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# **djio Documentation**

***Release 0.0.5***

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## 1.1 djio.errors

Did something go wrong? It did? Use something from this module to deal with it.

**exception** `djio.errors.DjioException` (*message: str, inner: Exception = None*)

Bases: `Exception`

This is a common base class for all custom djio exceptions.

**\_\_init\_\_** (*message: str, inner: Exception = None*)

### Parameters

- **message** – the exception message
- **inner** – the exception that caused this exception

### **inner**

Get the inner exception that caused this exception. :return: the inner exception

### **message**

Get the exception message. :return: the exception message

## 1.2 djio.geometry

Working with geometries? Need help? Here it is!

**class** `djio.geometry.Envelope` (*min\_x: float, min\_y: float, max\_x: float, max\_y: float, spatial\_reference: djio.geometry.SpatialReference*)

Bases: `djio.geometry.Polygon`

An envelope represents the minimum bounding rectangle (minimum x and y values, along with maximum x and y values) defined by coordinate pairs of a geometry. All coordinates for the geometry fall within the envelope.

**\_\_init\_\_** (*min\_x: float, min\_y: float, max\_x: float, max\_y: float, spatial\_reference: djio.geometry.SpatialReference*)

**Parameters**

- **min\_x** – the minimum X coordinate
- **min\_y** – the minimum Y coordinate
- **max\_x** – the maximum X coordinate
- **max\_y** – the maximum Y coordinate
- **spatial\_reference** – the spatial reference (or spatial reference ID) in which the coordinates are expressed

```
class djio.geometry.Geometry (shapely_geometry: <MagicMock id='140264541303920'>, spatial_reference: djio.geometry.SpatialReference = None)
```

Bases: object

This is the common base class for all of the geometry types.

```
__init__ (shapely_geometry: <MagicMock id='140264541303920'>, spatial_reference: djio.geometry.SpatialReference = None)
```

**Parameters**

- **shapely\_geometry** – a Shapely geometry
- **spatial\_reference** – the geometry's spatial reference

**dimensions**

How many dimensions does this geometry occupy? For example: a point is zero-dimensional (0); a line is one-dimensional (1); and a polygon is two-dimensional (2).

**Returns** the dimensionality of the geometry

**djiohash()**

Get this geometry's hash value.

**Returns** the hash value

**envelope**

Get the envelope (bounding box) of the geometry.

**Returns** the geometry's envelope

**flip\_coordinates()** → djio.geometry.Geometry

Create a geometry based on this one, but with the X and Y axis reversed.

**Returns** a new *Geometry* with reversed ordinals.

**static from\_ewkt()** → djio.geometry.Geometry

Create a geometry from EWKT, a PostGIS-specific format that includes the spatial reference system identifier an up to four (4) ordinate values (XYZM). For example: SRID=4326;POINT(-44.3 60.1) to locate a longitude/latitude coordinate using the WGS 84 reference coordinate system.

**Parameters ewkt** – the extended well-known text (EWKT)

**Returns** the geometry

```
static from_gealchemy2 (spatial_reference: djio.geometry.SpatialReference) →  
                        djio.geometry.Geometry
```

**static from\_gml()** → djio.geometry.Geometry

```
static from_ogr (spatial_reference: djio.geometry.SpatialReference = None) →  
                djio.geometry.Geometry
```

Create a djio geometry from an OGR geometry.

**Parameters**



- **ogr\_geom** – the OGR geometry
- **spatial\_reference** – the spatial reference

**Returns** a djio geometry based on the OGR geometry

**Raises** [\*GeometryException\*](#) – if the OGR has no spatial reference and no spatial reference is supplied

```
static from_shapely (spatial_reference: djio.geometry.SpatialReference) →  
                     djio.geometry.Geometry  
Create a new geometry based on a Shapely BaseGeometry.
```

**Parameters**

- **shapely\_geometry** – the Shapely base geometry
- **spatial\_reference** – the spatial reference (or spatial reference ID)

**Returns** the new geometry

**Seealso** [\*Point\*](#)

**Seealso** [\*Polyline\*](#)

**Seealso** [\*Polygon\*](#)

```
static from_wkb (spatial_reference: djio.geometry.SpatialReference) → djio.geometry.Geometry
```

```
static from_wkt (spatial_reference: djio.geometry.SpatialReference) → djio.geometry.Geometry
```

```
geometry_type
```

Get this geometry's type.

