2)
```

Run the MCMC:

```
srand(123);
mh_object = MH(logpost; init_est = zeros(2));
chain1 = mcmc(mh_object, r = 10000);
```

Extract the estimate

```
burn_in = 100;
thinning = 10;

# Expectation of the Posterior
est1 = mapslices(mean, chain1[(burn_in + 1):thinning:end, :, [1]]);
est1
# 1x2 Array{Float64,2}:
# -0.313208 -0.46376
```

Hamiltonian Monte Carlo

Implementation of the Hamiltonian Monte Carlo sampler for Bayesian inference.

HMC ($U::Function$, $K::Function$, $dU::Function$, $dK::Function$, $init_est::Array<Float64>$, $d::Int64$)

Construct a `Sampler` object for Hamiltonian Monte Carlo sampling.

Arguments

- U : the potential energy or the negative log posterior of the parameter of interest.
- K : the kinetic energy or the negative exponential term of the log auxiliary distribution.
- dU : the gradient or first derivative of the potential energy U .
- dK : the gradient or first derivative of the kinetic energy K .
- $init_est$: the initial/startng value for the markov chain.
- d : the dimension of the posterior distribution.

Value

Returns a `HMC` type object.

Example

In order to illustrate the modeling, the data is simulated from a simple linear regression expectation function. That is the model is given by

```
y_i = w_0 + w_1 x_i + e_i,    e_i ~ N(0, 1 / a)
```

To do so, let $B = [w_0, w_1]' = [.2, -.9]'$, $a = 1 / 5$. Generate 200 hypothetical data:

```
using DataFrames
using Distributions
using Gadfly
using StochMCMC
Gadfly.push_theme(:dark)

strand(123);

# Define data parameters
w0 = -.3; w1 = -.5; stdev = 5.; a = 1 / stdev

# Generate Hypothetical Data
n = 200;
x = rand(Uniform(-1, 1), n);
A = [ones(length(x)) x];
B = [w0; w1];
f = A * B;
```

```
y = f + rand(Normal(0, a), n);

my_df = DataFrame(Independent = round(x, 4), Dependent = round(y, 4));
```

Next is to plot this data which can be done as follows:

```
plot(my_df, x = :Independent, y = :Dependent)
```



In order to proceed with the Bayesian inference, the parameters of the model is considered to be random modeled by a standard Gaussian distribution. That is, $B \sim N(\mathbf{0}, I)$, where $\mathbf{0}$ is the zero vector. The likelihood of the data is given by,

```
L(w | [x, y], b) = _{i=1}^n N([x_i, y_i] | w, b)
```

Thus the posterior is given by,

```
P(w | [x, y]) = P(w) L(w | [x, y], b)
```

To start programming, define the probabilities

```
"""
The log prior function is given by the following codes:
"""

function logprior(theta::Array{Float64}; mu::Array{Float64} = zero_vec,
                   s::Array{Float64} = eye_mat)
    w0_prior = log(pdf(Normal(mu[1, 1], s[1, 1]), theta[1]))
    w1_prior = log(pdf(Normal(mu[2, 1], s[2, 2]), theta[2]))
    w_prior = [w0_prior w1_prior]

    return w_prior |> sum
end
```

```
"""
The log likelihood function is given by the following codes:
"""

function loglike(theta::Array{Float64}; alpha::Float64 = a, x::Array{Float64} =
    ↪= x, y::Array{Float64} = y)
    yhat = theta[1] + theta[2] * x

    likelihood = Float64[]
    for i in 1:length(yhat)
        push!(likelihood, log(pdf(Normal(yhat[i], alpha), y[i])))
    end

    return likelihood |> sum
end

"""
The log posterior function is given by the following codes:
"""

function logpost(theta::Array{Float64})
    loglike(theta, alpha = a, x = x, y = y) + logprior(theta, mu = zero_vec, s_=
    ↪= eye_mat)
end
```

To start the estimation, define the necessary parameters

```
# Hyperparameters
zero_vec = zeros(2)
eye_mat = eye(2)
```

Setup the necessary paramters including the gradients. The potential energy is the negative logposterior given by U, the gradient is dU; the kinetic energy is the standard Gaussian function given by K, with gradient dK. Thus,

