
matrixutils documentation

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OpenGeophysics Developers

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CHAPTER 1

Why

matrixutils is a python package that includes utilities for working with matrices as linear operators in python. It includes utilities for wrapping and unwrapping matrices and vectors, tools for creating matrices, and operators *Zero* and *Identity* which improve code efficiency without sacrificing readability.

It is used by [discretize](#) and [SimPEG](#).

CHAPTER 2

Installation

```
pip install matrixutils
```

To install as a developer

```
git clone https://github.com/opengeophysics/matrixutils.git
cd matrixutils
python setup.py install
```

or to build the installation in-place:

```
git clone https://github.com/opengeophysics/matrixutils.git
cd matrixutils
python setup.py install build_ext --inplace
```


Website: <http://simpeg.xyz>

Documentation: <http://matrixutils.readthedocs.io>

Code: <https://github.com/opengeophysics/matrixutils>

Tests: Coming soon...

Bugs & Issues: <https://github.com/opengeophysics/matrixutils/issues>

Questions: <https://groups.google.com/forum/#!forum/simpeg>

Chat: <http://slack.simpeg.xyz/>

3.1 Examples

3.1.1 Examples

3.2 API

3.2.1 Matrix Utilities

`matrixutils.matutils.mkvc(x, numDims=1)`

Creates a vector with the number of dimension specified

e.g.:

```
a = np.array([1, 2, 3])
```

```
mkvc(a, 1).shape  
> (3, )
```

```
mkvc(a, 2).shape
```

```
> (3, 1)

mkvc(a, 3).shape
> (3, 1, 1)
```

`matrixutils.matutils.sdiag(h)`

Sparse diagonal matrix

`matrixutils.matutils.sdInv(M)`

Inverse of a sparse diagonal matrix

`matrixutils.matutils.speye(n)`

Sparse identity

`matrixutils.matutils.kron3(A, B, C)`

Three kron prods

`matrixutils.matutils.spzeros(n1, n2)`

a sparse matrix of zeros

`matrixutils.matutils.ddx(n)`

Define 1D derivatives, inner, this means we go from n+1 to n

`matrixutils.matutils.av(n)`

Define 1D averaging operator from nodes to cell-centers.

`matrixutils.matutils.av_extrap(n)`

Define 1D averaging operator from cell-centers to nodes.

`matrixutils.matutils.ndgrid(*args, **kwargs)`

Form tensorial grid for 1, 2, or 3 dimensions.

Returns as column vectors by default.

To return as matrix input:

`ndgrid(..., vector=False)`

The inputs can be a list or separate arguments.

e.g.:

```
a = np.array([1, 2, 3])
b = np.array([1, 2])

XY = ndgrid(a, b)
> [[1 1]
   [2 1]
   [3 1]
   [1 2]
   [2 2]
   [3 2]]

X, Y = ndgrid(a, b, vector=False)
> X = [[1 1]
       [2 2]
       [3 3]]
> Y = [[1 2]
       [1 2]
       [1 2]]
```

`matrixutils.matutils.ind2sub(shape, inds)`

From the given shape, returns the subscripts of the given index

`matrixutils.matutils.sub2ind(shape, subs)`

From the given shape, returns the index of the given subscript

`matrixutils.matutils.getSubArray(A, ind)`

subArray

`matrixutils.matutils.inv3X3BlockDiagonal(a11, a12, a13, a21, a22, a23, a31, a32, a33, returnMatrix=True)`

`B = inv3X3BlockDiagonal(a11, a12, a13, a21, a22, a23, a31, a32, a33)`

inverts a stack of 3x3 matrices

Input: A - a11, a12, a13, a21, a22, a23, a31, a32, a33

Output: B - inverse

`matrixutils.matutils.inv2X2BlockDiagonal(a11, a12, a21, a22, returnMatrix=True)`

`B = inv2X2BlockDiagonal(a11, a12, a21, a22)`

Inverts a stack of 2x2 matrices by using the inversion formula

$\text{inv}(A) = (1/\det(A)) * \text{cof}(A)^T$

Input: A - a11, a12, a21, a22

Output: B - inverse

class `matrixutils.matutils.Zero`

An efficient zero object.

`transpose()`

T

class `matrixutils.matutils.Identity(positive=True)`

An efficient identity object.

T

`transpose()`

3.2.2 Curv Utilities

`matrixutils.curvutils.volTetra(xyz, A, B, C, D)`

Returns the volume for tetrahedras volume specified by the indexes A to D.

Parameters

- **xyz** (*numpy.ndarray*) – X,Y,Z vertex vector
- **A, B, C, D** (*numpy.ndarray*) – vert index of the tetrahedra

Return type *numpy.ndarray*

Returns V, volume of the tetrahedra

Algorithm <https://en.wikipedia.org/wiki/Tetrahedron#Volume>

$$V = \frac{1}{3}Ah$$

$$V = \frac{1}{6}|(a-d) \cdot ((b-d)(c-d))|$$

`matrixutils.curvutils.indexCube(nodes, gridSize, n=None)`

Returns the index of nodes on the mesh.