**Returns** the geometry's type

```
get_point_tuples () → Iterable[djio.geometry.PointTuple]
```

Get an ordered iteration of all the coordinates in the geometry as point tuples. :return: an enumeration of point tuples

```
iter_coords () → Iterable[Tuple[float, float]]
```

Retrieve the coordinates that define this geometry as a flattened, ordered iteration.

**Returns** and ordered iteration of tuples that describe the geometry's coordinates

```
project (preferred_spatial_reference: djio.geometry.SpatialReference = None, fall-  
        back_spatial_reference: djio.geometry.SpatialReference = 3857) → djio.geometry.Geometry  
Project (or re-project) this geometry.
```

**Parameters**

- **preferred\_spatial\_reference** – the preferred spatial reference
- **fallback\_spatial\_reference** – a spatial reference that may be used as a “fall-back” if the preferred spatial reference is not provided and a suitable projected spatial reference system isn't available

**Returns** a new, projected, geometry

**See also:**

[\*Projector\*](#)

```
representative_point
```

```
shapely_geometry
```

Get the Shapely geometry underlying this geometry object.

**Returns** the Shapely geometry

**spatial\_reference**

Get the geometry's spatial reference.

**Returns** the geometry's spatial reference

**to\_gml** (*version: int = 3*) → str

Export the geometry to GML.

**Parameters** **version** – the desired GML version

**Returns** the GML representation of the geometry

**to\_ogr**

Get the OGR geometry equivalent of this geometry.

**Returns** the OGR geometry equivalent

**transform** (*spatial\_reference: djio.geometry.SpatialReference*) → djio.geometry.Geometry

Create a new geometry based on this geometry but in another spatial reference.

**Parameters** **spatial\_reference** – the target spatial reference

**Returns** the new transformed geometry

**transform\_to\_utm** () → djio.geometry.Geometry

Transform this geometry to an appropriate UTM coordinate system based on its location.

**Returns** the new geometry

**exception** djio.geometry.**GeometryException** (*message: str, inner: Exception = None*)

Bases: [djio.errors.DjioException](#)

Raised when something goes wrong with a geometry.

**class** djio.geometry.**GeometryType**

Bases: enum.IntFlag

These are the supported geometric data types.

**POINT** = 1

**POLYGON** = 4

**POLYLINE** = 2

**UNKNOWN** = 0

**class** djio.geometry.**LatLonTuple**

Bases: tuple

This is a lightweight tuple that represents a specific latitude and longitude

**latitude**

Alias for field number 0

**longitude**

Alias for field number 1

**class** djio.geometry.**LateralSides**

Bases: enum.Enum

This is a simple enumeration that identifies the lateral side of line (left or right).

**LEFT** = 'left'

the left side of the line

**RIGHT** = 'right'  
the right side of the line

```
class djio.geometry.Point (shapely_geometry: <MagicMock id='140264541405312'>, spatial_reference: djio.geometry.SpatialReference = None)
Bases: djio.geometry.Geometry
```

In modern mathematics, a point refers usually to an element of some set called a space. More specifically, in Euclidean geometry, a point is a primitive notion upon which the geometry is built, meaning that a point cannot be defined in terms of previously defined objects. That is, a point is defined only by some properties, called axioms, that it must satisfy. In particular, the geometric points do not have any length, area, volume or any other dimensional attribute. A common interpretation is that the concept of a point is meant to capture the notion of a unique location in Euclidean space.

```
__init__ (shapely_geometry: <MagicMock id='140264541405312'>, spatial_reference:
djio.geometry.SpatialReference = None)
```

#### Parameters

- **shapely\_geometry** – a Shapely geometry
- **spatial\_reference** – the geometry's spatial reference

#### dimensions

A point is zero-dimensional (0) :return: zero (0)

**flip\_coordinates** () → djio.geometry.Point

Create a point based on this one, but with the X and Y axis reversed.

**Returns** a new *Geometry* with reversed ordinals.

```
static from_coordinates (y: float, spatial_reference: djio.geometry.SpatialReference, z:
Union[float, NoneType] = None)
```

Create a point from its coordinates.

#### Parameters

- **x** – the X coordinate
- **y** – the Y coordinate
- **spatial\_reference** – the spatial reference (or spatial reference ID)
- **z** – the Z coordinate

**Returns** the new *Point*

```
static from_lat_lon (longitude: float) → djio.geometry.Point
```

Create a geometry from a set of latitude, longitude coordinates.