```
U(theta::Array{Float64}) = - logpost(theta);
K(p::Array{Float64}); Σ = eye(length(p)) = (p' * inv(Σ) * p) / 2;
function dU(theta::Array{Float64}; alpha::Float64 = a, b::Float64 = eye_-
    ↪mat[1, 1])
    [-alpha * sum(y - (theta[1] + theta[2] * x));
     -alpha * sum((y - (theta[1] + theta[2] * x)) .* x)] + b * theta
end
dK(p::AbstractArray{Float64}); Σ::Array{Float64} = eye(length(p)) = inv(Σ) *_
    ↪p;
```

Run the MCMC:

```
srand(123);
HMC_object = HMC(U, K, dU, dK, zeros(2), 2);
chain2 = mcmc(HMC_object, leapfrog_params = Dict([: => .09, :τ => 20]), r =_
    ↪10000);
```

Extract the estimate

```
est2 = mapslices(mean, chain2[(burn_in + 1):thinning:end, :, [1]];
est2
# 1x2 Array{Float64,2}:
# -0.307151 -0.458954
```

Stochastic Gradient Hamiltonian Monte Carlo

Implementation of the Hamiltonian Monte Carlo sampler for Bayesian inference.

SGHMC (*dU::Function*, *dK::Function*, *dKΣ::Array{Float64}*, *C::Array{Float64}*, *V::Array{Float64}*,
init_est::Array{Float64}, *d:Int64*)

Construct a Sampler object for Hamiltonian Monte Carlo sampling.

Arguments

- *dU* : the gradient or first derivative of the potential energy *U*.
- *dK* : the gradient or first derivative of the kinetic energy *K*.
- *dKΣ* : the variance-covariance matrix in the gradient of the kinetic energy *dK*, this is set to identity matrix for the case of standard Gaussian distribution.
- *C* : the matrix factor in the frictional force term.
- *V* : the matrix factor in the random force term.
- *init_est* : the initial/starting value for the markov chain.
- *d* : the dimension of the posterior distribution.

Value

Returns a SGHMC type object.

Example

In order to illustrate the modeling, the data is simulated from a simple linear regression expectation function. That is the model is given by

```
y_i = w_0 + w_1 x_i + e_i,    e_i ~ N(0, 1 / a)
```

To do so, let *B* = [*w_0*, *w_1*]' = [.2, -.9]', *a* = 1 / 5. Generate 200 hypothetical data:

```
using DataFrames
using Distributions
using Gadfly
using StochMCMC
Gadfly.push_theme(:dark)

srand(123);

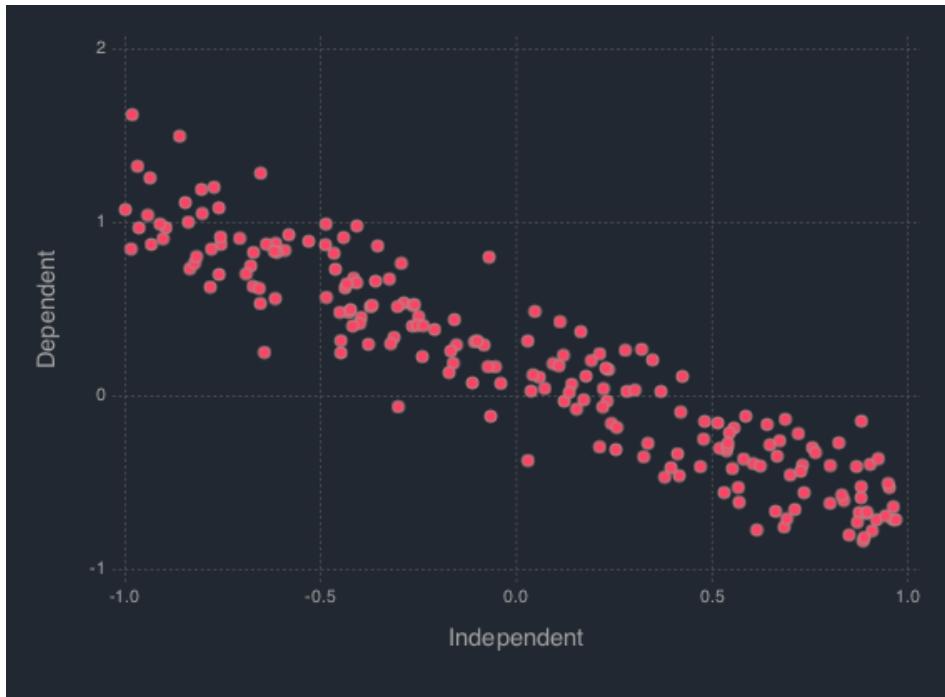
# Define data parameters
w0 = -.3; w1 = -.5; stdev = 5.; a = 1 / stdev