Input: nodes - string of which nodes to return. e.g. 'ABCD' gridSize - size of the nodal grid n - number of nodes each i,j,k direction: [ni,nj,nk]

Output: index - index in the order asked e.g. 'ABCD' -> (A,B,C,D)

TWO DIMENSIONS:

```

node(i, j)           node(i, j+1)
  A ----- B
  |           |
  |   cell(i, j)   |
  |           |
  |           |
  D ----- C
node(i+1, j)       node(i+1, j+1)

```

THREE DIMENSIONS:

```

           node(i, j, k+1)       node(i, j+1, k+1)
             E ----- F
            / |           / |
           /  |          /  |
          /   |         /   |
node(i, j, k)       node(i, j+1, k)
  A ----- B
  |           |
  |   H -----|----- G
  |   /cell(i, j) |   /
  |   /   I      |   /
  |   /           |   /
  D ----- C
node(i+1, j, k)       node(i+1, j+1, k)

```

`matrixutils.curvutils.faceInfo(xyz, A, B, C, D, average=True, normalizeNormals=True)`
 function [N] = faceInfo(y,A,B,C,D)

Returns the averaged normal, area, and edge lengths for a given set of faces.

If average option is FALSE then N is a cell array {nA,nB,nC,nD}

Input: xyz - X,Y,Z vertex vector A,B,C,D - vert index of the face (counter clockwise)

Options: average - [true]/false, toggles returning all normals or the average

Output: N - average face normal or {nA,nB,nC,nD} if average = false area - average face area edgeLengths - exact edge Lengths, 4 column vector [AB, BC, CD, DA]

see also testFaceNormal testFaceArea

@author Rowan Cockett

Last modified on: 2013/07/26

3.2.3 Mesh Utilities

`matrixutils.meshutils.meshTensor(value)`

meshTensor takes a list of numbers and tuples that have the form:

```
mT = [ float, (cellSize, numCell), (cellSize, numCell, factor) ]
```

For example, a time domain mesh code needs many time steps at one time:

```
[(1e-5, 30), (1e-4, 30), 1e-3]
```

Means take 30 steps at 1e-5 and then 30 more at 1e-4, and then one step of 1e-3.

Tensor meshes can also be created by increase factors:

```
[(10.0, 5, -1.3), (10.0, 50), (10.0, 5, 1.3)]
```

When there is a third number in the tuple, it refers to the increase factor, if this number is negative this section of the tensor is flipped right-to-left.

3.2.4 Interpolation Utilities

`matrixutils.interputils.interpmat` (*locs*, *x*, *y=None*, *z=None*)

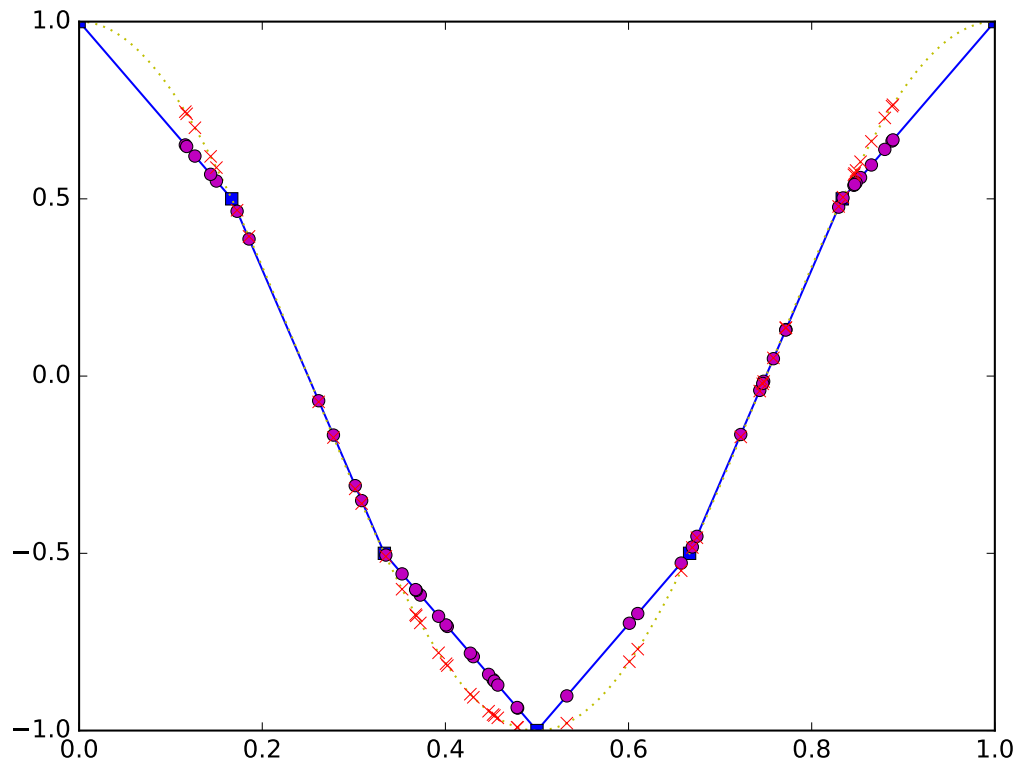
Local interpolation computed for each receiver point in turn

Parameters

- **loc** (*numpy.ndarray*) – Location of points to interpolate to
- **x** (*numpy.ndarray*) – Tensor of 1st dimension of grid.
- **y** (*numpy.ndarray*) – Tensor of 2nd dimension of grid. None by default.
- **z** (*numpy.ndarray*) – Tensor of 3rd dimension of grid. None by default.

Return type `scipy.sparse.csr_matrix`

Returns Interpolation matrix



3.3 Project Index & Search

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