#### Parameters

- **latitude** – the latitude
- **longitude** – the longitude

**Returns** *Point*

```
static from_latlon_tuple () → djio.geometry.Point
```

Create a point from a latitude/longitude tuple.

**Parameters** **latlon\_tuple** – the latitude/longitude tuple

**Returns** the new point

```
static from_point_tuple () → djio.geometry.Point
```

Create a point from a point tuple.

**Parameters** `point_tuple` – the point tuple

**Returns** the new point

**static** `from_shapely(srid: int) → djio.geometry.Point`

Create a new point based on a Shapely point.

**Parameters**

- **shapely** – the Shapely point
- **srid** – the spatial reference ID

**Returns** the new geometry

**Seealso** `Geometry.from_shapely()`

**geometry\_type**

Get the geometry type.

**Returns** `GeometryType.POINT`

**iter\_coords()** → Iterable[Tuple[float, float]]

Retrieve the coordinates that define this geometry. For a *Point*, the iteration shall contain a single set of coordinates. :return: an iteration containing a single tuple containing this point's coordinates

**to\_latlon\_tuple()** → djio.geometry.LatLonTuple

Get a lightweight latitude/longitude tuple representation of this point.

**Returns** the latitude/longitude tuple representation of this point

**to\_point\_tuple()** → djio.geometry.PointTuple

Get a lightweight tuple representation of this point.

**Returns** the tuple representation of the point

**x**

Get the X coordinate.

**Returns** the X coordinate

**y**

Get the Y coordinate.

**Returns** the Y coordinate

**z**

Get the Z coordinate.

**Returns** the Z coordinate

**class** `djio.geometry.PointTuple`

Bases: tuple

This is a lightweight tuple that represents a point.

**srid**

Alias for field number 3

**x**

Alias for field number 0

**y**

Alias for field number 1

**z**

Alias for field number 2

```
class djio.geometry.Polygon(shapely_geometry: <MagicMock id='140264541397344'>, spatial_reference: djio.geometry.SpatialReference = None)
Bases: djio.geometry.Geometry
```

In elementary geometry, a polygon is a plane figure that is bounded by a finite chain of straight line segments closing in a loop to form a closed polygonal chain or circuit. These segments are called its edges or sides, and the points where two edges meet are the polygon's vertices (singular: vertex) or corners. The interior of the polygon is sometimes called its body.

```
__init__(shapely_geometry: <MagicMock id='140264541397344'>, spatial_reference: djio.geometry.SpatialReference = None)
```

#### Parameters

- **shapely\_geometry** – a Shapely geometry
- **spatial\_reference** – the geometry's spatial reference

#### dimensions

A polygon is two-dimensional (2). :return: two (2)

#### geometry\_type

Get the geometry type.

Returns *GeometryType.POLYGON*

```
get_area(spatial_reference: Union[djio.geometry.SpatialReference, NoneType] = None) → <MagicMock id='140264541399360'>
```

```
iter_coords() → Iterable[Tuple[float, float]]
```

Retrieve the polygon's coordinates as a flattened enumeration. :return: an iteration containing the poly-line's coordinates

```
class djio.geometry.Polyline(shapely_geometry: <MagicMock id='140264565205312'>, spatial_reference: djio.geometry.SpatialReference = None)
Bases: djio.geometry.Geometry
```

In geometry, a polygonal chain is a connected series of line segments. More formally, a polygonal chain  $P$  is a curve specified by a sequence of points  $(A_1, A_2, \dots, A_n)$  called its vertices. The curve itself consists of the line segments connecting the consecutive vertices. A polygonal chain may also be called a polygonal curve, polygonal path, polyline, piecewise linear curve, broken line or, in geographic information systems (that's us), a linestring or linear ring.

```
__init__(shapely_geometry: <MagicMock id='140264565205312'>, spatial_reference: djio.geometry.SpatialReference = None)
```

#### Parameters

- **shapely\_geometry** – a Shapely geometry
- **spatial\_reference** – the geometry's spatial reference

#### dimensions

A polyline is one-dimensional (1) :return: one (1)

#### geometry\_type

Get the geometry type.