# Generate Hypothetical Data
n = 200;
x = rand(Uniform(-1, 1), n);
A = [ones(length(x)) x];
B = [w0; w1];
f = A * B;
y = f + rand(Normal(0, a), n);

my_df = DataFrame(Independent = round(x, 4), Dependent = round(y, 4));
```

Next is to plot this data which can be done as follows:

```
plot(my_df, x = :Independent, y = :Dependent)
```



In order to proceed with the Bayesian inference, the parameters of the model is considered to be random modeled by a standard Gaussian distribution. That is, $\mathbf{B} \sim N(\mathbf{0}, \mathbf{I})$, where $\mathbf{0}$ is the zero vector. The likelihood of the data is given by,

$$L(w | [x, y], b) = \prod_{i=1}^n N([x_i, y_i] | w, b)$$

Thus the posterior is given by,

$$P(w | [x, y]) \propto P(w) L(w | [x, y], b)$$

To start programming, define the probabilities

```
"""
The log prior function is given by the following codes:
"""

function logprior(theta::Array{Float64}; mu::Array{Float64} = zero_vec,
                   s::Array{Float64} = eye_mat)
    w0_prior = log(pdf(Normal(mu[1, 1], s[1, 1]), theta[1]))
    w1_prior = log(pdf(Normal(mu[2, 1], s[2, 2]), theta[2]))
    w_prior = [w0_prior w1_prior]

    return w_prior |> sum
end

"""
The log likelihood function is given by the following codes:
"""

function loglike(theta::Array{Float64}; alpha::Float64 = a, x::Array{Float64}
                  = x, y::Array{Float64} = y)
    yhat = theta[1] + theta[2] * x
```

```

likhood = Float64[]
for i in 1:length(yhat)
    push!(likhood, log(pdf(Normal(yhat[i], alpha), y[i])))
end

return likhood |> sum
end

"""
The log posterior function is given by the following codes:
"""

function logpost(theta::Array{Float64})
    loglike(theta, alpha = a, x = x, y = y) + logprior(theta, mu = zero_vec, s_
    ↵= eye_mat)
end

```

To start the estimation, define the necessary parameters

```

# Hyperparameters
zero_vec = zeros(2)
eye_mat = eye(2)

```

Setup the necessary paramters including the gradients.

```

function dU(theta::Array{Float64}; alpha::Float64 = a, b::Float64 = eye_-
    ↵mat[1, 1])
    [-alpha * sum(y - (theta[1] + theta[2] * x));
     -alpha * sum((y - (theta[1] + theta[2] * x)) .* x)] + b * theta
end
dK(p::AbstractArray{Float64}; Σ::Array{Float64} = eye(length(p))) = inv(Σ) *_
    ↵p;

```

Define the gradient noise and other parameters of the SGHMC:

```

function dU_noise(theta::Array{Float64}; alpha::Float64 = a, b::Float64 =_
    ↵eye_mat[1, 1])
    [-alpha * sum(y - (theta[1] + theta[2] * x));
     -alpha * sum((y - (theta[1] + theta[2] * x)) .* x)] + b * theta + randn(2,
    ↵1)
end

```

Run the MCMC:

```

 srand(123);
SGHMC_object = SGHMC(dU_noise, dK, eye(2), eye(2), eye(2), [0; 0], 2.);
chain3 = mcmc(SGHMC_object, leapfrog_params = Dict(:=> .09, :τ => 20)), r_
    ↵= 10000;

```

Extract the estimate:

```

est3 = mapslices(mean, chain3[(burn_in + 1):thinning:end, :], [1]);
est3
# 1×2 Array{Float64,2}:
# -0.302745 -0.430272

```

Plot it