Returns *GeometryType.POLYLINE*

```
iter_coords() → Iterable[Tuple[float, float]]
```

Retrieve the coordinates that define this line. :return: an iteration containing the polyline's coordinates

```
class djio.geometry.Projector
Bases: object
```

Use a projector to get a projected version of a geographic geometry, or to re-project a projected geometry.

**static** `get_instance()` → `djio.geometry.Projector`

Get the shared projector instance. :return: the shared projector instance

**static** `project` (*preferred\_spatial\_reference:* `djio.geometry.SpatialReference` = `None`, *fallback\_spatial\_reference:* `djio.geometry.SpatialReference` = `3857`) → `djio.geometry.Geometry`

Project a geometry. :param geometry: the original geometry :param preferred\_spatial\_reference: the preferred spatial reference (If no preferred spatial reference is supplied, the projector will attempt to select an appropriate metric projection.) :param fallback\_spatial\_reference: the fallback spatial reference (if your preferred spatial reference isn't available) :return: the projected geometry

**static** `set_instance()`

Set the shared projector instance. :param projector: the shared projector

**class** `djio.geometry.ProtoGeometry` (*spatial\_reference:* `djio.geometry.SpatialReference` = `4326`,  
*projector:* `djio.geometry.Projector` = `None`)

Bases: `object`

Use a proto-geometry build up a new geometry from individual coordinates.

**\_\_init\_\_** (*spatial\_reference:* `djio.geometry.SpatialReference` = `4326`, *projector:* `djio.geometry.Projector` = `None`)

Initialize self. See help(type(self)) for accurate signature.

**add** (*p:* `djio.geometry.Point`)

Add a point to the prototype's exterior :param p: the new coordinate you want to add

**clear** ()

Clear the current contents.

**to\_polygon** () → `djio.geometry.Polygon`

Create a *Polygon* from the contents of this proto-geometry. :return: the *Polygon*

**to\_polyline** () → `djio.geometry.Polyline`

Create a *Polyline* from the contents of this proto-geometry. :return: the *Polyline*

**class** `djio.geometry.SpatialReference` (*srid:* `int`)

Bases: `object`

A spatial reference system (SRS) or coordinate reference system (CRS) is a coordinate-based local, regional or global system used to locate geographical entities. A spatial reference system defines a specific map projection, as well as transformations between different spatial reference systems.

**See also:**

[https://en.wikipedia.org/wiki/Spatial\\_reference\\_system](https://en.wikipedia.org/wiki/Spatial_reference_system)

**\_\_init\_\_** (*srid:* `int`)

**Parameters** `srid` – the well-known spatial reference ID

**static** `from_srid` () → `djio.geometry.SpatialReference`

**static** `get_utm_for_zone` () → `djio.geometry.SpatialReference`

Get the UTM (Universal Trans-Mercator) spatial reference for a given zone. :param zone: the UTM zone :return: the UTM spatial reference :raises `SpatialReferenceException`: if the UTM zone has no supported spatial reference

**static** `get_utm_from_longitude` () → `djio.geometry.SpatialReference`

Get the UTM (Universal Trans-Mercator) spatial reference for a given longitude. :param longitude: the longitude :return: the UTM spatial reference :raises `SpatialReferenceException`: if the UTM zone has no supported spatial reference

**is\_geographic**

Is this spatial reference geographic?

**Returns** *true* if this is a geographic spatial reference, otherwise *false*

**is\_metric**

Is this a projected spatial reference system that measures linear units in single meters?

**Returns** *true* if this is a projected spatial reference system that measures linear units in single meters

**is\_projected**

Is this spatial reference projected?

**Returns** *true* if this is a projected spatial reference, otherwise *false*

**is\_same\_as** (*other*: *djio.geometry.SpatialReference*) → bool

Test a spatial reference or SRID to see if it represents this spatial reference. :param other: the other spatial reference (or SRID) :return: True if the other parameter represents the same spatial reference, otherwise False

**is\_utm****ogr\_sr**

Get the OGR spatial reference.

**Returns** the OGR spatial reference

**srid**

Get the spatial reference's well-known ID (srid).

**Returns** the well-known spatial reference ID

**utm\_zone**

Get the UTM (Universal Trans-Mercator) zone associated with this spatial reference. :return: the associated UTM zone

**exception** *djio.geometry.SpatialReferenceException* (*message*: *str*, *inner*: *Exception* = *None*)

Bases: *djio.errors.DjioException*

Raised when something goes wrong with a spatial reference.

## 1.3 djio.hashing

Need to know at a glance if two geometries are the same?

*djio.hashing.bytes\_to\_int* (*b*: *bytes*)

Convert a byte array to an integer.

**Parameters** *b* – the byte array

**Returns** the integer

*djio.hashing.djiohash\_v1* (*geometry\_type\_code*: *int*, *srid*: *int*, *coordinates*: *Iterable[Tuple[float, float]]*, *precision*: *int* = 4) → bytearray

This is the first version of the djio hashing algorithm.

**Parameters**

- **geometry\_type\_code** – an integer indicating the type of the geometry
- **srid** – the numeric spatial reference ID

- **coordinates** – a flattened, ordered iteration of coordinates in the geometry expressed as tuples
- **precision** – the maximum precision (points behind decimal places) to consider in the supplied coordinates

**Returns** a hash value for the geometry

**See also:**

`djio.geometry.GeometryType`

`djio.hashing.int_to_bytes` (*i: int, width: int, unsigned: bool = False, as\_iterable: bool = False*) →  
bytearray

Convert an integer to a fixed-width byte array.

**Parameters**

- **i** – the integer
- **width** – the number of bytes in the array
- **unsigned** – *True* if the sign of the *int* may be disregarded, otherwise *False*
- **as\_iterable** – when *True* the function returns a list of byte-sized *int*'s instead of a *'bytearray'*.

**Returns** the byte array



---

## Python Module Dependencies

---

The `requirements.txt` file contains this project's module dependencies. You can install these dependencies using `pip`.

```
pip install -r requirements.txt
```

### 2.1 requirements.txt

```
alabaster>=0.7.10,<1
Babel>=2.5.3,<3
CaseInsensitiveDict>=1.0.0,<2
certifi>=2018.1.18
chardet==3.0.4
docutils==0.14
GDAL>=2.1.0,<3
GeoAlchemy2>=0.4.0,<1
idna==2.6
imagesize>=0.7.1
Jinja2>=2.10,<3
MarkupSafe==1.0
measurement>=1.8.0,<2
mock>=2.0.0,<3
numpy>=1.13.3,<2
Pygments==2.2.0
pyparsing>=2.2.0
pytz>=2018.3
pytest>=3.4.0,<4
pytest-cov>=2.5.1,<3
pytest-pythonpath>=0.7.2,<1
requests==2.18.4
setuptools>=38.4.0
Shapely>=1.6.1,<2
```

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```
six==1.11.0
snowballstemmer==1.2.1
Sphinx>=1.7.0,<2
sphinx-rtd-theme==0.2.4
sphinxcontrib-websupport==1.0.1
SQLAlchemy>=1.1.14,<2
sympy==0.7.6.1
urllib3==1.22
```

djio is in the early stages of development.

## 3.1 How To...

### 3.1.1 How To Install GDAL/OGR Packages on Ubuntu

GDAL is a translator library for raster and vector geospatial data formats.

OGR Simple Features Library is a C++ open source library (and commandline tools) providing read (and sometimes write) access to a variety of vector file formats including ESRI Shapefiles, S-57, SDTS, PostGIS, Oracle Spatial, and Mapinfo mid/mif and TAB formats.

OGR is a part of the GDAL library.

GDAL/OGR are used in [numerous GIS software projects](#) and, lucky for us, there are [bindings for python](#). In fact, you may want to check out the [Python GDAL/OGR Cookbook](#).

This article describes a process you can follow to install GDAL/OGR on Ubuntu.

#### Before You Begin: Python 3.6

If you are installing the GDAL/OGR packages into a virtual environment based on Python 3.6, you may need to install the `python3.6-dev` package.

```
sudo apt-get install python3.6-dev
```

For more information about creating virtual environments on Ubuntu 16.04 LTS, see [A Note About Python 3.6 and Ubuntu 16.04 LTS](#).

## Install GDAL/OGR

Much of this section is taken from a really helpful [blog post by Sara Safavi](#). Follow these steps to get GDAL/OGR installed.

To get the latest GDAL/OGR version, add the PPA to your sources, then install the gdal-bin package (this should automatically grab any necessary dependencies, including at least the relevant libgdal version).

```
sudo add-apt-repository ppa:ubuntugis/ppa && sudo apt-get update
```

Once you add the repository, go ahead and update your source packages.