```

my_df_sghmc = my_df;
my_df_sghmc[:Yhat] = mapslices(mean, chain3[(burn_in + 1):thinning:end, :], ↵
    ↵[1]) [1] + mapslices(mean, chain3[(burn_in + 1):thinning:end, :], [1])[2] * ↵
    ↵my_df[:Independent];

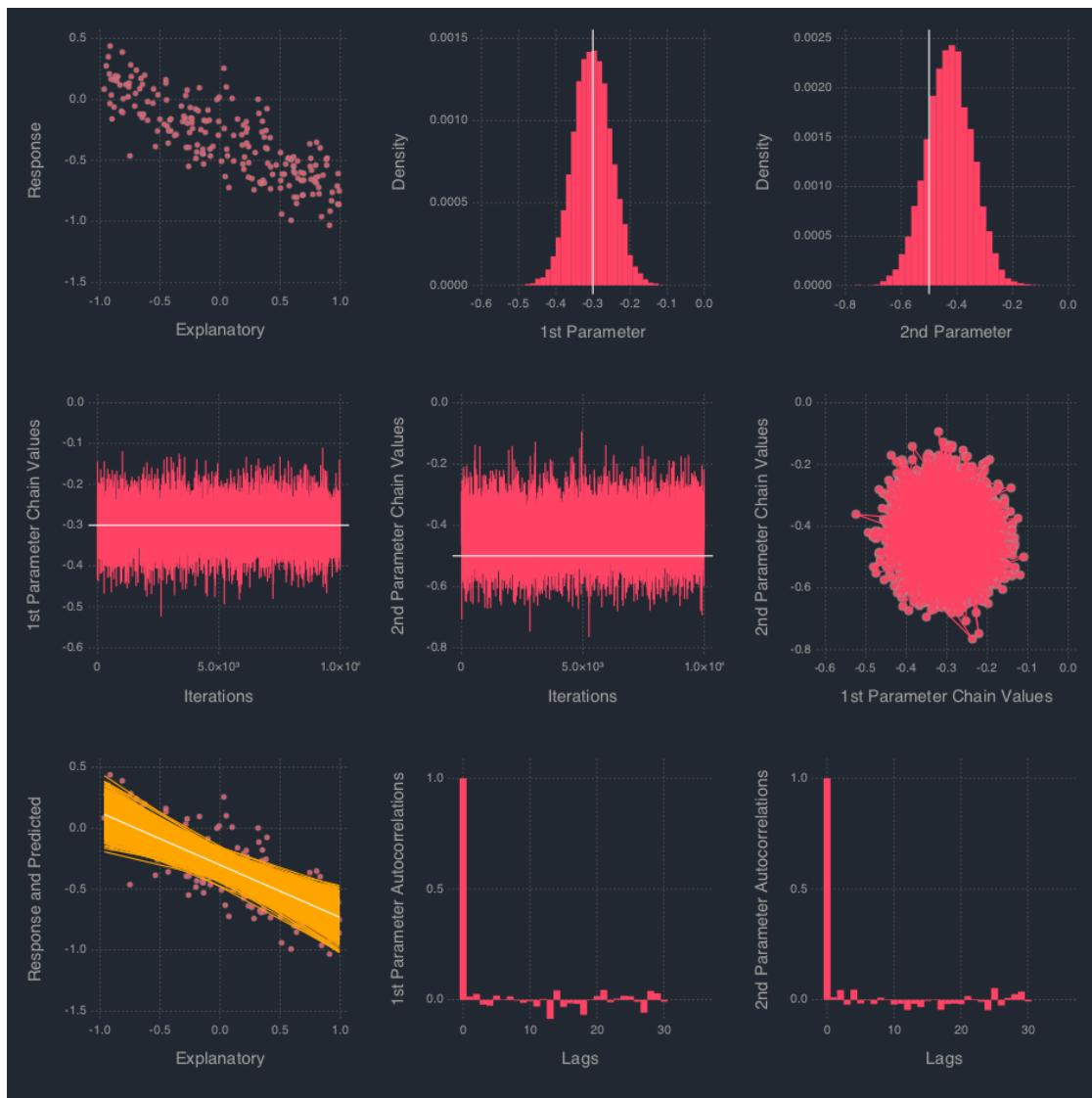
for i in (burn_in + 1):thinning:10000
    my_df_sghmc[Symbol("Yhat_Sample_") * string(i)] = chain3[i, 1] + ↵
    ↵chain3[i, 2] * my_df_sghmc[:Independent]
end