```
sudo apt-get update
```

Now you should be able to install the GDAL/OGR package.

```
sudo apt-get install gdal-bin
```

To verify the installation, you can run `ogrinfo --version`.

```
ogrinfo --version
```

## Install GDAL for Python

Before installing the [GDAL Python libraries](#), you'll need to install the GDAL development libraries.

```
sudo apt-get install libgdal-dev
```

You'll also need to export a couple of environment variables for the compiler.

```
export CPLUS_INCLUDE_PATH=/usr/include/gdal
export C_INCLUDE_PATH=/usr/include/gdal
```

Now you can use `pip` to install the Python GDAL bindings.

```
pip install GDAL
```

## Putting It All Together

If you want to run the whole process at once, we've collected all the commands above in the script below.

```
#!/usr/bin/env bash

sudo add-apt-repository ppa:ubuntugis/ppa && sudo apt-get update
sudo apt-get update
sudo apt-get install gdal-bin
sudo apt-get install libgdal-dev
export CPLUS_INCLUDE_PATH=/usr/include/gdal
export C_INCLUDE_PATH=/usr/include/gdal
pip install GDAL
```

## Try It Out

Now that GDAL/OGR is installed, and you can program against it in Python, why not try it out? The code block below is a [sample](#) from the [Python OGR/GDAL Cookbook](#) that gets all the layers in an Esri file geodatabase.

```
# standard imports
import sys

# import OGR
from osgeo import ogr

# use OGR specific exceptions
ogr.UseExceptions()

# get the driver
driver = ogr.GetDriverByName("OpenFileGDB")

# opening the FileGDB
try:
    gdb = driver.Open(gdb_path, 0)
except Exception, e:
    print e
    sys.exit()

# list to store layers' names
featsClassList = []

# parsing layers by index
for featsClass_idx in range(gdb.GetLayerCount()):
    featsClass = gdb.GetLayerByIndex(featsClass_idx)
    featsClassList.append(featsClass.GetName())

# sorting
featsClassList.sort()

# printing
for featsClass in featsClassList:
    print featsClass

# clean close
del gdb
```

## Acknowledgements

Thanks to [Sara Safavi](#) and [Paul Whipp](#) for contributing some of the leg work on this.

### 3.1.2 How To Set Up a Virtual Python Environment (Linux)

`virtualenv` is a tool to create isolated Python environments. You can read more about it in the [Virtualenv documentation](#). This article provides a quick summary to help you set up and use a virtual environment.

#### A Note About Python 3.6 and Ubuntu 16.04 LTS

If you're running Ubuntu 16.04 LTS (or and earlier version), Python 3.5 is likely installed by default. *Don't remove it!* To get Python 3.6, follow the instructions in this section.

## Add the PPA

Run the following command to add the Python 3.6 PPA.

```
sudo add-apt-repository ppa:jonathonf/python-3.6
```

## Check for Updates and Install

Check for updates and install Python 3.6 via the following commands.

```
sudo apt-get update
sudo apt-get install python3.6
```

Now you have three Python version, use `python` to run version 2.7, `python3` for version 3.5, and `python3.6` for version 3.6.

For more information on this subject, check out Ji m's article [How to Install Python 3.6.1 in Ubuntu 16.04 LTS](#).

## Create a Virtual Python Environment

`cd` to your project directory and run `virtualenv` to create the new virtual environment.

The following commands will create a new virtual environment under `my-project/my-venv`.

```
cd my-project
virtualenv --python python3.6 venv
```

## Activate the Environment

Now that we have a virtual environment, we need to activate it.

```
source venv/bin/activate
```

After you activate the environment, your command prompt will be modified to reflect the change.

## Add Libraries and Create a *requirements.txt* File

After you activate the virtual environment, you can add packages to it using `pip`. You can also create a description of your dependencies using `pip`.

The following command creates a file called `requirements.txt` that enumerates the installed packages.

```
pip freeze > requirements.txt
```

This file can then be used by collaborators to update virtual environments using the following command.

```
pip install -r requirements.txt
```

## **Deactivate the Environment**

To return to normal system settings, use the `deactivate` command.

```
deactivate
```

After you issue this command, you'll notice that the command prompt returns to normal.

## **Acknowledgments**

Much of this article is taken from [The Hitchhiker's Guide to Python](#). Go buy a copy right now.





## CHAPTER 4

---

### Indices and tables

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