my_stack_sghmc = DataFrame(X = repeat(Array(my_df_sghmc[:Independent]), ↵
    ↵outer = length((burn_in + 1):thinning:10000)), ↵
    ↵Y = repeat(Array(my_df_sghmc[:Dependent]), outer ↵
    ↵= length((burn_in + 1):thinning:10000)), ↵
    ↵Var = Array(stack(my_df_sghmc[:, 4:end])[1]), ↵
    ↵Val = Array(stack(my_df_sghmc[:, 4:end])[2]));
chlcor_df = DataFrame(x = collect(0:1:(length(autocor(chain3[(burn_in + ↵
    ↵1):thinning:10000, 1])) - 1)), ↵
    ↵y1 = autocor(chain3[(burn_in + 1):thinning:10000, 1]), ↵
    ↵y2 = autocor(chain3[(burn_in + 1):thinning:10000, 2]));

p0 = plot(my_df, x = :Independent, y = :Dependent, Geom.point, style(default_ ↵
    ↵point_size = .05cm), Guide.xlabel("Explanatory"), Guide.ylabel("Response ↵
    ↵"));
p1 = plot(DataFrame(chain3), x = :x1, xintercept = [-.3], Geom.vline(color = ↵
    ↵colorant"white"), Geom.histogram(bincount = 30, density = true), Guide. ↵
    ↵xlabel("1st Parameter"), Guide.ylabel("Density"));
p2 = plot(DataFrame(chain3), x = :x2, xintercept = [-.5], Geom.vline(color = ↵
    ↵colorant"white"), Geom.histogram(bincount = 30, density = true), Guide. ↵
    ↵xlabel("2nd Parameter"), Guide.ylabel("Density"));
p3 = plot(DataFrame(chain3), x = collect(1:nrow(DataFrame(chain3))), y = :x1, ↵
    ↵yintercept = [-.3], Geom.hline(color = colorant"white"), Geom.line, Guide. ↵
    ↵xlabel("Iterations"), Guide.ylabel("1st Parameter Chain Values"));
p4 = plot(DataFrame(chain3), x = collect(1:nrow(DataFrame(chain1))), y = :x2, ↵
    ↵yintercept = [-.5], Geom.hline(color = colorant"white"), Geom.line, Guide. ↵
    ↵xlabel("Iterations"), Guide.ylabel("2nd Parameter Chain Values"));
p5 = plot(DataFrame(chain3), x = :x1, y = :x2, Geom.path, Geom.point, Guide. ↵
    ↵xlabel("1st Parameter Chain Values"), Guide.ylabel("2nd Parameter Chain ↵
    ↵Values"));
p6 = plot(layer(my_df_sghmc, x = :Independent, y = :Yhat, Geom.line, ↵
    ↵style(default_color = colorant"white")), ↵
    ↵layer(my_stack_sghmc, x = :X, y = :Val, group = :Var, Geom.line, ↵
    ↵style(default_color = colorant"orange")), ↵
    ↵layer(my_df_sghmc, x = :Independent, y = :Dependent, Geom.point, ↵
    ↵style(default_point_size = .05cm)), ↵
    ↵Guide.xlabel("Explanatory"), Guide.ylabel("Response and Predicted ↵
    ↵"));
p7 = plot(chlcor_df, x = :x, y = :y1, Geom.bar, Guide.xlabel("Lags"), Guide. ↵
    ↵ylabel("1st Parameter Autocorrelations"), Coord.cartesian(xmin = -1, xmax ↵
    ↵= 36, ymin = -.05, ymax = 1.05));
p8 = plot(chlcor_df, x = :x, y = :y2, Geom.bar, Guide.xlabel("Lags"), Guide. ↵
    ↵ylabel("2nd Parameter Autocorrelations"), Coord.cartesian(xmin = -1, xmax ↵
    ↵= 36, ymin = -.05, ymax = 1.05));

vstack(hstack(p0, p1, p2), hstack(p3, p4, p5), hstack(p6, p7, p8))

```



Indices

- genindex

Index

H

HMC() (built-in function), [6](#)

M

MH() (built-in function), [3](#)

S

SGHMC() (built-in function), [9](#)